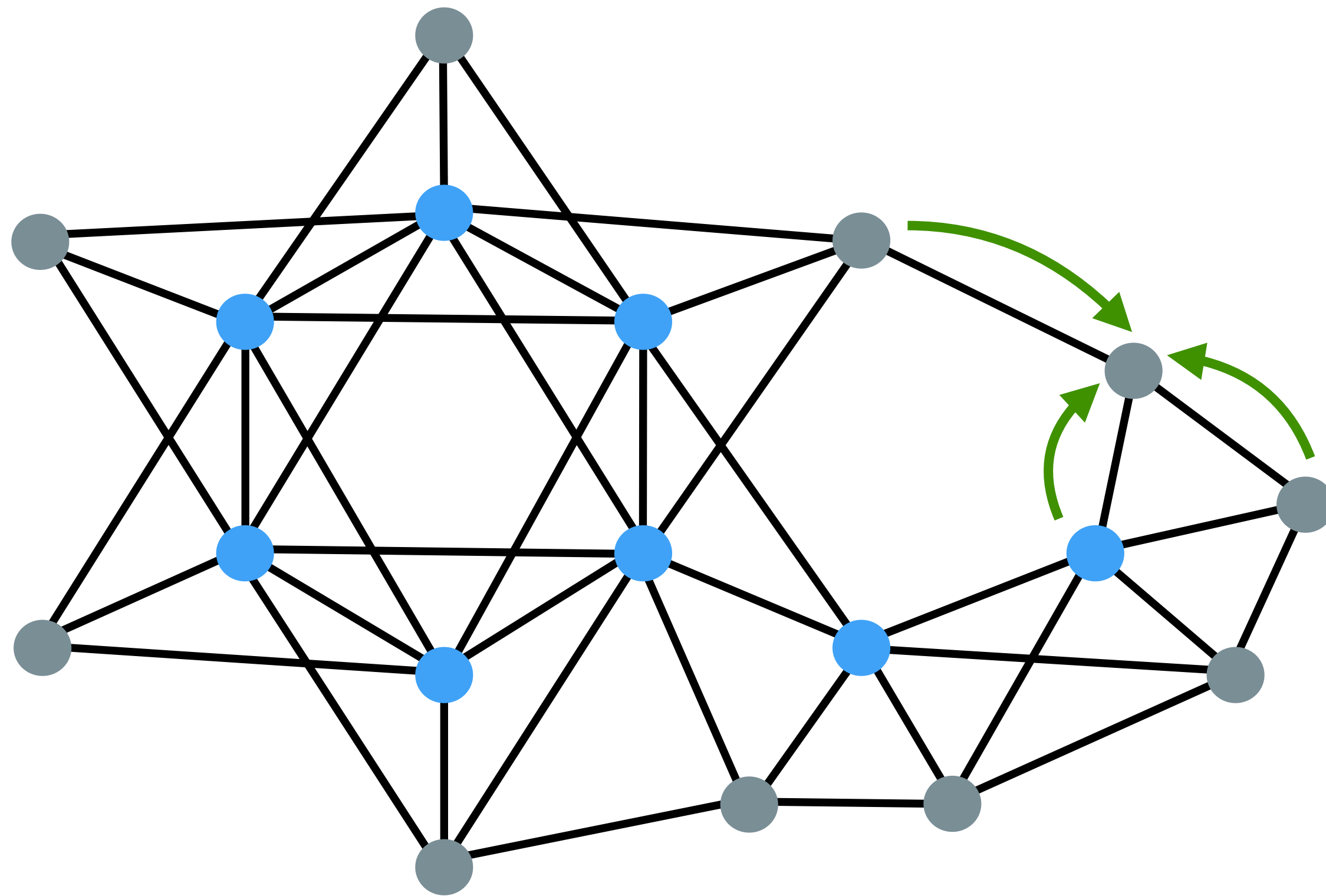


Practical Introduction to Neural Network Potentials Day 5:

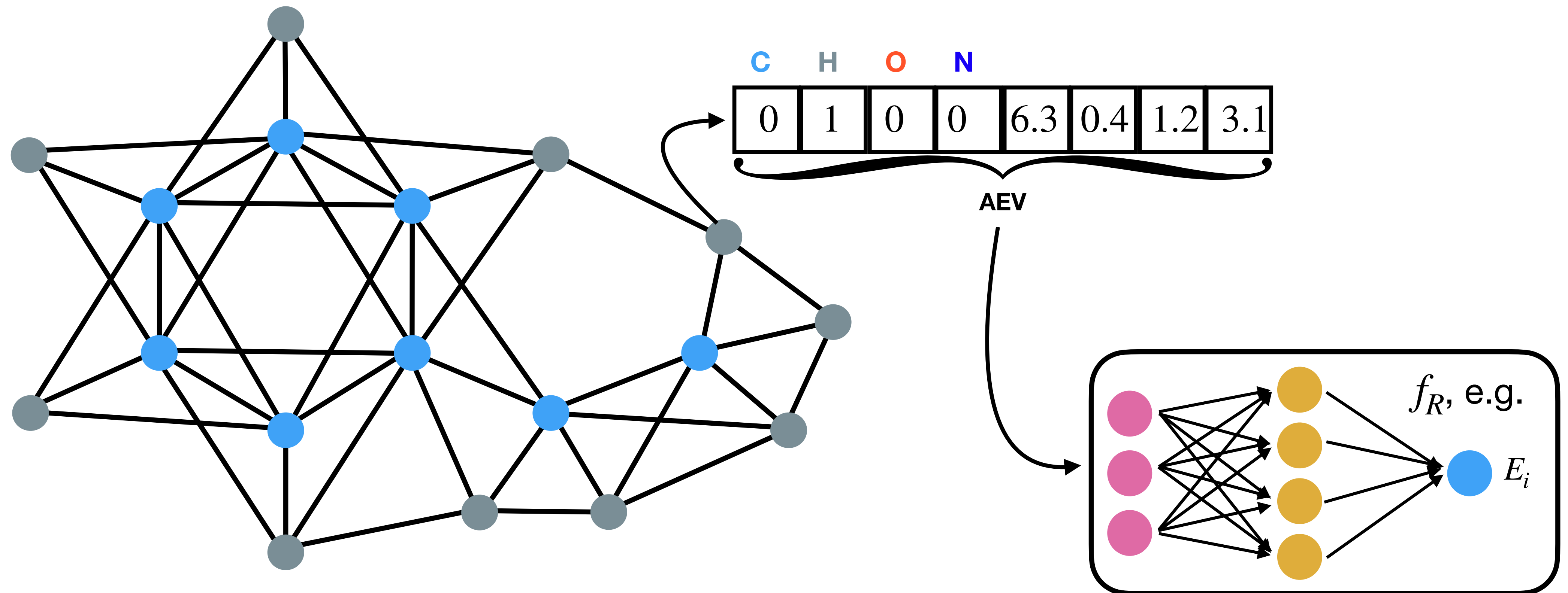
## **Equivariant message-passing neural networks**

# Review: Message-passing neural networks (MPNNs)



1. Initialize nodes  $\vec{x}_i$  and edges  $\vec{e}_{ij}$
2. Pass messages between all atoms  $\vec{m}_{ij}$
3. Accumulate messages  $\vec{M}_i$
4. Repeat
5. Readout

# Review: Message-passing neural networks (MPNNs)



# Review: Message-passing neural networks (MPNNs)

Open Access | Published: 09 January 2017

**Quantum-chemical insights from deep tensor neural networks**

Kristof Schuett, Patrick Riley, Steven Kearnes, Oriol Vinyals, George E. Dahl

**Molecular graph convolutions: moving beyond fingerprints**

Steven Kearnes<sup>1</sup>  
Patrick Riley<sup>2</sup>

**Convolutional Networks on Graphs for Learning Molecular Fingerprints**

**SchNet: A continuous-filter convolutional neural network for modeling quantum interactions**

K. T. Schütt<sup>1\*</sup>, P.-J. Kindermans<sup>1</sup>, H. E. Sauceda<sup>2</sup>, S. Chmiela<sup>1</sup>, A. Tkatchenko<sup>3</sup>, K.-R. Müller<sup>1,4,5†</sup>

<sup>1</sup> Machine Learning Group, Technische Universität Berlin, Germany

<sup>2</sup> Theory Department, Fritz-Haber-Institut der Max-Planck-Gesellschaft, Berlin, Germany

<sup>3</sup> Physics and Materials Science Research Unit, University of Luxembourg, Luxembourg

<sup>4</sup> Max-Planck-Institut für Informatik, Saarbrücken, Germany

<sup>5</sup> Dept. of Brain and Cognitive Engineering, Korea University, Seoul, South Korea

\* kristof.schuett@tu-berlin.de † klaus-robert.mueller@tu-berlin.de

**Neural Message Passing for Quantum Chemistry**

Justin Gilmer<sup>1</sup> Samuel S. Schoenholz<sup>1</sup> Patrick F. Riley<sup>2</sup> Oriol Vinyals<sup>3</sup> George E. Dahl<sup>1</sup>

## Definition: Invariance

$$f : X \mapsto y$$

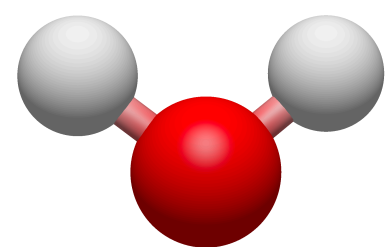
$f$  is a function that maps a molecule ( $X$ ) to a property ( $y$ )



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151.12 Har.

