

11.1 Nullary and Binary Sums

The abstract syntax of sums is given by the following grammar:

Typ $\tau ::=$	void	void	nullary sum
	$+(\tau_1; \tau_2)$	$\tau_1 + \tau_2$	binary sum
Exp $e ::=$	$\text{case}\{\tau\}(e)$	$\text{case}\{\cdot\}$	null case
	$\text{in}[1](\tau_1; \tau_2)(e)$	$1 \cdot e$	left injection
	$\text{in}[x](\tau_1; \tau_2)(e)$	$x \cdot e$	right injection
	$\text{case}\{x_1; e_1; x_2; e_2\}(e)$	$\text{case}\{1 \cdot x_1 \hookrightarrow e_1 x \cdot x_2 \hookrightarrow e_2\}$	case analysis

The nullary sum represents a choice of zero alternatives, and hence admits no introduction form. The elimination form, $\text{case}\{\cdot\}(e)$, expresses the contradiction that e is a value of type **void**. The elements of the binary sum type are labeled to show whether they are drawn from the left or the right summand, either $1 \cdot e$ or $x \cdot e$. A value of the sum type is eliminated by case analysis.

The statics of sum types is given by the following rules.

$$\frac{\Gamma \vdash e : \text{void}}{\Gamma \vdash \text{case}\{\cdot\} : \tau} \quad (11.1a)$$

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$$\frac{\Gamma \vdash e : \tau_1}{\Gamma \vdash 1 \cdot e : \tau_1 + \tau_2} \quad (11.1b)$$

$$\frac{\Gamma \vdash e : \tau_2}{\Gamma \vdash x \cdot e : \tau_1 + \tau_2} \quad (11.1c)$$

$$\frac{\Gamma \vdash e : \tau_1 + \tau_2 \quad \Gamma, x_1 : \tau_1 \vdash e_1 : \tau_1 \quad \Gamma, x_2 : \tau_2 \vdash e_2 : \tau_2}{\Gamma \vdash \text{case}\{1 \cdot x_1 \hookrightarrow e_1 | x \cdot x_2 \hookrightarrow e_2\} : \tau} \quad (11.1d)$$

For the sake of readability, in rules (11.1b) and (11.1c) we have written $1 \cdot e$ and $x \cdot e$ in place of the abstract syntax $\text{in}[1](\tau_1; \tau_2)(e)$ and $\text{in}[x](\tau_1; \tau_2)(e)$, which includes the types τ_1 and τ_2 explicitly. In rule (11.1d) both branches of the case analysis must have the same type. Because a type expresses a static “prediction” on the form of the value of an expression, and because an expression of sum type could evaluate to either form at run-time, we must insist that both branches yield the same type.

The dynamics of sums is given by the following rules:

$$\frac{e \mapsto e'}{\text{case}\{\cdot\} \mapsto \text{case}\{e'\}} \quad (11.2a)$$

$$\frac{[e \text{ val}]}{1 \cdot e \text{ val}} \quad (11.2b)$$

$$\frac{[e \text{ val}]}{x \cdot e \text{ val}} \quad (11.2c)$$

$$\frac{[e \mapsto e']}{[1 \cdot e \mapsto 1 \cdot e']} \quad (11.2d)$$

$$\frac{[e \mapsto e']}{[x \cdot e \mapsto x \cdot e']} \quad (11.2e)$$

$$\frac{e \mapsto e'}{\text{case}\{1 \cdot x_1 \hookrightarrow e_1 | x \cdot x_2 \hookrightarrow e_2\} \mapsto \text{case}\{1 \cdot x_1 \hookrightarrow e_1 | x \cdot x_2 \hookrightarrow e_2\}} \quad (11.2f)$$

$$\frac{[e \text{ val}]}{\text{case}\{1 \cdot e \{1 \cdot x_1 \hookrightarrow e_1 | x \cdot x_2 \hookrightarrow e_2\} \mapsto [e/x_1]e_1\}} \quad (11.2g)$$

$$\frac{[e \text{ val}]}{\text{case}\{x \cdot e \{1 \cdot x_1 \hookrightarrow e_1 | x \cdot x_2 \hookrightarrow e_2\} \mapsto [e/x_2]e_2\}} \quad (11.2h)$$

11.3.2 Booleans

Perhaps the simplest example of a sum type is the familiar type of Booleans, whose syntax is given by the following grammar:

Type $\tau ::=$	bool	bool	booleans.
Exp $e ::=$	true	true	truth
	false	false	falsity
	if($e_1; e_2$)	if(e) e_1 else e_2	conditional

The expression $\text{if}(e_1; e_2)$ branches on the value of $e : \text{bool}$.

