A New Deep Learning Method for Solar Flare Prediction

Authors: Yash Chaudhary, Yasser Abduallah, Jason T. L. Wang **Institution:** New Jersey Institute of Technology **Date:** August 6, 2025

1. Overview

This package contains the code and data for a new deep learning framework for the prediction of solar flares. The model is designed to forecast the probability of a \geq M-class solar flare within a 24-hour window using time-series data from NASA's Solar Dynamics Observatory.

This package provides the full model architecture, the training and testing scripts, and the processed data necessary to replicate the model's state-of-the-art performance, which achieves a **True Skill Statistic (TSS) of 0.90.**

2. Environment Setup

The following cell imports all necessary libraries. Please ensure they are installed, for example, by using the included requirements.txt file (pip install -r requirements.txt).

```
In [2]: # --- Core Libraries ---
import torch
import torch.nn as nn
import torch.optim as optim
from torch.utils.data import DataLoader, TensorDataset
import numpy as np
import os
from tqdm.notebook import tqdm
from sklearn.metrics import confusion_matrix
print("Libraries imported successfully.")
```

Libraries imported successfully.

3. Model Architecture

The core of our predictor is a new deep learning model based on a transformer architecture. The model is defined in the class below.

Key Architectural Concepts:

- Patching: The input time-series (24 hours) is first divided into non-overlapping 'patches' (2 hours each). This allows the model to learn local patterns within each short time window.
- Embedding: Each patch is linearly projected into a higher-dimensional space, creating a rich representation for the transformer to process.
- Transformer Encoder: A standard Transformer Encoder then learns the long-range dependencies and relationships between these patches.
- Classification Head: Finally, the information from all patches is aggregated to produce a single probability for the 24-hour forecast window.

```
In [3]: class Patching(nn.Module):
                                    def __init__(self, patch_length):
                                                 super().__init__()
                                                 self.patch_length = patch_length
                                    def forward(self, x):
                                                 num_patches = x.shape[1] // self.patch_length
                                                 return x.view(x.shape[0], num_patches, self.patch_length, x.shape[2])
                         class MTST(nn.Module):
                                      def __init__(self, num_features, time_steps, patch_length, d_model, num_heads, num_encoder_layers, dim_feedforward, dropout=0.1):
                                                super().__init__()
                                                 assert time_steps % patch_length == 0, "Time steps must be divisible by patch length"
                                                 self.patching = Patching(patch_length)
                                                 num_patches = time_steps // patch_length
                                                 # Correctly calculate input dimension for the linear projection
                                                 patch_input_dim = patch_length * num_features
                                                 self.linear_projection = nn.Linear(patch_input_dim, d_model)
                                                  self.positional_encoding = nn.Parameter(torch.zeros(1, num_patches, d_model))
                                                 encoder\_layer = nn. Transformer Encoder Layer ( \verb|d_model| = d_model|, nhead=num_heads, dim_feedforward=dim_feedforward, dropout=dropout, dropout=dropout=dropout, dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=dropout=drop
```

```
self.transformer_encoder = nn.TransformerEncoder(encoder_layer, num_layers=num_encoder_layers)

self.output_aggregation_pool = nn.AdaptiveAvgPool1d(1)
    self.classification_output_layer = nn.Linear(d_model, 1)

def forward(self, x):
    x = self.patching(x)
    B, N, P, F = x.shape
    x = x.reshape(B, N, P * F)
    x = self.linear_projection(x)
    x = x + self.positional_encoding
    x = self.transformer_encoder(x)
    x = x.permute(0, 2, 1)
    x = self.output_aggregation_pool(x).squeeze(-1)
    output_logits = self.classification_output_layer(x)
    return output_logits
```

MTST model architecture defined.

4. Model Training

This cell executes the full training pipeline. It will:

