```
1 pthread_t thread[MAXTHREADS];
2 struct thread_data data[MAXTHREADS];
3 void pthread_reduce(void) {
      for (i = 1; k \le nrows - 1; ++k) {
5
         for (i = k + 1; i \le nrows; ++i) {
6
            data[i] = /* Setup worker. */;
            pthread_create(&thread[i], NULL, worker,
7
8
               &data[i]);
9
10
11
         /* Bug! Should be i \le nrows */
12
         for (i = k + 1; i < nrows; ++i)
13
            pthread_join(thread[i], NULL);
14
15 }
```

Figure 1—pthread gaussian elimination.

```
1 /* Forks a deterministic child. Returns 0 into the
2 * child and 1 into the parent. */
3 int dfork(pid_t childid);
4 /* Merges a child's changes into the parent after
5 * the child issues a dret(). */
6 void djoin(pid_t childid);
8 void det_reduce(void) {
9
     for (i = 1; k \le nrows - 1; ++k) {
        for (i = k + 1; i \le nrows; ++i)
10
            data[i] = /* Setup worker. */;
11
12
            if (!dfork(i)) { worker(&data[i]); dret(); }
13
14
15
        /* Bug! Should be i \le nrows */
        for (i = k + 1; i < nrows; ++i)
16
17
            djoin(i);
18
19 }
```

Figure 2—Deterministic Gaussian elimination.

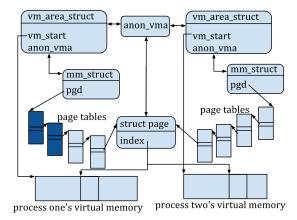


Figure 3—Data structure relationships associated with object-based reverse mapping. The struct page C type encapsulates information about every page frame of physical memory. Two processes map virtual memory to the same page readonly (possibly at different addresses). In order for the kernel to swap a given page to disk, object-based reverse mapping assumes each process maps the page to vm_area_struct->vm_start + page->index in virtual memory.

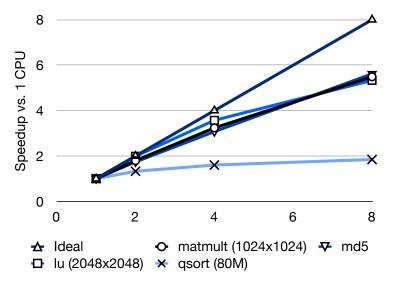


Figure 4—Deterministic speedup for the parallel benchmarks.

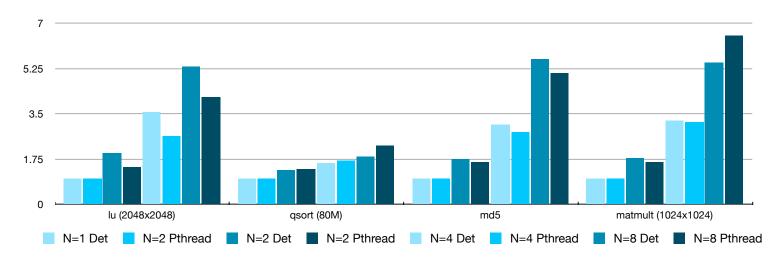


Figure 5—Comparing the speedup over N=1 for the deterministic and pthread versions of the benchmarks. This figure demonstrates the ability of both versions to scale as we add more CPU cores.

	lu				matmult			
Dimension	N = 1	N = 2	N = 4	N = 8	N=1	N = 2	N = 4	N=8
16×16	13.1 (41.5%)	45.0 (46.7%)	46.3 (45.8%)	30.9 (31.5%)	9.6 (48.2%)	21.8 (45.0%)	37.8 (45.2%)	16.0 (26.5%)
32×32	8.5 (34.0%)	37.3 (45.5%)	45.9 (46.1%)	29.1 (31.1%)	3.3 (37.7%)	13.4 (42.0%)	21.1 (42.2%)	17.5 (24.1%)
64×64	2.6 (19.5%)	20.6 (41.6%)	42.1 (44.2%)	32.1 (30.9%)	1.3 (13.4%)	3.8 (26.3%)	7.8 (34.0%)	13.2 (25.8%)
128×128	1.4 (2.3%)	6.0 (32.8%)	22.4 (39.0%)	30.8 (31.0%)	1.0 (0.3%)	1.9 (1.7%)	4.5 (13.3%)	6.7 (18.2%)
256×256	1.1 (0.5%)	2.1 (11.0%)	7.0 (25.9%)	18.8 (31.1%)	1.0 (0.0%)	1.2 (1.0%)	1.8 (1.6%)	2.3 (5.0%)
512×512	1.0 (0.1%)	1.2 (1.4%)	2.3 (9.4%)	5.9 (19.4%)	1.0 (0.0%)	1.0 (0.5%)	1.1 (0.9%)	1.5 (3.0%)
1024×1024	1.4 (0.0%)	1.0 (0.3%)	1.2 (1.5%)	1.9 (8.4%)	1.0 (0.0%)	0.9 (0.0%)	1.0 (0.1%)	1.2 (0.2%)
2048×2048	1.4 (0.0%)	1.0 (0.0%)	1.0 (0.1%)	1.1 (1.0%)	-	-	-	-

Table 1: Deterministic overhead for *lu* and *matmult*. Overhead is deterministic run time divided by pthread run time. The numbers in parentheses indicate time spent in the kernel performing a virtual memory merge as a percentage of overall runtime.