## Definition: Invariance

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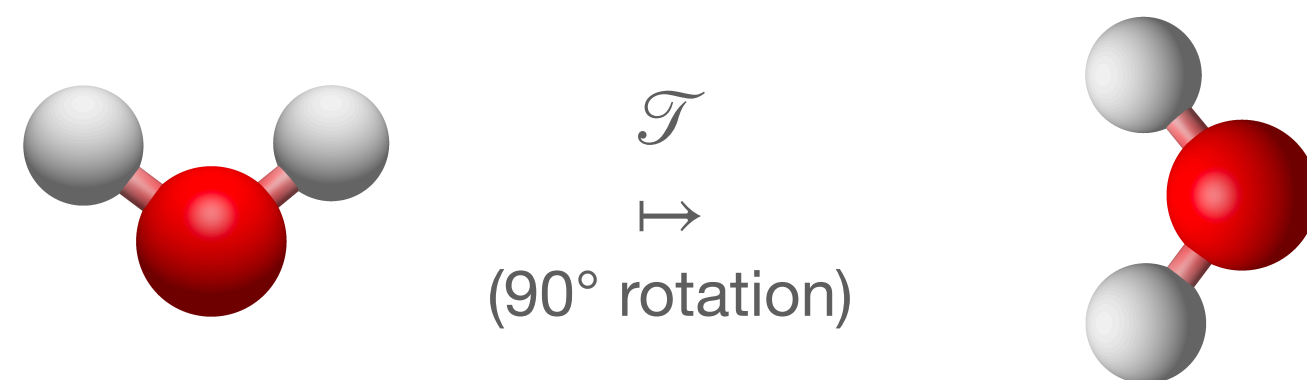
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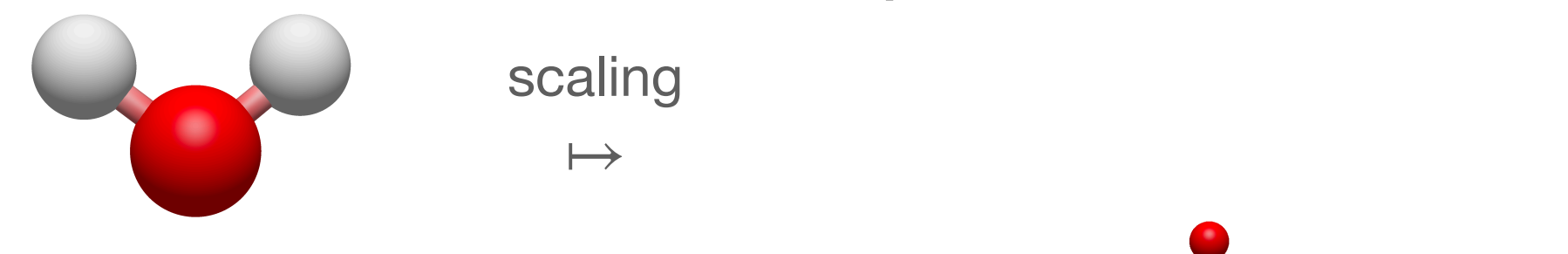
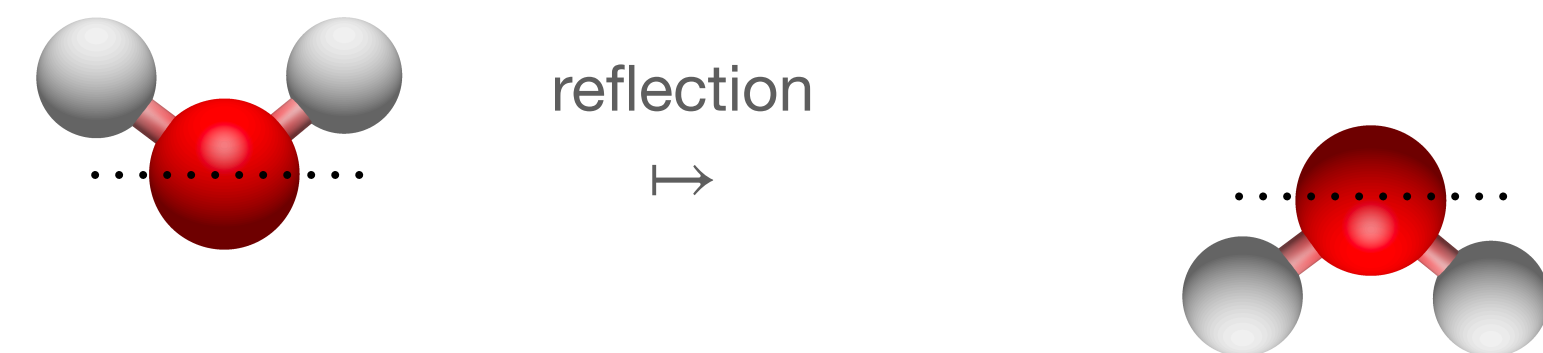
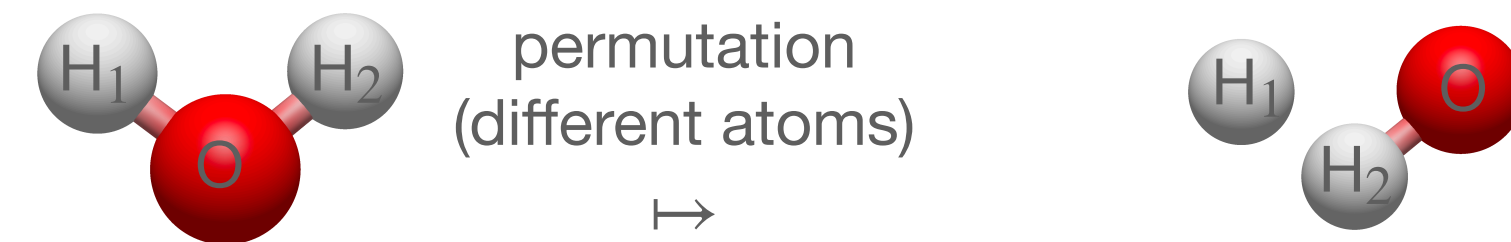
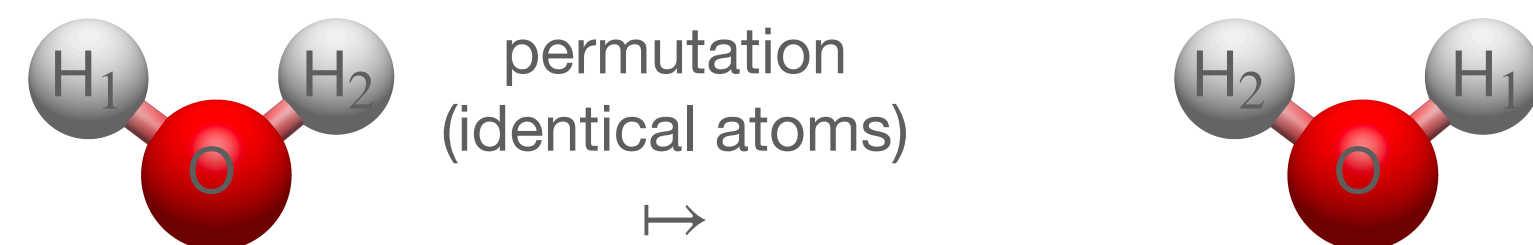
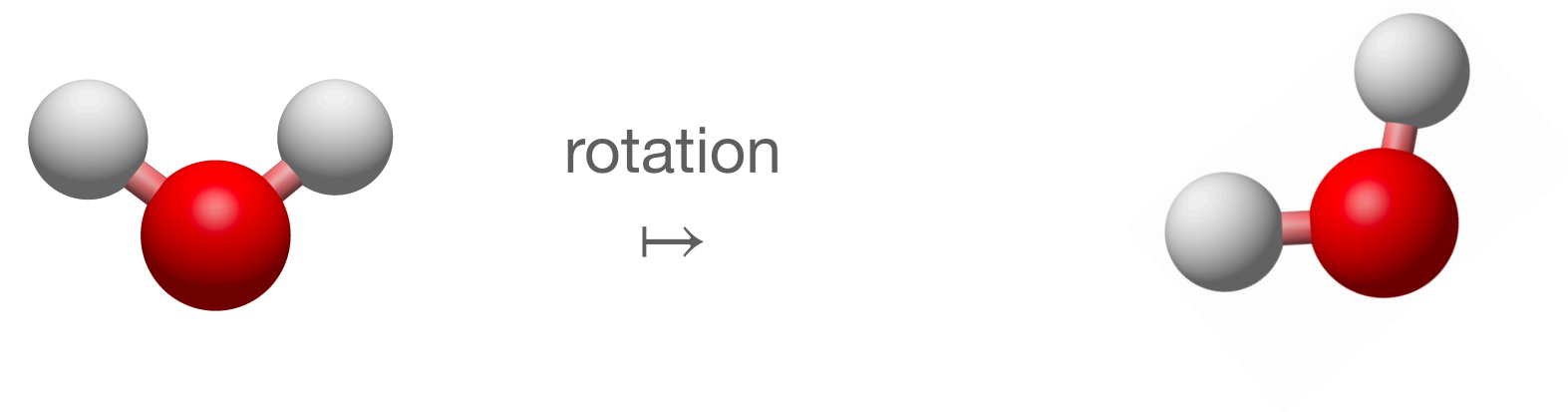
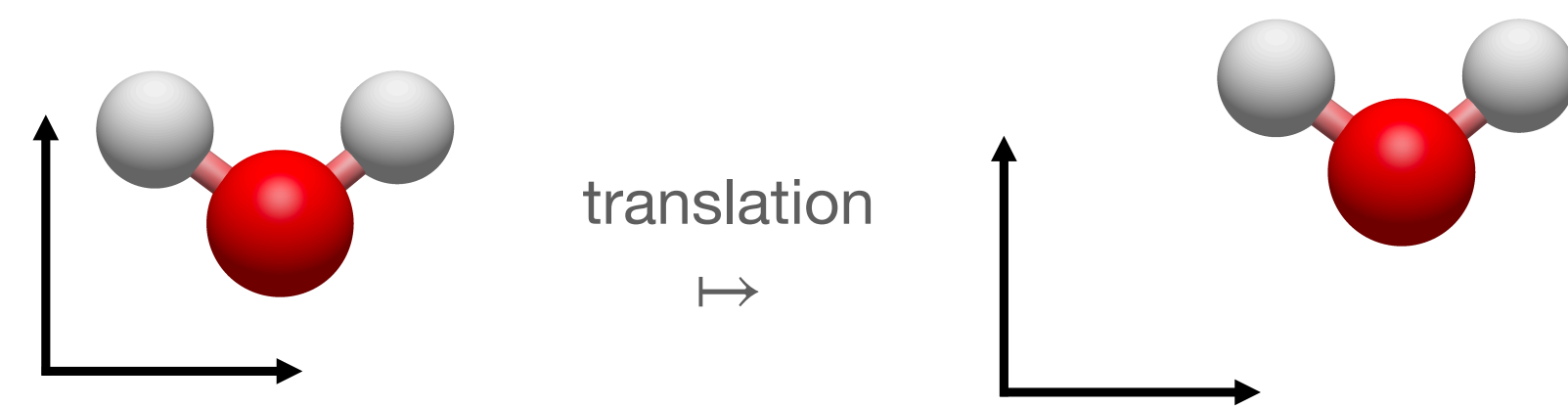
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$$f(X) \equiv f(\mathcal{T}X)$$