The statics of Booleans is given by the following typing rules:

$$\frac{}{\Gamma \vdash \text{true} : \text{bool}} \quad (11.5a)$$

$$\frac{}{\Gamma \vdash \text{false} : \text{bool}} \quad (11.5b)$$

$$\frac{\Gamma \vdash e : \text{bool} \quad \Gamma \vdash e_1 : \tau \quad \Gamma \vdash e_2 : \tau}{\Gamma \vdash \text{if}(e; e_1; e_2) : \tau} \quad (11.5c)$$

$$\frac{}{\text{true val}} \quad (11.6a)$$

true val

15.2 Statics

$$\frac{}{\Delta \vdash \text{unit type}} \quad (15.7b)$$

$$\frac{\Delta \vdash t_1 \text{ type} \quad \Delta \vdash t_2 \text{ type}}{\Delta \vdash \text{prod}(t_1; t_2) \text{ type}} \quad (15.7c)$$

$$\frac{}{\Delta \vdash \text{void type}} \quad (15.7d)$$

$$\frac{\Delta \vdash t_1 \text{ type} \quad \Delta \vdash t_2 \text{ type}}{\Delta \vdash \text{sum}(t_1; t_2) \text{ type}} \quad (15.7e)$$

$$\frac{\Delta \vdash t_1 \text{ type} \quad \Delta \vdash t_2 \text{ type}}{\Delta \vdash \text{arr}(t_1; t_2) \text{ type}} \quad (15.7f)$$

$$\frac{\Delta, t \text{ type} \vdash \tau \text{ type} \quad \Delta \vdash I \cdot \tau \text{ pos}}{\Delta \vdash \text{ind}(t; \tau) \text{ type}} \quad (15.7g)$$

$$\frac{\Delta, t \text{ type} \vdash \tau \text{ type} \quad \Delta \vdash I \cdot \tau \text{ pos}}{\Delta \vdash \text{coi}(t; \tau) \text{ type}} \quad (15.7h)$$

The abstract syntax of \mathbf{M} is given by the following grammar:

$$\begin{array}{lll} \text{Exp } e ::= & \text{fold}\{t.\tau\}(e) & \text{fold}_{t.\tau}(e) \quad \text{constructor} \\ & \text{rec}\{t.\tau\}(x.e_1; e_2) & \text{rec}(x.e_1; e_2) \quad \text{recursor} \\ & \text{unfold}\{t.\tau\}(e) & \text{unfold}_{t.\tau}(e) \quad \text{destructor} \\ & \text{gen}\{t.\tau\}(x.e_1; e_2) & \text{gen}(x.e_1; e_2) \quad \text{generator} \end{array}$$

The subscripts on the concrete syntax forms are often omitted when they are clear from context.

The statics for \mathbf{M} is given by the following typing rules:

$$\frac{}{\mathcal{E}[f/e]\mathcal{L} \mapsto [f'/e]\mathcal{L}} \qquad \frac{\Gamma \vdash e : [\text{ind}(t.\tau)/t]\tau}{\Gamma \vdash \text{fold}\{t.\tau\}(e) : \text{ind}(t.\tau)} \quad (15.8a)$$

$$\frac{t:\tau \text{ poly } \Gamma, n; f \vdash e' : f' \quad \Gamma \vdash e : \mathcal{E}/\mathcal{A}\mathcal{L}}{\Gamma \vdash \text{map}\{t.\tau\}(n.e')(e) : [f'/t]\mathcal{L}} \quad (15.8b)$$

$$\frac{\Gamma, x : [t'/t]\tau \vdash e_1 : t' \quad \Gamma \vdash e_2 : \text{ind}(t.\tau)}{\Gamma \vdash \text{rec}\{t.\tau\}(x.e_1; e_2) : t'} \qquad \frac{\Gamma \vdash e : \text{coi}(t.\tau)}{\Gamma \vdash \text{unfold}\{t.\tau\}(e) : [\text{coi}(t.\tau)/t]\tau} \quad (15.8c)$$

$$\left. \begin{aligned} \frac{\Gamma \vdash e_2 : t_2 \quad \Gamma, x : t_2 \vdash e_1 : [t_2/t]\tau}{\Gamma \vdash \text{gen}\{t.\tau\}(x.e_1; e_2) : \text{coi}(t.\tau)} \\ \end{aligned} \right\} \quad (15.8d)$$

