CSE6730 Modeling & Simulation : Project-1

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Chapter 1

Hierarchical Index

1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

_Topology	5
calender_queue	6
event_compare	1
EventBase	1
Event0 < T, OBJ >	7
Event1 < T, OBJ, U1, T1 >	8
Event2 < T, OBJ, U1, T1, U2, T2 >	9
$ \text{Event3} < \text{T, OBJ, U1, T1, U2, T2, U3, T3} > \dots $	0
Intersection	2
IntersectionwithoutSignal	3
IntersectionwithSignal	5
prioqueue	6
RandomNumGen	6
RoadSegment	7
Simulator	7
TrafficLight	8
VehicleClass	9
VehicleQueue 1	o

2 **Hierarchical Index**

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

_Topology	5
calender_queue	6
Event0 < T, OBJ >	7
$ Event1 < T, OBJ, U1, T1 > \ldots $	8
Event2< T, OBJ, U1, T1, U2, T2 >	9
Event3 < T, OBJ, U1, T1, U2, T2, U3, T3 >	10
event_compare	11
EventBase	11
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IntersectionwithoutSignal	13
IntersectionwithSignal	15
prioqueue	16
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RoadSegment	17
Simulator	17
TrafficLight	18
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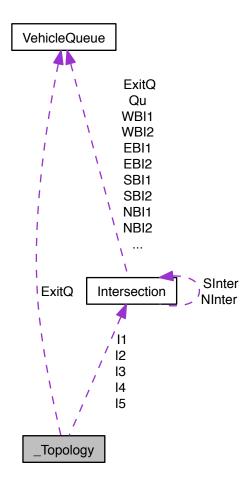
Class Index

Chapter 3

Class Documentation

3.1 _Topology Class Reference

Collaboration diagram for _Topology:



Public Attributes

- Intersection * I1
- Intersection * I2
- Intersection * I3
- Intersection * I4
- Intersection * I5
- VehicleQueue * ExitQ

The documentation for this class was generated from the following file:

• Topology.h

3.2 calender_queue Class Reference

```
#include <calender_queue.h>
```

Public Member Functions

- void insert (EventBase *)
- void dequeue (EventBase *)
- EventBase * PopNext ()
- EventBase * next_event (int)
- void remove_event (int, EventBase *)
- int isEmpty ()
- int get_bucket_count ()
- int getQsize ()
- int gettimeframe ()
- void check659bucket ()

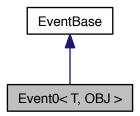
3.2.1 Detailed Description

Name changed from prioqueue to calender_queue for sake of clearity

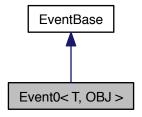
- · calender queue.h
- calender_queue.cc

3.3 Event0 < T, OBJ > Class Template Reference

Inheritance diagram for Event0< T, OBJ >:



Collaboration diagram for Event0< T, OBJ >:



Public Member Functions

- Event0 (double t, void(T::*f)(), OBJ *obj0)
- void CallHandler ()

Public Attributes

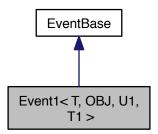
- void(T::* handler)(void)
- OBJ * obj

The documentation for this class was generated from the following file:

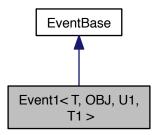
· Events.h

3.4 Event1< T, OBJ, U1, T1> Class Template Reference

Inheritance diagram for Event1< T, OBJ, U1, T1 >:



Collaboration diagram for Event1 < T, OBJ, U1, T1 >:



Public Member Functions

- **Event1** (double t, void(T::*f)(U1), OBJ *obj0, T1 t1_0)
- void CallHandler ()

Public Attributes

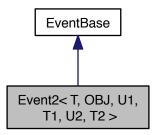
- void(T::* handler)(U1)
- OBJ * obj
- T1 **t1**

The documentation for this class was generated from the following file:

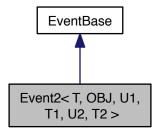
• Events.h

3.5 Event2< T, OBJ, U1, T1, U2, T2> Class Template Reference

Inheritance diagram for Event2< T, OBJ, U1, T1, U2, T2 >:



Collaboration diagram for Event2< T, OBJ, U1, T1, U2, T2 >:



Public Member Functions

- Event2 (double t, void(T::*f)(U1, U2), OBJ *obj0, T1 t1_0, T2 t2_0)
- void CallHandler ()

