

## 源码

```
#include <iostream>
#include <cmath>
using namespace std;
class Point
{
public:
double x;
double y;
bool sign; //设置为这个点是否是交点
Point(double x,double y):x(x),y(y)
{sign = false;}
Point(){sign = false;}
void print()
{
    cout<<"交点为"<<endl;
    cout<<"("<<x<<','<<y<<")"<<endl;
}
};
class line
{
public:
double A;
double B;
double C;

line(double A,double B,double C)
{
    if(A==0&&B==0)
    {
        cout<<"false"<<endl;
    }
    else
    {
        this->A = A;
        this->B = B;
        this->C = C;
    }
}

//得到交点
void getPoint(line &line1,Point *p);
};
void line::getPoint(line &line1,Point *p)
{
```

```

//判断平行或者重合
if(A == 0&&line1.A == 0&&line1.B!=0&&B!=0)
{
    p ->sign = false;
    return;
}
if(B==0&&line1.B==0&&line1.A!=0&&A!=0)
{
    p ->sign = false;
    return;
}
if(B!=0)
{
    double A1 = line1.A;
    double B1 = line1.B;
    double C1 = line1.C;
    if(line1.B!=0)
    {
        //判断平行或者重合
        if(fabs(A/B-line1.A/line1.B)<1e-6)
        {
            p->sign = false;
            return;
        }
        p->sign = true;
        p->x = (B*C1/B1-C)/(A-A1*B/B1);
        p->y = -A1/B1*p->x-C1/B1;
        return ;
    }
    else
    {
        p->sign = true;
        p->x = -C1/A1;
        p->y = -A/B*p->x-C/B;
        return;
    }
}
if (line1.B!=0)
{
    p->sign = true;
    p->x = -C/A;
    p->y = line1.A*C/(line1.B*A) - line1.C/line1.B;
}
}

```

```

class circle
{
public:

```

```

double R; //半径
Point P0; //圆点
circle(Point &p,double r):P0(p),R(r) {}
void getPoint_Line_circle(line &l,Point *p1,Point *p2);
};

void circle::getPoint_Line_circle(line &l,Point *p1,Point *p2)
{
    double X0 = P0.x;
    double Y0 = P0.y;
    double A = l.A;
    double B = l.B;
    double C = l.C;
    double d = fabs(A*X0+B*Y0+C)/sqrt(A*A+B*B); //表示圆点到直线的距离
    if(d > R) //圆点到直线的距离大于R，没有交点
    {
        p1->sign = p2->sign = false;
        return ;
    }
    //当斜率不存在时，单独求点
    p1->sign = true;
    p2->sign = true;
    if(l.B==0)
    {
        p1->x = p2->x = -l.C/l.A;
        p1->y = Y0+sqrt(R*R-(l.C/A+X0)*(l.C/A));
        p2->y = Y0-sqrt(R*R-(l.C/A+X0)*(l.C/A));
        return ;
    }

    //获得二次方程的a,b,c计算坐标
    double a = 1+(A/B)*(A/B);
    double b = 2*A*C/(B*B) - 2*X0 + 2*Y0*A/B;
    double c = X0*X0 + (C/B)*(C/B) - R*R+2*Y0*C/B;
    d = b*b-4*a*c;

    if(fabs(d) < 1e-6)
    {
        p2->x = p1->x = -b/(2*a);
        p2->y = p1->y = -A/B*p1->x - C/B;
    }
    else
    {
        p1->x = (-b+sqrt(d))/(2*a);
        p2->x = (-b-sqrt(d))/(2*a);
        p1->y = -A/B*p1->x - C/B;
        p2->y = -A/B*p2->x - C/B;p1->sign = p2->sign = true;
    }
}

