

$$1. \text{proj}_{\vec{v}_1} \vec{y} = \frac{\vec{v}_1 \cdot \vec{y}}{|\vec{v}_1|^2} \vec{v}_1 \quad \text{proj}_{\vec{v}_2} \vec{y} = \frac{\vec{v}_2 \cdot \vec{y}}{|\vec{v}_2|^2} \vec{v}_2$$

$$a) \cos^{-1} \frac{\vec{y} \cdot \vec{v}_i}{|\vec{y}| |\vec{v}_i|} = \cos^{-1} \frac{\vec{y} \cdot \frac{\vec{v}_i \cdot \vec{y}}{|\vec{v}_i|^2} \vec{v}_i}{|\vec{y}| \frac{|\vec{v}_i \cdot \vec{y}|}{|\vec{v}_i|} |\vec{v}_i|}$$

$$c) (\vec{y} - \text{proj}_{\vec{v}_1} \vec{y}) \cdot (\vec{y} - \text{proj}_{\vec{v}_1} \vec{y}) = \left(\vec{y} - \frac{\vec{v}_1 \cdot \vec{y}}{|\vec{v}_1|^2} \vec{v}_1 \right)^2$$

$$d) \left(\vec{y} - \frac{\vec{v}_1 \cdot \vec{y}}{|\vec{v}_1|^2} \vec{v}_1 \right)^2 < \left(\vec{y} - \frac{\vec{v}_2 \cdot \vec{y}}{|\vec{v}_2|^2} \vec{v}_2 \right)^2$$

$$2. a) \text{Span} \left\{ \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ -1 \end{bmatrix}, \begin{bmatrix} -3 \\ -5 \\ -1 \end{bmatrix}, \begin{bmatrix} 4 \\ 8 \\ 2 \end{bmatrix} \right\}$$

dimension = 4

$$c) \text{Span} \{ (1 \ -1 \ -3 \ 4), (3 \ -3 \ -5 \ 8), (1 \ -1 \ -1 \ 2) \}$$

dimension = 3

$$b) \left[\begin{array}{cccc|c} 1 & -1 & -3 & 4 & 0 \\ 3 & -3 & -5 & 8 & 0 \\ 1 & -1 & -1 & 2 & 0 \end{array} \right]$$

$$2. \begin{bmatrix} 1 & -1 & -3 & 4 \\ 3 & -3 & -5 & 8 \\ 1 & -1 & -1 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$a) \text{span} \left\{ \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}, \begin{bmatrix} -3 \\ -5 \\ -1 \end{bmatrix} \right\} \quad \dim = 2$$

$$c) \text{span} \left\{ (1 \ -1 \ -3 \ 4), (3 \ -3 \ -5 \ 8) \right\} \quad \dim = 2$$

$$b) \begin{aligned} x_1 &= x_2 - x_4 \\ x_3 &= x_4 \end{aligned} \quad \begin{bmatrix} x_2 - x_4 \\ x_2 \\ x_4 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} x_2 + \begin{bmatrix} -1 \\ 0 \\ 1 \\ 1 \end{bmatrix} x_4$$

$$\text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right\} \quad \dim = 2$$

$$d) A^T = \begin{bmatrix} 1 & 3 & 1 \\ -1 & -3 & -1 \\ -3 & -5 & -1 \\ 4 & 8 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 1 \\ 0 & 0 & 0 \\ 0 & 4 & 2 \\ 0 & -4 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \begin{aligned} x_1 &= -x_2 \\ x_3 &= -2x_2 \end{aligned} \quad \begin{bmatrix} -1 \\ 1 \\ -2 \end{bmatrix}$$

$$\text{span} \left\{ \begin{bmatrix} -1 \\ 1 \\ -2 \end{bmatrix} \right\} \quad \dim = 1$$

3. a) $[\vec{v}_1 \ \vec{v}_2 \ \dots \ \vec{v}_i] \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & & \\ \vdots & & \ddots & \\ 0 & & & \lambda_i \end{bmatrix} \begin{bmatrix} \vec{v}_1 \\ \vec{v}_2 \\ \dots \\ \vec{v}_i \end{bmatrix}^T$

b) 400 eigen vectors are required

c) ipython

d) 15

4 a) $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

b) 1 one-hop

0 two-hop

1 three-hop

c) ~~both are $\frac{1}{2}$~~ both are $\frac{1}{2}$

d) $\begin{bmatrix} 0 & 1 & \frac{1}{3} & \frac{1}{3} \\ 0 & 0 & \frac{1}{3} & \frac{1}{3} \\ 0 & 0 & 0 & \frac{1}{3} \\ 1 & 0 & \frac{1}{3} & 0 \end{bmatrix}$

