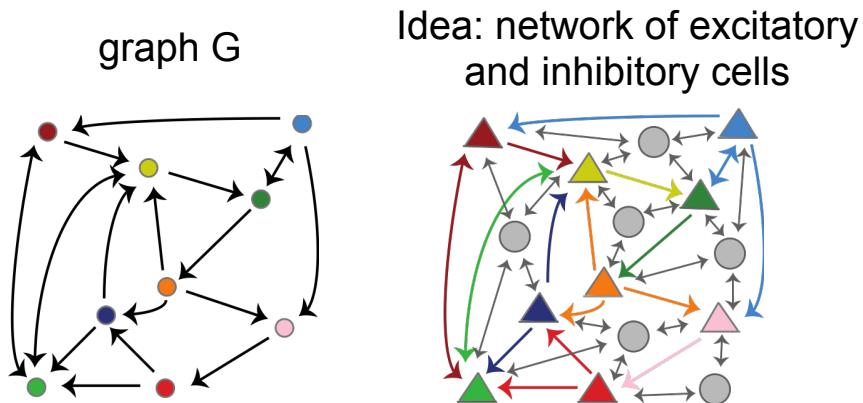


So far, everything we have done for CTLNs/gCTLNs has assumed negative (**inhibitory**) weights on the  $W$  matrix.

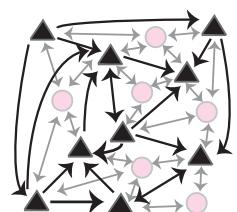


The **gCTLN** is defined by a **graph  $G$**  and two vectors of parameters:

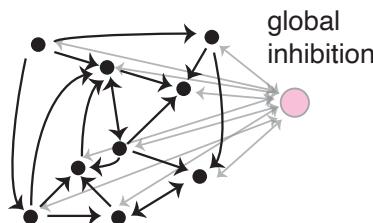
$$W_{ij} = \begin{cases} -1 + \varepsilon_j & \text{if } j \rightarrow i, \text{ weak inhibition} \\ -1 - \delta_j & \text{if } j \not\rightarrow i, \text{ strong inhibition} \\ 0 & \text{if } i = j. \end{cases}$$

# E-I TLNs from graphs

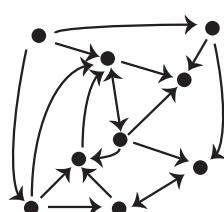
A excitatory neurons  
in a sea of inhibition



B E-I network



C graph G



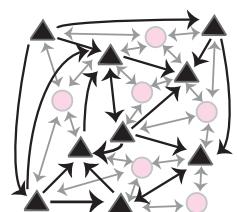
$$\frac{dx_i}{dt} = -x_i + \left[ \sum_{j=1}^n W_{ij} x_j + W_{iI} (x_I - W_{Ii} x_i) + b_i \right]_+, \quad i = 1, \dots, n,$$

$$\frac{dx_I}{dt} = \frac{1}{\tau_I} \left( -x_I + \left[ \sum_{j=1}^n W_{Ij} x_j + b_I \right]_+ \right).$$

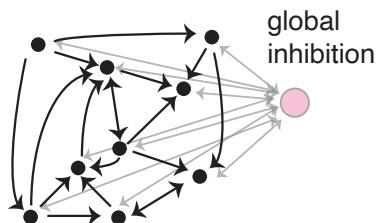
$$W_{ij} = \begin{cases} a_j & \text{if } j \rightarrow i \text{ in } G, \\ 0 & \text{if } j \not\rightarrow i \text{ in } G, \\ 0 & \text{if } i = j, \end{cases} \quad \text{and} \quad \begin{aligned} W_{Ij} &= c_j, \\ W_{iI} &= -1, \\ W_{II} &= 0. \end{aligned}$$

# E-I TLNs from graphs

A excitatory neurons in a sea of inhibition

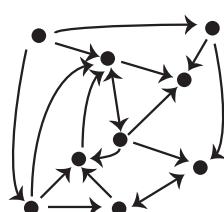


B E-I network

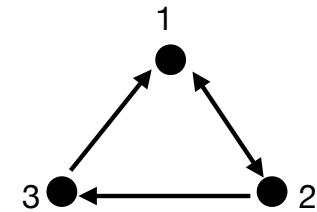


C

graph G



Example G:



$$\frac{dx_i}{dt} = -x_i + \left[ \sum_{j=1}^n W_{ij} x_j + W_{iI} (x_I - W_{II} x_i) + b_i \right]_+, \quad i = 1, \dots, n,$$

$$\frac{dx_I}{dt} = \frac{1}{\tau_I} \left( -x_I + \left[ \sum_{j=1}^n W_{Ij} x_j + b_I \right]_+ \right).$$

$$W_{ij} = \begin{cases} a_j & \text{if } j \rightarrow i \text{ in } G, \\ 0 & \text{if } j \not\rightarrow i \text{ in } G, \\ 0 & \text{if } i = j, \end{cases} \quad \text{and} \quad \begin{aligned} W_{Ij} &= c_j, \\ W_{iI} &= -1, \\ W_{II} &= 0. \end{aligned}$$

W for E-I TLN

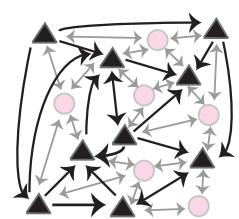
$$W = \begin{pmatrix} 0 & a_2 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

W for gCTLN

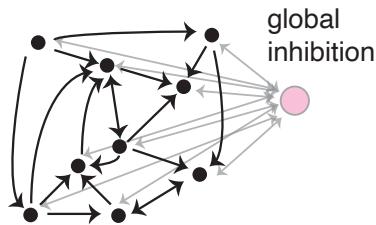
$$W = \begin{pmatrix} 0 & -1 + \varepsilon_2 & -1 + \varepsilon_3 \\ -1 + \varepsilon_1 & 0 & -1 - \delta_3 \\ -1 - \delta_1 & -1 + \varepsilon_2 & 0 \end{pmatrix}$$

There is a mapping from E-I TLNs to gCTLNs that preserves fixed points

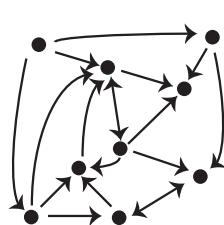
A excitatory neurons  
in a sea of inhibition



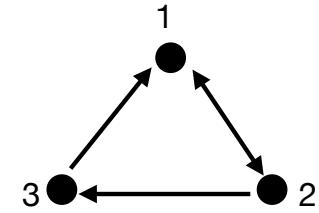
B E-I network



C graph G



Example G:



$$\frac{dx_i}{dt} = -x_i + \left[ \sum_{j=1}^n W_{ij}x_j + \boxed{W_{iI}(x_I - W_{Ii}x_i)} + b_i \right]_+, \quad i = 1, \dots, n,$$

$$\frac{dx_I}{dt} = \frac{1}{\tau_I} \left( -x_I + \left[ \sum_{j=1}^n W_{Ij}x_j + b_I \right]_+ \right).$$

Parameter mapping  
to get the same  
fixed points:

$$\begin{aligned} \varepsilon_j &= 1 + a_j - c_j, \\ \delta_j &= c_j - 1. \end{aligned}$$

W for E-I TLN

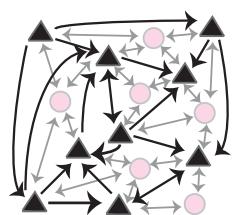
$$W = \begin{pmatrix} 0 & a_2 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