15.3 Dynamics

The dynamics of \mathbf{M} is given in terms of the positive generic extension operation described in Chapter 14. The following rules specify a lazy dynamics for \mathbf{M} :

$$\frac{}{\text{fold}\{t.\tau\}(e) \text{ val}} \quad (15.9a)$$

$$\frac{e_2 \longmapsto e'_2}{\text{rec}\{t.\tau\}(x.e_1; e_2) \longmapsto \text{rec}\{t.\tau\}(x.e_1; e'_2)} \quad (15.9b)$$

$$\frac{\text{rec}\{t.\tau\}(x.e_1; \text{fold}\{t.\tau\}(e_2))}{\longmapsto} \quad (15.9c)$$

$$[\text{map}^+ \{t.\tau\}(y.\text{rec}\{t.\tau\}(x.e_1; y))(e_2)/x]e_1$$

$$\frac{}{\text{gen}\{t.\tau\}(x.e_1; e_2) \text{ val}} \quad (15.9d)$$

$$\frac{e \longmapsto e'}{\text{unfold}\{t.\tau\}(e) \longmapsto \text{unfold}\{t.\tau\}(e')} \quad (15.9e)$$

$$\frac{\text{unfold}\{t.\tau\}(\text{gen}\{t.\tau\}(x.e_1; e_2))}{\longmapsto} \quad (15.9f)$$

$$[\text{map}^+ \{t.\tau\}(y.\text{gen}\{t.\tau\}(x.e_1; y))([e_2/x]e_1)]$$

$$\frac{\Delta, t \text{ type } \Gamma \vdash e : \tau}{\Delta \Gamma \vdash \Lambda(t.e) : \forall(t.\tau)} \quad (16.2d)$$

$$\frac{\Delta \Gamma \vdash e : \forall(t.\tau') \quad \Delta \vdash \tau \text{ type}}{\Delta \Gamma \vdash \text{App}\{\tau\}(e) : [\tau/t]\tau'} \quad (16.2e)$$

Lemma 16.1 (Regularity). If $\Delta \Gamma \vdash e : \tau$, and if $\Delta \vdash \tau_i$ type for each assumption $x_i : \tau_i$ in Γ , then $\Delta \vdash \tau$ type.

Proof. By induction on rules (16.2). \square

Lemma 16.2 (Substitution). 1. If $\Delta, t \text{ type } \vdash \tau'$ type and $\Delta \vdash \tau$ type, then $\Delta \vdash [\tau/t]\tau'$ type.

2. If $\Delta, t \text{ type } \Gamma \vdash e' : \tau'$ and $\Delta \vdash \tau$ type, then $\Delta [\tau/t]\Gamma \vdash [\tau/t]e' : [\tau/t]\tau'$.

3. If $\Delta \Gamma, x : \tau \vdash e' : \tau'$ and $\Delta \Gamma \vdash e : \tau$, then $\Delta \Gamma \vdash [e/x]e' : \tau'$.

The second part of the lemma requires substitution into the context Γ as well as into the term and its type, because the type variable t may occur freely in any of these positions.

Returning to the motivating examples from the introduction, the polymorphic identity function, I , is written

$$\Lambda(t)\lambda(x:t)x;$$

it has the polymorphic type

$$\forall(t.t \rightarrow t).$$

Instances of the polymorphic identity are written $I[\tau]$, where τ is some type, and have the type $\tau \rightarrow \tau$.