e) 1 two-hop path

1 three-hop path

f) 0.33, 0.17, 0.12, 0.38

g) $\begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & \frac{1}{2} & 0 & 0 \end{bmatrix}$

h) 0 paths

i) 0.2, 0.2, 0.4, 0.1, 0.1

~~the~~ In graph c some nodes don't relate to each other at all

5. Gary Li

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EE16A Homework 4

Image Compression

```
In [1]: %pylab inline
```

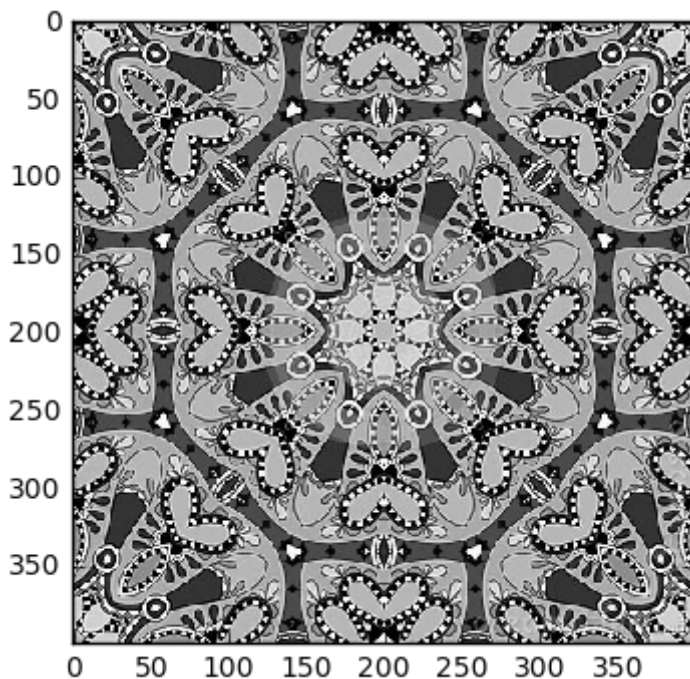
Populating the interactive namespace from numpy and matplotlib

```
In [2]: import numpy as np
        from scipy import ndimage as nd
        from scipy import misc
        from scipy import io
```

Part b

```
In [23]: #Load Pattern Image
        pattern = np.load('pattern.npy')
        plt.imshow(pattern, cmap='gray', interpolation='nearest')
```

```
Out[23]: <matplotlib.image.AxesImage at 0x110b27eb8>
```



Use the command `shape`

(<http://docs.scipy.org/doc/numpy/reference/generated/numpy.ndarray.shape.html>) to find the dimensions of the image. How many eigenvalues do you expect?

Run the code below to find the eigenvector and eigenvalues of `pattern` and sort them in descending order (first eigenvalue/vector corresponds to the largest eigenvalue)

```
In [28]: eig_vals, eig_vectors = np.linalg.eig(pattern)
         idx = (abs(eig_vals).argsort())
         idx = idx[::-1]
         eig_vals = eig_vals[idx]
         eig_vectors = eig_vectors[:,idx]
         print(np.shape(pattern))

(400, 400)
```

Part c

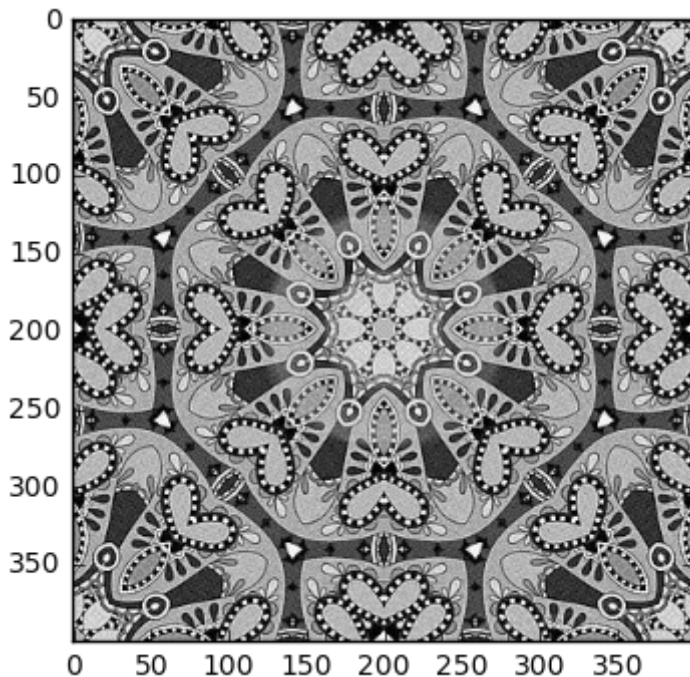
Find the pattern approximation using 100 largest eigenvalues/eigenvectors.