W for gCTLN

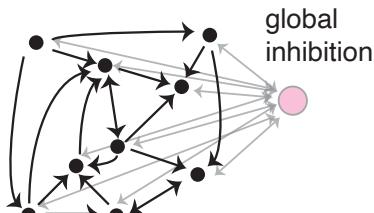
$$W = \begin{pmatrix} 0 & -1 + \varepsilon_2 & -1 + \varepsilon_3 \\ -1 + \varepsilon_1 & 0 & -1 - \delta_3 \\ -1 - \delta_1 & -1 + \varepsilon_2 & 0 \end{pmatrix}$$

There is a mapping from E-I TLNs to gCTLNs that preserves fixed points

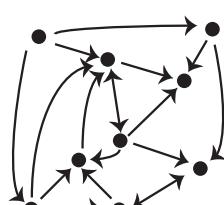
A excitatory neurons in a sea of inhibition



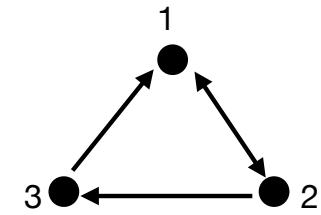
B E-I network



C graph G



Example G:



$$\frac{dx_i}{dt} = -x_i + \left[ \sum_{j=1}^n W_{ij}x_j + W_{iI}(x_I - W_{Ii}x_i) + b_i \right]_+, \quad i = 1, \dots, n,$$

$$\frac{dx_I}{dt} = \boxed{\frac{1}{\tau_I}} \left( -x_I + \left[ \sum_{j=1}^n W_{Ij}x_j + b_I \right]_+ \right).$$

Parameter mapping  
to get the same  
fixed points:

$$\begin{aligned} \varepsilon_j &= 1 + a_j - c_j, \\ \delta_j &= c_j - 1. \end{aligned}$$

The mapping says nothing about the timescale of inhibition!

W for E-I TLN

$$W = \begin{pmatrix} 0 & a_2 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

W for gCTLN

$$W = \begin{pmatrix} 0 & -1 + \varepsilon_2 & -1 + \varepsilon_3 \\ -1 + \varepsilon_1 & 0 & -1 - \delta_3 \\ -1 - \delta_1 & -1 + \varepsilon_2 & 0 \end{pmatrix}$$

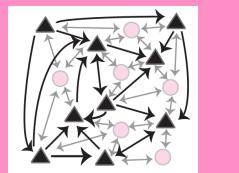
# TLNs, CTLNs, and gCTLNs ... and E-I TLNs from graphs

linear  
models

TLNs

all recurrent network models

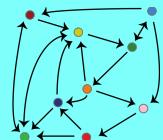
E-I TLNs  
from graphs



competitive TLNs

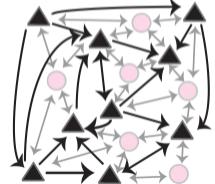
CTLNs

gCTLNs

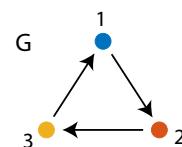


## Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

excitatory neurons  
in a sea of inhibition



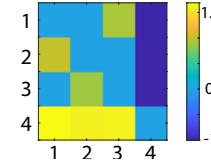
A



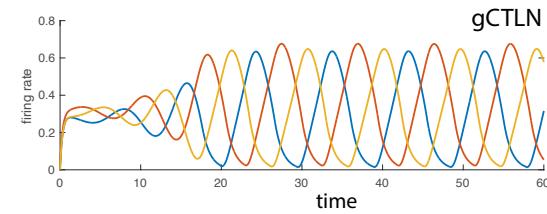
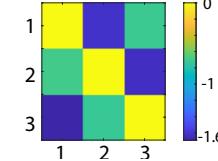
W for E-I TLN

$$W = \begin{pmatrix} 0 & 0 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

W for E-I TLN

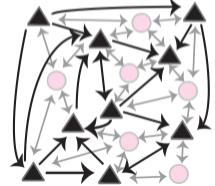


W for gCTLN

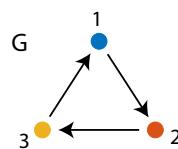


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excitatory neurons  
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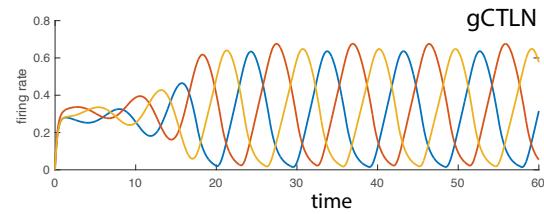
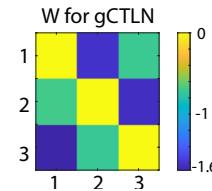
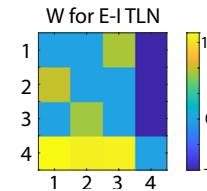
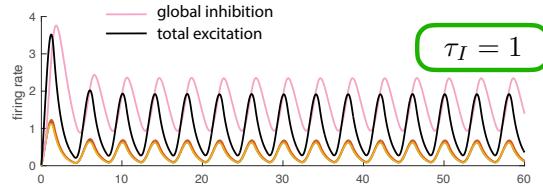
A



W for E-I TLN

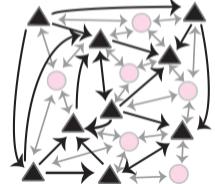
$$W = \begin{pmatrix} 0 & 0 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

B

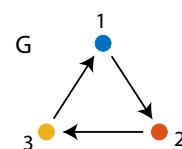


## Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

excitatory neurons  
in a sea of inhibition

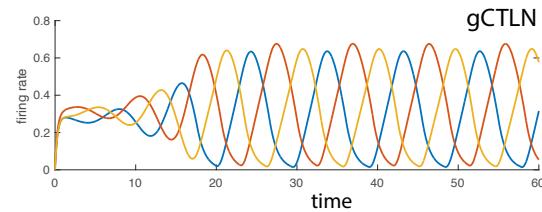
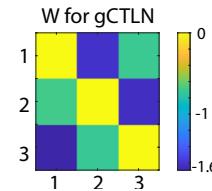
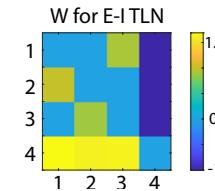
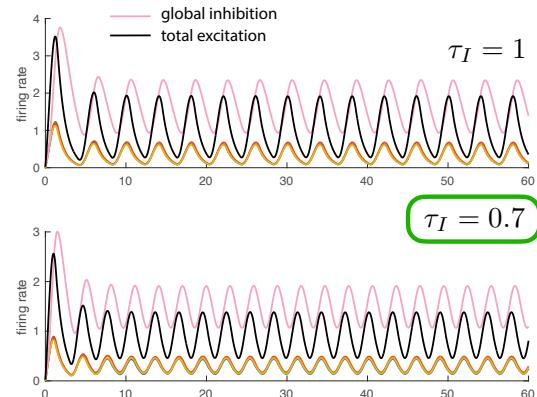


A



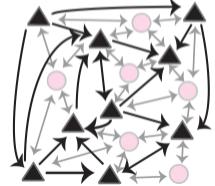
$$W \text{ for E-I TLN} = \begin{pmatrix} 0 & 0 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

