Riemann manifold Langevin and Hamiltonian Monte Carlo methods

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January 9, 2020

Overview

- Rational for new methods
- 2 Hamiltonian Monte Carlo methods
- Parameters Influence
- 4 Riemann Manifold HMC
- 5 Comparison with MCMC Algorithms Example of Bayesian Logistic Regression
- **6** Conclusion

Shortcomings of Monte Carlo algorithms

- Not scalable for target densities in high dimension
- Can demonstrate high correlations
- Can demonstrate low acceptation rates
 - ⇒ Need for new methods

HMC

<u>Goal</u>: Simulate a random variable $\theta \in \mathbb{R}^D \sim \pi$ a target density.

- Introduction of an **independent** auxiliary variable $\mathbf{Y} \in \mathbb{R}^D \sim \nu = \mathcal{N}(0, M)$ where M is called the mass matrix
- The negative log-proba of the joint distribution follows:

$$H(\theta, \mathbf{Y}) = -\underbrace{\mathcal{L}(\theta)}_{\text{energy function}} + \frac{1}{2} \log[(2\pi)^D |M|] + \underbrace{\frac{1}{2} \mathbf{Y}^\top M^{-1} \mathbf{Y}}_{\text{kinetic energy}}$$

• The derivatives of H give

$$\begin{aligned} \frac{d\theta}{d\tau} &= \frac{\partial H}{\partial \mathbf{Y}} = \mathbf{M}^{-1}\mathbf{Y} \\ \frac{d\mathbf{Y}}{d\tau} &= \frac{\partial H}{\partial \theta} = \nabla_{\theta} \mathcal{L}(\mathbf{X}) \end{aligned}$$

HMC

Stormer - Verlet (leapfrog) integrator

$$\begin{aligned} \mathbf{Y}(\tau+\varepsilon/2) &= \mathbf{Y}(\tau) + \varepsilon \nabla_{\theta} \mathcal{L}(\theta)/2 \\ \theta(\tau+\varepsilon) &= \theta(\tau) + \varepsilon M^{-1} \mathbf{Y}(\tau+\varepsilon/2) \\ \mathbf{Y}(\tau+\varepsilon) &= \mathbf{Y}(\tau+\varepsilon/2) + \varepsilon \nabla_{\theta} \mathcal{L}(\theta(\tau+\varepsilon))/2 \end{aligned} \tag{Stormer - Verlet}$$

• HMC sampling of $\pi(\theta)$ as a Gibbs sampler:

$$egin{aligned} \mathbf{Y}^{n+1} | heta^n &\sim \mathbf{Y}^{n+1} \sim \mathcal{N}(0, M) \ heta^{n+1} | \mathbf{Y}^{n+1} &\sim \mu(heta^{n+1} | \mathbf{Y}^{n+1}) \end{aligned}$$

- $\mu(\theta^{n+1}|\mathbf{Y}^{n+1})$ simulated using Stormer Verlet scheme and $(\tilde{\theta}, \tilde{\mathbf{Y}})$ is accepted with with probability $\min\{1, \exp(-H(\tilde{\theta}, \tilde{\mathbf{Y}}) + H(\theta^n, \mathbf{Y}^{n+1}))\}$
- $\bullet \Longrightarrow \mathsf{produces}$ an ergodic, time reversible Markov Chain with stationary density π
- Difficulty to select M regardless of the target density

Leapfrog Impact

Sampling of
$$\mathcal{N}(\mathbf{5}, \mathbf{\Sigma})$$
 where $\mathbf{\Sigma} = \begin{pmatrix} 0.2 & 0 \\ 0 & 0.8 \end{pmatrix}$

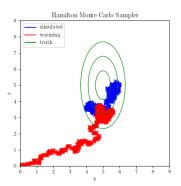


Figure: Leapfrog steps = 2, ε = 0.01

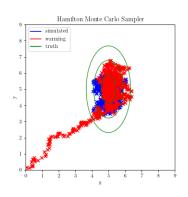


Figure: Leapfrog steps = 5, ε = 0.01

Leapfrog Impact

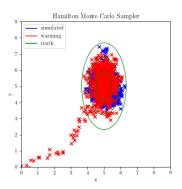


Figure: Leapfrog steps = 10, ε = 0.01

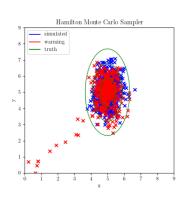


Figure: Leapfrog steps = 20, ε = 0.01

Acceptance Ratio

- Dimensions ranging from D=1 to 50
- Sampling of $\mathcal{N}(\mathbf{5}, \mathbf{I})$