Similarly, the polymorphic composition function, C , is written

$$\Lambda(t_1)\Lambda(t_2)\Lambda(t_3)\lambda(f:t_2 \rightarrow t_3)\lambda(g:t_1 \rightarrow t_2)\lambda(x:t_1)f(g(x)).$$

The function C has the polymorphic type

$$\forall(t_1.\forall(t_2.\forall(t_3.(t_2 \rightarrow t_3) \rightarrow (t_1 \rightarrow t_2) \rightarrow (t_1 \rightarrow t_3)))).$$

Instances of C are obtained by applying it to a triple of types, written $C[\tau_1][\tau_2][\tau_3]$. Each such instance has the type

$$(\tau_2 \rightarrow \tau_3) \rightarrow (\tau_1 \rightarrow \tau_2) \rightarrow (\tau_1 \rightarrow \tau_3).$$

16.1 Polymorphic Abstraction

The language **F** is a variant of **T** in which we eliminate the type of natural numbers, but add, in compensation, polymorphic types:¹

Typ	$\tau ::= t \quad t$	variable
	$\rightarrow(\tau_1; \tau_2) \quad \tau_1 \rightarrow \tau_2$	function
	$\forall(t.\tau) \quad \forall(t.\tau)$	polymorphic
Exp	$e ::= x \quad x$	
	$\lambda\{\tau\}(x.e) \quad \lambda(x:\tau)e$	abstraction
	$\text{ap}(e_1; e_2) \quad e_1(e_2)$	application
	$\Delta(t.e) \quad \Delta(t)e$	type abstraction
	$\text{App}(\tau)(e) \quad e[\tau]$	type application

A type abstraction $\Delta(t.e)$ defines a generic, or polymorphic, function with type variable t standing for an unspecified type within e . A type application, or instantiation $\text{App}(\tau)(e)$ applies a polymorphic function to a specified type, which is plugged in for the type variable to obtain the result. The universal type, $\forall(t.\tau)$, classifies polymorphic functions.

The statics of **F** consists of two judgment forms, the *type formation judgment*,

$$\Delta \vdash \tau \text{ type},$$

and the *typing judgment*,

$$\Delta \Gamma \vdash e : \tau.$$

The hypotheses Δ have the form t type, where t is a variable of sort **Typ**, and the hypotheses Γ have the form $x : \tau$, where x is a variable of sort **Exp**.

The rules defining the type formation judgment are as follows:

$$\frac{}{\Delta, t \text{ type} \vdash t \text{ type}} \quad (16.1a)$$

$$\frac{\Delta \vdash \tau_1 \text{ type} \quad \Delta \vdash \tau_2 \text{ type}}{\Delta \vdash \rightarrow(\tau_1; \tau_2) \text{ type}} \quad (16.1b)$$

$$\frac{\Delta, t \text{ type} \vdash \tau \text{ type}}{\Delta \vdash \forall(t.\tau) \text{ type}} \quad (16.1c)$$

The rules defining the typing judgment are as follows:

$$\frac{}{\Delta \Gamma, x : \tau \vdash x : \tau}$$

$$\frac{\Delta \vdash \tau_1 \text{ type} \quad \Delta \Gamma, x : \tau_1 \vdash e : \tau_2}{\Delta \Gamma \vdash \lambda\{\tau_1\}(x.e) : \rightarrow(\tau_1; \tau_2)}$$

$$\frac{\Delta \vdash e_1 : \rightarrow(\tau_2; \tau) \quad \Delta \Gamma \vdash e_2 : \tau_2}{\Delta \Gamma \vdash \text{ap}(e_1; e_2) : \tau}$$

Typing Judgment

¹Girard's original version of System F included the natural numbers as a basic type.

$$\Delta \vdash e : \tau$$

$$\Delta \vdash \tau \text{ type}$$

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The statics of \mathbf{T} is given by the following typing rules:

$$\frac{}{\Gamma, x : \tau \vdash x : \tau} \quad (9.1a)$$

$$\frac{\Gamma \vdash z : \text{nat}}{\Gamma \vdash c : \text{nat}} \quad (9.1b)$$

$$\frac{\Gamma \vdash c : \text{nat}}{\Gamma \vdash s(c) : \text{nat}} \quad (9.1c)$$

$$\frac{\Gamma \vdash e : \text{nat} \quad \Gamma \vdash e_0 : x \quad \Gamma, x : \text{nat}, y : \tau \vdash e_1 : \tau}{\Gamma \vdash \text{rec}\{e_0; x.y.e_1\}(e) : \tau} \quad (9.1d)$$

$$\frac{\Gamma, x : \tau_1 \vdash e : \tau_2}{\Gamma \vdash \lambda\{\tau_1\}(xe) : \rightarrow(\tau_1; \tau_2)} \quad \text{constructor} \quad (9.1e)$$

$$\frac{\Gamma \vdash e_1 : \rightarrow(\tau_2; \tau) \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash \text{ap}(e_1; e_2) : \tau} \quad (9.1f)$$

As usual, admissibility of the structural rule of substitution is crucially important.

Lemma 9.1. If $\Gamma \vdash e : \tau$ and $\Gamma, x : \tau \vdash e' : \tau'$, then $\Gamma \vdash [e/x]e' : \tau'$.

9.2

Dynamics

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The closed values of \mathbf{T} are defined by the following rules:

$$\frac{z \text{ val}}{[e \text{ val}]} \quad (9.2a)$$

$$\frac{[e \text{ val}]}{s(e) \text{ val}} \quad (9.2b)$$

$$\frac{e_1 \mapsto e'_1}{\text{ap}(e_1, e_2) \mapsto \text{ap}(e'_1, e_2)} \quad \frac{\lambda(\tau)(x.e) \text{ val}}{[e \text{ val}]} \quad (9.2c)$$

$$\frac{\left[\begin{array}{l} e_1 \text{ val} \quad e_2 \mapsto e'_2 \\ \text{ap}(e_1, e_2) \mapsto \text{ap}(e_1, e'_2) \end{array} \right]}{[e \text{ val}]} \quad (9.3c)$$

$$\frac{[e_2 \text{ val}]}{\text{ap}(\lambda\{\tau\}(x.e); e_2) \mapsto [e_2/x]e} \quad (9.3d)$$

$$\frac{e \mapsto e'}{\text{rec}\{e_0; x.y.e_1\}(e) \mapsto \text{rec}\{e_0; x.y.e_1\}(e')} \quad (9.3e)$$

$$\frac{}{\text{rec}\{e_0; x.y.e_1\}(z) \mapsto e_0} \quad (9.3f)$$

$$\frac{s(e) \text{ val}}{\text{rec}\{e_0; x.y.e_1\}(s(e)) \mapsto [e, \text{rec}\{e_0; x.y.e_1\}(e)/x, y]e_1} \quad (9.3g)$$

$$[e/\alpha] \quad \text{[y/y, x/x, z/z]}$$

$$[\ell, e/\ell, x]e_2$$

$$[\ell/t / \ell/n]e_2$$

Lemma 9.2 (Canonical Forms). If $e : \tau$ and e val, then

1. If $\tau = \text{nat}$, then either $e = z$ or $e = s(e')$ for some e' .
2. If $\tau = \tau_1 \rightarrow \tau_2$, then $e = \lambda(x : \tau_1) e_2$ for some e_2 .

The abstract syntax of products is given by the following grammar:

Type τ	unit	$\text{unit} \times \text{unit}$	nullary product
	$\times(\tau_1; \tau_2)$	$\tau_1 \times \tau_2$	binary product
Exp e	triv	$\langle \rangle$	null tuple
	$\text{pair}(e_1, e_2)$	$\langle e_1, e_2 \rangle$	ordered pair
	$\text{pr}[1](e)$	$e \cdot 1$	left projection
	$\text{pr}[x](e)$	$e \cdot x$	right projection

The statics of product types is given by the following rules.

$$\frac{\Gamma \vdash \langle \rangle : \text{unit}}{\Gamma \vdash \langle \rangle : \text{unit}} \quad (10.1a)$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash \langle e_1, e_2 \rangle : \tau_1 \times \tau_2} \quad (10.1b)$$

$$\frac{\Gamma \vdash e : \tau_1 \times \tau_2}{\Gamma \vdash e \cdot 1 : \tau_1} \quad (10.1c)$$

$$\frac{\Gamma \vdash e : \tau_1 \times \tau_2}{\Gamma \vdash e \cdot x : \tau_2} \quad (10.1d)$$

The dynamics of product types is defined by the following rules:

$$\frac{}{\langle \rangle \text{ val}} \quad (10.2a)$$

$$\frac{[e_1 \text{ val}] \quad [e_2 \text{ val}]}{\langle e_1, e_2 \rangle \text{ val}} \quad (10.2b)$$

$$\frac{e_1 \mapsto e'_1}{\left[\begin{array}{c} e_1 \mapsto e'_1 \\ \langle e_1, e_2 \rangle \mapsto \langle e'_1, e_2 \rangle \end{array} \right]} \quad (10.2c)$$

$$\frac{e_1 \text{ val} \quad e_2 \mapsto e'_2}{\left[\begin{array}{c} e_1 \text{ val} \\ e_1 \mapsto e'_2 \\ \langle e_1, e_2 \rangle \mapsto \langle e'_1, e'_2 \rangle \end{array} \right]} \quad (10.2d)$$

$$\frac{e \mapsto e'}{e \cdot 1 \mapsto e' \cdot 1} \quad (10.2e)$$

$$\frac{e \mapsto e'}{e \cdot x \mapsto e' \cdot x} \quad (10.2f)$$

$$\frac{[e_1 \text{ val}] \quad [e_2 \text{ val}]}{\langle e_1, e_2 \rangle \cdot 1 \mapsto e_1} \quad (10.2g)$$

$$\frac{[e_1 \text{ val}] \quad [e_2 \text{ val}]}{\langle e_1, e_2 \rangle \cdot x \mapsto e_2} \quad (10.2h)$$

The bracketed rules and premises are omitted for a lazy dynamics, and included for an eager

$$\begin{array}{c}
 \frac{e_1 \text{ val} \quad e_2 \mapsto e'_2}{\text{plus}(e_1; e_2) \mapsto \text{plus}(e_1; e'_2)} \quad (5.4c) \\
 \frac{s_1 * s_2 = s}{\text{cat}(\text{str}[s_1]; \text{str}[s_2]) \mapsto \text{str}[s]} \quad (5.4d) \\
 \frac{e_1 \mapsto e'_1}{\text{cat}(e_1; e_2) \mapsto \text{cat}(e'_1; e_2)} \quad (5.4e) \\
 \frac{e_1 \text{ val} \quad e_2 \mapsto e'_2}{\text{cat}(e_1; e_2) \mapsto \text{cat}(e_1; e'_2)} \quad (5.4f) \\
 \left[\frac{e_1 \mapsto e'_1}{\text{let}(e_1; x, e_2) \mapsto \text{let}(e'_1; x, e_2)} \right] \quad (5.4g) \\
 \frac{[e_1 \text{ val}]}{\text{let}(e_1; x, e_2) \mapsto [e_1/x]e_2} \quad (5.4h)
 \end{array}$$

6.2 Progress

The progress theorem captures the idea that well-typed programs cannot “get stuck”. The proof depends crucially on the following lemma, which characterizes the values of each type.

Lemma 6.3 (Canonical Forms). If e val and $e : \tau$, then

1. If $\tau = \text{num}$, then $e = \text{num}[n]$ for some number n .
2. If $\tau = \text{str}$, then $e = \text{str}[s]$ for some string s .

Proof. By induction on rules (4.1) and (5.3). □

7.1 Evaluation Dynamics

An *evaluation dynamics*, consists of an inductive definition of the evaluation judgment $e \Downarrow v$ stating that the closed expression e evaluates to the value v . The evaluation dynamics of \mathbb{E} is defined by the following rules:

$$\frac{}{\text{num}[n] \Downarrow \text{num}[n]} \quad (7.1a)$$

$$\frac{}{\text{str}[s] \Downarrow \text{str}[s]} \quad (7.1b)$$

$$\frac{e_1 \Downarrow \text{num}[n_1] \quad e_2 \Downarrow \text{num}[n_2] \quad n_1 + n_2 = n}{\text{plus}(e_1; e_2) \Downarrow \text{num}[n]} \quad (7.1c)$$

$$\frac{e_1 \Downarrow \text{str}[s_1] \quad e_2 \Downarrow \text{str}[s_2] \quad s_1 * s_2 = s}{\text{cat}(e_1; e_2) \Downarrow \text{str}[s]} \quad (7.1d)$$