B

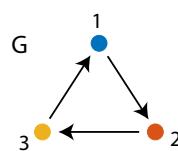


# Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

excitatory neurons  
in a sea of inhibition



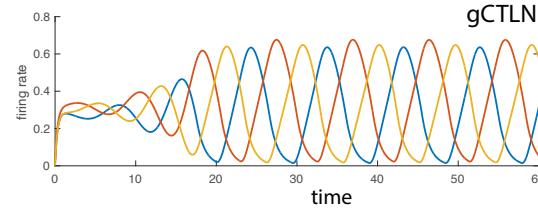
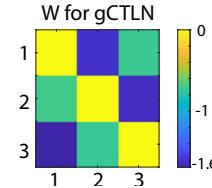
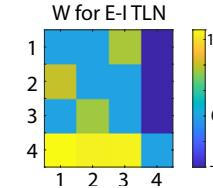
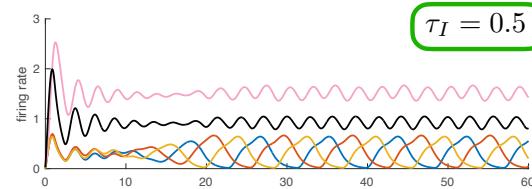
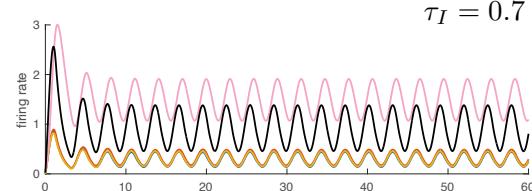
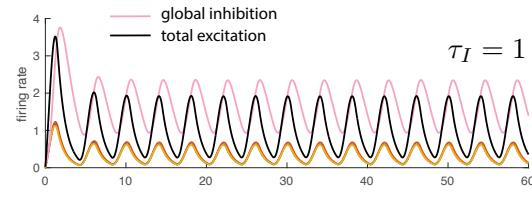
A



W for E-I TLN

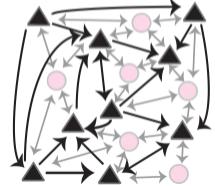
$$W = \begin{pmatrix} 0 & 0 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

B

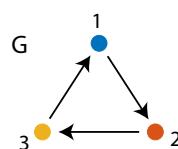


# Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

excitatory neurons  
in a sea of inhibition



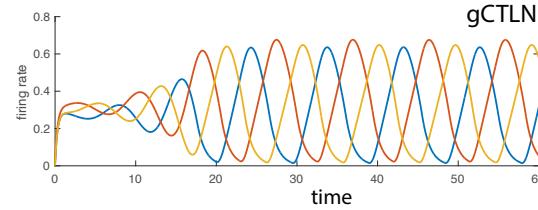
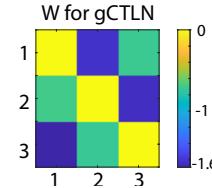
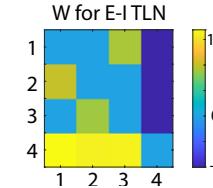
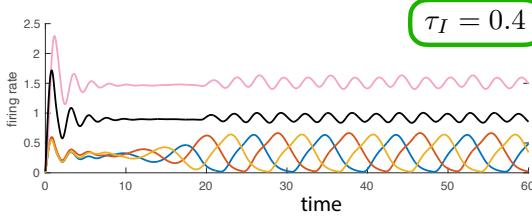
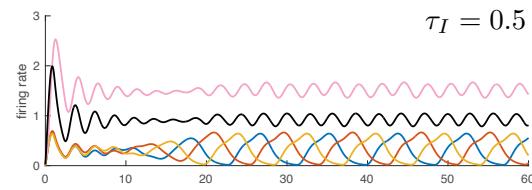
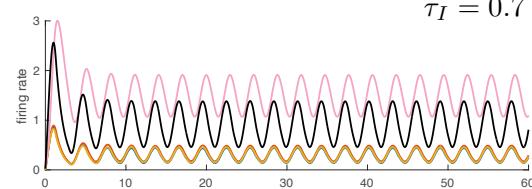
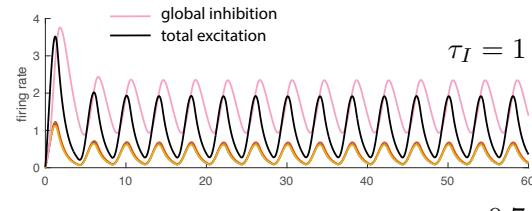
A



W for E-I TLN

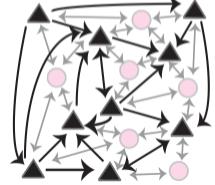
$$W = \begin{pmatrix} 0 & 0 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

B



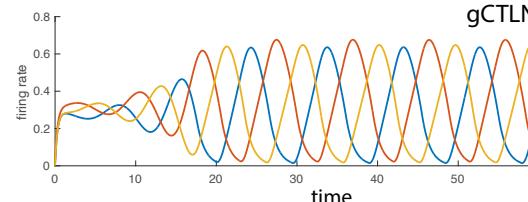
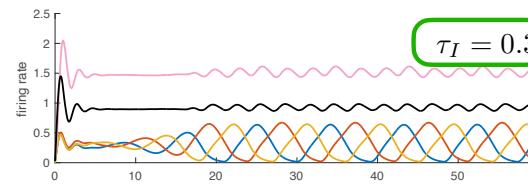
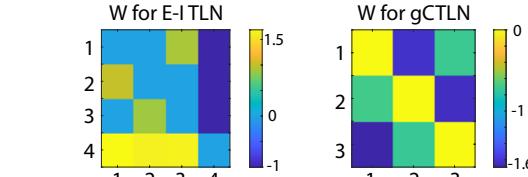
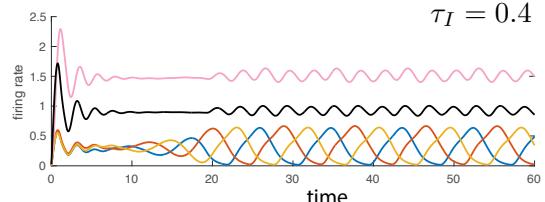
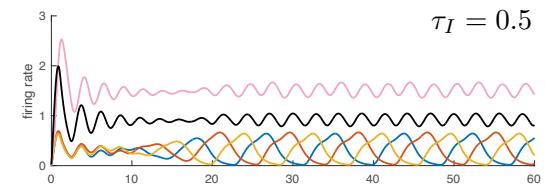
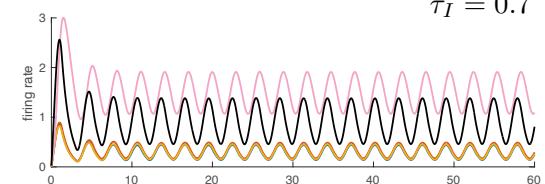
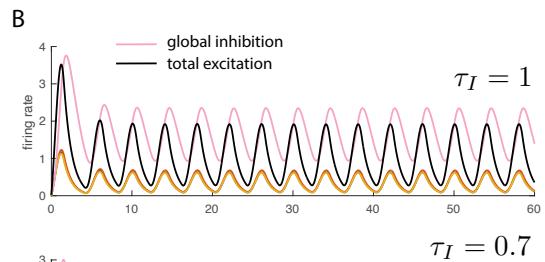
# Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

excitatory neurons  
in a sea of inhibition



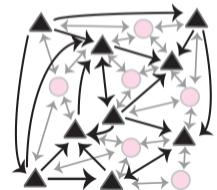
A

$$W = \begin{pmatrix} 0 & 0 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