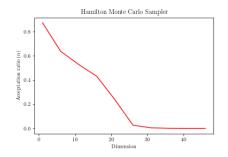


Figure: Leapfrog steps = 20, ε = 0.01

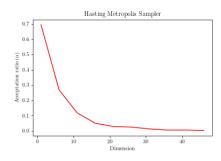


Figure: Sampled from $\mathcal{N}(\mathbf{0}, \mathbf{I})$

- Sampling of $\mathcal{N}(\mathbf{5}, \mathbf{I})$
- Leapfrog steps = 20, ε = 0.01 (HMC)
- Sampled from $\mathcal{N}(\mathbf{0}, \mathbf{I})$ (HM)

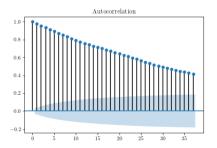


Figure: HMC (D = 2)

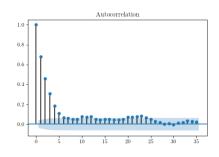


Figure: HM (D = 2)

- Sampling of $\mathcal{N}(\mathbf{5}, \mathbf{I})$
- Leapfrog steps = 20, ε = 0.01 (HMC)
- Sampled from $\mathcal{N}(\mathbf{0}, \mathbf{I})$ (HM)

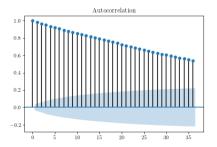


Figure: HMC (D = 5)

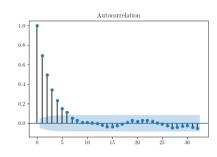


Figure: HM (D = 5)

- Sampling of $\mathcal{N}(\mathbf{5}, \mathbf{I})$
- Leapfrog steps = 20, ε = 0.01 (HMC)
- Sampled from $\mathcal{N}(\mathbf{0}, \mathbf{I})$ (HM)

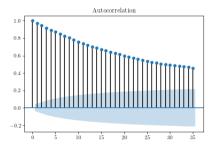


Figure: HMC (D = 10)

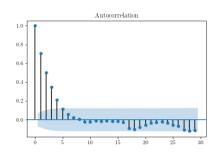


Figure: HM (D = 10)

- Sampling of $\mathcal{N}(\mathbf{5}, \mathbf{I})$
- Leapfrog steps = 20, ε = 0.01 (HMC)
- Sampled from $\mathcal{N}(\mathbf{0}, \mathbf{I})$ (HM)

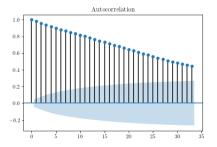


Figure: HMC (D = 20)

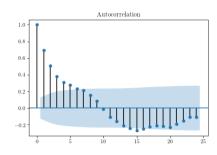


Figure: HM (D = 20)

Influence of M

- Leapfrog steps = 20, ε = 0.01
- warm start = 5000

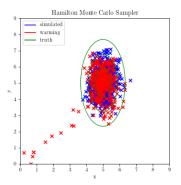


Figure: M = I

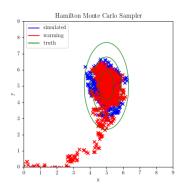


Figure: M = 10

Influence of M

- Leapfrog steps = 20, ε = 0.01
- warm start = 5000

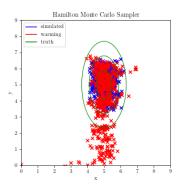


Figure:
$$M = \begin{pmatrix} 1 & 0 \\ 0 & 10 \end{pmatrix}$$
.

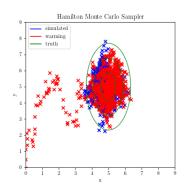


Figure:
$$M = \begin{pmatrix} 10 & 0 \\ 0 & 1 \end{pmatrix}$$
.