```

```

class rectangle
{
    //默认左下和右上两点确定矩形
    Point p1;
    Point p2;
public:
    rectangle(double x1,double y1,double x2,double y2)
    {
        p1.x = x1;
        p1.y = y1;
        p2.x = x2;
        p2.y = y2;
    }
    rectangle(Point &p1,Point&p2)
    {
        this->p1.x = p1.x;
        this->p1.y = p1.y;
        this->p2.x = p2.x;
        this->p2.y = p2.y;
    }
    void getPoint_line_rectangle(line &l ,Point *p1,Point *p2);
    bool judgePointInRectangle(Point *p);
};

void rectangle::getPoint_line_rectangle( line &l,Point *p3,Point *p4)
{
    double A = l.A;
    double B = l.B;
    double C = l.C;
    if(l.B == 0)
    {
        //如果直线在矩形范围内
        double x = -C/A;
        if( x > p1.x && x < p2.x)
        {
            p3->sign = p4->sign = true;
            p3->x = p4->x = x;
            p3->y = p1.y;
            p4->y = p2.y;
            return;
        }
        else if(fabs(x-p1.x)<1e-6||fabs(x-p2.x)<1e-6)
        {
            cout<<"直线和矩形的边界重合"<<endl;
            p3->sign = p4->sign = false;
        }
    }
    {
        p3->sign = p4->sign = false;
    }
}

```

```

        return;
    }
}
else if(l.A == 0)
{
    double y = -C/B;
    if(y > p1.y && y < p2.y)
    {
        p3->sign = p4->sign = true;
        p3->y = p4->y = y;
        p3->x = p1.x;
        p4->y = p2.y;
        return;
    }
    else if(fabs(y-p1.y) < 1e-6 || fabs(y-p2.y) < 1e-6)
    {
        cout<<"直线和矩形边界重合"<<endl;
        p3->sign = p4->sign = false;
    }
    else
    {
        p3->sign = p4->sign = false;
        return;
    }
}
else
{
    //求出直线和组成矩形的四条直线的交点，判断交点是否在矩形范围内就可以得出矩形和直线的交点
    line l_x1(1,0,-p1.x);
    line l_x2(1,0,-p2.x);
    line l_y1(0,1,-p1.y);
    line l_y2(0,1,-p2.y);
    Point *P[4];
    int sign = 0; //判断是否已经有交点
    for (int i = 0; i < 4; ++i)
    {
        P[i] = new Point();
    }
    l.getPoint(l_x1,P[0]);
    l.getPoint(l_x2,P[1]);
    l.getPoint(l_y1,P[2]);
    l.getPoint(l_y2,P[3]);
    for(int i = 0; i < 4; ++i)
    {
        if(P[i]->sign && judgePointInRectangle(P[i]))
        {
            if(sign == 0)
            {

```

```

        p3->x = P[i]->x;
        p3->y = P[i]->y;
        p4->x = P[i]->x;
        p4->y = P[i]->y;
        sign = 1;
    }
    else if(sign==1)
    {
        p4->x = P[i]->x;
        p4->y = P[i]->y;
        sign++;
    }
}
delete P[i];
}
if(sign == 0)
{
    p3->sign = p4->sign = false;
}
else
{
    p3->sign = p4->sign = true;
}
}
}
bool rectangle::judgePointInRectangle(Point *p)
{
    bool aboutX1 = p->x>p1.x||fabs(p->x-p1.x) < 1e-6;
    bool aboutX2 = p->x<p2.x||fabs(p->x-p2.x) < 1e-6;
    bool aboutY1 = p->y>p1.y||fabs(p->y-p1.y) < 1e-6;
    bool aboutY2 = p->y<p2.y||fabs(p->y-p2.y) < 1e-6;
    if(aboutX1&&aboutX2&&aboutY1&&aboutY2)
    {
        return true;
    }
    else
    {
        return false;
    }
}

int main(int, char**) {

//测试
line l1(1,1,-1);
//line l2(1,-1,2);
Point *p = new Point();
cout<<"直线方程成为"<<endl;

```

```

cout<<"x+y-1=0"<<endl;
/*cout<<"圆的方程为"<<endl;
cout<<"(x-1)^2+(y-1)^2=1"<<endl;*/
Point p0(2,1);
Point p3(1,0);
Point *p1 = new Point();
Point *p2 = new Point();
//circle c(p0,1);
//c.getPoint_Line_circle(l1,p1,p2);
rectangle r(p3,p0);
r.getPoint_line_rectangle(l1,p1,p2);
cout << "矩形的左下坐标为(1,),右上坐标为(2,1)"<<endl;
if(p1->sign&& p2->sign)
{
    p1->print();
    p2->print();
}
else
{
    cout<<"没有交点或直线与边界重合有无数个交点"<<endl;
}

delete p;
delete p1,p2;
}

