Carl Kolon

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I am a full stack and AI engineer with a strong mathematical foundation. I write APIs, frontend applications, and performant backend code. Before that, I spent 5 years leading engineering and safety teams aboard nuclear submarines. I hold a TS/SCI clearance.

EDUCATION

US Naval Academy – B.S. Mathematics (Distinction and Honors).

3.89 GPA, Trident Scholar, Julian Clancy Frazier Mathematics Research Award, Chinese Minor.

Thesis: Stability of Nonlinear Swarms on Flat and Curved Surfaces.

PROFESSIONAL EXPERIENCE

Senior Forward Deployed Software Engineer: Vannevar Labs

(Apr 2025 – Present)

- Built our economic analysis platform frontend, backend, and data platform from nothing.
- Contribute code to almost every project in the company, from mature to experimental products.
- Promoted from intern to senior faster than anyone else in Vannevar's history.

Forward Deployed Software Engineer: Vannevar Labs

(Jun 2023 – Mar 2025)

- Managed a LLM API deployment to government customers as the lead dev/main point of contact.
- Built my company's geospatial tool, with a fast ~10b row database and feature-rich frontend.

Nuclear Submarine QA/Safety Officer: US Navy

(May 2018 – Jun 2023)

- Built a culture of compliance with rigorous <u>SUBSAFE</u> standards.
- Led 62 nuclear trained sailors and responsible for \$1 billion of equipment.
- Selected as Submarine Junior Officer of the Year for 2022.

ACADEMIC EXPERIENCE

Researcher: US Naval Academy (Trident Scholar)

(Mar 2017 - May 2018)

- Proved novel math results about the stability of swarm models, a nonlinear dynamics problem.
- Presented my work at <u>UMD</u>, <u>SASMC</u>, and Trident Scholar Conferences.

Research Intern: Naval Research Laboratory

(Jun 2017 – Jul 2017)

Swarm collisions with delay coupling.

ACADEMIC WORK

- C. Kolon, C. Medynets, I. Popovici. On the stability of Rotating States in Second-Order Self-Propelled Multi-Particle Systems. 2023.
- Presented <u>Seeing Underwater with Neural Networks</u> at Google X Tidal Ocean Seminar, Jun 2023.
- Presented <u>Stability of Nonlinear Swarms on Flat and Curved Surfaces</u> at UMD Graduate Mathematics Seminar, Apr 2018, Service Academy Student Mathematics Conference, May 2018, and Trident Scholar Conference, May 2018 (video).
- C. Kolon and I. Schwartz. *The Dynamics of Interacting Swarms*. 2017.

PROJECTS - These and many others are described fully on my blog.

- A RNN-based sonar processing algorithm that outperforms the Navy's current tools.
- A semantic search tool for the Navy's longest manual.
- A multiplayer submarine combat game that runs in the browser.
- An in-port ship scheduler that writes fair watchbills with simulated annealing.

SKILLS

Professional Experience In: Python (Django, FastAPI), Typescript/Javascript (Node.js, React), Containerized Environments (Kubernetes, Docker), Temporal, SQL (PostGIS/Postgres, SQLite), Vector DBs (Qdrant, PGVector), training ML models (Pytorch), deploying ML models (Ray Serve).

Academic Experience In: Tensorflow (certified), Wolfram Mathematica, LaTeX, Robotics Simulation.

Hobby Experience In: Liquid (Jekyll), C#, C++, R, Gusek, Ruby, QGIS, Rust.

Language Skills: Working proficiency in Mandarin. Lived in Beijing for 9 years