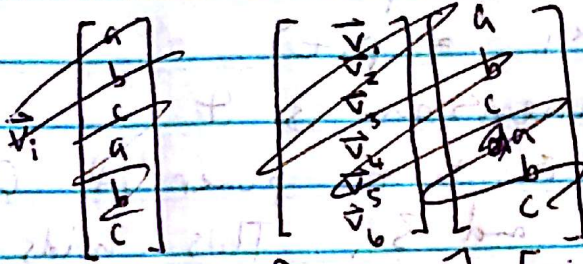


1. a) It can recover from only one erasure  
It can't handle patterns where both a's are lost or both b's, etc.

b)



$\alpha_1$	$\beta_1$	$\gamma_1$	$\alpha_1$	$\beta_1$	$\gamma_1$	a
$\alpha_2$	$\beta_2$	$\gamma_2$	$\alpha_2$	$\beta_2$	$\gamma_2$	b
$\alpha_3$	$\beta_3$	$\gamma_3$	$\alpha_3$	$\beta_3$	$\gamma_3$	c
$\alpha_4$	$\beta_4$	$\gamma_4$	$\alpha_4$	$\beta_4$	$\gamma_4$	a
$\alpha_5$	$\beta_5$	$\gamma_5$	$\alpha_5$	$\beta_5$	$\gamma_5$	b
$\alpha_6$	$\beta_6$	$\gamma_6$	$\alpha_6$	$\beta_6$	$\gamma_6$	c

c)  $[1, 0, 0]$ ,  $[0, 1, 0]$ ,  $[0, 0, 1]$ ,  $[1, 0, 0]$ ,  $[0, 1, 0]$ ,  $[0, 0, 1]$

d) When the letters in the place of the ones at that time i is present. For example, you wouldn't be able to figure out "a" if "a" was missing at  $i=1$  and "a" and "b" was missing at  $i=4$  and etc.

$$e) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 6 \\ ? \\ ? \\ 2 \\ 3 \\ ? \\ ? \end{bmatrix}$$

$$a = 6$$

$$b = -4$$

$$c = -3$$

f) She should choose the strategy in part a because at this point he knows neither a, b, nor c, and it's hard to solve for combinations of summations of a, b, c if he doesn't know any of them.



2. a)  $p(t)$  is closed under both addition and multiplication

$$p(t) + 0 = p(t)$$

$$p(t) \times 1 = p(t)$$

the dimension is 4

one is to the power of 0, and 1, and 2, and 3. This adds up to 4 different dimensions

b)  $p(t)$  is literally a linear combination of the canonical polynomials.

$$\begin{bmatrix} c_0 & c_1 & c_2 & c_3 \end{bmatrix} \begin{bmatrix} 1 \\ t \\ t^2 \\ t^3 \end{bmatrix}$$

$$= c_0 + c_1 t + c_2 t^2 + c_3 t^3$$

Does this look familiar?

It's the exact same as  $p(t)$  but with  $c$ 's instead of  $p$ 's

c) the  $c$  vector consists of the constants that we are multiplying  $\phi(t)$  by the elements of

d) True;  $\phi(t)$  is definitely linearly independent, as any combination of  $t^2$  can't equal  $t$  and etc., and linear combinations of the elements of  $\phi(t)$  can form any ~~poly~~ cubic polynomial with real values



$$2e) (1-t)^3 = (t^2 - 2t + 1)(1-t) = t^2 - 2t + 1 - t^3 + 2t^2 - t = -t^3 + 3t^2 - 3t + 1$$

$$3t(1-t)^2 = 3t^3 - 6t^2 + 3t$$

$$3t^2(1-t) = 3t^2 - 3t^3$$

$$B(t) = \begin{bmatrix} -t^3 + 3t^2 - 3t + 1 \\ 3t^3 - 6t^2 + 3t \\ -3t^3 + 3t^2 \\ t^3 \end{bmatrix}$$

$$R = \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

calculator

because there is a pivot in each row,  $R$  is linearly independent and invertible.