- 1. Load the training data from the data/processed/ directory.
- 2. Initialize the model, loss function, and optimizer.
- 3. Run the training loop for 50 epochs.
- 4. Save the final trained model weights to models/mtst_flare_model.pth.

```
In [4]: # --- Configuration ---
                  PROCESSED_DATA_DIR = 'data/processed'
                  MODELS_DIR = 'models'
                  MODEL_SAVE_PATH = os.path.join(MODELS_DIR, 'mtst_flare_model.pth')
                  os.makedirs(MODELS_DIR, exist_ok=True)
                  # --- Hyperparameters ---
                  NUM FEATURES = 16
                  BATCH_SIZE = 64
                  NUM EPOCHS = 50
                  LEARNING_RATE = 0.0001
                  WEIGHT_DECAY = 2e-5
                  # --- Data Loading ---
                  print("Loading training data...")
                  X_train = np.load(os.path.join(PROCESSED_DATA_DIR, 'X_train.npy'))
                  y_train = np.load(os.path.join(PROCESSED_DATA_DIR, 'y_train.npy'))
                  train\_dataset = TensorDataset(torch.tensor(X\_train, \ dtype=torch.float32), \ torch.tensor(y\_train, \ dtype=torch.float32).unsqueeze(1))
                  train_loader = DataLoader(train_dataset, batch_size=BATCH_SIZE, shuffle=True)
                  print("Data loaded.")
                  # --- Initialization ---
                  device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
                  \verb|model| = MTST(num\_features=16, time\_steps=24, patch\_length=2, d\_model=128, num\_heads=8, num\_encoder\_layers=3, dim\_feedforward=256, droping=128, num\_encoder\_layers=3, dim\_feedforward=128, droping=128, num\_encoder\_layers=3, dim\_feedforward=128, droping=128, num\_encoder\_layers=3, dim\_feedforward=128, droping=128, num\_encoder\_layers=3, dim\_feedforward=128, droping=128, droping=12
                  criterion = nn.BCEWithLogitsLoss()
                  optimizer = optim.Adam(model.parameters(), lr=LEARNING_RATE, weight_decay=WEIGHT_DECAY)
                  # --- Training Loop ---
                  print(f"\n--- Starting Model Training on {device} ---")
                  model.train()
                  for epoch in range(NUM_EPOCHS):
                           total loss = 0
                          for features, labels in tqdm(train_loader, desc=f"Epoch {epoch+1}/{NUM_EPOCHS}"):
                                  features, labels = features.to(device), labels.to(device)
                                   optimizer.zero_grad()
                                   outputs = model(features)
                                   loss = criterion(outputs, labels)
                                  loss.backward()
                                   optimizer.step()
                                   total_loss += loss.item()
                           print(f"Epoch [{epoch+1}/{NUM_EPOCHS}], Average Loss: {total_loss / len(train_loader):.4f}")
                  torch.save(model.state_dict(), MODEL_SAVE_PATH)
                  print(f"\\ \  \  \, Index \  \, aved \  \, to \, \, \{MODEL\_SAVE\_PATH\} \,\, ---")
```

```
--- Starting Model Training on cuda ---
Epoch 1/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [1/50], Average Loss: 0.0967
Epoch 2/50: 0% 0/1057 [00:00<?, ?it/s]
Epoch [2/50], Average Loss: 0.0784
Epoch 3/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [3/50], Average Loss: 0.0703
Epoch 4/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [4/50], Average Loss: 0.0615
Epoch 5/50: 0% 0/1057 [00:00<?, ?it/s]
Epoch [5/50], Average Loss: 0.0541
Epoch 6/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [6/50], Average Loss: 0.0471
Epoch 7/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [7/50], Average Loss: 0.0421
Epoch 8/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [8/50], Average Loss: 0.0369
Epoch 9/50: 0% 0/1057 [00:00<?, ?it/s]
Epoch [9/50], Average Loss: 0.0331
Epoch 10/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [10/50], Average Loss: 0.0299
Epoch 11/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [11/50], Average Loss: 0.0281
Epoch 12/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [12/50], Average Loss: 0.0253
Epoch 13/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [13/50], Average Loss: 0.0240
Epoch 14/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [14/50], Average Loss: 0.0238
Epoch 15/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [15/50], Average Loss: 0.0229
Epoch 16/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [16/50], Average Loss: 0.0224
Epoch 17/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [17/50], Average Loss: 0.0200
Epoch 18/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [18/50], Average Loss: 0.0199
Epoch 19/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [19/50], Average Loss: 0.0205
Epoch 20/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [20/50], Average Loss: 0.0193
Epoch 21/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [21/50], Average Loss: 0.0192
Epoch 22/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [22/50], Average Loss: 0.0182
Epoch 23/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [23/50], Average Loss: 0.0183
Epoch 24/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [24/50], Average Loss: 0.0171
Epoch 25/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [25/50], Average Loss: 0.0166
Epoch 26/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [26/50], Average Loss: 0.0163
Epoch 27/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [27/50], Average Loss: 0.0162
Epoch 28/50: 0% 0/1057 [00:00<?, ?it/s]
Epoch [28/50], Average Loss: 0.0154
Epoch 29/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [29/50], Average Loss: 0.0160
Epoch 30/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [30/50], Average Loss: 0.0154
Epoch 31/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [31/50], Average Loss: 0.0142
Epoch 32/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [32/50], Average Loss: 0.0149
Epoch 33/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [33/50], Average Loss: 0.0145
Epoch 34/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [34/50], Average Loss: 0.0143
Epoch 35/50: 0% 0/1057 [00:00<?, ?it/s]
Epoch [35/50], Average Loss: 0.0137
Epoch 36/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [36/50], Average Loss: 0.0140
Epoch 37/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [37/50], Average Loss: 0.0136
Epoch 38/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [38/50], Average Loss: 0.0126
Epoch 39/50: 0% | 0/1057 [00:00<?, ?it/s]
Epoch [39/50], Average Loss: 0.0128
Epoch 40/50: 0%
                     | 0/1057 [00:00<?, ?it/s]
```

```
Epoch [40/50], Average Loss: 0.0127
Epoch 41/50: 0%
                         | 0/1057 [00:00<?, ?it/s]
Epoch [41/50], Average Loss: 0.0135
Epoch 42/50: 0% 0/1057 [00:00<?, ?it/s]
Epoch [42/50], Average Loss: 0.0130
Epoch 43/50:
             0%
                         | 0/1057 [00:00<?, ?it/s]
Epoch [43/50], Average Loss: 0.0123
                         0/1057 [00:00<?, ?it/s]
Epoch 44/50:
             0%
Epoch [44/50], Average Loss: 0.0123
                        | 0/1057 [00:00<?, ?it/s]
Epoch 45/50: 0%
Epoch [45/50], Average Loss: 0.0120
                         0/1057 [00:00<?, ?it/s]
Epoch 46/50: 0%
Epoch [46/50], Average Loss: 0.0121
Epoch 47/50:
             0%
                         | 0/1057 [00:00<?, ?it/s]
Epoch [47/50], Average Loss: 0.0110
Epoch 48/50: 0%
                         | 0/1057 [00:00<?, ?it/s]
Epoch [48/50], Average Loss: 0.0118
Epoch 49/50: 0%
                   | 0/1057 [00:00<?, ?it/s]
Epoch [49/50], Average Loss: 0.0118
             0%
                         0/1057 [00:00<?, ?it/s]
Epoch 50/50:
Epoch [50/50], Average Loss: 0.0116
--- Training complete! Model saved to models/mtst_flare_model.pth ---
```

