

## **A Survey on Performance Metrics** for Object-Detection Algorithms





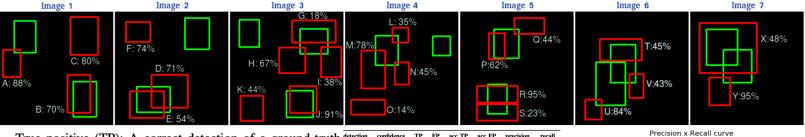
"In the object detection context, a true negative (TN) result does not apply, as there are infinite number of bounding boxes that should not be detected within any given image."

 $t \to \text{threshold}$ 

 $IOU > t \rightarrow correct$ 

$$P = \frac{TP}{TP + FP} = \frac{TP}{\text{all detections}},$$

$$R = \frac{\text{TP}}{\text{TP} + \text{FN}} = \frac{\text{TP}}{\text{all ground truths}}$$



- True positive (TP): A correct detection of a ground-truth detection bounding box;
- False positive (FP): An incorrect detection of a nonexistent object or a misplaced detection of an existing object;
- False negative (FN): An undetected ground-truth bounding ground-truth bounding box

$$J(B_p, B_{gt}) = \text{IOU} = \frac{\text{area}(B_p \cap B_{gt})}{\text{area}(B_p \cup B_{gt})}$$
Intersection over Union

-Jaccard Index

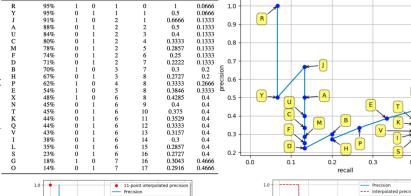
$$AP_{11} = \frac{1}{11} \sum_{R \in \{0, 0.1, \dots, 0.9, 1\}} P_{\text{interp}}(R)$$

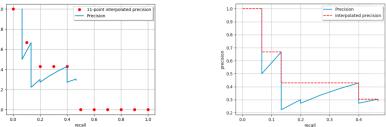
$$P_{ ext{interp}}(R) = \max_{ ilde{R}: ilde{R} \geq R} P( ilde{R})$$

$$\begin{aligned} & \text{IOU} < t \rightarrow \text{incorrect} & P_{\text{interp}}(R) = \max_{\tilde{R}: \tilde{R} \geq R} P(\tilde{R}) \\ P & = \frac{\text{TP}}{\text{TP} + \text{FP}} = \frac{\text{TP}}{\text{all detections}}, & \text{AP}_{\text{all}} = \sum_{n} (R_{n+1} - R_n) P_{\text{interp}}(R_{n+1}) \\ R & = \frac{\text{TP}}{\text{TP} + \text{FN}} = \frac{\text{TP}}{\text{all ground truths}} & P_{\text{interp}}(R_{n+1}) = \max_{\tilde{R}: \tilde{R} \geq R_{n+1}} P(\tilde{R}) \end{aligned}$$

$$& \text{AP}_{i} \rightarrow i\text{-th class}$$

$$P_{\text{interp}}(R_{n+1}) = \max_{\tilde{R}: \tilde{R} > R_{n+1}} P(\tilde{R})$$





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