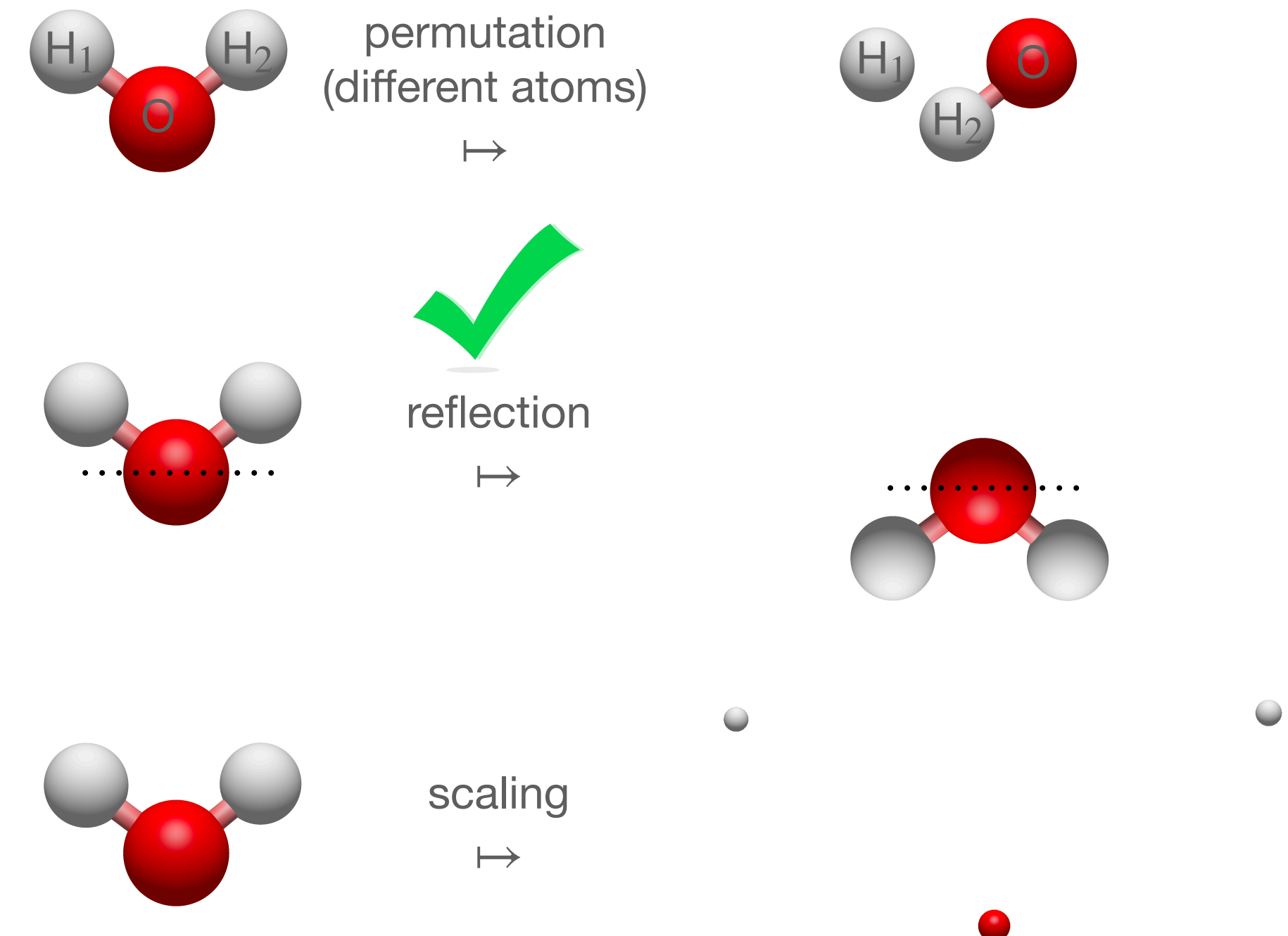
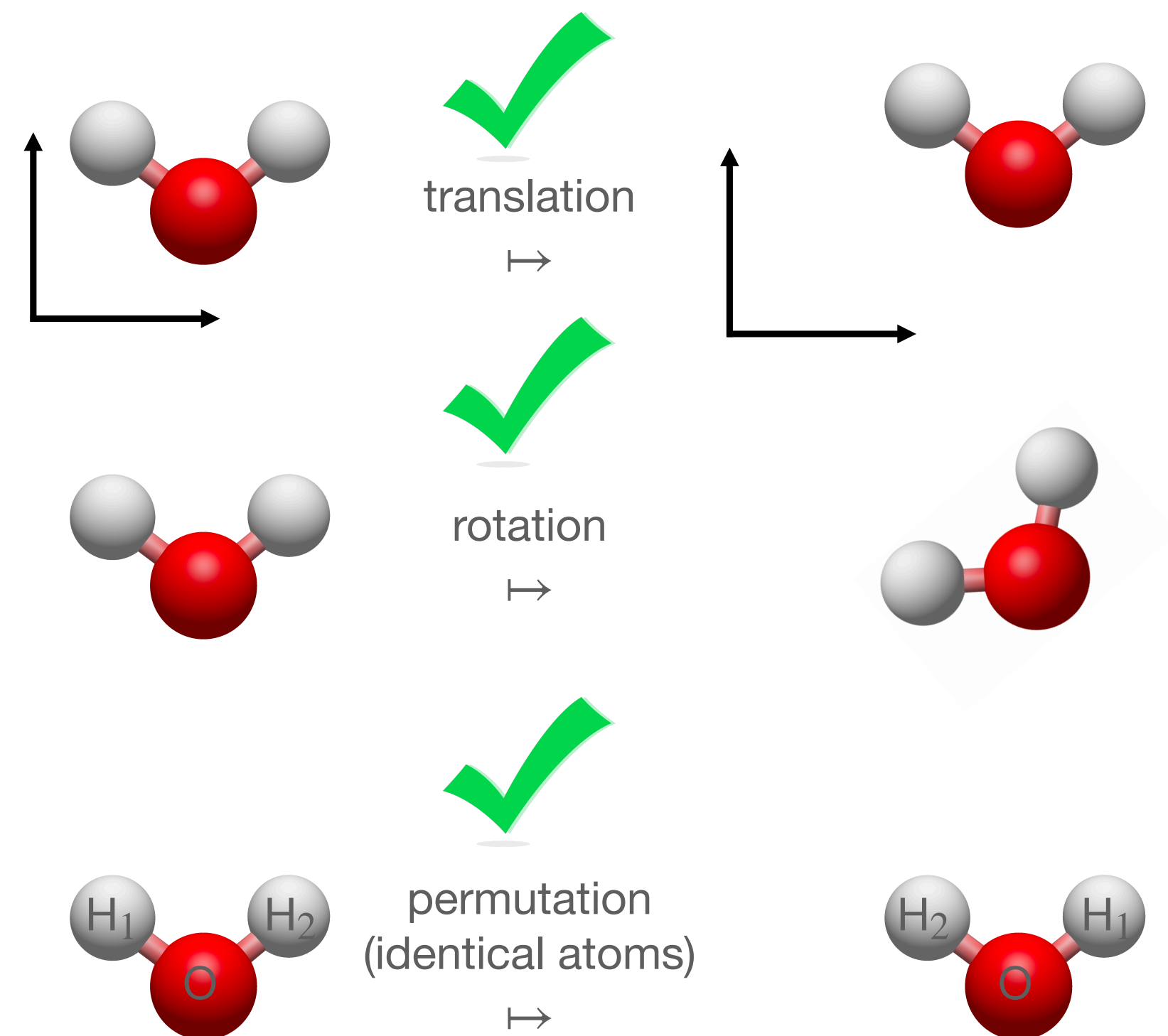
# Examples of Invariance

The molecular energy ( $f$ ) is **invariant** to which of the following transformations ( $\mathcal{T}$ )?



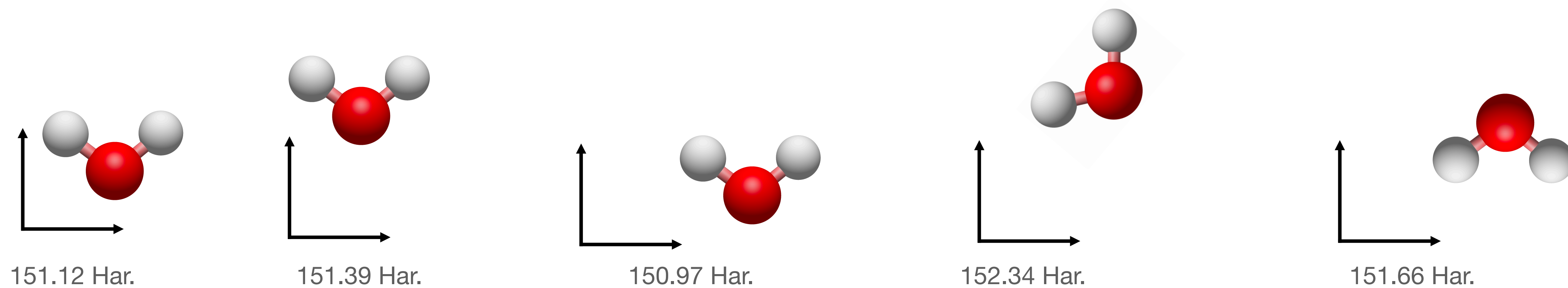
# Examples of Invariance

The molecular energy ( $f$ ) is **invariant** to which of the following transformations ( $\mathcal{T}$ )?



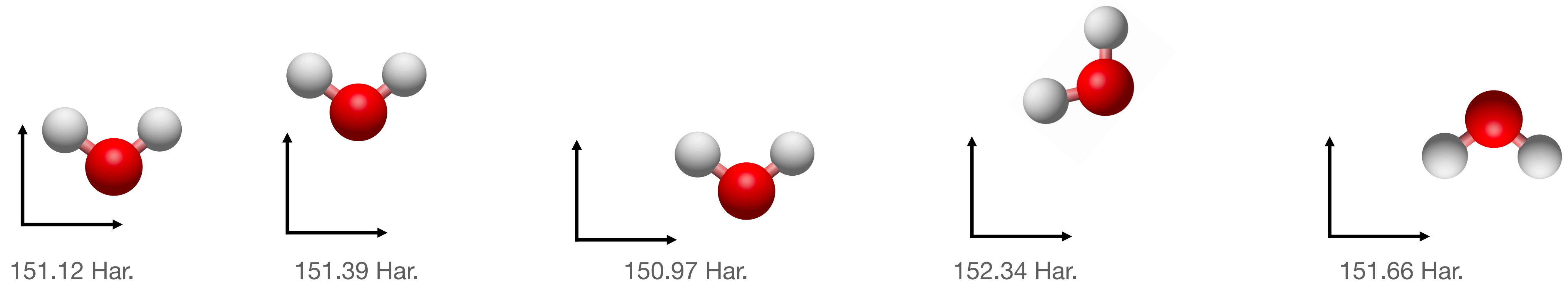
# Why Care about **Invariance**?