```

## 结果示例

### 直线

The first screenshot shows the output for the case where the lines intersect at a single point. The output is:

```

直线方程成为
y+1=0和 x-3=0
交点为
(3,-1)
[1] + Done
"/usr/bin/gdb" --interpreter=mi --tty=${DbgTerm} 0<"/tmp/Microsoft-MIEngine-In-53pqi3l1.no1" 1>"/t
mp/Microsoft-MIEngine-Out-gyywou5u.8x7"
ccp@ccp-Lenovo-XiaoXinAir-14I1L-2020: ~/zuoye$

```

The second screenshot shows the output for the case where the lines are parallel and do not intersect. The output is:

```

直线方程成为
x+y+1=0和 x-y+1=0
交点为
(-1,5,0,5)
[1] + Done
"/usr/bin/gdb" --interpreter=mi --tty=${DbgTerm} 0<"/tmp/Microsoft-MIEngine-In-0k08ud16.j2]" 1>"/t
mp/Microsoft-MIEngine-Out-gq6apkg6.1m7"
ccp@ccp-Lenovo-XiaoXinAir-14I1L-2020: ~/zuoye$

```

```
问题 输出 调试控制台 终端 2: cppdbg: zuoye + - - - x

直线方程成为
x+y+1=0和 x-y+1=0
交点为
(-1,0)
[1] + Done "/usr/bin/gdb" --interpreter=mi --tty=${DbgTerm} 0<"/tmp/Microsoft-MIEngine-ln-3trmv5mf.3i7" 1>"/t
mp/Microsoft-MIEngine-Out-1sqr6bek.9ws"
ccp@ccp-Lenovo-XiaoXinAir-1411L-2020: ~/zuoye$
```

圆

```
问题 输出 调试控制台 终端 2: cppdbg: zuoye + - - - x

直线方程成为
x-1=0
圆的方程为
x^2+y^2=1
交点为
(1,0)
交点为
(1,0)
[1] + Done "/usr/bin/gdb" --interpreter=mi --tty=${DbgTerm} 0<"/tmp/Microsoft-MIEngine-ln-68hi802h.2el" 1>"/t
mp/Microsoft-MIEngine-Out-1sqr6bek.9ws"

[Running] cd "/home/ccp/zuoye/" && g++ main.cpp -o main && "/home/ccp/zuoye/"main
直线方程成为
x+y+1=0
圆的方程为
(x-1)^2+(y-1)^2=1
没有交点或者与边界重合有无数个交点

[Done] exited with code=0 in 0.231 seconds
```

矩形

```
问题 输出 调试控制台 终端 2: cppdbg: zuoye + - - - x

直线方程成为
x+y-1=0
矩形的左下坐标为(0,0),右上坐标为(1,1)
交点为
(0,1)
交点为
(1,0)
[1] + Done "/usr/bin/gdb" --interpreter=mi --tty=${DbgTerm} 0<"/tmp/Microsoft-MIEngine-ln-ck89rvdb.pjf" 1>"/t
mp/Microsoft-MIEngine-Out-srqptm5h.wvl"
ccp@ccp-Lenovo-XiaoXinAir-1411L-2020: ~/zuoye$

[Running] cd "/home/ccp/zuoye/" && g++ main.cpp -o main && "/home/ccp/zuoye/"main
直线方程成为
x+y-1=0
矩形的左下坐标为(1,0),右上坐标为(2,1)
交点为
(1,0)
交点为
(1,0)

[Done] exited with code=0 in 0.241 seconds

[Running] cd "/home/ccp/zuoye/" && g++ main.cpp -o main && "/home/ccp/zuoye/"main
直线方程成为
x+y-1=0
矩形的左下坐标为(1,1),右上坐标为(2,2)
没有交点或者与边界重合有无数个交点

[Done] exited with code=0 in 0.245 seconds
```