Public Attributes

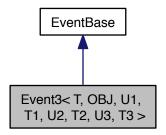
- void(T::* handler)(U1, U2)
- OBJ * obj
- T1 t1
- T2 **t2**

The documentation for this class was generated from the following file:

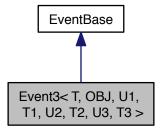
• Events.h

3.6 Event3 < T, OBJ, U1, T1, U2, T2, U3, T3 > Class Template Reference

Inheritance diagram for Event3< T, OBJ, U1, T1, U2, T2, U3, T3 >:



Collaboration diagram for Event3< T, OBJ, U1, T1, U2, T2, U3, T3 >:



Public Member Functions

- Event3 (double t, void(T::*f)(U1, U2, U3), OBJ *obj0, T1 t1_0, T2 t2_0, T3 t3_0)
- void CallHandler ()

Public Attributes

- void(T::* handler)(U1, U2, U3)
- OBJ * obj
- T1 **t1**
- T2 t2
- T3 t3

The documentation for this class was generated from the following file:

· Events.h

3.7 event_compare Class Reference

Public Member Functions

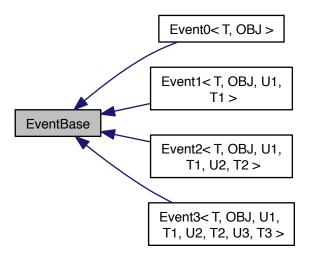
• bool operator() (EventBase *const &I, const EventBase *const &r) const

The documentation for this class was generated from the following file:

· Events.h

3.8 EventBase Class Reference

Inheritance diagram for EventBase:



Public Member Functions

- EventBase (Time_t t)
- virtual void CallHandler ()=0
- Time_t getTime ()

Public Attributes

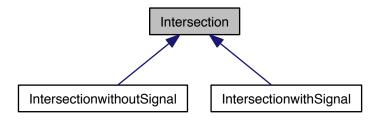
• Time_t time

The documentation for this class was generated from the following file:

· Events.h

3.9 Intersection Class Reference

Inheritance diagram for Intersection:



Collaboration diagram for Intersection:



Public Member Functions

- Intersection (int)
- int getID ()
- void VehiclePass (VehicleClass *vehicle, int Turn)
- void VehicleDeparture (VehicleClass *vehicle)
- void **EvictQ** (VehicleQueue *joinqueue)
- virtual void addVehicletoQueue (VehicleQueue *joinqueue, VehicleClass *vehicle)=0

- virtual int QCanGo (int direction, int lane)=0
- int getQdirection (VehicleQueue *Q)
- int getQlane (VehicleQueue *Q)
- void **NextQInfo** (VehicleQueue *currentQ, VehicleClass *vehicle, Intersection *&NextInter, VehicleQueue *&FutureQ, bool &isfull, int &Turn)

Public Attributes

- VehicleQueue * EBI1
- VehicleQueue * EBI2
- VehicleQueue * WBI1
- VehicleQueue * WBI2
- VehicleQueue * NBI1
- VehicleQueue * NBI2
- VehicleQueue * SBI1
- VehicleQueue * SBI2
- VehicleQueue * Qu [4][2]
- dir routingtable [12]
- int NBIlength
- · int SBllength
- VehicleQueue * ExitQ
- Intersection * NInter
- Intersection * SInter

Protected Attributes

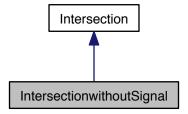
- int **ID**
- · bool haveSignal
- bool busy

The documentation for this class was generated from the following files:

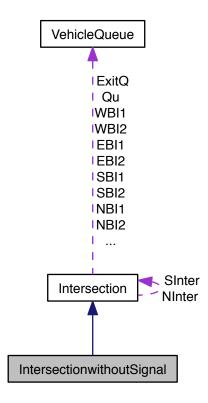
- · Intersection.h
- · Intersection.cpp

3.10 IntersectionwithoutSignal Class Reference

Inheritance diagram for IntersectionwithoutSignal:



Collaboration diagram for IntersectionwithoutSignal:



Public Member Functions

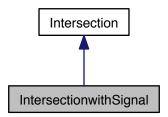
- virtual void addVehicletoQueue (VehicleQueue *joinqueue, VehicleClass *vehicle)
- virtual int QCanGo (int direction, int lane)
- IntersectionwithoutSignal (int)