Riemann Manifold HMC

• Distance between two density functions $\Longrightarrow p(\mathbf{X}; \theta)$ and $p(\mathbf{X}; \theta + \delta \theta) = \delta \theta^{\top} \mathbf{G}(\theta) \delta \theta$ where $G(\theta)$ is the expected Fisher information matrix

$$\mathbf{G}(\theta) = -\mathbb{E}_{\mathbf{X}|\theta} \Big[\frac{\partial^2}{\partial \theta^2} \log(\rho(\mathbf{X}|\theta)) \Big] = \text{cov} \Big[\frac{\partial}{\partial \theta} \log(\rho(\mathbf{X}|\theta)) \Big]$$

⇒ position specific metric on a Riemann manifold

The Hamiltonian follows

$$H(\theta, \mathbf{Y}) = -\underbrace{\mathcal{L}(\theta)}_{\text{energy function}} + \frac{1}{2} \log[(2\pi)^D |G(\theta)|] + \underbrace{\frac{1}{2} \mathbf{Y}^\top \mathbf{G}(\theta)^{-1} \mathbf{Y}}_{\text{kinetic energy}}$$

• Baysian approach \Longrightarrow $\mathbf{G}(\theta) = -\mathbb{E}_{\mathbf{X}|\theta} \Big[\frac{\partial^2}{\partial \theta^2} \log(p(\mathbf{X},\theta)) \Big]$

Riemann Manifold HMC

• Again the Riemann HMC sampling of $\pi(\theta)$ can be seen as a Gibbs sampler:

$$\mathbf{Y}^{n+1}| heta^n \sim \mathcal{N}(0,\mathbf{G}(heta^n))$$

 $heta^{n+1}|\mathbf{Y}^{n+1} \sim \mu(heta^{n+1}|\mathbf{Y}^{n+1})$

- $\mu(\theta^{n+1}|\mathbf{Y}^{n+1})$ simulated using generalized Stormer Verlet scheme and $(\tilde{\theta}, \tilde{\mathbf{Y}})$ is accepted with with probability $\min\{1, \exp(-H(\tilde{\theta}, \tilde{\mathbf{Y}}) + H(\theta^n, \mathbf{Y}^{n+1}))\}$
- $\bullet \Longrightarrow \mathsf{produces}$ an ergodic, time reversible Markov Chain with stationary density π
- M mass matrix replaced by position specific metric $\mathbf{G}(\theta) \longrightarrow$ no need to tune the M coefficients
 - \Longrightarrow Need for a new time-reversible numerical integrator for solving the non-separable Hamiltonian
- How to choose the metric G?

Example of Bayesian Logistic Regression

- The model:
 - Let $\mathbf{X} \in \mathbb{R}^{N \times D}$ be the design matrix
 - $\beta \in \mathbb{R}^D$ regression parameter with $\beta \sim \pi = \mathcal{N}(\mathbf{0}, \alpha \mathbf{I})$ with α given
 - We look for β such that $\mathbf{Y}_n = s(\mathbf{X}_n^\top \beta^\top)$ where s is the sigmoid function
- The metric tensor follows:

$$\begin{aligned} \mathbf{G}(\beta) &= -\mathbb{E}_{\mathbf{Y}|\beta} \Big[\frac{\partial^2}{\partial \beta^2} \log(p(\mathbf{Y},\beta)) \Big] \\ &= \underbrace{\mathbb{E}_{\mathbf{Y}|\beta} \Big[\frac{\partial^2}{\partial \beta^2} \log(p(\mathbf{Y}|\beta)) \Big]}_{\text{Fisher-Rao}} - \underbrace{\frac{\partial^2}{\partial \beta^2} \log(\pi(\beta))}_{\text{NegativeHessian}} \\ &= \mathbf{X}_n^\top \Lambda \mathbf{X} + \alpha^{-1} \mathbf{I} \end{aligned}$$

where Λ is diagonal and $\Lambda_{n,n} = s(\beta^{\top} \mathbf{X}_n^{\top})(1 - s(\beta^{\top} \mathbf{X}_n^{\top}))$

Comparison

- Models considered
 - Component-wise adaptive MH
 - Joint updating Gibbs
 - MALA
 - HMC
 - RHMC Student
 - Iterated weighted least squares

Name	Covariates (D)	Data points (N)	Dimension of $\beta(b)$
Pima Indian	7	532	8
Australian credit	14	690	15
German credit	24	1000	25
Heart	13	270	14
Ripley	2	250	7

Figure: Dataset

Results

• Criteria: $ESS = N(1 + 2\sum_k \gamma(k))$ on each covariate. N: the number of posterior samples $\sum_k \gamma(k)$: sum of the K monotone sample auto-correlations.