Models that ignore physical **invariances** perform poorly and train inefficiently:



# Why Care about **Invariance**?

Models that ignore physical **invariances** perform poorly and train inefficiently:



Models that have unphysical **invariances** are wrong, no matter how much data:

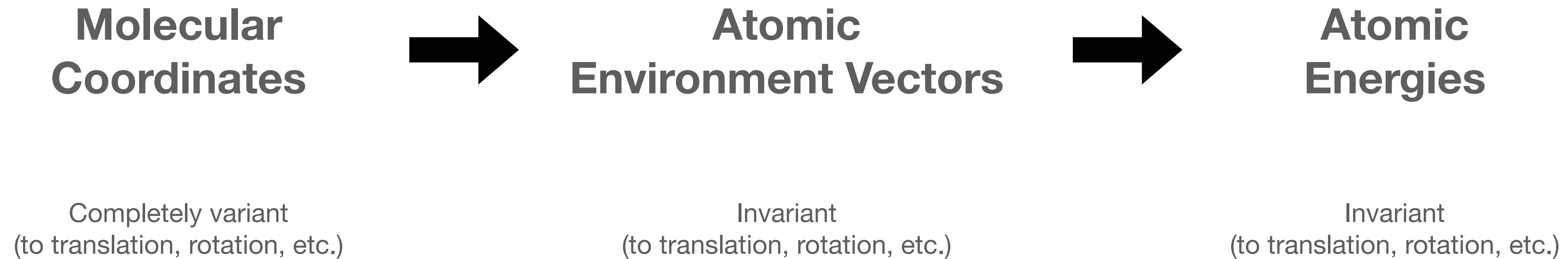
$$\hat{y} = -0.6n_H - 38.1n_C - 54.8n_N - 75.2n_O - 99.9n_F$$

# How do NN Potentials Enforce Invariance?



**Invariance** is enforced at the level of the atomic feature vector.

# How do NN Potentials Enforce Invariance?



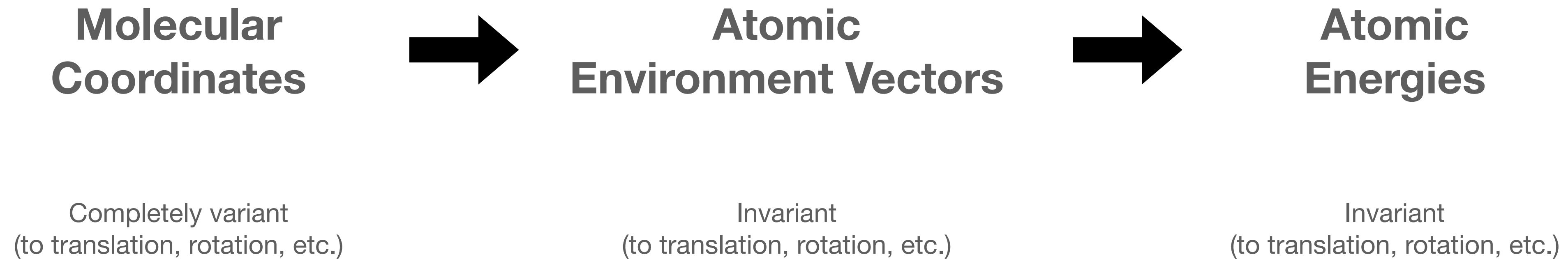
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This could be a problem for two reasons:

- 1) We may want to model a variant property with a NN (e.g. dipole)  
**Invariant** AEVs can't do this.



# How do NN Potentials Enforce Invariance?

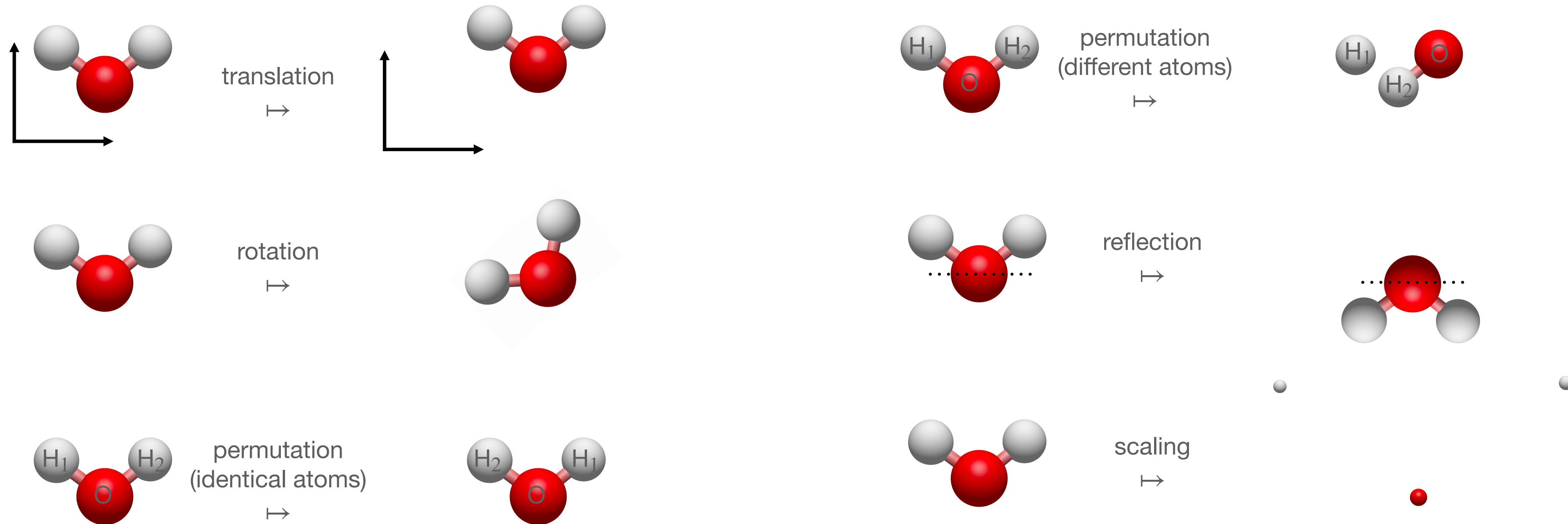


**Invariance** is enforced at the level of the atomic feature vector.

This could be a problem for two reasons:

- 1) We may want to model a variant property with a NN (e.g. dipole)  
**Invariant** AEVs can't do this.
- 2) **Invariant** AEVs contain less info than the original (variant) coordinates.  
We want to include this info (w/o losing **invariance** of prediction)

Is the molecular dipole  $\vec{\mu} = (\mu_x, \mu_y, \mu_z)$  **invariant** or otherwise **variant** to each of the following transformations?

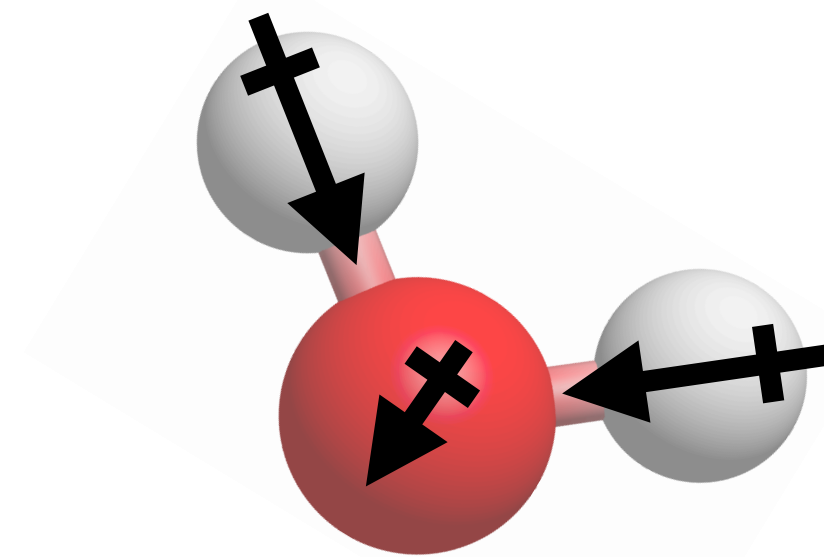


$\vec{\mu} = (\mu_x, \mu_y, \mu_z)$  **varies with rotation and reflection, unlike energy.**

# Atomic Dipole Variance

The dipole vector norm is **invariant** to rotation/reflection, but the dipole direction isn't

$$\vec{\mu}_{H_1} = (0.1, -0.4)$$

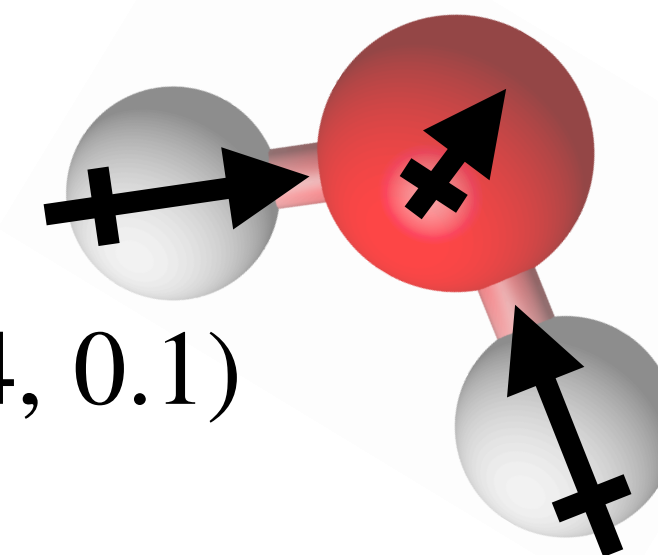


$$\vec{\mu}_O = (-0.1, -0.1)$$

$$\vec{\mu}_{H_2} = (-0.4, -0.1)$$

$$\vec{\mu}_O = (0.1, 0.1)$$

$$\vec{\mu}_{H_2} = (0.4, 0.1)$$



$$\vec{\mu}_{H_1} = (-0.1, 0.4)$$

This specific type of directional variance is called **equivariance**

## Definition: **Equivariance**

$$f : X \mapsto y$$

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$$\mathcal{T} : X \mapsto X'$$

$\mathcal{T}$  is a function that transforms a molecules ( $X$ ) to some other molecule ( $X'$ )

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$$\mathcal{T}(f(X)) \equiv f(\mathcal{T} X)$$

