

Chapter 23 Minimum Spanning Trees

Algorithm Analysis
School of CSEE

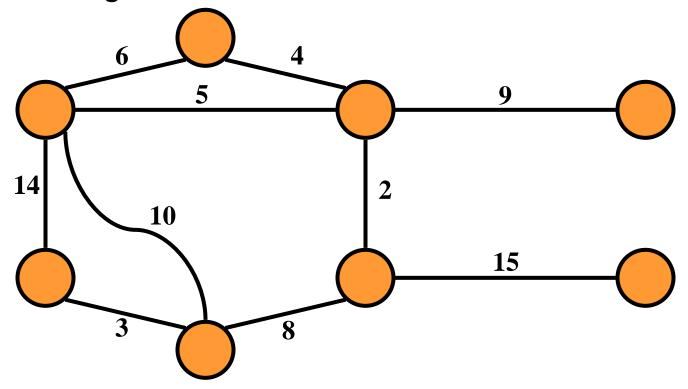




Minimum Spanning Tree



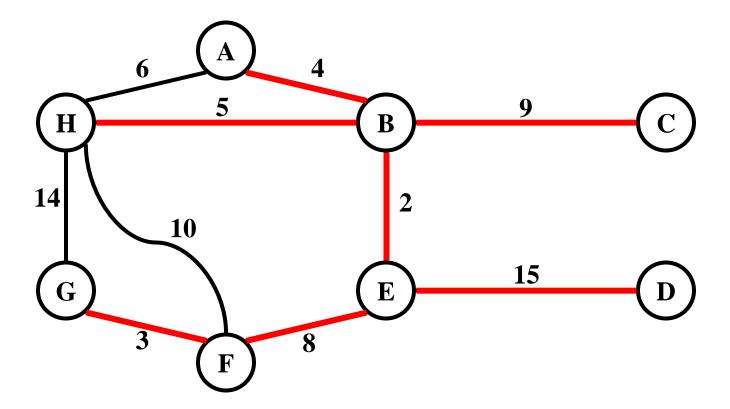
 Problem: given a connected, undirected, weighted graph, find a spanning tree using edges that minimize the total weight.





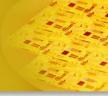
Minimum Spanning Tree

Which edges form the minimum spanning tree (MST) of the below graph?





Minimum spanning tree

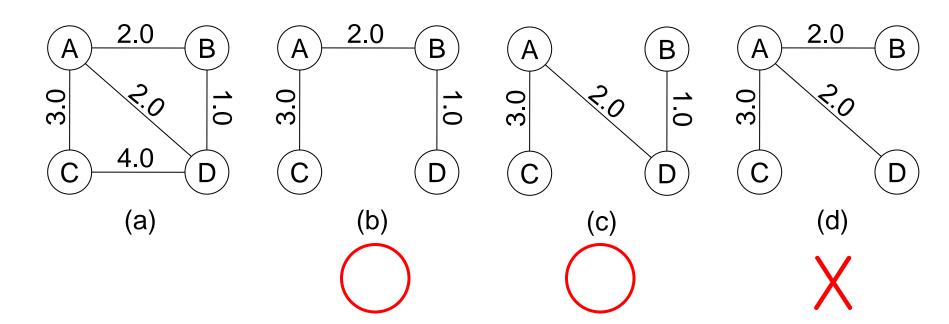


- Undirected graph G = (V, E)
- Weight w(u,v) on each edge $(u,v) \in E$
- Spanning tree of G' is a minimal subgraph of G such that
 - -V(G')=V(G) and G' is connected.
 - Any connected graph with n vertices must have at least *n*-1 edges. All connected graphs with *n*-1 edges are trees.
- Find *T* ⊂ *E* s.t.
 - T connects all vertices (T is a spanning tree), and
 - $w(T) = \sum_{(u,v) \in E} w(u,v)$ is minimized.



Minimum spanning tree

- A spanning tree whose weight is minimum over all spanning trees is called a minimum spanning tree or MST.
 - Has n -1 edges, no cycle, might not be unique



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Minimum spanning tree



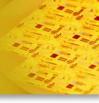
Example)

Interconnect *n* pins with *n*-1 wires, each connecting two pins so that we use the least amount of wire.