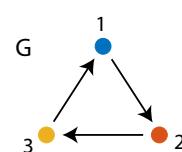


## Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

excitatory neurons  
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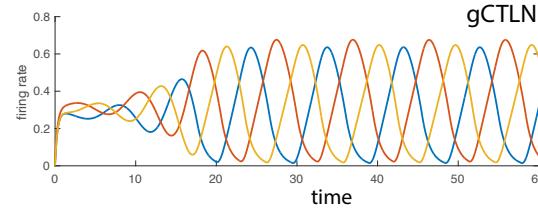
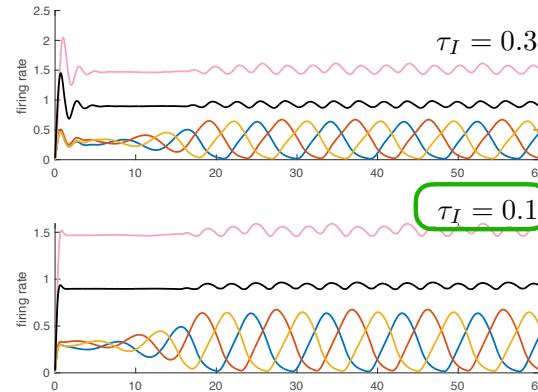
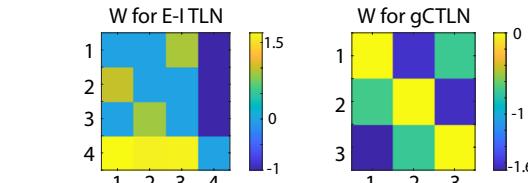
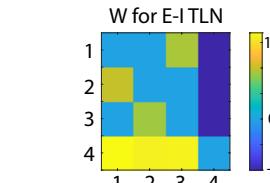
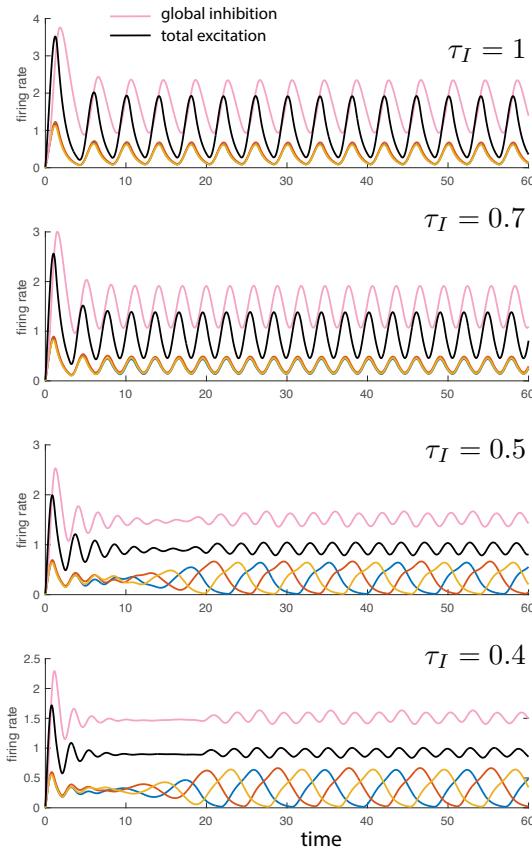
A



W for E-I TLN

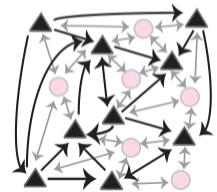
$$W = \begin{pmatrix} 0 & 0 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

B

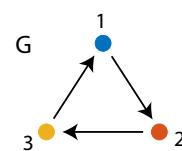


# Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

excitatory neurons  
in a sea of inhibition



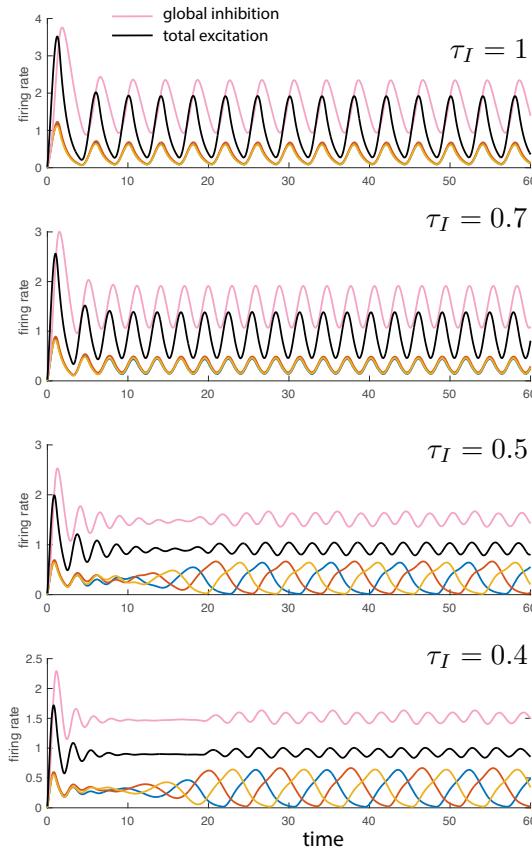
A



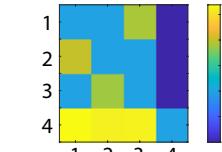
W for E-I TLN

$$W = \begin{pmatrix} 0 & 0 & a_3 & -1 \\ a_1 & 0 & 0 & -1 \\ 0 & a_2 & 0 & -1 \\ c_1 & c_2 & c_3 & 0 \end{pmatrix}$$

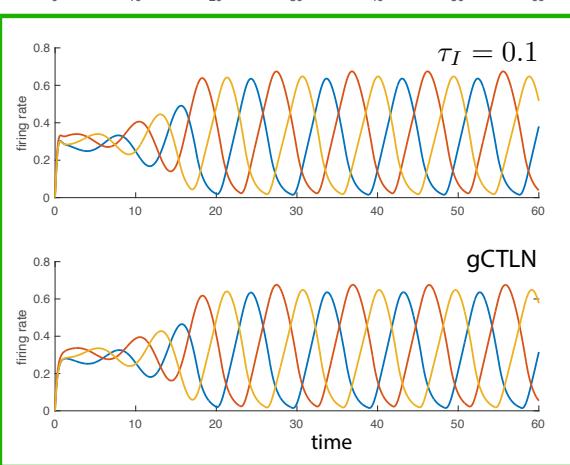
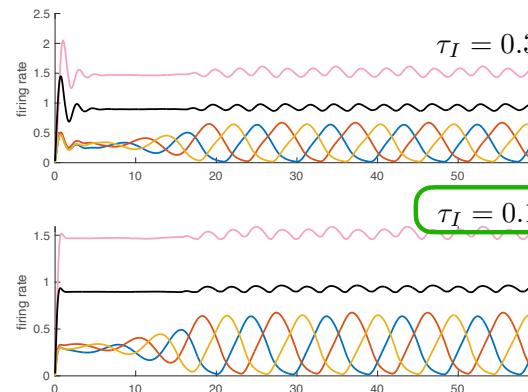
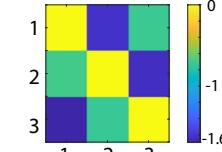
B



