Implementing Tensor Calc functions in Diderot

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April 2, 2018

1 Overview

Shorthand for code

Path = https://github.com/cchiw Exs = Path/latte/ DATm = Path/DATm Diderot.Dev = Path/Diderot-DevVis15 = vis15

Shorthand for Text

[Doc] = Exs/writeup/paper.pdf [dissertation] = Chiw'17 dissertation [AST paper] = Chiw'17 ICSE-AST paper

1.1 Composition

1.1.1 Design and Implementation

```
field#k(d0)[\sigma] F0;
field#k(d1)[d0] F1;
field#k(d1)[\sigma] H = F0 \circ F1;
tensor[d1] pos;
tensor[\sigma] out = H(pos);
```

Representation We represent the field composition operator with the generic EIN operator.

$$\Longrightarrow_{init} H = \lambda(F,G) \Big\langle F_{\alpha} \circ [\langle G_{\beta} \rangle_{\hat{\beta}}] \Big\rangle_{\hat{\alpha}} (F0,F1) \quad \text{where } \hat{\alpha} = \sigma \text{ and } \hat{\beta} = [d0]$$

The field terms F and G represent fields in the composition. F and G have separate index spaces. F is bound by α and G is bound by β .

Normalization The probe of a composition $(e_1 \circ [\langle e_2 \rangle_{\hat{\beta}}])(x)$ is rewritten depending on the structure of the outer term e_1 . When the outer term is a constant the result does not depend on the composition operation.

$$(c \circ e_c)(x) \xrightarrow{rule} c$$

Similarly, when the outer term is a non-field:

$$(\delta_{\alpha} \circ e_c)(x) \xrightarrow[rule]{rule} \delta_{\alpha} \qquad (\mathcal{E}_{\alpha} \circ e_c)(x) \xrightarrow[rule]{rule} \mathcal{E}_{\alpha}$$

$$(Z_{\alpha} \circ e_c)(x) \xrightarrow[rule]{rule} Z_{\alpha} \qquad (\mathbf{lift}_d(e) \circ e_c)(x) \xrightarrow[rule]{rule} e$$

The probe operator is pushed past arithmetic operators:

$$(\odot_1 e \circ e_c)(x) \xrightarrow{rule} \odot_1 (e \circ e_c)(x)$$
$$(\sum_{\hat{\alpha}} e \circ e_c)(x) \xrightarrow{rule} \sum_{\hat{\alpha}} (e \circ e_c)(x)$$

The probe is distributed:

$$((e_a - e_b) \circ e_c)(x) \xrightarrow{rule} (e_a \circ e_c)(x) - (e_b \circ e_c)(x)$$
$$((e_a * e_b * e_s) \circ e_c)(x) \xrightarrow{rule} (e_a \circ e_c)(x) * (e_b \circ e_c)(x) * (e_s \circ e_c)(x)$$

The derivative of a field composition is applied by using the chain rule.

$$\nabla(F \circ G) \longrightarrow_{direct-stule} (\nabla F \circ G) \bullet (\nabla G)$$

The derivative of a field composition of two fields is represented in the EIN IR as

$$\nabla_{j}(F_{\alpha} \circ [\langle G_{i\beta} \rangle_{\hat{i\beta}}]) \xrightarrow[rule]{} \sum_{\hat{i}} ((\nabla_{k} F_{\alpha} \circ [\langle G_{i\beta} \rangle_{\hat{i\beta}}]) * (\nabla_{j} G_{k\beta}))$$

Generally we use the rewrite rule to apply the rewrite between two EIN expressions:

$$\nabla_{j}(e_{1} \circ [\langle e_{2} \rangle_{i\hat{\beta}}]) \xrightarrow[rule]{} \sum_{\hat{k}} ((\nabla_{k} e_{1} \circ [\langle e_{2} \rangle_{i\hat{\beta}}]) * (\nabla_{j} e_{2[i/k]}))$$

Flatten composition operator

$$(a \circ [\langle b \rangle_{\hat{m}}]) \circ e_c \xrightarrow[rule]{} a \circ [\langle b \rangle_{\hat{m}}, e_c]$$

$$a \circ [\langle b \circ e_c \rangle_{\hat{m}}] \xrightarrow{rule} a \circ [\langle b \rangle_{\hat{m}}, e_c]$$

