

1 forward propagate

$$W_1 \cdot x_1 + W_3 \cdot x_2 + W_5 \cdot x_3 + b_1 = Z_{h_2}$$
 $W_2 \cdot x_1 + W_4 \cdot x_2 + W_6 \cdot x_3 + b_1 = Z_{h_2}$
 $h_1 = \sigma(Z_{h_2})$
 $h_2 = \sigma(Z_{h_2})$
 $W_1 h_1 + W_2 \cdot h_2 + b_2 = Z_{01}$
 $W_3 h_1 + W_{10} \cdot h_2 + b_2 = Z_{02}$
 $O_1 = \sigma(Z_{01})$
 $O_2 = \sigma(Z_{02})$

1 update weights

$$W_{1} = W_{1} - \alpha \cdot \frac{\partial E}{\partial W_{1}}$$

$$\vdots$$

$$W_{10} = W_{10} - \alpha \cdot \frac{\partial E}{\partial W_{10}}$$

$$b_{1} = b_{1} - \alpha \cdot \frac{\partial E}{\partial b_{1}}$$

$$b_{2} = b_{2} - \alpha \cdot \frac{\partial E}{\partial b_{2}}$$

- 3 forward propagate to get output
- 3 define error/cost function
- @ backpropagate
- 1 update weights

3 error function

$$E = \frac{1}{2} \left[(o_1 - t_1)^2 + (o_2 - t_2)^2 \right]$$

$$\frac{\partial E}{\partial o_1} = o_1 - t_1$$

$$\frac{\partial E}{\partial o_2} = o_2 - t_2$$

1 back propagate

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

$$\frac{\partial E}{\partial w_{\eta}} = \frac{\partial E}{\partial o_{1}} \cdot \frac{\partial o_{1}}{\partial z_{01}} \cdot \frac{\partial z_{01}}{\partial w_{\eta}} = (o_{1} - t_{1}) \cdot (o_{1}(1 - o_{1})) \cdot h_{1} \quad \frac{d\sigma}{dx} = \frac{e^{-x}}{(1 + e^{-x})^{2}}$$

$$\frac{\partial E}{\partial w_{\theta}} = \frac{\partial E}{\partial o_{2}} \cdot \frac{\partial o_{2}}{\partial z_{02}} \cdot \frac{\partial z_{02}}{\partial w_{\theta}} = (o_{1} - t_{1}) \cdot (o_{1}(1 - o_{1})) \cdot h_{1} \quad \frac{d\sigma}{dx} = \frac{e^{-x}}{(1 + e^{-x})^{2}}$$

$$= \sigma(x) \left(1 - \sigma(x)\right)$$

$$\vdots \quad \frac{e^{-x}}{1 + e^{-x}} = 1 - \frac{1}{1 + e^{-x}}$$

error derivatives
$$\frac{\partial E}{\partial w_q} = \frac{\partial E}{\partial 0_1} \cdot \frac{\partial 0_1}{\partial 2_{01}} \cdot \frac{\partial Z_{01}}{\partial w_q}$$

$$\frac{\partial E}{\partial W_{10}} = \frac{\partial E}{\partial o_2} \cdot \frac{\partial O_2}{\partial Z_{02}} \cdot \frac{\partial Z_{02}}{\partial W_{10}}$$

$$\frac{\partial E}{\partial b_2} = \frac{\partial E}{\partial 0_1} \cdot \frac{\partial 0_1}{\partial z_{01}} \cdot \frac{\partial Z_{01}}{\partial b_2} + \frac{\partial E}{\partial 0_2} \cdot \frac{\partial 0_2}{\partial Z_{02}} \cdot \frac{\partial Z_{02}}{\partial b_2}$$

$$\frac{\partial E}{\partial w_1} = \frac{\partial E}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_{h_1}} \cdot \frac{\partial z_{h_1}}{\partial w_1}$$

$$\frac{\partial E}{\partial o_1} \cdot \frac{\partial o_1}{\partial z_{h_1}} \cdot \frac{\partial z_{h_1}}{\partial h_1} + \frac{\partial E}{\partial o_2} \cdot \frac{\partial o_2}{\partial z_{h_2}} \cdot \frac{\partial z_{h_2}}{\partial h_1}$$

error derivatives
$$\frac{\partial E}{\partial w_5} = \frac{\partial E}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_{h_1}} \cdot \frac{\partial Z_h}{\partial w_5}$$

$$\frac{\partial E}{\partial w_2} = \frac{\partial E}{\partial h_2} \frac{\partial h_2}{\partial z_{h_2}} \frac{\partial^2 h_2}{\partial w_2}$$

$$\frac{\partial E}{\partial v_1} \frac{\partial v_1}{\partial z_{h_1}} \frac{\partial v_2}{\partial h_2} + \frac{\partial E}{\partial v_2} \frac{\partial v_2}{\partial z_{h_2}} \frac{\partial^2 v_1}{\partial h_2}$$

$$\frac{\partial E}{\partial W_4} = \frac{\partial E}{\partial h_2} \cdot \frac{\partial h_2}{\partial z_{h_2}} \cdot \frac{\partial z_{h_2}}{\partial W_4}$$

$$\frac{\partial E}{\partial b_1} = \frac{\partial E}{\partial o_1} \cdot \frac{\partial o_1}{\partial z_{01}} \cdot \frac{\partial z_{01}}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_{h_1}} \cdot \frac{\partial z_{h_1}}{\partial b_1} + \frac{\partial E}{\partial o_2} \cdot \frac{\partial o_2}{\partial z_{02}} \cdot \frac{\partial z_{02}}{\partial h_2} \cdot \frac{\partial h_2}{\partial z_{h_2}} \cdot \frac{\partial z_{h_2}}{\partial b_1}$$