W for E-I TLN

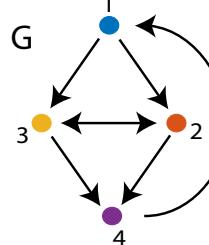


W for gCTLN



## Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

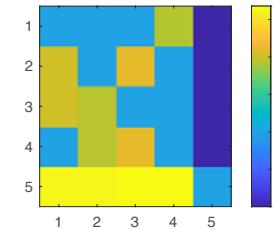
A



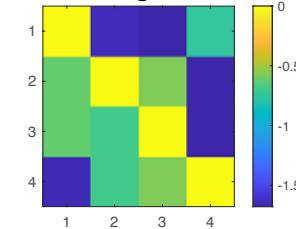
W for E-I TLN

$$W = \begin{pmatrix} 0 & 0 & 0 & a_4 & -1 \\ a_1 & 0 & a_3 & 0 & -1 \\ a_1 & a_2 & 0 & 0 & -1 \\ 0 & a_2 & a_3 & 0 & -1 \\ c_1 & c_2 & c_3 & c_4 & 0 \end{pmatrix}$$

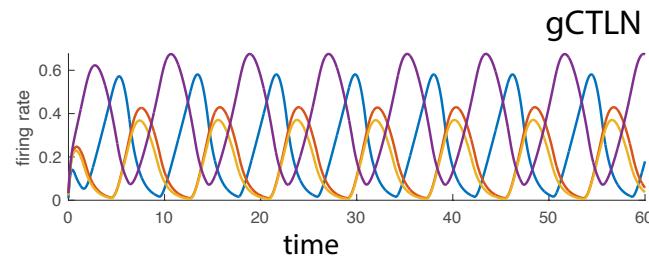
W for E-I TLN



W for gCTLN

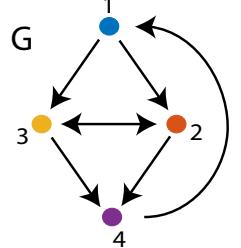


gCTLN



## Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

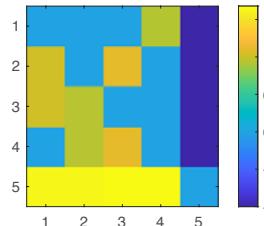
A



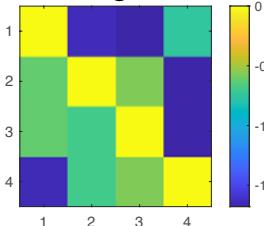
W for E-I TLN

$$W = \begin{pmatrix} 0 & 0 & 0 & a_4 & -1 \\ a_1 & 0 & a_3 & 0 & -1 \\ a_1 & a_2 & 0 & 0 & -1 \\ 0 & a_2 & a_3 & 0 & -1 \\ c_1 & c_2 & c_3 & c_4 & 0 \end{pmatrix}$$

W for E-I TLN



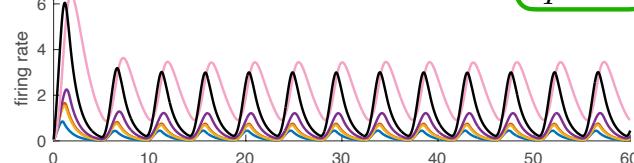
W for gCTLN



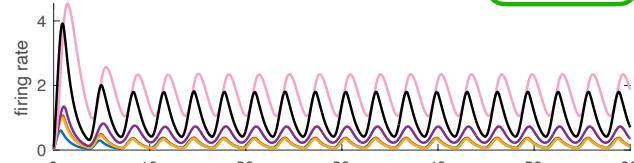
B

— global inhibition  
— total excitation

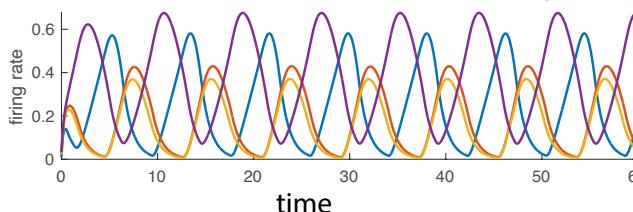
$\tau_I = 1$



$\tau_I = 0.7$

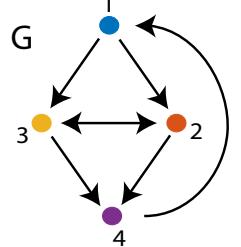


gCTLN



## Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?

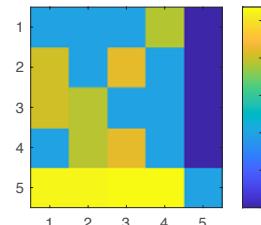
A



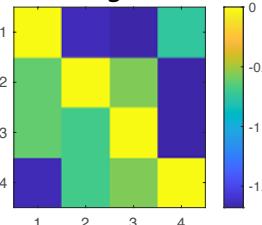
W for E-I TLN

$$W = \begin{pmatrix} 0 & 0 & 0 & a_4 & -1 \\ a_1 & 0 & a_3 & 0 & -1 \\ a_1 & a_2 & 0 & 0 & -1 \\ 0 & a_2 & a_3 & 0 & -1 \\ c_1 & c_2 & c_3 & c_4 & 0 \end{pmatrix}$$