Split After being normalized the probed composition operator is split into several probes.

$$\operatorname{out} = \lambda F, G, x \left\langle F_{\alpha} \circ [\langle G_{\beta} \rangle_{\hat{\beta}}](x) \right\rangle_{\alpha} (F0, F1, x) \xrightarrow[split]{} \operatorname{t}_{0} = \lambda G, x \left\langle G_{\beta}(x) \right\rangle_{\hat{\beta}} (F1, x)$$

1.1.2 Testing results

Comp-B1 Mistake in index scope when using substitution.

```
\begin{array}{ll} \mathbf{field} \# k \, (2) \, [2 \, , 2] & F0 \, ; \\ \mathbf{field} \# k \, (2) \, [2] & F1 \, ; \\ \mathbf{field} \# k \, (2) \, [2] & F2 \, ; \\ \mathbf{field} \# k \, (2) \, [2 \, , 2] & G = \, (F0 \, \circ \, F1) \, \bullet \, F2 \, ; \end{array}
```

There was a mistake in the substitution method. The scope of the composition indices were handled incorrectly. The following is the expected and observed representation of the computation in the EIN IR.

Expected:
$$e = \sum_{\hat{j}} A_{ij} \circ [\langle B_i \rangle_{\hat{\beta}}] * C_j$$

Observed: $e = \sum_{\hat{k}} A_{ik} \circ [\langle B_i \rangle_{\hat{\beta}}] * C_j$
in $\lambda(A, B, C) \langle e \rangle_{\hat{\beta}} (\text{F0,F1,F2}).$

DATm Command: python3 cte.py 4 36 17 10 13

Comp-B2 Missing cases in split method.

Probes of a composition are handled differently before reconstruction.

$$\sum F(x)$$
 and $\sum (\text{Comp}(F,G,-))(x)$.

Missing case in method leads to a compile time error. Additionally (Comp(Comp -)-) label:-

Comp-B3 Differentiate a composition

The jacobian of a field composition:

$$\begin{array}{ll} \textbf{field} \# k \left(\text{d1} \right) \left[\text{d} \right] & \text{F0}; \\ \textbf{field} \# k \left(\text{d1} \right) \left[\text{d1} \right] & \text{F1}; \\ \textbf{field} \# k \left(\text{d1} \right) \left[\text{d}, \text{d1} \right] & \text{G} = \nabla \otimes & (\text{F0} \circ \text{F1}); \end{array}$$

is represented as $\langle \nabla_j(\text{Comp}(A_i, B_i, i)) \rangle_{ij}$

In accordance with the chain rule ($(f \circ g)' = (f' \circ g) \cdot g'$) the rewriting system multiplies the inner derivative (g') with a new composition operation ($f' \circ g$). In practice, the implementation does a point-wise multiplication when it should

```
do an inner product. Expected: \sum_{\hat{k}} (\nabla_k A_i \circ [\langle B_i \rangle_{\hat{\beta}}] * \nabla_j G_k) Observed: \nabla_j A_\beta \circ [\langle B_i \rangle_{\hat{i}}] * (\nabla_j G_i) in \lambda(A, B) \langle e \rangle_{ij} (\text{F0,F1}).
```

1.2 Concatenation

1.2.1 Design and Implementation

A user can define new tensors by concatenating tensors together. A Diderot program

```
\begin{array}{l} \textbf{tensor} \left[ \, d_1 \, \right] S \, ; \\ \textbf{tensor} \left[ \, d_2 \, \right] T \, ; \\ \textbf{tensor} \left[ \, d_1 \, , d_2 \, \right] M \, = \, \left[ \, S \, , T \, \right] ; \end{array}
```

A user can refer to components of tensor fields by using the slice operation as shown in the following code. A Diderot program

```
\begin{array}{l} \textbf{field} \# k(d) \big[ \, d_1 \, , d_2 \big] A; \\ \textbf{field} \# k(d) \big[ \, d_1 \, , d_2 \big] B; \\ \textbf{field} \# k(d) \big[ \, d_1 \big] F = A \big[ : \, , 0 \big]; \\ \textbf{field} \# k(d) \big[ \, d_1 \big] G = B \big[ : \, , 1 \big]; \end{array}
```