Method	Time	ESS (min, avg, max)	s/min ESS	Relative speed
Metropolis	23.4	(167, 613, 1015)	0.140	13.3
Mala	3.5	(95.5, 316, 667)	0.037	50.3
НМС	117.9	(3182, 3632, 3986)	0.037	50.3
IWLS	7.8	(4.2, 9.9, 69)	1.1862	1
RHMC - S	257.4	(3981, 4934, 5000)	0.065	28.6
RMHMC	246.6	(4757, 5000, 5000)	0.052	35.8

Table: Results (D = 24, N = 1000)

Conclusion

- Strong demonstrated results
- Choice of the metric to be further investigated (Student, ...)
- Choice of the kinetic energy to be further investigated
- What about even bigger dimensions (100, 1000, ...) ?
 - ⇒ Computation cost scaling

Proposition

Proposition: The transition kernel:

$$P(\theta, A) = \int_{\mathcal{Y}} \mathbf{1}(\tilde{\Phi}^{N}(\theta, y)) \alpha((\theta, y, \Phi^{N}(\theta, y)) \nu(y) dy$$
$$+ \mathbf{I}_{\theta}(A) \int_{\mathcal{Y}} (1 - \alpha((\theta, y, \Phi^{N}(\theta, y)) \nu(y) dy$$

where Φ^N is the outcome of N leapfrog step and $\tilde{\Phi}(\theta,y)=\theta$

Proposition: π is stationary for P

Proof

Proof let f be a Borel function

$$\begin{split} \mathbb{E}\Big[f(\theta^{n+1})|\mathcal{F}_n\Big] &= \mathbb{E}_{\mathbf{Y}}\Big[\mathbb{E}\Big[f(\theta^{n+1}|\mathcal{F}_n,\mathbf{Y}_{n+1}]\Big] \\ &= \int_{\mathcal{Y}} \mathbb{E}_{(U,\theta)}\Big[f(\tilde{\Phi}^N(\theta,y)\mathbf{I}_{\{U \leq \alpha((\theta,y,\Phi^N(\theta,y))\}} \\ &+ f(\theta^n)\mathbf{I}_{\{U > \alpha((\theta,y,\Phi^N(\theta,y))\}}\Big]\nu(y)dy \\ &= \int_{\theta} \int_{\mathcal{Y}} f(\tilde{\Phi}^N(\theta,y))\alpha((\theta,y,\Phi^N(\theta,y))\nu(y)dyd\theta \\ &+ \int_{\theta} \delta_{\theta^n}(f) \int_{\mathcal{Y}} (1 - \alpha((\theta,y,\Phi^N(\theta,y)))\nu(y)dyd\theta \end{split}$$

Proof

Sketch of proof: We use the balanced equation $\pi(\theta)P(\theta',\theta) = \pi(\theta')P(\theta,\theta')$ "

0

$$\pi(\theta) * \alpha((\theta, y, \theta', y') * \nu(y) = \pi(\theta) * \min\left(1, \frac{\pi(\theta')\nu(y')}{\pi(\theta)\nu(y)}\right) * \nu(y)$$
$$= \pi(\theta') * \alpha(\theta', y', \theta, y) * \nu(y')$$

•

$$\int_{A \times B} \pi(d\theta) P_2(\theta, d\theta') = \int_{A \cap B} \pi(d\theta) h(\theta, \cdot)$$

$$= \int_{A \cap B} \pi(d\theta') h(\theta, \cdot)$$

$$= \int_{A \times B} \pi(d\theta') P_2(\theta', d\theta)$$