- We'll look at two greedy algorithms.
 - Kruskal's algorithm
 - Prim's algorithm



Building up the solution



- Build a set A of edges.
- Initially, A is empty.
- As we add edges to A, maintain a loop invariant : A is a subset of some MST.
- Add only edges that maintain the invariant.
 - If A is a subset of some MST, an edge (u,v) is safe for A if and only if A U { (u,v) } is also a subset of some MST.
 - So, we will add only safe edges.



Generic MST algorithm



GENERIC-MST(G, w)

$$A = \emptyset$$

while A is not a spanning tree

do find an edge (u,v) that is safe for A

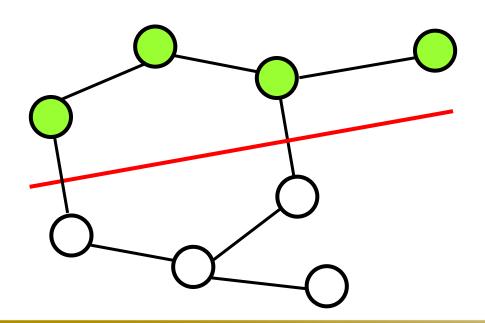
$$A = A \cup \{ (u,v) \}$$

return A



Finding a safe edge

- Let $S \subset V$ and $A \subseteq E$.
 - -A cut (S, V-S) is a partition of vertices into disjoint sets S and V - S.
 - Edge $(u,v) \in E$ crosses cut (S, V-S) if one endpoint is in S and the other is in V-S.





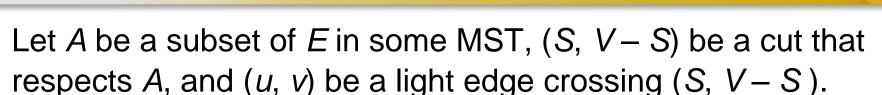
Finding a safe edge

- Let S ⊂ V and A ⊆ E.
 - A cut respects A if and only if no edge in A crosses the cut.
 - An edge is a *light edge* crossing a cut if and only if its weight is minimum over all edges crossing the cut. For a given cut, there can be more than one light edge crossing it.

A : set of blue edges



Theorem



Then, (u, v) is safe for A.

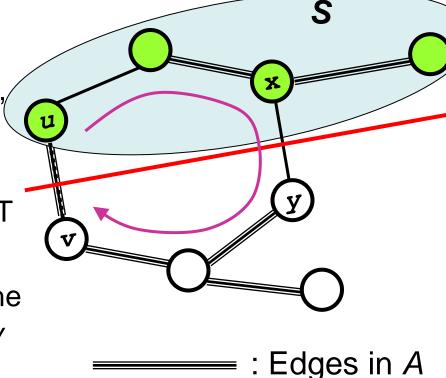
Proof)

1. Let *T* be a MST that includes *A*, and assume that *T* does not contain the light edge (*u*, *v*).

2. We shall construct another MST T' that includes $A \cup \{(u,v)\}$.

3. Edge (*u*, *v*) forms a cycle with the edges on the path *p* from *u* to *v* in *T*.

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Theorem

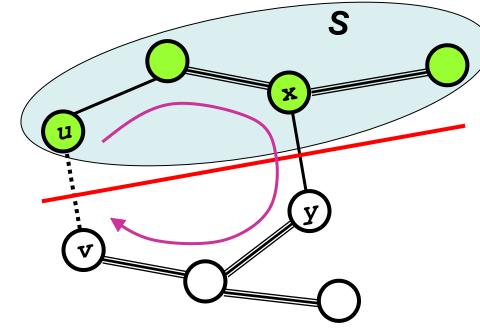


- 4. Since u and v are on opposite sides of the cut (S, V S) there is at least one edge in T on the path p that also crosses the cut. Let (x,y) be any such edge.
- Removing (x,y) breaks T into two components. And adding (u,v) reconnects them to form a new spanning tree T'.

$$w(T') = w(T) - w(x,y) + w(u,v)$$

$$\leq w(T)$$

Thus, T' must be a MST.



And since $A \cup \{(u,v)\} \subseteq T'$, (u,v) is safe for A.



Corollary



Let A be a subset of E that is included in some minimum spanning tree for G, and let $C = (V_c, E_c)$ be a connected component (tree) in the forest $G_A = (V, A)$. If (u, v) is a light edge connecting C to some other component in G_A , then (u,v) is safe for A.