Additional Inherited Members

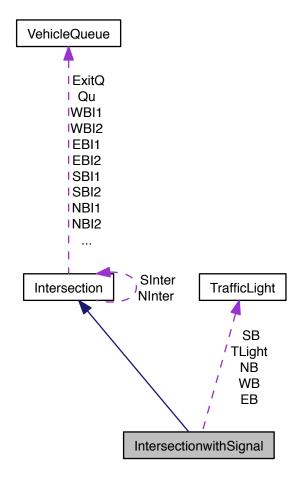
- · IntersectionwoSignal.h
- IntersectionwoSignal.cpp

3.11 IntersectionwithSignal Class Reference

Inheritance diagram for IntersectionwithSignal:



Collaboration diagram for IntersectionwithSignal:



Public Member Functions

- void changeSignalTrigger (int LightID)
- virtual void addVehicletoQueue (VehicleQueue *joinqueue, VehicleClass *vehicle)
- virtual int **QCanGo** (int direction, int lane)
- · IntersectionwithSignal (int)

Public Attributes

```
• TrafficLight * EB
```

- TrafficLight * WB
- TrafficLight * NB
- TrafficLight * SB
- TrafficLight * TLight [4]

Additional Inherited Members

The documentation for this class was generated from the following files:

- · IntersectionwithSignal.h
- · IntersectionwithSignal.cpp

3.12 prioqueue Class Reference

Public Member Functions

- void enqueue (EventBase *)
- EventBase * dequeue (EventBase *)
- EventBase * PopNext ()
- bool isEmpty ()

The documentation for this class was generated from the following file:

· prioqueue.h

3.13 RandomNumGen Class Reference

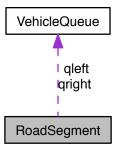
Public Member Functions

- RandomNumGen (unsigned long x0)
- · double Next ()
- · void Reset ()
- unsigned long GetState ()

- · RandomNum.h
- RandomNum.cc

3.14 RoadSegment Class Reference

Collaboration diagram for RoadSegment:



Public Member Functions

- RoadSegment (dir direction, Intersection *par, int cap)
- void AddVehicle (VehicleClass *vehicle)
- void EvictVehicle ()

Public Attributes

- · VehicleQueue qright
- VehicleQueue qleft

The documentation for this class was generated from the following files:

- · RoadSegment.h
- · RoadSegment.cpp

3.15 Simulator Class Reference

Collaboration diagram for Simulator:



Public Member Functions

- void Stop ()
- Time_t getNow ()
- template<typename T, typename OBJ, typename U1, typename T1 > void Schedule (double t, void(T::*handler)(U1), OBJ *obj, T1 t1)
- template<typename T, typename OBJ, typename U1, typename T1, typename U2, typename T2 > void Schedule (double t, void(T::*handler)(U1, U2), OBJ *obj, T1 t1, T2 t2)
- template<typename T , typename OBJ , typename U1 , typename T1 , typename U2 , typename T2 , typename U3 , typename T3 > void Schedule (double t, void(T::*handler)(U1, U2, U3), OBJ *obj, T1 t1, T2 t2, T3 t3)

Static Public Member Functions

- static void Run ()
- static void StopAt (Time t)
- template<typename T, typename OBJ >
 static void Schedule (double t, void(T::*handler)(void), OBJ *obj)
- static Time_t Now ()

Static Public Attributes

• static Simulator * instance =0

The documentation for this class was generated from the following files:

- · Simulator.h
- · Simulator.cpp

3.16 TrafficLight Class Reference

Public Member Functions

- int getType ()
- state getState ()
- TrafficLight (int id, int typ, state initialState, double Ph1, double Ph2, double Ph3, double Ph4, double Ph5, double Ph6, IntersectionwithSignal *p)
- · void cyclestate ()

Public Attributes

· int myid

- · TrafficLight.h
- · TrafficLight.cpp

3.17 VehicleClass Class Reference

Public Member Functions

- void **setEndTime** (Time_t t)
- int getID ()
- void updateDirection (dir Direction)

!Constructor

- dir getDirection ()
- void setLastQ (VehicleQueue *Q)
- VehicleQueue * getLastQ ()
- int getDestination ()
- VehicleClass (int id, int start, int Dest, Time_t starttime)

The documentation for this class was generated from the following files:

- · VehicleClass.h
- · VehicleClass.cpp

3.18 VehicleQueue Class Reference

- · VehicleQueue.h
- · VehicleQueue.cpp

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```