- Index into above variables to choose the first 100 eigenvalues and eigenvectors.
- You can use the command `np.outer` (<http://docs.scipy.org/doc/numpy/reference/generated/numpy.outer.html>) to find the outer product of two vectors

```
In [29]: rank = 100
         S = np.zeros(pattern.shape)
         for i in range(rank):
             vec_i = eig_vectors[:,i] # i-th largest eigenvector
             val_i = eig_vals[i]      # i-th largest eigenvalue
             S += np.outer(np.outer(vec_i, val_i), vec_i.T)

         plt.imshow(S, cmap='gray', vmin=0, vmax=255)
```

```
Out[29]: <matplotlib.image.AxesImage at 0x111c552e8>
```



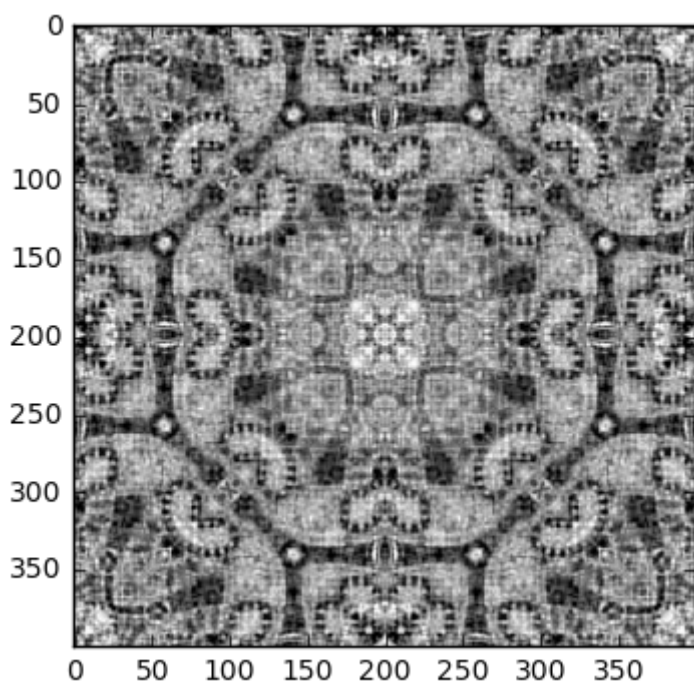
Part d

Find the pattern approximation using 50 largest eigenvalues/eigenvectors

```
In [36]: rank = 15
S = np.zeros(pattern.shape)
for i in range(rank):
    vec_i = eig_vectors[:,i] # i-th largest eigenvector
    val_i = eig_vals[i]      # i-th largest eigenvalue
    S += np.outer(np.outer(vec_i, val_i), vec_i.T)

plt.imshow(S, cmap='gray', vmin=0, vmax=255)
```

Out[36]: <matplotlib.image.AxesImage at 0x1171ddc50>



Paths of a Surfer

```

In [22]: # There is no required ipython component, but you may wish to use iPython for
B = np.array([[0, 1, 1/3, 1/3],
              [0, 0, 1/3, 1/3],
              [0, 0, 0, 1/3],
              [1, 0, 1/3, 0]])
vbi = np.array([1/4, 1/4, 1/4, 1/4])
print(np.dot(B, np.dot(B, np.dot(B, np.dot(B, np.dot(B, np.dot(B, np.dot(B,

C = np.array([[0, 1, 0, 0, 0],
              [1, 0, 0, 0, 0],
              [0, 0, 0, 1, 1],
              [0, 0, 1/2, 0, 0],
              [0, 0, 1/2, 0, 0]])
vci = np.array([1/5, 1/5, 1/5, 1/5, 1/5])
final = np.dot(C, vci)
for _ in range(100):
    final = np.dot(C, final)
print(final)

[ 0.33373554  0.1663576  0.12448983  0.37541703]
[ 0.2  0.2  0.4  0.1  0.1]

```

In []: