CHET CORCOS

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Los Angeles, CA

Claremont, CA

Graduated May 2013

Fall 2013 - Present

EDUCATION

University of Southern California

Phd in Computer Science Cumulative GPA: 3.5

Robotic Embedded Systems Lab (RESL)

Harvey Mudd College

Bachelor of Science in Engineering

Cumulative GPA: 3.7

Dean's List: Spring 2010 - Spring 2012

Tau Beta Pi Engineering Honor Society Member

Norin Memorial Scholarship Recipient for Communications Engineering and Related Fields (SP 2012)

Relevant Coursework:

Analysis of Algorithms | Probabilistic Graphical Models | Machine Learning | Mobile Robotics Control Systems Engineering | Microprocessor Design and Application | Communication Systems

Publications:

• Towards Interactive Object Recognition (Karol Hausman, Chet Corcos, Joerg Mueller, Fei Sha, Gaurav S. Sukhatme), In IROS 2014 3rd Workshop on Robots in Clutter: Perception and Interaction in Clutter, 2014.

PROFESSIONAL EXPERIENCE

SpaceX - Avionics Intern

Hawthorne, CA - Summer 2013

- · Designed pan-tilt control system for custom laser scanning infrared range finder (LiDAR).
- · Designed calibration and simulation rigs in CAD along with engineering drawings for machining and 3D printing.

One Aura - Software Developer and Bio-signal Analyst

Tustin, CA - Summer 2012

- · Developed an iPhone App involving Bluetooth communication and GPS tracking.
- · Used frequency domain tools for heart beat detection from an infrared sensor.

RESEARCH EXPERIENCE

USC Robotic Embedded Systems Lab - *Phd Student*

Los Angeles, CA - Fall 2013 - Present

- · Smoothing and Mapping (SAM) simulations with heterogeneous multi-robot teams
- · Probabilistic graphical model for robotic interactive object recognition

UC Davis Center for Neuroscience - Intern

Davis, CA - Summer 2011

· Wrote MATLAB scripts using EEGLab toolbox for analyzing inter-cranial brain signals from rats and humans.

PROJECT EXPERIENCE

Eaton Aerospace Engineering Clinic

Harvey Mudd College, CA - Fall 2012

- · Designed modular, nonlinear control systems for various types of hydraulic aircraft nose-wheel steering systems.
- · Implemented sliding mode and adaptive control.

Electric Truck

Fair Oaks, CA - Summer 2008

- · Built an electric truck using the body, chassis and manual transmission of a 1999 S-10 with a blown engine.
- · Installed power brakes, power steering, welded battery trays, designed 12V and 120V circuits.

High Power Rockets

Harvey Mudd College, CA - Fall 2010

- · Built and flew high-powered rockets (I-motors) with custom sensor payload.
- · Designed and built a protoboard with a data-logger, 3-directional gyroscopes, and 3-directional accelerometers.
- · Developed a 6 DOF model in MATLAB for determining the rocket's 3D position and orientation throughout flight.

OTHER PROJECTS:

D3 Network Visualization | RSA Encryption Demo | Password Rhythm Authentication | OpenCV Eye Tracking MIPS multi-cycle processor implementation | One-handed Keyboard | Wide-band Antenna design | Classic car restoration

SKILLS

Programming:

Python | JavaScript (Meteor.js, Node.js, d3.js) | MATLAB | C | C++ CAD (NX 7.5, OpenSCAD) | Objective-C | System Verilog | Prolog | Racket | Java