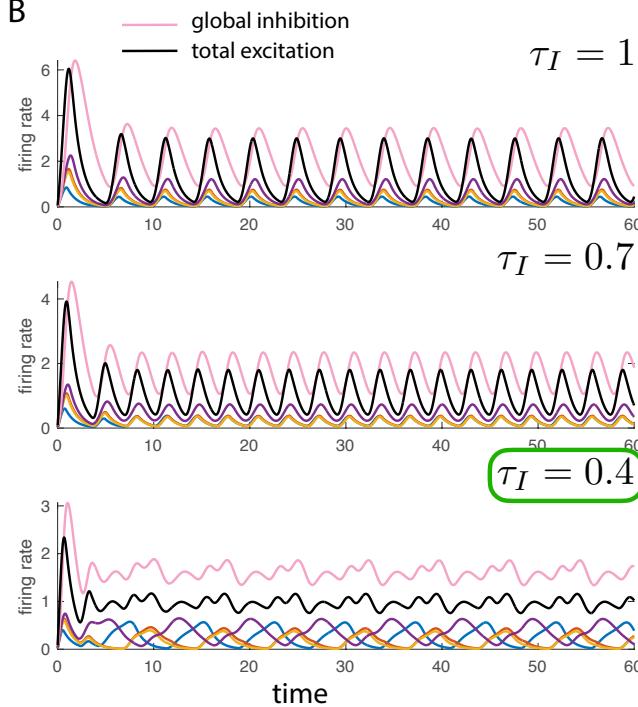
W for E-I TLN



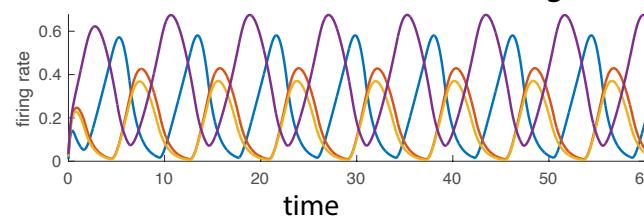
W for gCTLN



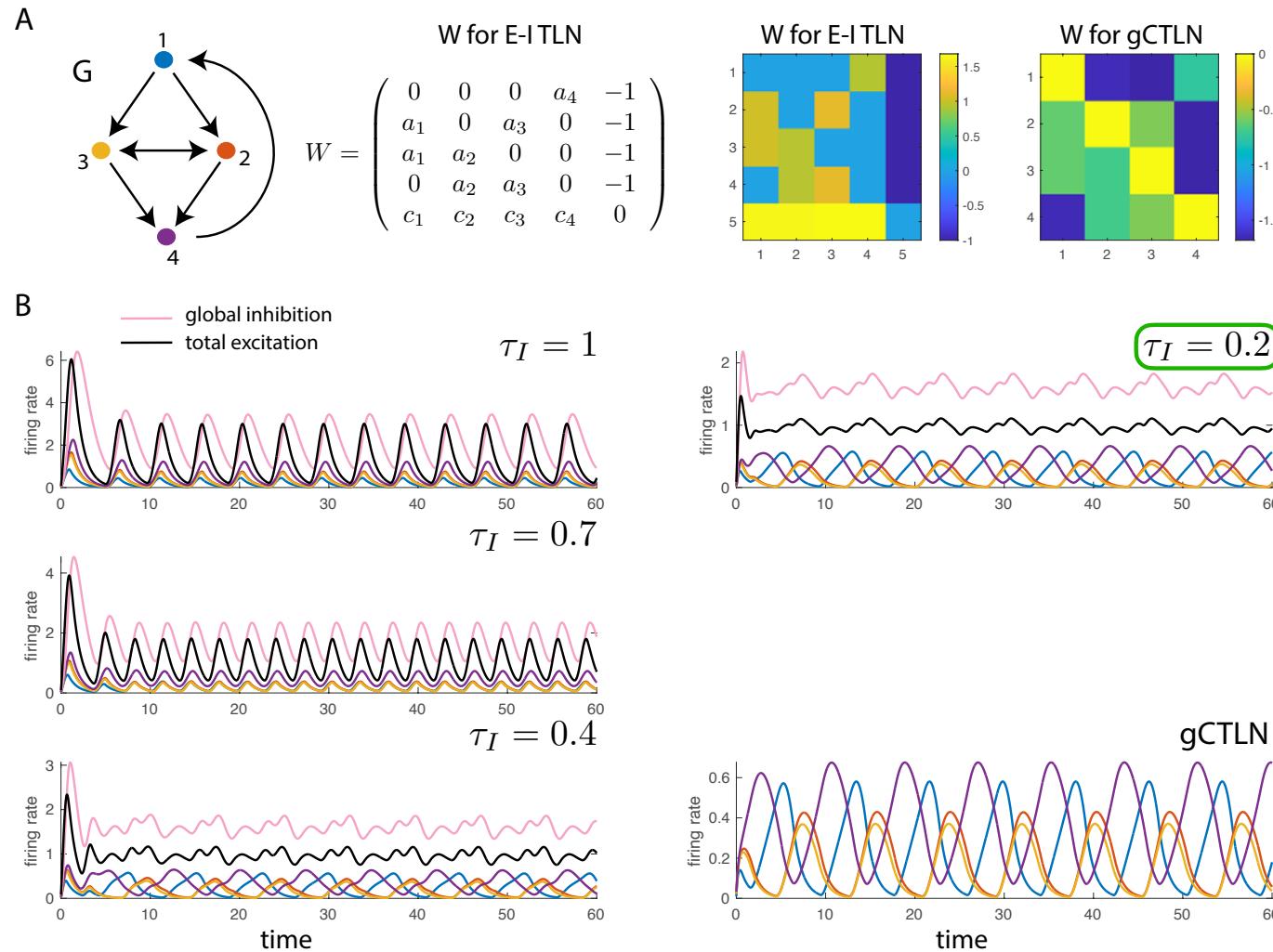
B