We would like to provide a way to define new tensors fields by concatenating components together. Using the tensor field variables F and G defined earlier in the program the Diderot code should support the line

$$field\#k(d)[2,d_1]H = [F, G];$$

We illustrate the structure of H below.

$$H = \left[\begin{array}{cc} F_0 & F_1 \\ G_0 & G_1 \end{array} \right]$$

Representation We can use EIN expressions as building blocks to represent field concatenation. In EIN each field term is represented by an expression and it is enabled with a delta function

$$\Longrightarrow_{init} H = \lambda F, G. \langle F_j \delta_{0i} + G_j \delta_{1i} \rangle_{i:2,j:2} (F,G)$$

After substitution the new EIN operator would be

$$\Longrightarrow_{subst} H = \lambda A, B. \langle A_{j0} \delta_{0i} + B_{j1} \delta_{1i} \rangle_{\hat{i}\hat{j}} (A, B).$$

In the compiler we choose to create generic versions of an EIN operator that can be instantiated to certain types.

$$\begin{array}{l} \lambda F, G. \langle F_{\alpha} \delta_{0i} + G_{\alpha} \delta_{1i} \rangle_{i:2\hat{\alpha}}(\mathbf{F}, \mathbf{G}) \\ \lambda F, G, H. \langle F_{\alpha} \delta_{0i} + G_{\alpha} \delta_{1i} + H_{\alpha} \delta_{2i} \rangle_{i:3\hat{\alpha}}(\mathbf{F}, \mathbf{G}, \mathbf{H}) \end{array}$$

To implement this operator we need to add to cases to the Diderot typechecker and add the generic representations but not much else. Since we are solely using existing EIN expressions to represent this computation, we can rely on the existing code to handle the EIN syntax.

1.2.2 Testing results

concat-B1 One was in the creation of the EIN operator for the concat operator. The indices on the terms in the concat EIN operator were switched.

concat-B2 The bug arose when computing the determinant of the concatenation of a field.

$$field\#k(d)[2]F,G;$$

 $field\#k(d)[]H = det(concat(F,G));$

The bug was caused by the rewriting system. Our rewriting system applies index-based rewrites to reduce EIN expressions. A specific index rewrite is applied when the index in the delta term matches an index in tensor (or field) term. The rewrite checked if two indices were equal and did not distinguish between variable and constant indices. It is mathematically incorrect to reduce constant indices, because they are not equivalent to variable indices.

Max and Min 1.3

Design and Implementation 1.3.1

Design Need to add new syntax to support differentiation of max and min.

$$\begin{array}{lll} cond & = & e > e \mid e < e & \text{conditional} \\ e & = & \operatorname{Max}(a,b) \mid \operatorname{Min}(a,b) & \operatorname{Binary EIN operators} \\ & \mid & \operatorname{if}(cond,e,e) & \operatorname{If wrapper returns tensor-valued expression} \\ & \mid & \operatorname{Abs}(e) & \operatorname{Absolute function} \\ & \mid & \operatorname{Sgn}(e) & \operatorname{Returns Sign (-1, 0, 1)} \end{array}$$

Differentiation rules Differentiation of an absolute expression:

$$\frac{\partial}{\partial x_{\alpha}} \operatorname{abs}(e) \to (\frac{\partial}{\partial x_{\alpha}} e) * (\operatorname{Sgn}(e))$$

Differentiation creates an if wrapper expressions.

$$\frac{\partial}{\partial x_{\alpha}} \operatorname{Max}(a, b) \to i f(a > b, \frac{\partial}{\partial x_{\alpha}} a, \frac{\partial}{\partial x_{\alpha}} b)$$
$$\frac{\partial}{\partial x_{\alpha}} \operatorname{Min}(a, b) \to i f(a < b, \frac{\partial}{\partial x_{\alpha}} a, \frac{\partial}{\partial x_{\alpha}} b)$$

Differentiation of an If wrapper is pushed to leaves.

$$\frac{\partial}{\partial x_{\alpha}} \mathrm{If}(cond,c,d) \to if(cond,\frac{\partial}{\partial x_{\alpha}}c,\frac{\partial}{\partial x_{\alpha}}d)$$

other rules Otherwise, Max and Min are treated like other binary operators. The following pushes the probes to the leaves.