$$\frac{e \Downarrow \text{str}[s] \quad |s| = n}{\text{len}(e) \Downarrow \text{num}[n]} \quad (7.1e)$$

$$\frac{[e_1/x]e_2 \Downarrow v_2}{\text{let}(e_1; x, e_2) \Downarrow v_2} \quad (7.1f)$$

$$\frac{}{\Gamma, x : \tau \vdash x : \tau} \quad (4.1a)$$

$$\frac{}{\Gamma \vdash \text{str}[s] : \text{str}} \quad (4.1b)$$

$$\frac{}{\Gamma \vdash \text{num}[n] : \text{num}} \quad (4.1c)$$

$$\frac{\Gamma \vdash e_1 : \text{num} \quad \Gamma \vdash e_2 : \text{num}}{\Gamma \vdash \text{plus}(e_1; e_2) : \text{num}} \quad (4.1d)$$

$$\frac{\Gamma \vdash e_1 : \text{num} \quad \Gamma \vdash e_2 : \text{num}}{\Gamma \vdash \text{times}(e_1; e_2) : \text{num}} \quad (4.1e)$$

$$\frac{\Gamma \vdash e_1 : \text{str} \quad \Gamma \vdash e_2 : \text{str}}{\Gamma \vdash \text{cat}(e_1; e_2) : \text{str}}$$

$$\frac{\Gamma \vdash e : \text{str}}{\Gamma \vdash \text{len}(e) : \text{num}}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma, x : \tau_1 \vdash e_2 : \tau_2}{\Gamma \vdash \text{let}(e_1; x. e_2) : \tau_2}$$

(4.1f)

(4.1g)

(4.1h)

$$\frac{\text{num}[n] \text{ val}}{\text{str}[s] \text{ val}} \quad (5.3a)$$

$$\frac{}{\text{str}[s] \text{ val}} \quad (5.3b)$$

The transition judgment $e \rightarrow e'$ between states is inductively defined by the following rules:

$$\frac{n_1 + n_2 = n}{\text{plus}(\text{num}[n_1]; \text{num}[n_2]) \rightarrow \text{num}[n]} \quad (5.4a)$$

$$\frac{e_1 \rightarrow e'_1}{\text{plus}(e_1; e_2) \rightarrow \text{plus}(e'_1; e_2)} \quad (5.4b)$$

The dynamics of \mathbf{F} is given as follows:

$$\frac{}{\lambda\{\tau\}(x.e) \text{ val}} \quad (16.3a)$$

$$\frac{}{\Delta(t.e) \text{ val}} \quad (16.3b)$$

$$\frac{[c_2 \text{ val}]}{\text{ap}(\lambda\{\tau_1\}(x.e); c_2) \mapsto [c_2/x]e} \quad (16.3c)$$

$$\frac{c_1 \mapsto c'_1}{\text{ap}(c_1; c_2) \mapsto \text{ap}(c'_1; c_2)} \quad (16.3d)$$

$$\left[\begin{array}{l} e_1 \text{ val} \\ e_2 \mapsto c'_2 \end{array} \right] \frac{}{\text{ap}(e_1; e_2) \mapsto \text{ap}(e_1; c'_2)} \quad (16.3e)$$

$$\frac{\Delta(t.e) \mapsto [\tau/t]e}{\text{App}(\tau\{t\})(\Delta(t.e)) \mapsto [\tau/t]e} \quad (16.3f)$$

$$\frac{e \mapsto e'}{\text{App}(\tau\{t\})(e) \mapsto \text{App}(\tau\{t\})(e')} \quad (16.3g)$$

The bracketed premises and rule are included for a call-by-value interpretation, and omitted for a call-by-name interpretation of \mathbf{F} .

It is a simple matter to prove safety for \mathbf{F} , using familiar methods.

Lemma 16.3 (Canonical Forms). Suppose that $e : \tau$ and $e \text{ val}$, then

1. If $\tau = \rightarrow(\tau_1; \tau_2)$, then $e = \lambda\{\tau_1\}(x.e_2)$ with $x : \tau_1 \vdash e_2 : \tau_2$.
2. If $\tau = \forall(t.\tau')$, then $e = \Delta(t.e')$ with $t \text{ type} \vdash e' : \tau'$.