5. Model Evaluation

Finally, this cell loads the trained model from the previous step and evaluates its performance on the held-out test set. It calculates and prints the final Confusion Matrix and True Skill Statistic (TSS).

```
In [5]: # --- Data Loading ---
        print("Loading test data...")
        X_test = np.load(os.path.join(PROCESSED_DATA_DIR, 'X_test.npy'))
        y_test = np.load(os.path.join(PROCESSED_DATA_DIR, 'y_test.npy'))
        # --- Load Trained Model ---
        device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
        eval_model = MTST(num_features=16, time_steps=24, patch_length=2, d_model=128, num_heads=8, num_encoder_layers=3, dim_feedforward=256,
        eval_model.load_state_dict(torch.load(MODEL_SAVE_PATH, map_location=device))
        eval_model.to(device)
        eval_model.eval()
        print(f"Model loaded and ready for evaluation.")
        # --- Inference ---
        print("Generating predictions...")
        with torch.no_grad():
            logits = eval_model(torch.tensor(X_test, dtype=torch.float32).to(device))
            predictions = (torch.sigmoid(logits).squeeze().cpu().numpy() >= 0.5).astype(int)
        # --- Metrics ---
        tn, fp, fn, tp = confusion_matrix(y_test, predictions).ravel()
        sensitivity = tp / (tp + fn) if (tp + fn) > 0 else 0.0
        specificity = tn / (tn + fp) if (tn + fp) \rightarrow 0 else 0.0
        tss = sensitivity + specificity - 1
        print("\n--- Final Model Performance Metrics ---")
        print(f"Confusion Matrix (TN, FP, FN, TP): ({tn}, {fp}, {fn}, {tp})")
        print(f"True Skill Statistic (TSS): {tss:.4f}")
       Loading test data...
       Model loaded and ready for evaluation.
       Generating predictions...
       --- Final Model Performance Metrics ---
       Confusion Matrix (TN, FP, FN, TP): (16313, 56, 49, 493)
       True Skill Statistic (TSS): 0.9062
```

The model was trained and validated on a high-performance computing cluster. The primary metric for validation is the True Skill Statistic (TSS), as it is well-suited for the imbalanced classification task of flare prediction. The trained model achieves a TSS of 0.9062.

How to Replicate the Results

- 1. Install Dependencies: pip install -r requirements.txt
- 2. Train the model: python train.py (This will create models/mtst_flare_model.pth)
- 3. **Evaluate the model:** python test.py (This will load the saved model and print the final TSS score.)