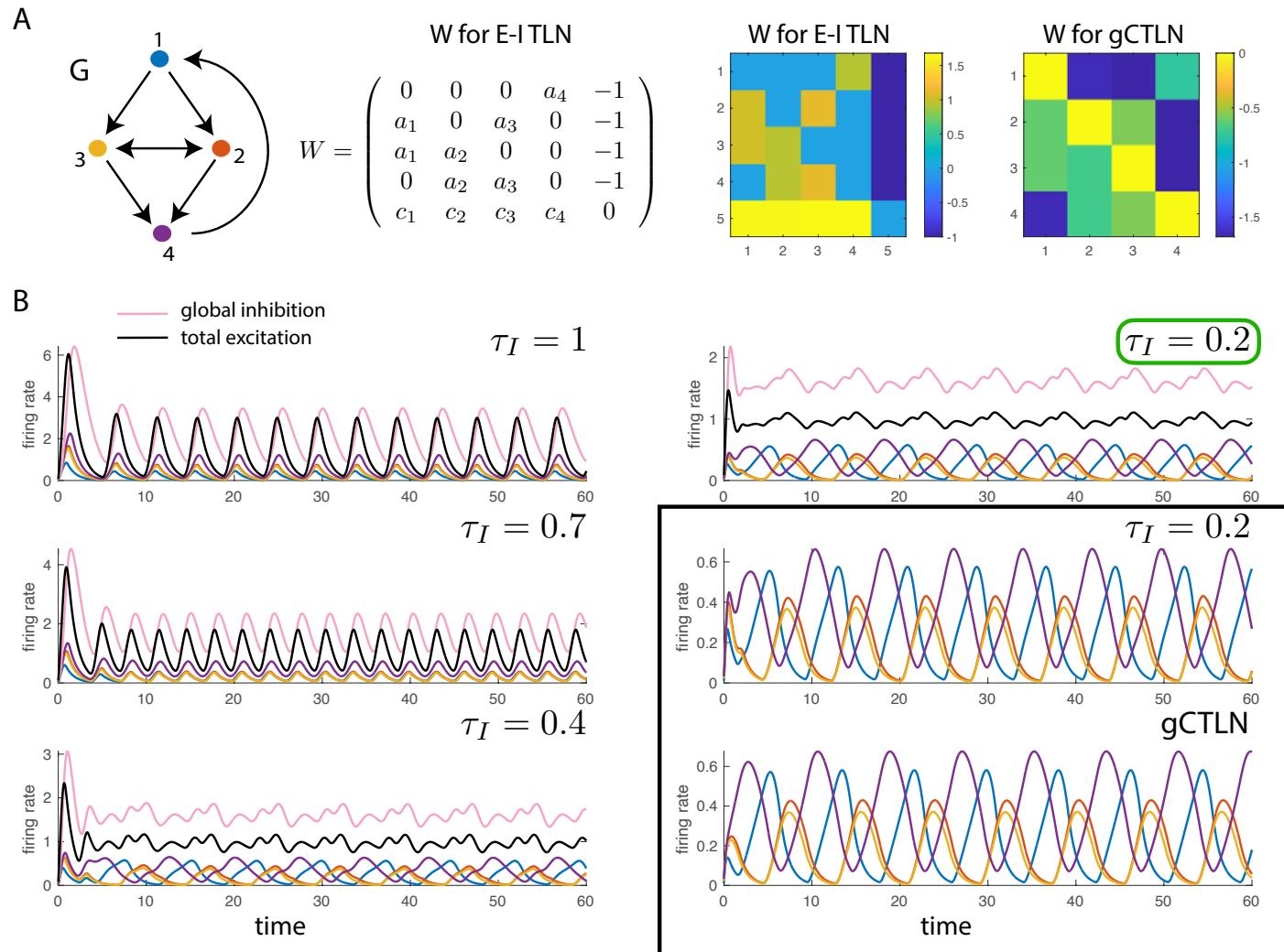
gCTLN



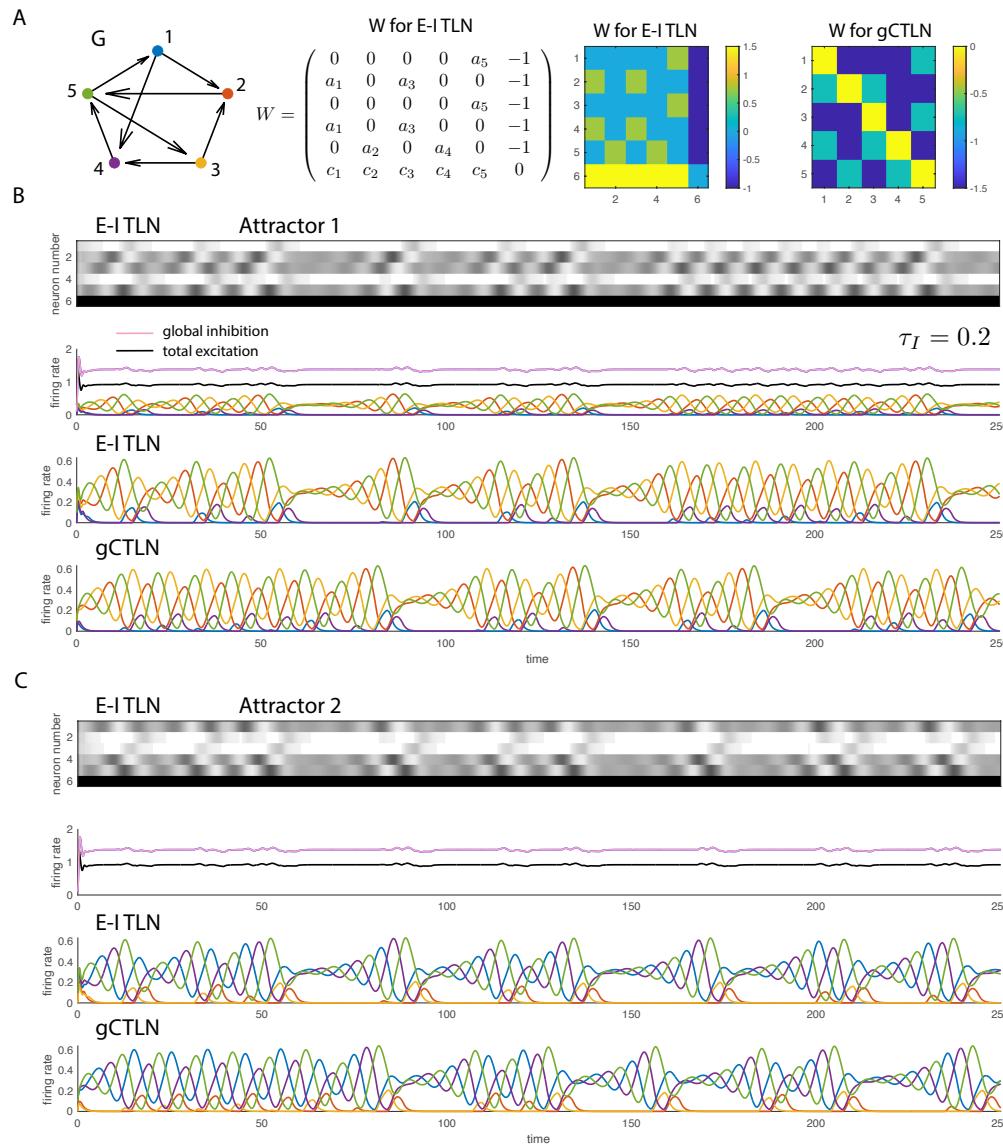
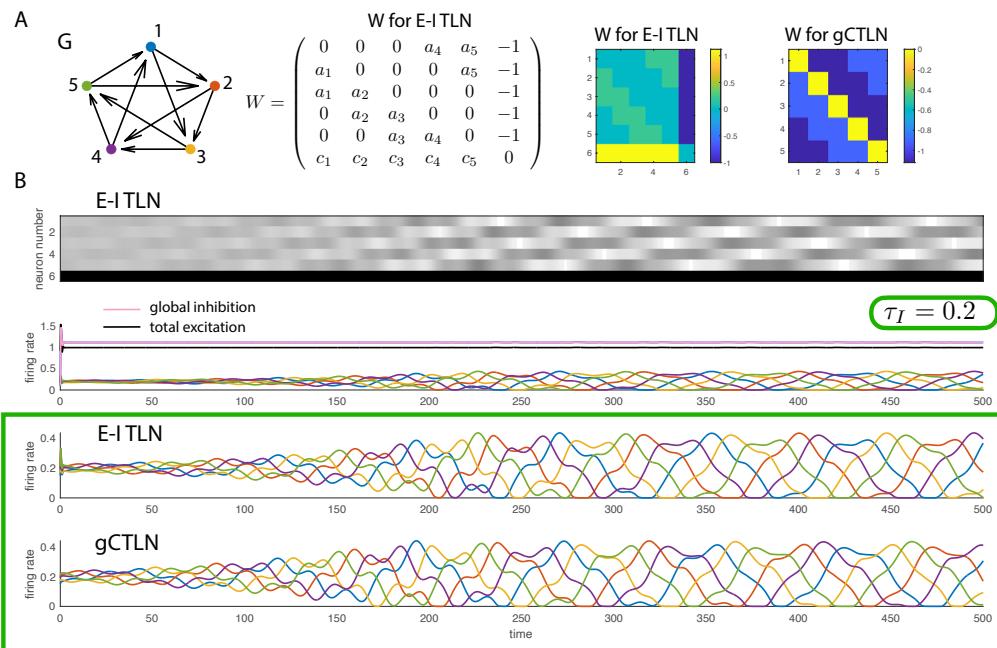
## Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?