$$R^{-1} = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & \frac{1}{3} & 1 \\ 0 & \frac{1}{3} & \frac{2}{3} & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} \quad R^{-1} \vec{B}(t) = \vec{Q}(t)$$

$$\vec{B}_0(t) + \frac{4}{3} \vec{B}_1(t) + 2 \vec{B}_2(t) + 4 \vec{B}_3(t) = \vec{P}_0 t + \vec{P}_1 t + \vec{P}_2 t^2 + \vec{P}_3 t^3$$

3. a)  $\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$

b)  $\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0.3 \\ 0.7 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

c) no;  $x_2[1]$  always equals zero so that gives us no information, and  $x_1[1]$  is just  $x_1[0] + x_2[0]$  and here we're trying to solve two variables with one equation, which doesn't work.

d) It shows that the form  $A\vec{x} = \vec{b}$  doesn't have a unique solution and <sup>matrix A</sup> therefore isn't invertible. As a result, we can't do  $A^{-1}\vec{b} = \vec{x}$  to find out the initial water levels.

e) matrix A is therefore ~~invertible~~ invertible and we can recover the initial state, as when we put it in the form  $A\vec{x} = \vec{b}$ ,

$$A^{-1}A\vec{x} = A^{-1}\vec{b}$$

$$\vec{x} = A^{-1}\vec{b}$$

and we can find  $\vec{x}$ , the initial state.

This means that the experiment is reproducible.



$$4. a) \vec{x}[1] = A\vec{x}[0] + \vec{b}u[0]$$

$$b) \vec{x}[2] = A(A\vec{x}[0] + \vec{b}u[0]) + \vec{b}u[1] \\ = A^2\vec{x}[0] + A\vec{b}u[0] + \vec{b}u[1]$$

$$c) \vec{x}[3] = A^3\vec{x}[0] + A^2\vec{b}u[0] + A\vec{b}u[1] + \vec{b}u[2]$$

$$d) \vec{x}[4] = A^4\vec{x}[0] + A^3\vec{b}u[0] + A^2\vec{b}u[1] + A\vec{b}u[2] + \vec{b}u[3]$$

$$e) \vec{x}[N] = A^N\vec{x}[0] + \vec{b}(A^{N-1}u[0] + A^{N-2}u[1] + \dots + A^0u[N-1])$$

$$f) \vec{x}[2] = A^2\vec{x}[0] + A\vec{b}u[0] + \vec{b}u[1]$$

$$\vec{0} - A^2\vec{x}[0] = A\vec{b}u[0] + \vec{b}u[1]$$

$$\begin{bmatrix} A\vec{b} \\ \vec{b} \end{bmatrix} \begin{bmatrix} u[0] \\ u[1] \end{bmatrix} = -A^2\vec{x}[0]$$

no; the columns of the coefficient matrix aren't linearly independent

$$g) \vec{x}[3] - A^3\vec{x}[0] = A^2\vec{b}u[0] + A\vec{b}u[1] + \vec{b}u[2]$$

$$\begin{bmatrix} A^2\vec{b} \\ A\vec{b} \\ \vec{b} \end{bmatrix} \begin{bmatrix} u[0] \\ u[1] \\ u[2] \end{bmatrix} = -A^3\vec{x}[0]$$

no; there isn't a pivot in every column so the coefficient matrix can't be solved with a unique solution

$$h) \begin{bmatrix} A^3\vec{b} \\ A^2\vec{b} \\ A\vec{b} \\ \vec{b} \end{bmatrix} \begin{bmatrix} u[0] \\ u[1] \\ u[2] \\ u[3] \end{bmatrix} = -A^4\vec{x}[0]$$

yes; ~~it~~ ~~now~~ the coefficient matrix now reduces to the identity matrix, so the columns are linearly independent and there is a unique ~~for~~ solution

j)  $\vec{0} \in A^N \times [0]$  must be in the span of  $\{\vec{b}, A\vec{b}, A^2\vec{b}, \dots, A^{N-1}\vec{b}\}$

k)  $\vec{x}[N] \in A^N \times [0]$  needs to be in  $\text{span}\{\vec{b}, A\vec{b}, A^2\vec{b}, \dots, A^{N-1}\vec{b}\}$

yes this would be cool!

5. By myself