## Invariance

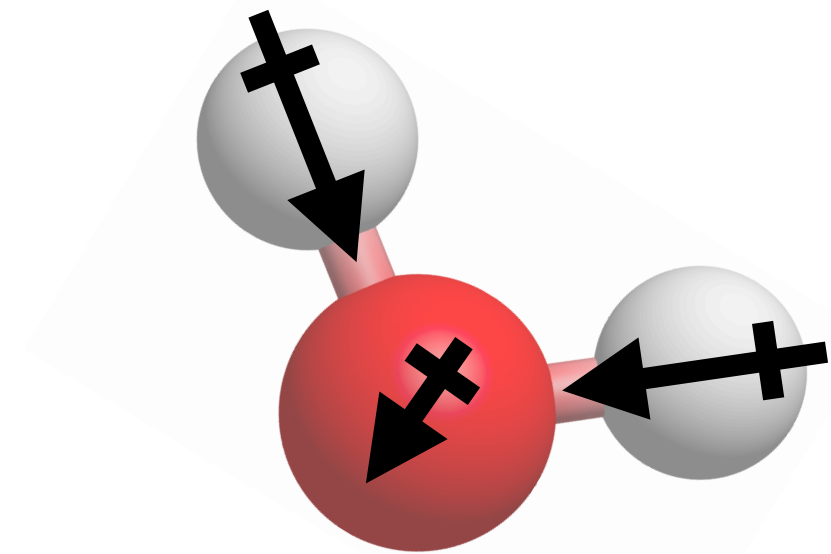
$$f(X) \equiv f(\mathcal{T} X)$$

## Equivariance

$$\mathcal{T}(f(X)) \equiv f(\mathcal{T} X)$$

Problem: Our models are *rotationally invariant*

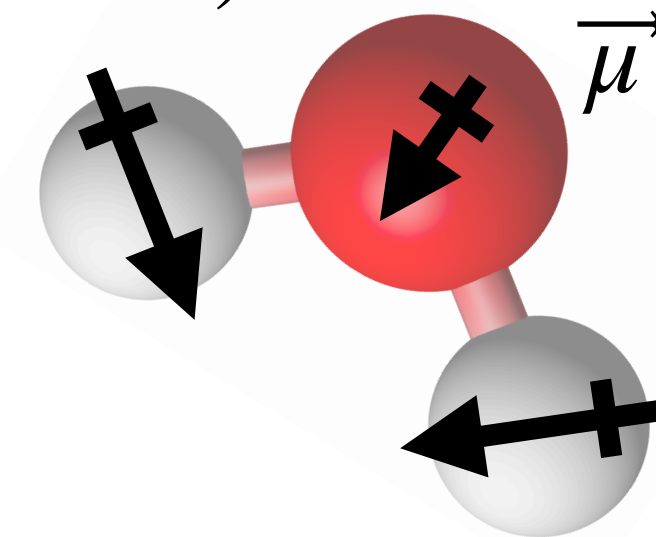
$$\vec{\mu}_{H_1} = (0.1, -0.4)$$



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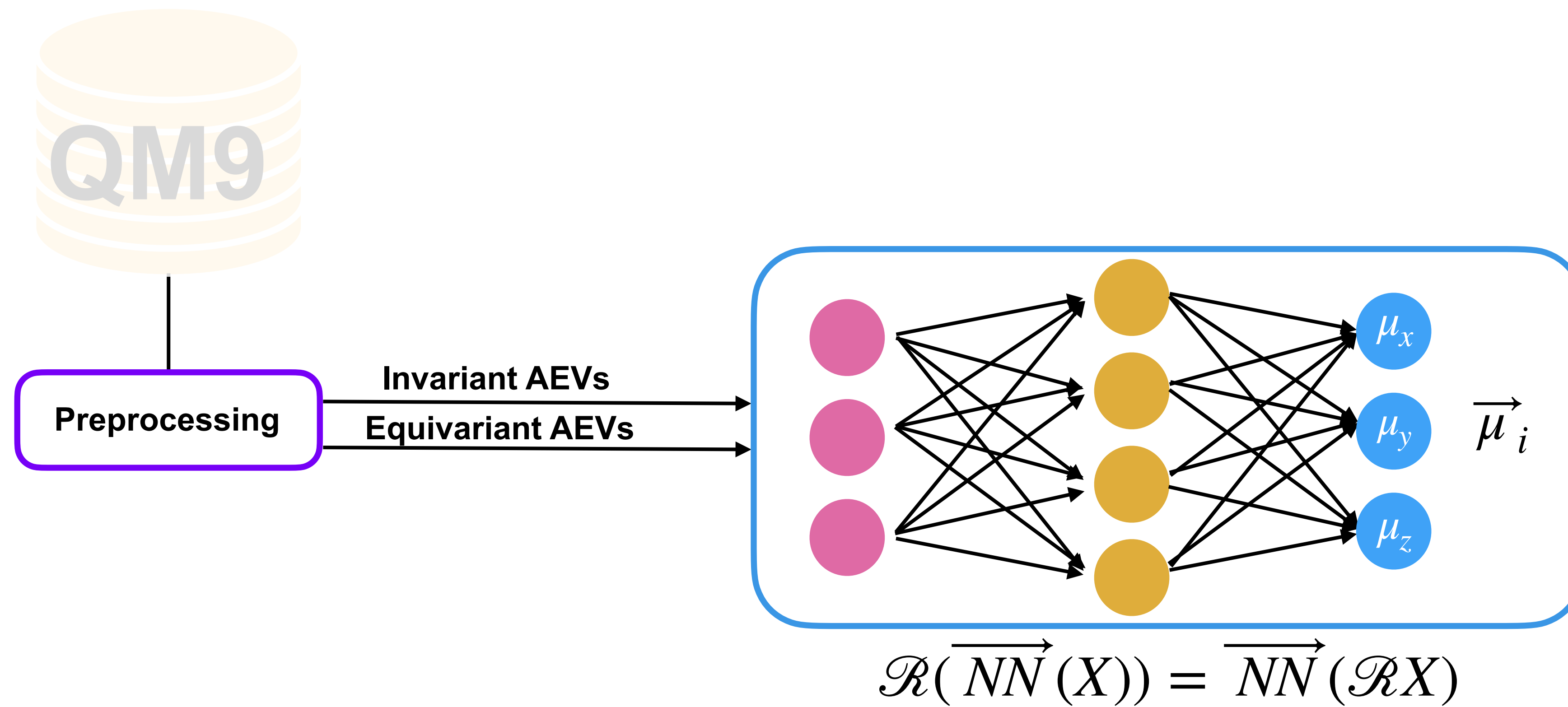
$$\vec{\mu}_{H_2} = (-0.4, -0.1)$$



$$\vec{\mu}_O = (-0.1, -0.1)$$

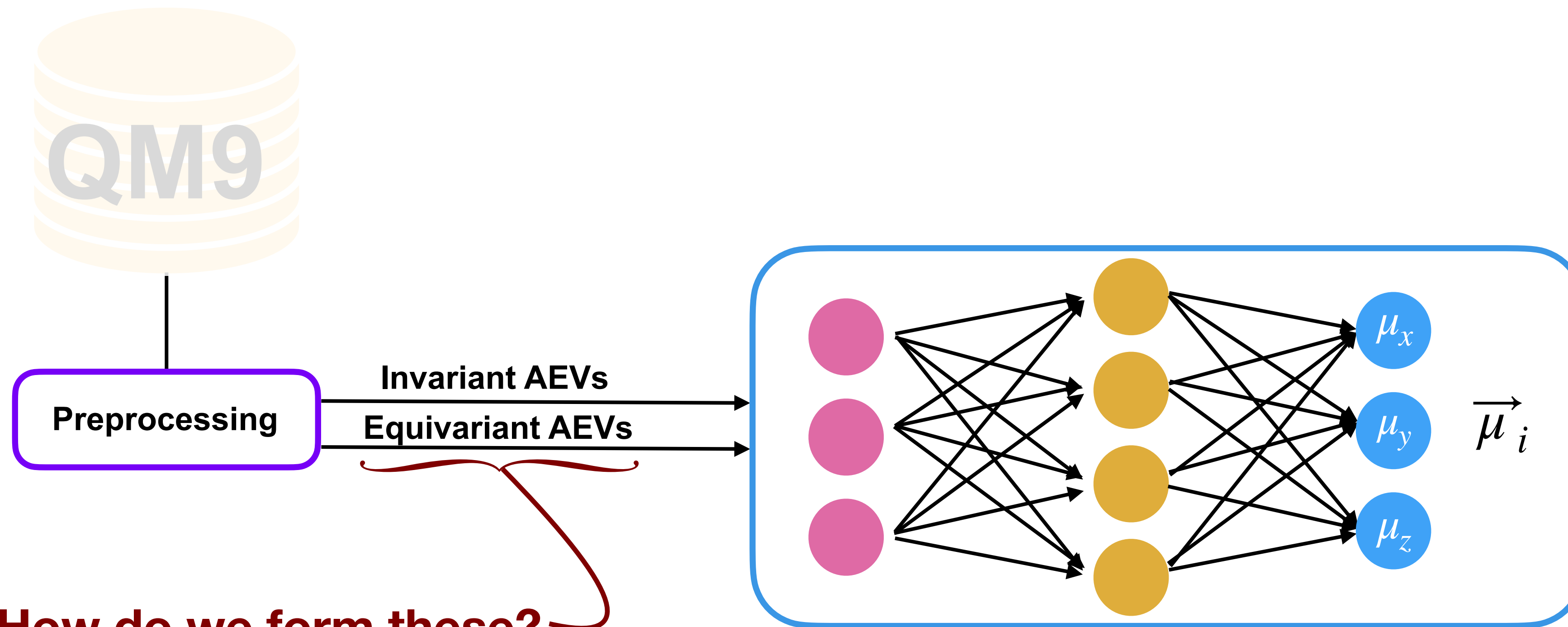
$$\vec{\mu}_{H_1} = (0.1, -0.4)$$

# Predicting properties with rotational **equivariance**





# Predicting properties with rotational **equivariance**



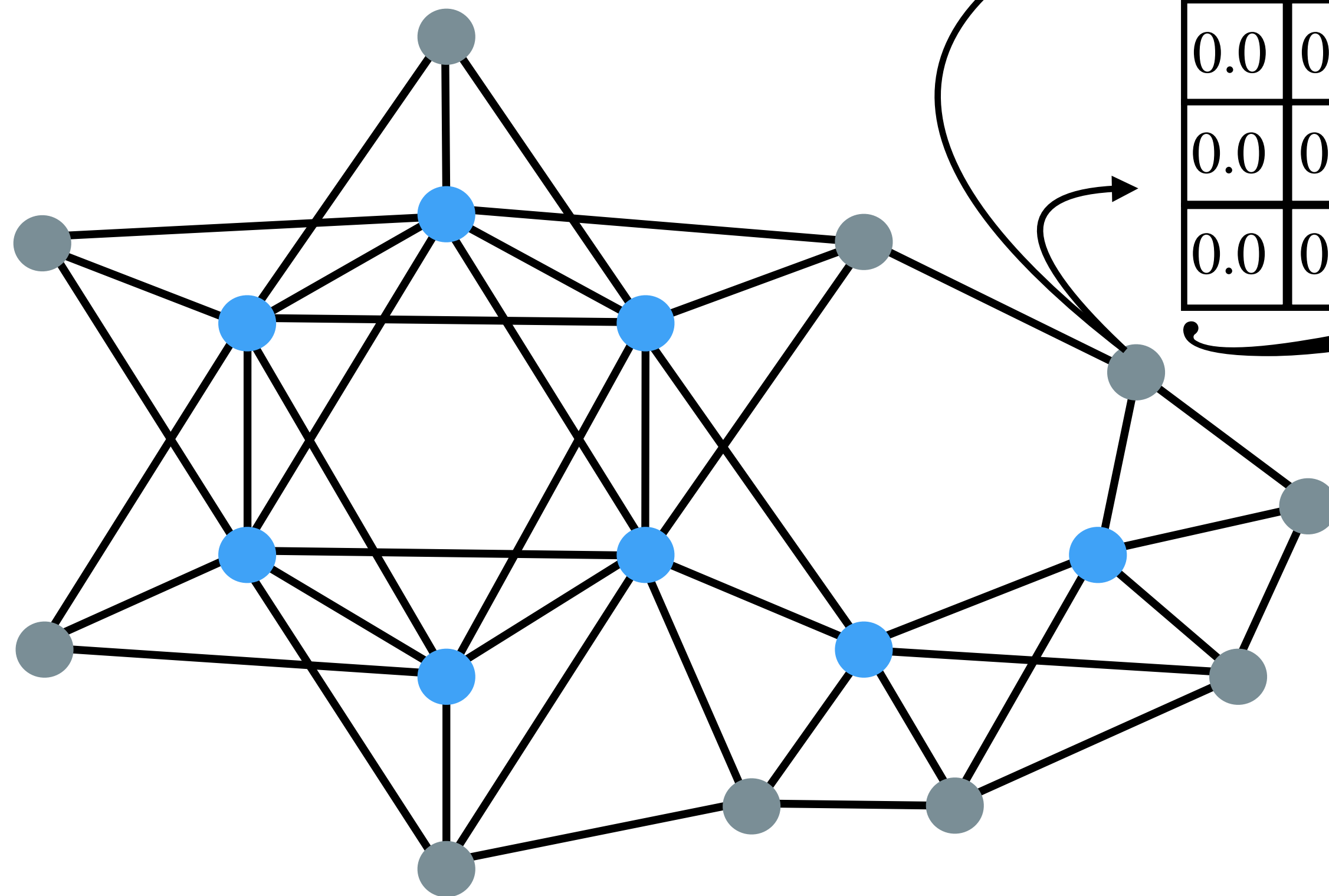
1. How do we form these?
2. How do we enforce this?

$$\mathcal{R}(\vec{NN}(X)) = \vec{NN}(\mathcal{R}X)$$

A red curly bracket is drawn under this equation, pointing towards the second question in the list above.