Proof) The cut (Vc, V-Vc) respects A, and (u,v) is a light edge for this cut. Therefore, (u,v) is safe for A.



- Sort edges into nondecreasing order by w.
- The algorithm maintains A, a forest of trees.
- Repeatedly merges two components into one by choosing the light edge that connects them.

i.e.,

- 1. Choose the light edge crossing the cut between them.
- 2. (If it forms a cycle, the edge is discarded.)

- What is the design strategy of Kruskal's algorithm?
 - Greedy!!

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Specific pseudo-code



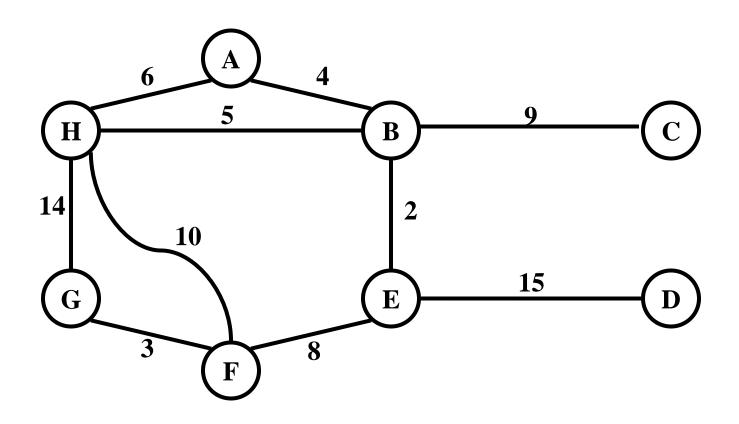
MST-Kruskal(G,w)

```
R = E;
F = 0;
While (R is not empty)
  Remove the light edge, (u,v), from R;
  if ((u,v) does not make a cycle in F)
      Add (u,v) to F;
return F;
```

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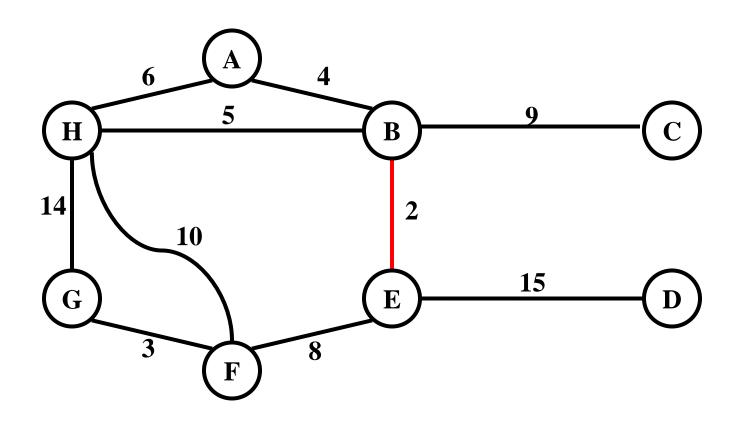




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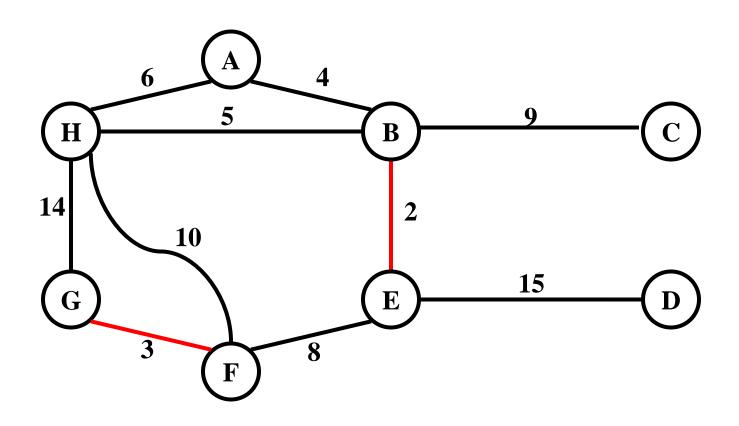