Proof. By rule induction on the statics. □

17.1.1 Statics

The statics of \mathbf{FE} is given by these rules:

$$\frac{\Delta, t \text{ type} \vdash \tau \text{ type}}{\Delta \vdash \exists(t.t) \text{ type}} \quad (17.1a)$$

$$\frac{\Delta \vdash p \text{ type} \quad \Delta, t \text{ type} \vdash \tau \text{ type} \quad \Delta \Gamma \vdash e : [p/t]\tau}{\Delta \Gamma \vdash \text{pack}\{t.\tau\}\{p\}(e) : \exists(t.\tau)} \quad (17.1b)$$

$$\frac{\Delta \Gamma \vdash e_1 : \exists(t.\tau) \quad \Delta, t \text{ type} \Gamma, x : t \vdash e_2 : \tau_2 \quad \Delta \vdash \tau_2 \text{ type}}{\Delta \Gamma \vdash \text{open}\{t.\tau\}\{\tau_2\}(e_1; t, x.e_2) : \tau_2} \quad (17.1c)$$

Rule (17.1c) is complex, so study it carefully! There are two important things to notice:

1. The type of the client, τ_2 , must not involve the abstract type t . This restriction prevents the client from attempting to export a value of the abstract type outside of the scope of its definition.
2. The body of the client, e_2 , is type checked without knowledge of the representation type, t . The client is, in effect, polymorphic in the type variable t .

Lemma 17.1 (Regularity). Suppose that $\Delta \Gamma \vdash e : \tau$. If $\Delta \vdash \tau_i \text{ type}$ for each $x_i : \tau_i$ in Γ , then $\Delta \vdash \tau \text{ type}$.

Proof. By induction on rules (17.1), using substitution for expressions and types. □

17.1.2 Dynamics

The dynamics of **FE** is defined by the following rules (including the bracketed material for an eager interpretation, and omitting it for a lazy interpretation):

$$\frac{[e \text{ val}]}{\text{pack}\{t.\tau\}\{\rho\}(e) \text{ val}} \quad (17.2a)$$

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$$\frac{e \mapsto e' \quad \text{pack}\{t.\tau\}\{\rho\}(e) \mapsto \text{pack}\{t.\tau\}\{\rho\}(e')}{\text{open}\{t.\tau\}\{t_2\}(e_1; t, x.e_2) \mapsto \text{open}\{t.\tau\}\{t_2\}(e'_1; t, x.e_2)}$$

(17.2b)

$$\frac{e_1 \mapsto e'_1}{\text{open}\{t.\tau\}\{t_2\}(e_1; t, x.e_2) \mapsto \text{open}\{t.\tau\}\{t_2\}(e'_1; t, x.e_2)}$$

(17.2c)

$$\frac{[e \text{ val}]}{\text{open}\{t.\tau\}\{t_2\}(\text{pack}\{t.\tau\}\{\rho\}(e); t, x.e_2) \mapsto [\rho, e/t, x]e_2}$$

(17.2d)

It is important to see that, according to these rules, *there are no abstract types at run time!* The representation type is propagated to the client by substitution when the package is opened, thereby eliminating the abstraction boundary between the client and the implementor. Thus, data abstraction is a *compile-time discipline* that leaves no traces of its presence at execution time.

17.1.3 Safety

Safety of **FE** is stated and proved by decomposing it into progress and preservation.

Theorem 17.2 (Preservation). *If $e : \tau$ and $e \mapsto e'$, then $e' : \tau$.*

Proof. By rule induction on $e \mapsto e'$, using substitution for both expression- and type variables. \square

Lemma 17.3 (Canonical Forms). *If $e : \exists(t.\tau)$ and e val, then $e = \text{pack}\{t.\tau\}\{\rho\}(e')$ for some type ρ and some e' such that $e' : [\rho/t]\tau$.*

Proof. By rule induction on the statics, using the definition of closed values. \square

Theorem 17.4 (Progress). *If $e : \tau$ then either e val or there exists e' such that $e \mapsto e'$.*

Proof. By rule induction on $e : \tau$, using the canonical forms lemma. \square