# 1. How do we form rotationally **equivariant** features?

Initialize



Invariant AEV

C H O N

0	1	0	0	0.0	0.0	0.0	0.0
---	---	---	---	-----	-----	-----	-----

0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

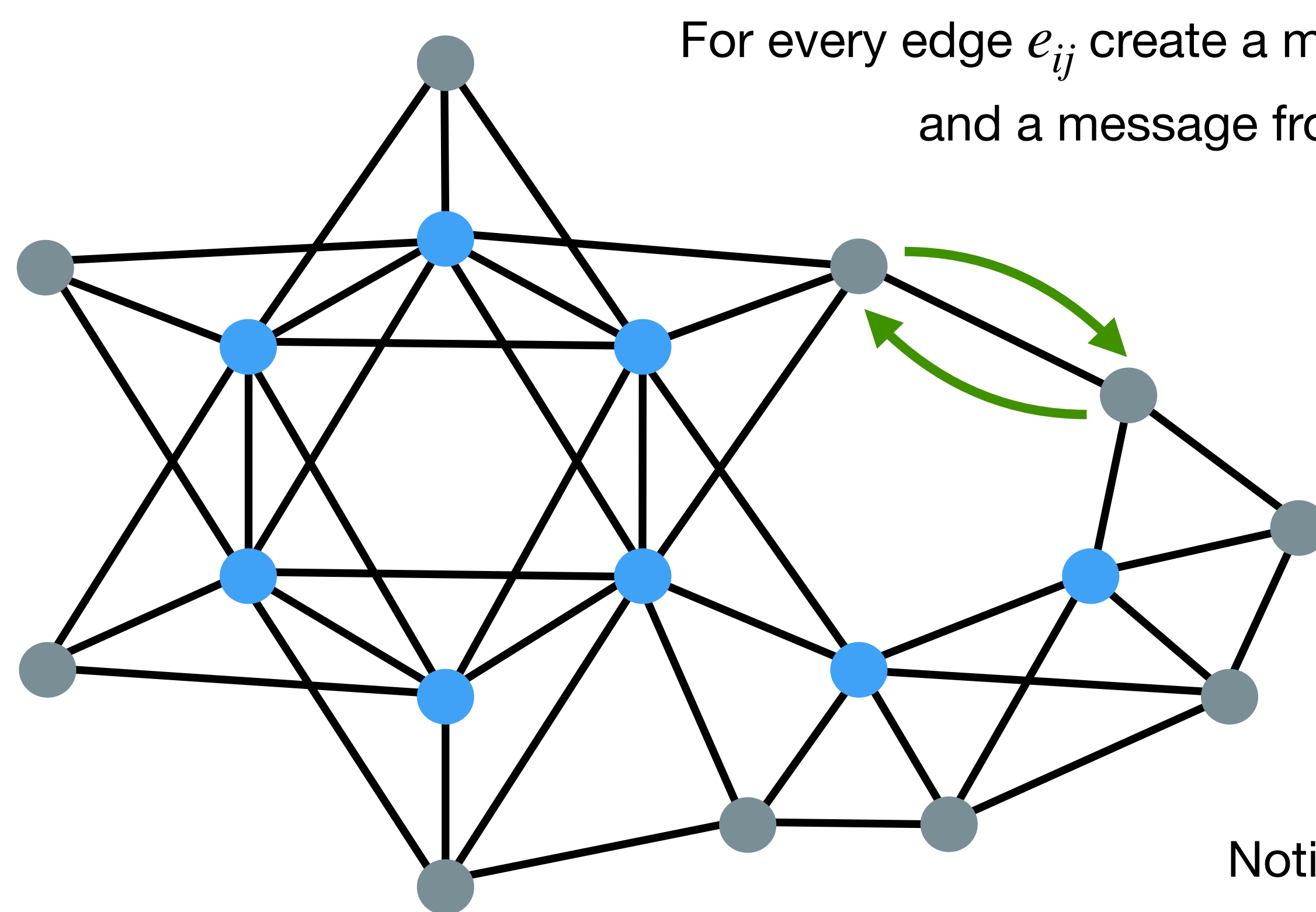
Equivariant AEV

$$\vec{h}_i \in \mathbb{R}^{n_f}$$

$$\vec{\mathbf{x}}_i \in \mathbb{R}^{3 \times n_f}$$

# 1. How do we form rotationally **equivariant** features?

## Pass messages



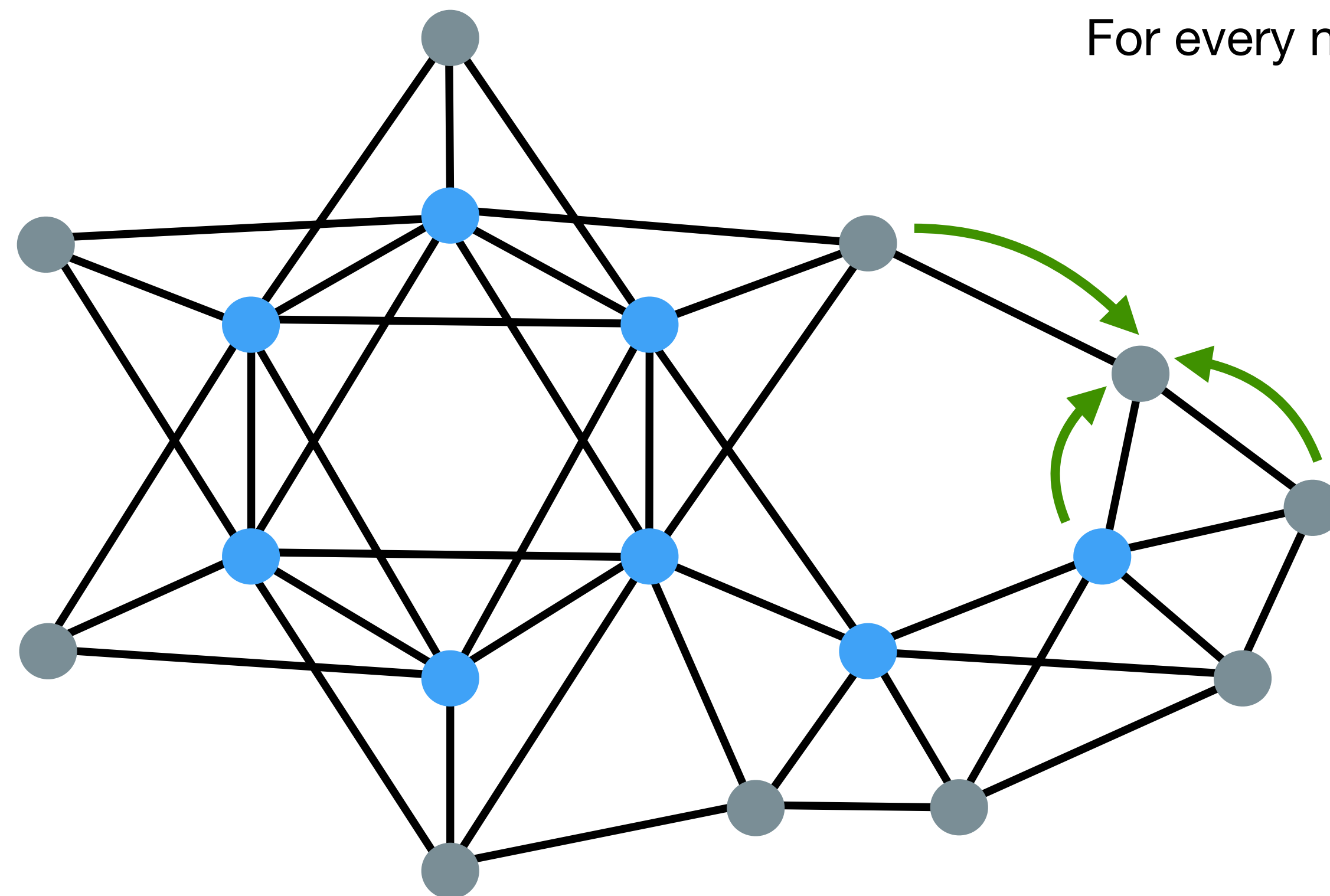
For every edge  $e_{ij}$  create a message from  $i$  to  $j$ ,  $\vec{m}_{ij}$   
and a message from  $j$  to  $i$ ,  $\vec{m}_{ji}$

$$\vec{m}_{ij} = f_m(\vec{h}_i, \vec{h}_j, \vec{e}_{ij}, \underbrace{||\vec{\mathbf{x}}_i - \vec{\mathbf{x}}_j||^2})$$