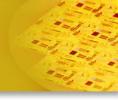


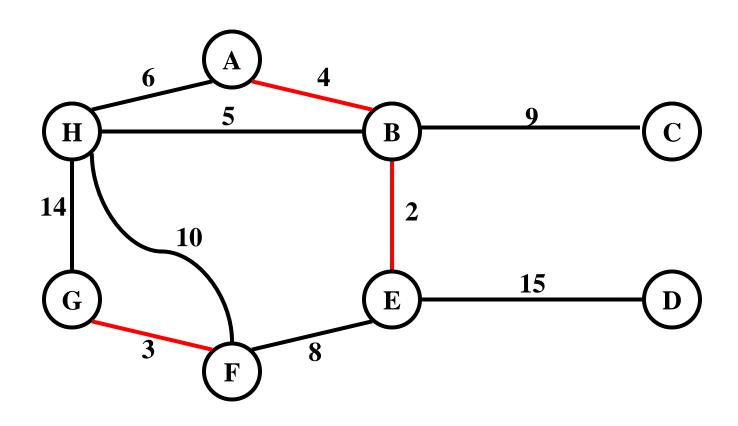






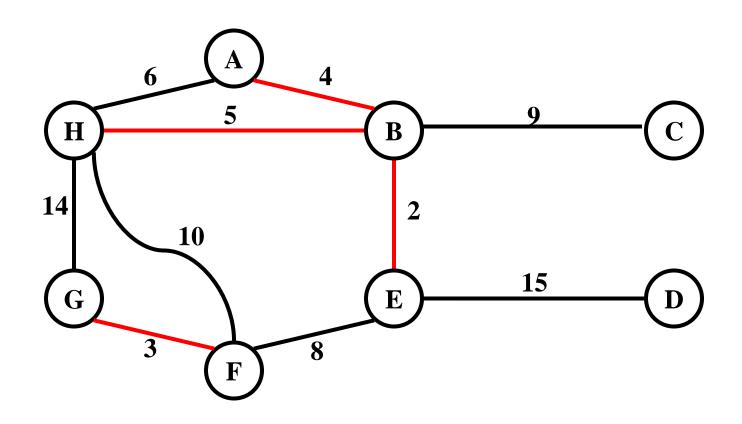






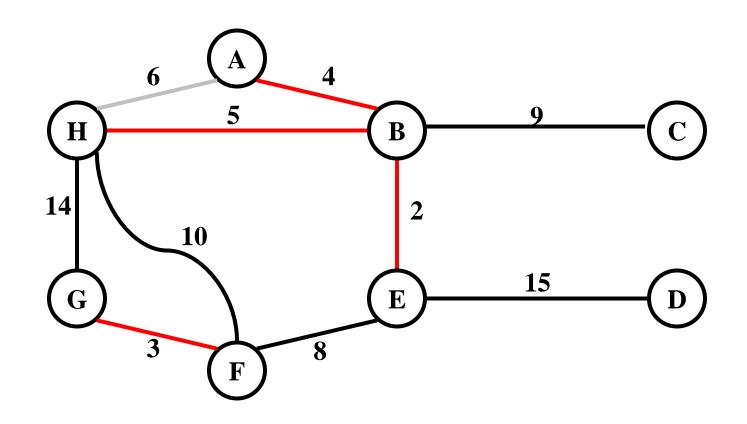








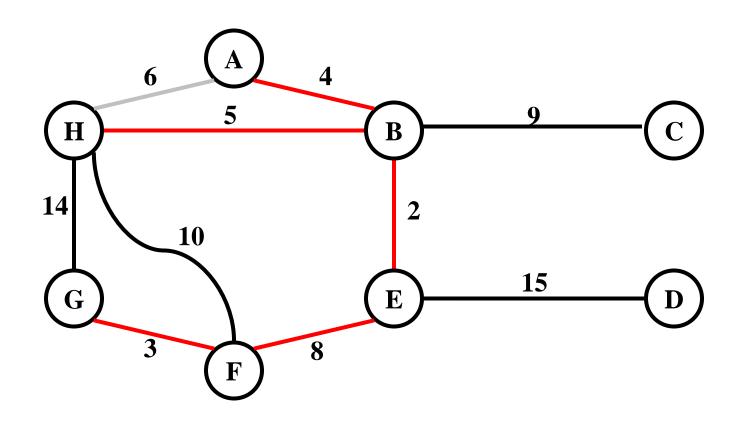




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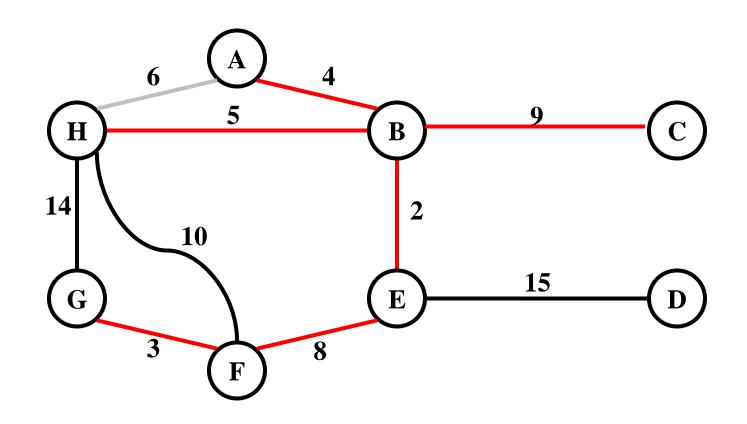








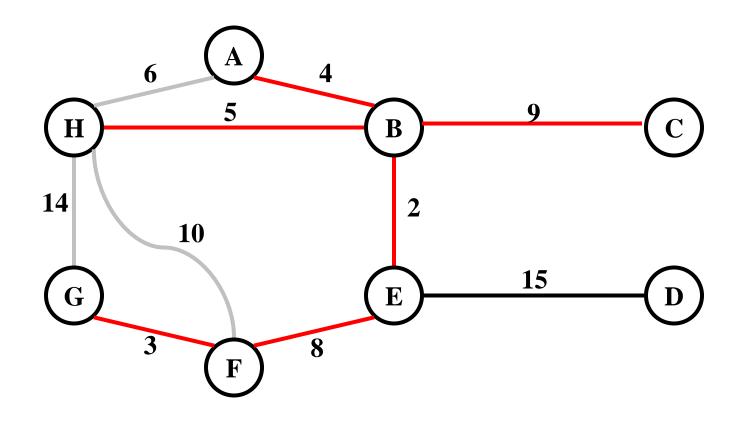




Algorithm Analysis Chapter 23 23

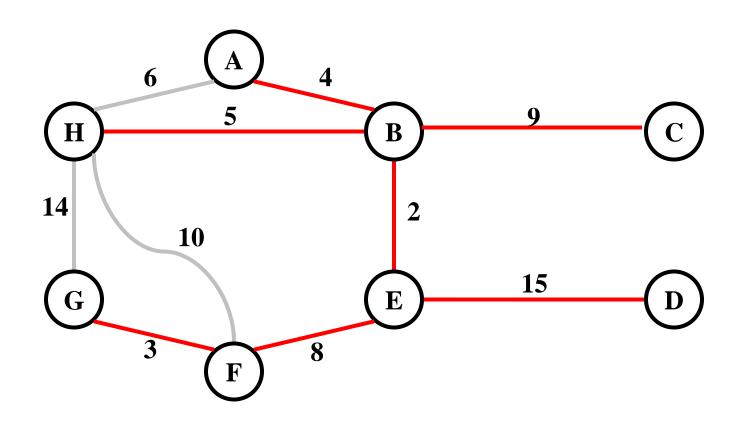
















- Builds one tree, so A is always a tree.
- Start from an arbitrary "root" r.
- At each step, find a light edge crossing cut (V_{\triangle} , V_{-} V_{A}), where V_{A} = vertices that A is incident on.
- $\pi[v]$ = parent of v, NIL if it has no parent or v = r.
- To find a light edge quickly
 - use a priority queue Q.



Prim's MST: Outline



PrimMST(G,n)

Initialize all vertices as unseen.

Select an arbitrary vertex r to start the tree; reclassify it as tree

Reclassify all vertices adjacent to r as fringe.

While there are fringe vertices;

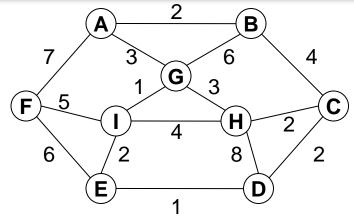
Select an edge of minimum weight between a tree vertex t and a fringe vertex *v*;

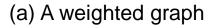
Reclassify v as *tree*; add edge (t, v) to the tree;

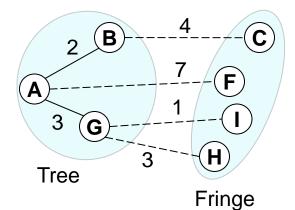
Reclassify all *unseen* vertices adjacent to *v* as *fringe*



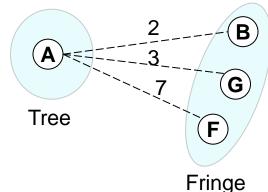
The Algorithm in action, e.g.