$$(\operatorname{Max}(a,b))(x) \to \operatorname{Max}(a(x),b(x))$$

1.3.2 Testing results

maxmix_B1 Using If Wrapper with other field operators

$$field #4(2)[]G = compose(minF((F0),(F1)),(F2*0.1));$$

Field operators need to be applied to the leaves in if wrapper. The composition is a field operator so it needed to be pushed to the leaves.

$$(\mathrm{If}(c,e3,e4))\circ es\to \mathrm{If}(c,e3\circ es,e4\circ es)$$

1.4 Other

Unsupported functionality:
• radial basis functions

- absolute value
- sign (positive/negative)
- if statement

2 Alternate field definitions

Closed form expression 2.1

Implementation

Representation As an ongoing example, consider the function $F(x) = x^3$. We can define this function with the following syntax:

$$\begin{array}{l} \mathbf{real} \;\; \mathbf{p} \, ; \\ \mathbf{ofield} \, \# 1(2)[] \;\; \mathbf{F} = \; \mathbf{cfexp} \left(p^3 \, , \mathbf{p} \, \right); \\ \mathbf{tensor} \, [] \;\; \mathbf{out} \; = \; \mathbf{F} \big(\, \mathbf{pos} \, \big); \end{array}$$

The language is translated inside the compiler as:

$$\overrightarrow{init} \quad \begin{array}{ll} & \mathcal{F} = \lambda() \left\langle PolyWrap_p(p^3) \right\rangle() \\ & \overrightarrow{init} \quad \text{out} = \lambda(F,x) \left\langle F(x) \right\rangle(\mathcal{F},\mathbf{x}) \end{array} \qquad \overrightarrow{\underbrace{subst}} \quad \text{out} = \lambda(x) \left\langle PolyWrap_p(p^3)(x) \right\rangle(\mathbf{x})$$

Replace polynomial variable

The variable p represents a vector of length 2, where p = [X,Y].

The term P_0 represents the 0th component of the vector, or X. In the following, we will use the terms X and Y, in place of P_0 and P_1 .

The polynomial variable is instantiated with the position.

 \Rightarrow out= $\lambda(p)\langle e\rangle(x)$ where e=p*p*p.

The EIN term (p) is replaced with an EIN term that represents the vector components. In the 2-d case there are two terms indexed with a constant index in $p = X\delta_{0i} + Y\delta_{1i}$

Occurrances for P are replaced inside the expression:

$$\to (P_0 \delta_{0i} + P_1 \delta_{1i}) * (P_0 \delta_{0i} + P_1 \delta_{1i}) * (P_0 \delta_{0i} + P_1 \delta_{1i}).$$

$$= (X\delta_{0i} + Y\delta_{1i}) * (X\delta_{0i} + Y\delta_{1i}) * (X\delta_{0i} + Y\delta_{1i}).$$

Normalization

Similar terms are collected:

$$P_0 * P_0 \rightarrow {P_0}^2$$
 or $X * X \rightarrow X^2$

The differentiation operator is distributed over the EIN term, as usual, and pushed to a polynomial term

$$\frac{\partial}{\partial x_i}({P_0}^2+e) \to \frac{\partial}{\partial x_i}{P_0}^2+\frac{\partial}{\partial x_i}e \quad \text{ or } \quad \frac{\partial}{\partial x_i}(X^2+e) \to \frac{\partial}{\partial x_i}X^2+\frac{\partial}{\partial x_i}e$$

Evaluation

During the evaluation the variable index in a differentiation operator is bound to a number. An EIN term such as $\frac{\partial}{\partial x_i} P_c^n$ is evaluated.

When i and c are both 0:

$$\frac{\partial}{\partial x_0}X \to 1 \qquad \frac{\partial}{\partial x_0}X^2 \to 2*X \qquad \frac{\partial}{\partial x_0}X^3 \to 3*X^2$$

When i and c are both 1:

$$\frac{\partial}{\partial x_1}Y \to 1$$
 $\frac{\partial}{\partial x_1}Y^2 \to 2*Y$ $\frac{\partial}{\partial x_1}Y^3 \to 3*Y^2$

When i and c are not the same

$$\frac{\partial}{\partial x_1} X^n \to 0 \qquad \frac{\partial}{\partial x_1} Y^n \to 0$$