Notice this term is **invariant** to rotations

# 1. How do we form rotationally **equivariant** features?

## Update equivariant features



For every node, update  $\vec{\mathbf{x}}_i$  preserving rotational equivariance

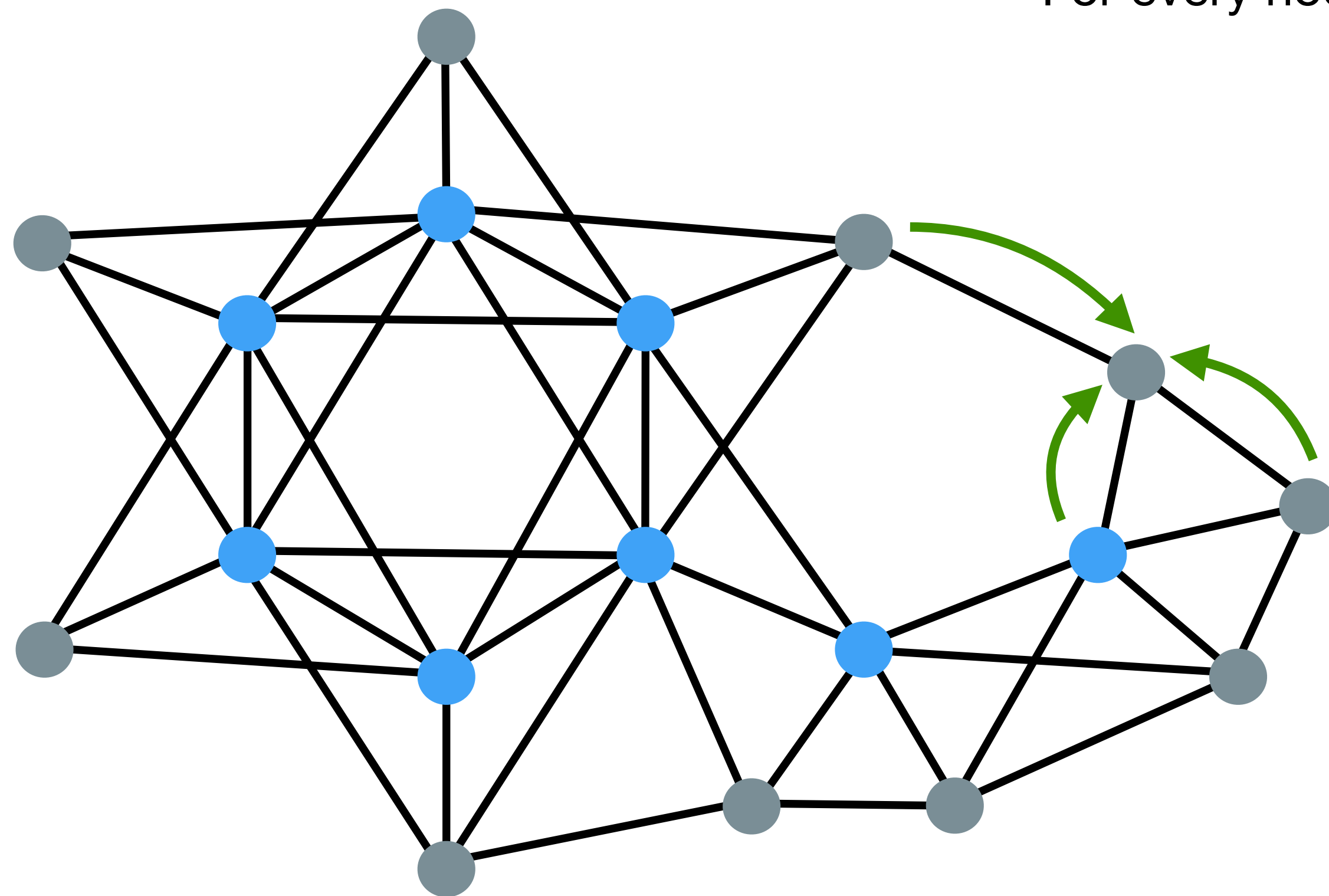
$$\vec{\mathbf{x}}_i + = \frac{1}{N_j} \sum_{j \in \mathcal{N}(i)} \underbrace{(\vec{\mathbf{x}}_i - \vec{\mathbf{x}}_j)}_{\text{Notice this term is equivariant to rotations}} \underbrace{f_{\mathbf{x}}(\vec{m}_{ij})}_{\text{Another free function}}$$

Notice this term is **equivariant** to rotations

Another free function

# 1. How do we form rotationally **equivariant** features?

## Update invariant features



For every node, accumulate all messages  $\{\vec{m}_{ji}\}$  into a bundle  $\vec{M}_i$

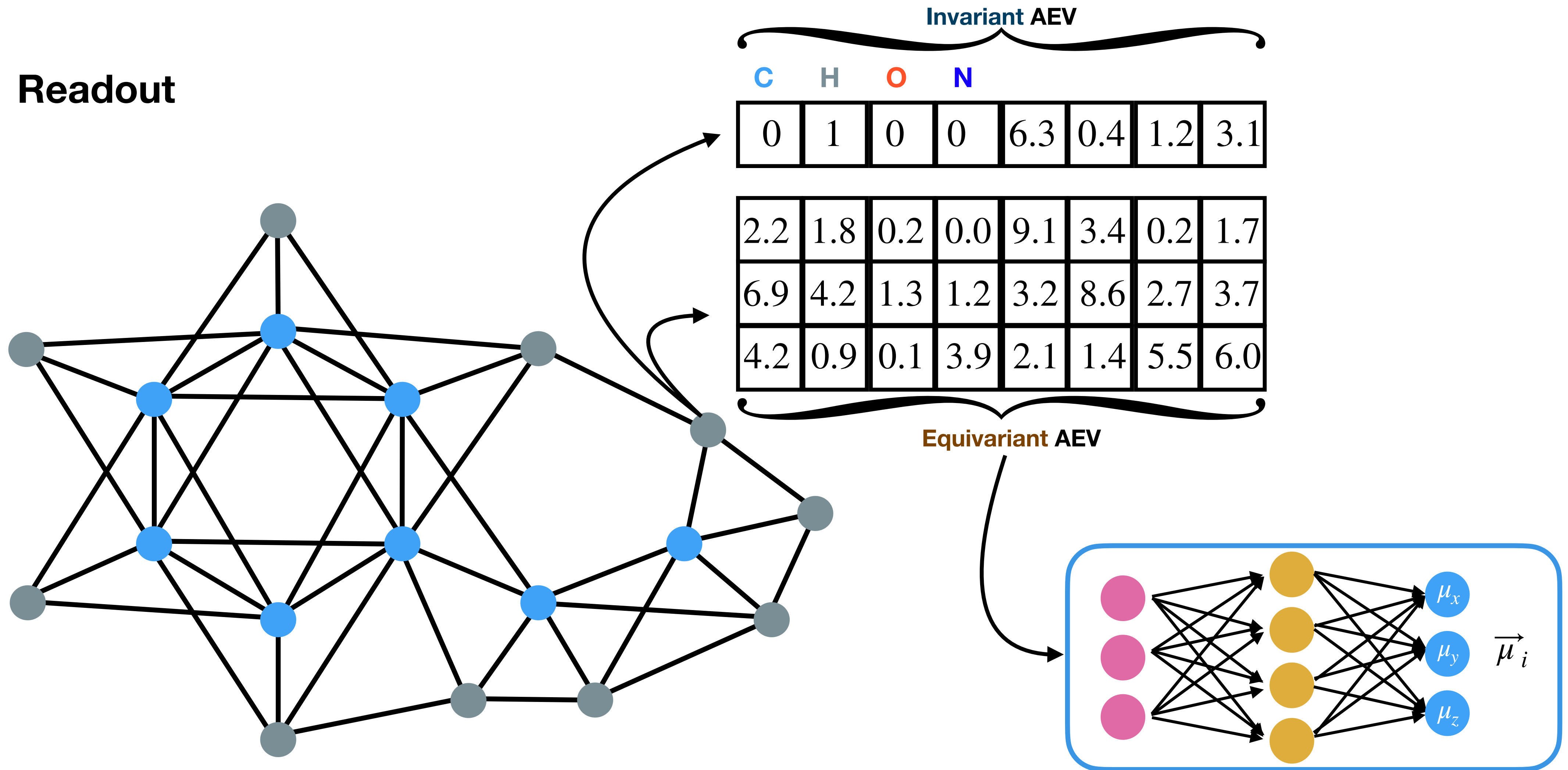
$$\vec{M}_i = \sum_j \vec{m}_{ji}$$

Update node states  $\vec{h}_i$  based on message bundle  $\vec{M}_i$

$$\vec{h}_i = f_U(\vec{h}_i, \vec{M}_i)$$

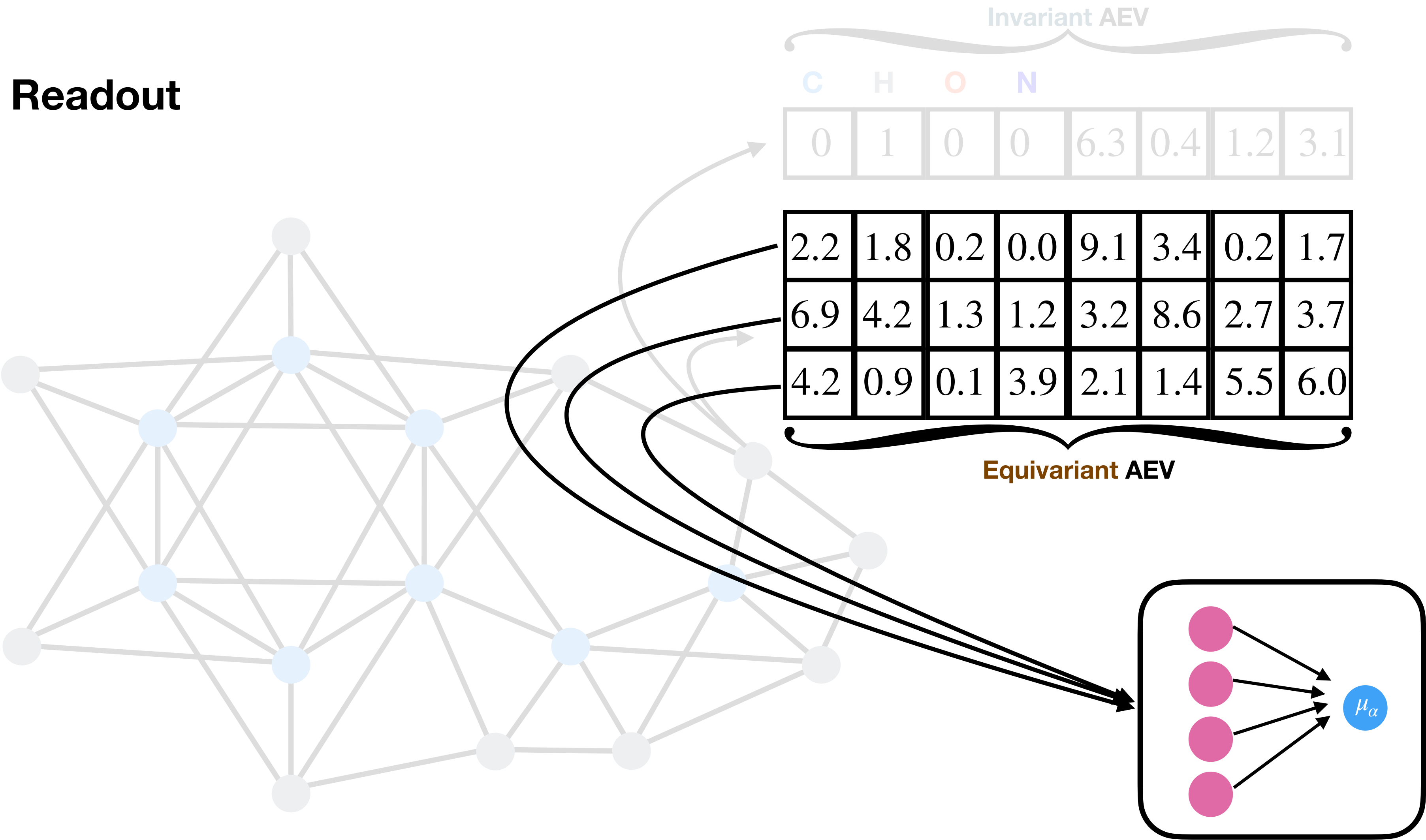
# 1. How do we form rotationally **equivariant** features?