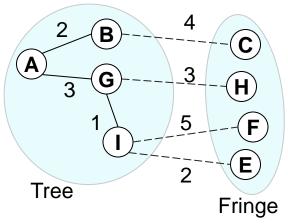




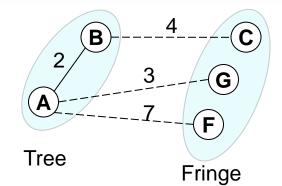
(d) After A G is selected and fringe and candidates are updated



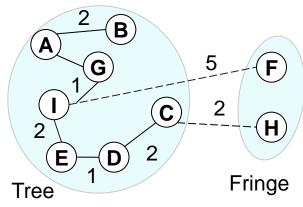
(b) After selection of the starting vertex



(e) I F has replaced A F as a candidate.



(c) *BG* was considered but did not replace *AG* as a candidate.



(f) After several more passes: The two candidate edges will be put in the tree





```
MST-Prim(G, w, r)
   Q = V[G];
   for each u \in Q
      key[u] = \infty; \pi[u] = NIL;
   key[r] = 0;
   \pi[r] = \text{NULL};
   while (Q not empty)
      u = ExtractMin(Q);
      for each v \in Adi[u]
         if (v \in Q \text{ and } w(u,v) < key[v])
           \pi[V] = U;
            key[v] = w(u,v);
```

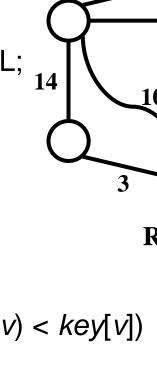


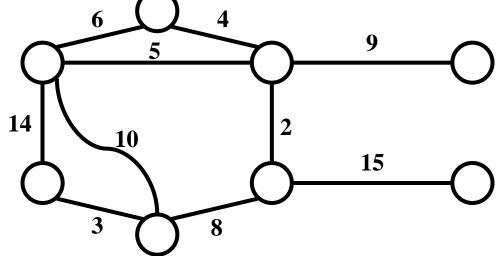


MST-Prim(G, w, r)

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 $\pi[r] = NULL;$
while $(Q \text{ not empty})$
 $u = \text{ExtractMin}(Q);$





Run on example graph

for each
$$v \in Adj[u]$$

if $(v \in Q \text{ and } w(u,v) < key[v])$
 $\pi[v] = u;$
 $key[v] = w(u,v);$





MST-Prim(G, w, r)

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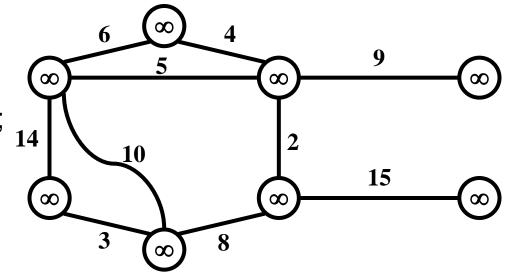
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Run on example graph



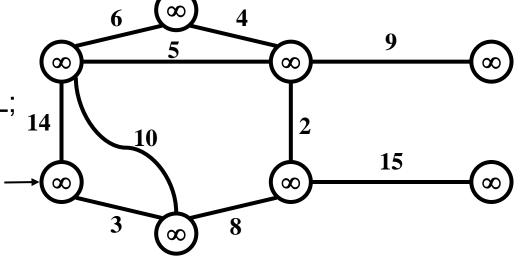


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if $(v \in Q \text{ and } w(u,v) < key[v])$
 $\pi[v] = u;$

key[v] = w(u,v);



Pick a start vertex r





MST-Prim(G, w, r)

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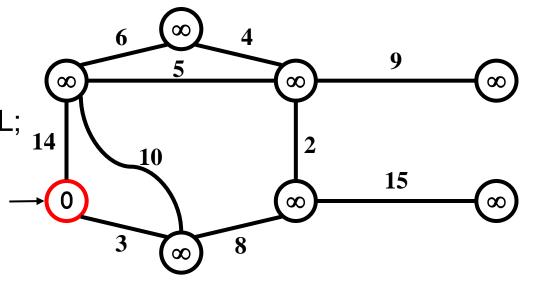
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Red vertices have been removed from Q





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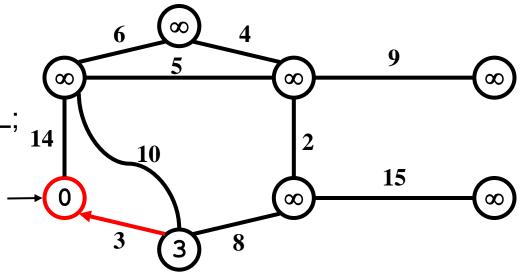
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$$\pi[V] = U;$$

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Red arrows indicate parent pointers



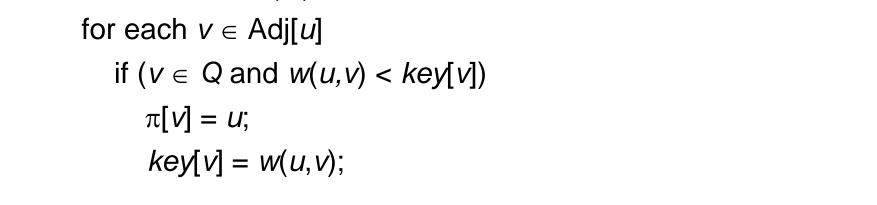


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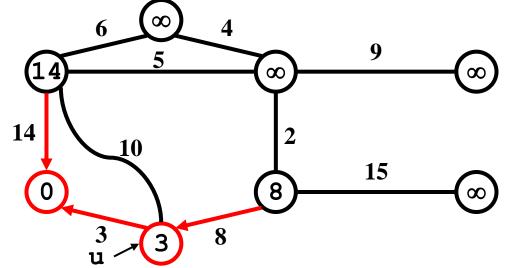
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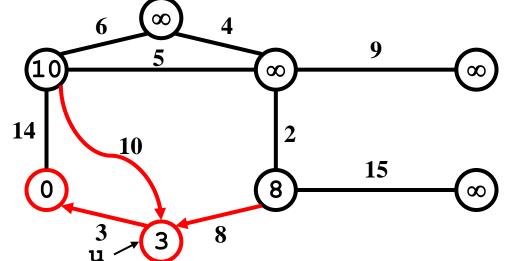


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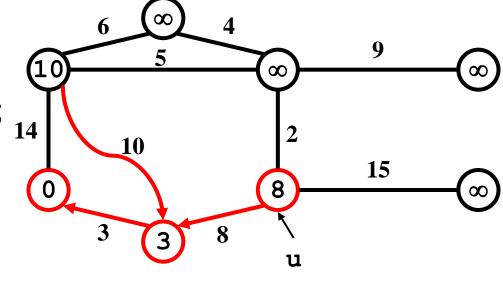
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for each $v \in Adj[u]$ if $(v \in Q \text{ and } w(u,v) < key[v])$ $\pi[v] = u;$ key[v] = w(u,v);



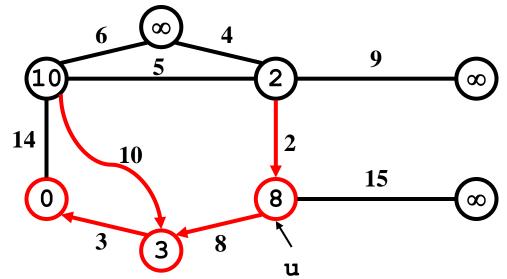


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MST-Prim(G, w, r)

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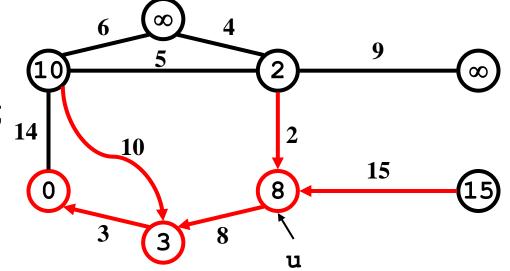
key[r] = 0;