Readout



2. How do we form enforce an **equivariant** readout?

Readout



$$\mu_\alpha = w \overrightarrow{\mathbf{X}}_\alpha + b$$

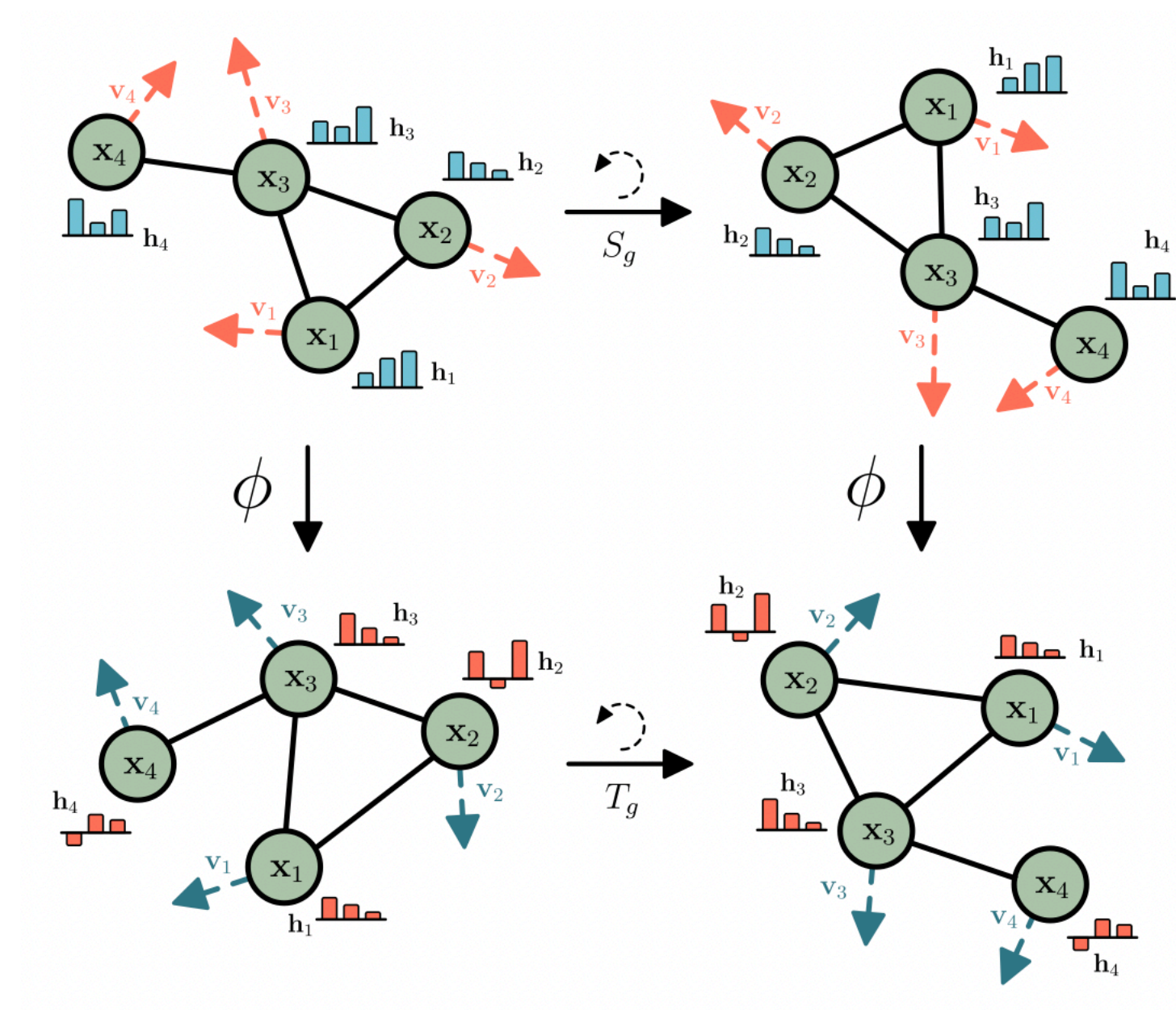
$\alpha \in \{x, y, z\}$   
 $w \in \mathbb{R}^{n_f}$   
 $b \in \mathbb{R}^3$



# E(n) equivariance: The framework presented here

## E(n) Equivariant Graph Neural Networks

Victor Garcia Satorras<sup>1</sup> Emiel Hoogetboom<sup>1</sup> Max Welling<sup>1</sup>



# Generalizing **equivariance**

e3nn is a python library that implements general arbitrary **equivariant** convolutions

This is done with spherical harmonics and tensor products

## e3nn

e3nn: a modular PyTorch framework for Euclidean neural networks

[View My GitHub Profile](#)

### Welcome!

#### Getting Started

[How to use the Resources](#)

[Installation](#)

#### Help

#### Contributing

#### Resources

[Math that's good to know](#)

[e3nn\\_tutorial](#)

[e3nn\\_book](#)

[Papers](#)

[Previous Talks](#)

[Poster](#)

[Slack](#)

[Recurring Meetings / Events](#)

#### Calendar

#### e3nn Team

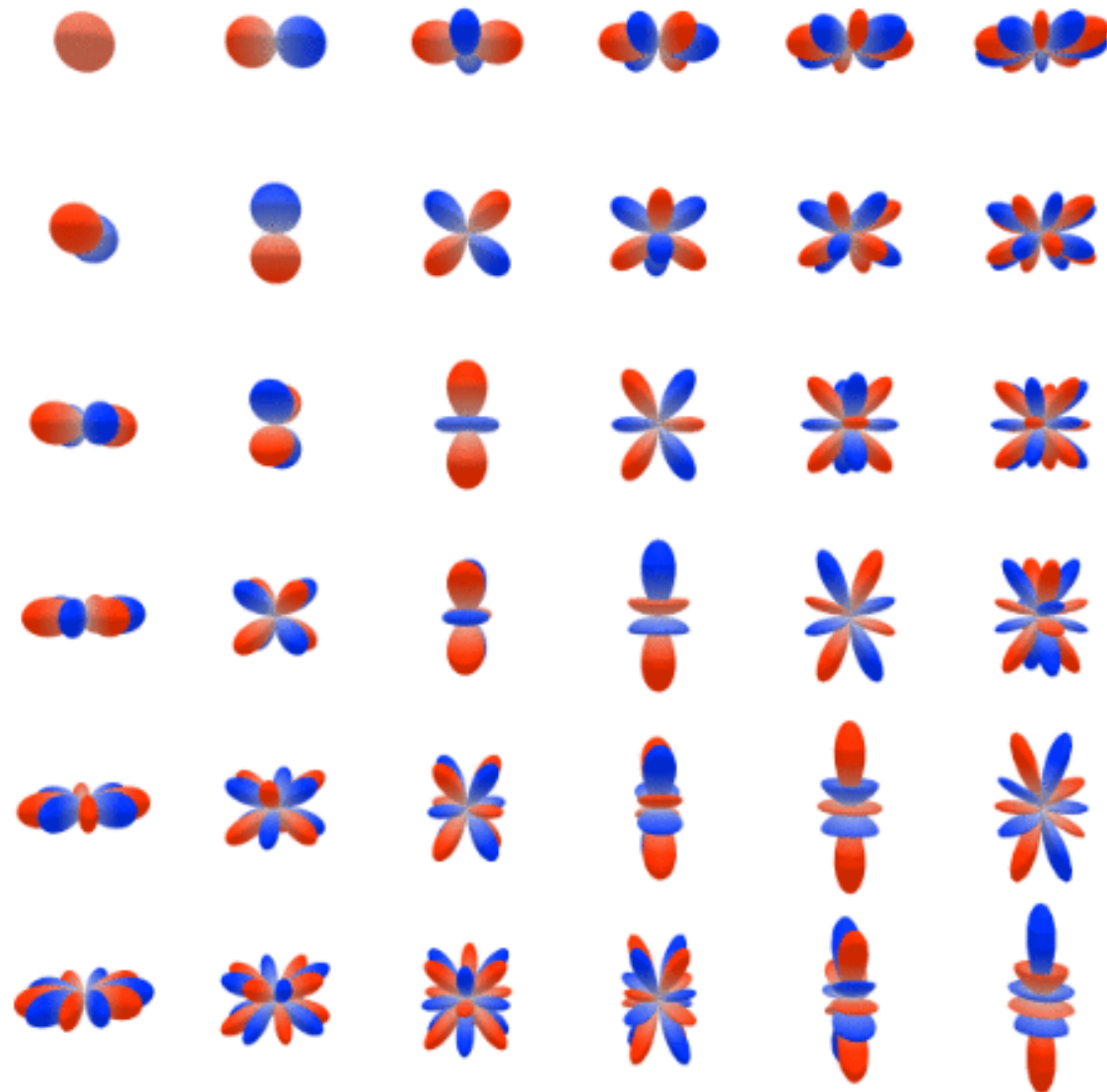
## Welcome to e3nn!

This is the website for the e3nn repository

<https://github.com/e3nn/e3nn/>

[Documentation](#)

$E(3)$  is the [Euclidean group](#) in dimension 3. That is the group of rotations, translations and mirror. e3nn is a [pytorch](#) library that aims to create  **$E(3)$**  equivariant **neural networks**.



**Equivariant NNs model invariant properties better than invariant NNs**

(4.7 mEV is 0.108 kcal / mol)

Model	$U_0$	$U$	$H$	$G$
Schnet [25]	14	19	14	14
DimeNet++ [54]	6.3	6.3	6.5	7.6
Cormorant [23]	22	21	21	20
LieConv [55]	19	19	24	22
L1Net [56]	13.5	13.8	14.4	14.0
SphereNet [57]	6.3	7.3	6.4	8.0
EGNN [32]	11	12	12	12
ET [40]	6.2	6.3	6.5	7.6
NoisyNodes [58]	7.3	7.6	7.4	8.3
PaiNN [27]	5.9	5.7	6.0	7.4
Allegro, 1 layer	<u>5.7</u> (0.2)	<u>5.3</u>	<u>5.3</u>	<u>6.6</u>
Allegro, 3 layers	<b>4.7</b> (0.2)	<b>4.4</b>	<b>4.4</b>	<b>5.7</b>

TABLE III: Comparison of models on the QM9 data set, measured by the MAE in units of [meV]. Allegro outperforms all existing message passing and transformer-based models, in particular even with a single layer. Best methods in bold, second-best method underlined.

# Takeaways

**NNs are powerful nonlinear regressors**

**Libraries like PyTorch make it easy to write and train complicated NNs**

**Training a NN can require significant hyperparameter tuning**

**Neural Networks aren't a one-size-fits-all tool**

# Takeaways

**NNs are powerful nonlinear regressors**

**Libraries like PyTorch make it easy to write and train complicated NNs**

**Training a NN can require significant hyperparameter tuning**

**Neural Networks aren't a one-size-fits-all tool**

**A useful NN requires carefully considering the nature of the input/output**

- To a first approximation, energy is linear in the number of atoms
- Chemistry is local, so atomic environments can be too
- *Ad hoc* AEVs (symfuncs) aren't as expressive as NN-learned AEVs (MPNNs)
- Most (scalar) properties are invariant to Euclidian transforms
- Other (tensorial) properties are equivariant with these transforms