\pi[r] = NULL;

while (Q \text{ not empty})

u = \text{ExtractMin}(Q);

for each v \in \text{Adj}[u]
```



if $(v \in Au][u]$ if $(v \in Q \text{ and } w(u,v) < key[v])$ $\pi[v] = u;$ key[v] = w(u,v);





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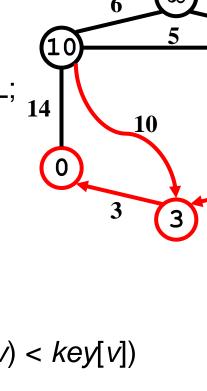
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for each $v \in Adj[u]$

 $\pi[V]=U;$



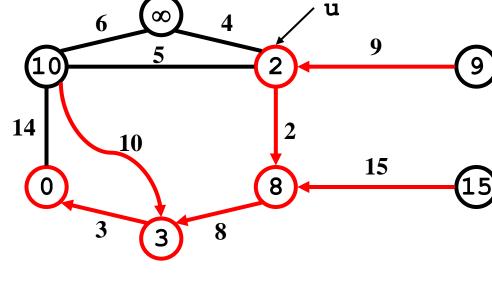




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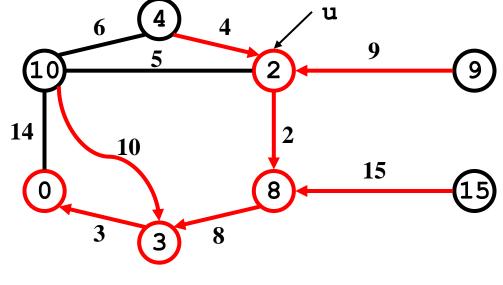
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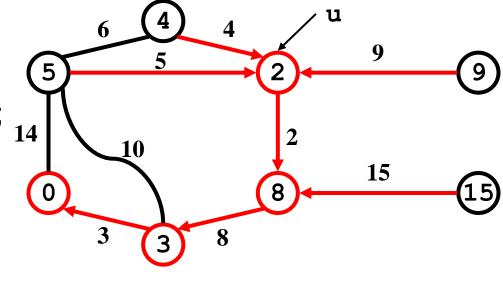




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u = ExtractMin(Q);



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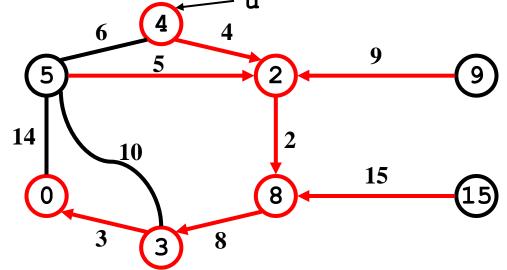
\pi[v] = u;

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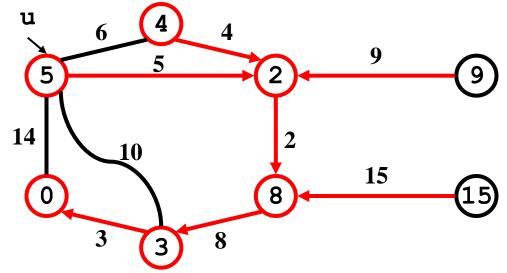


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```

 $\pi[V]=U;$

key[v] = w(u,v);



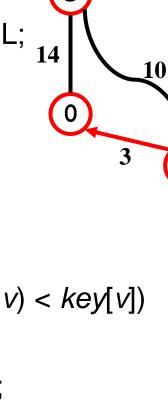




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while (Q not empty)
```

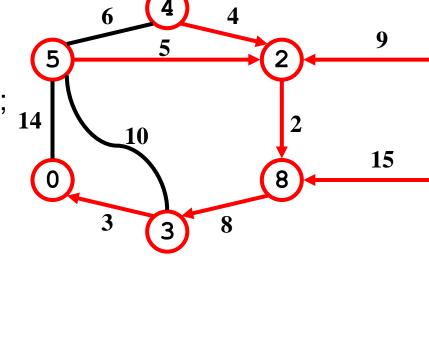






MST-Prim(G, w, r)

```
Q = V[G];
for each u \in Q
   key[u] = \infty; \pi[u] = NIL;
key[r] = 0;
\pi[r] = \text{NULL};
while (Q not empty)
   u = ExtractMin(Q);
```



for each $v \in Adj[u]$ if $(v \in Q \text{ and } w(u,v) < key[v])$ $\pi[V]=U;$ key[v] = w(u,v);