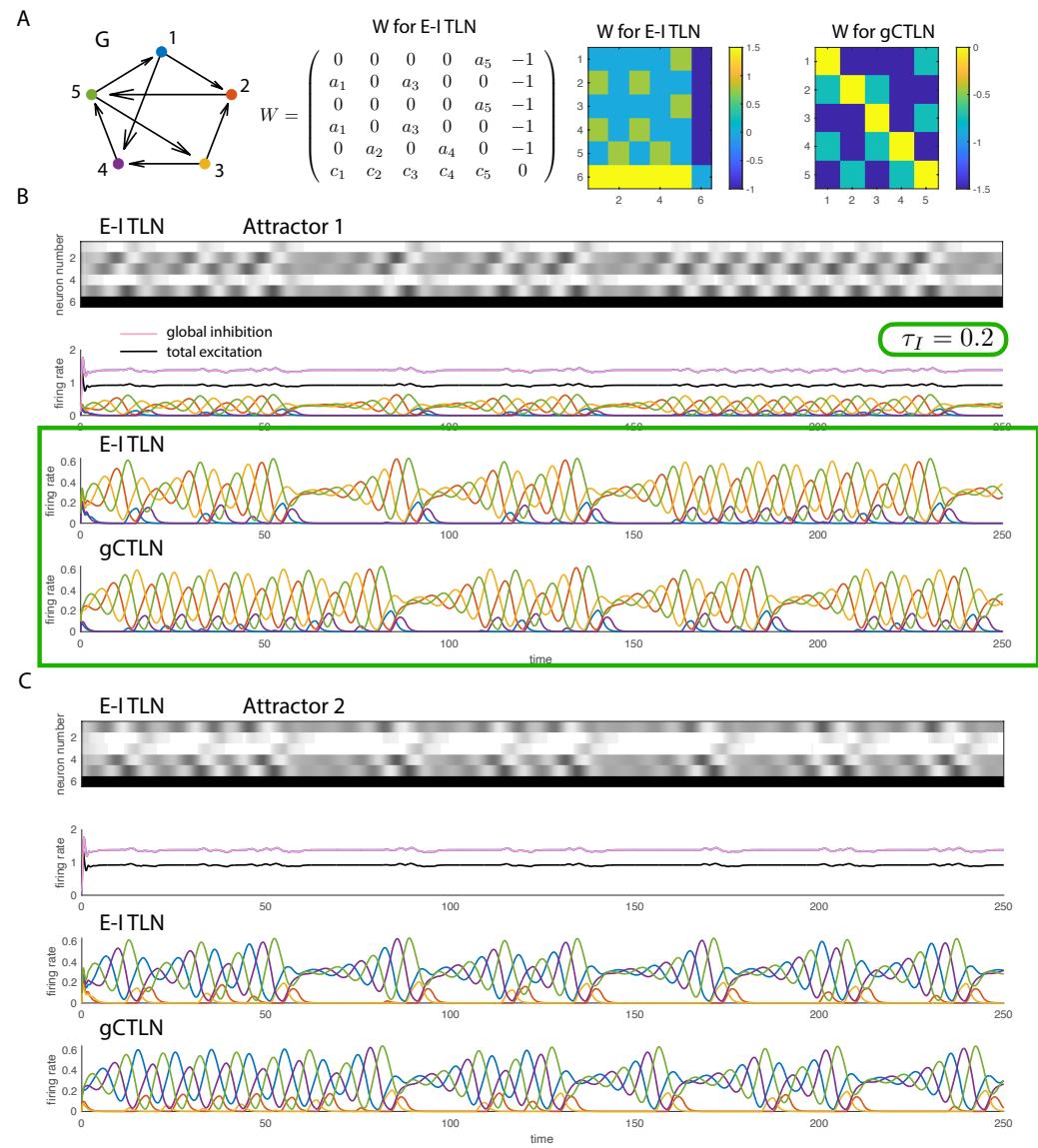
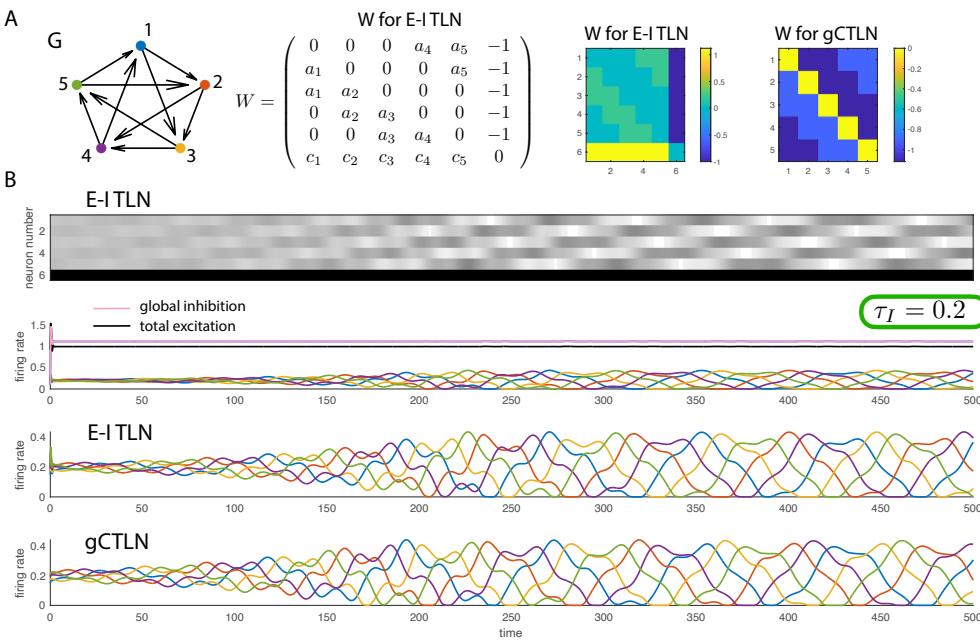
## Beyond fixed points: do E-I TLNs produce similar dynamics to gCTLNs?



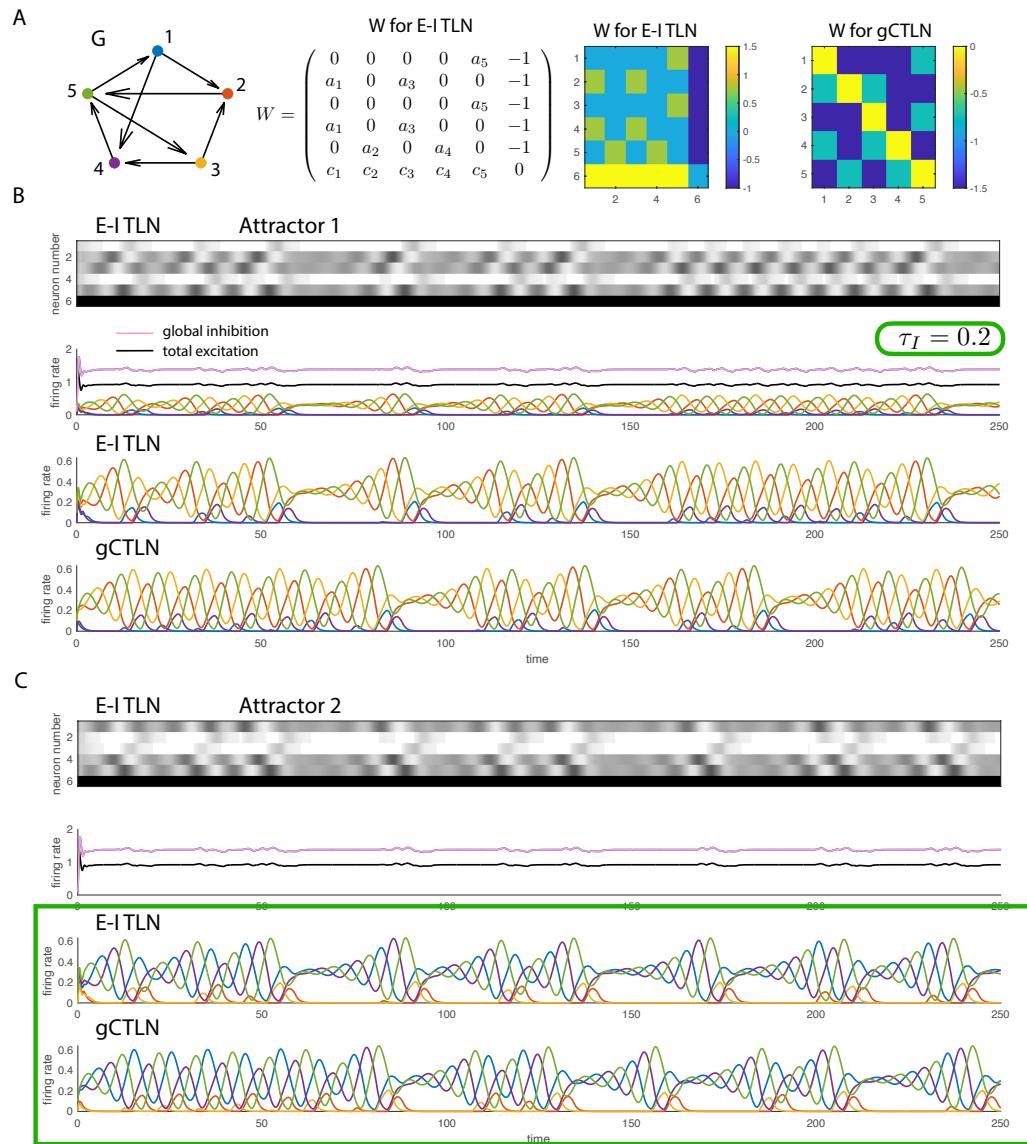
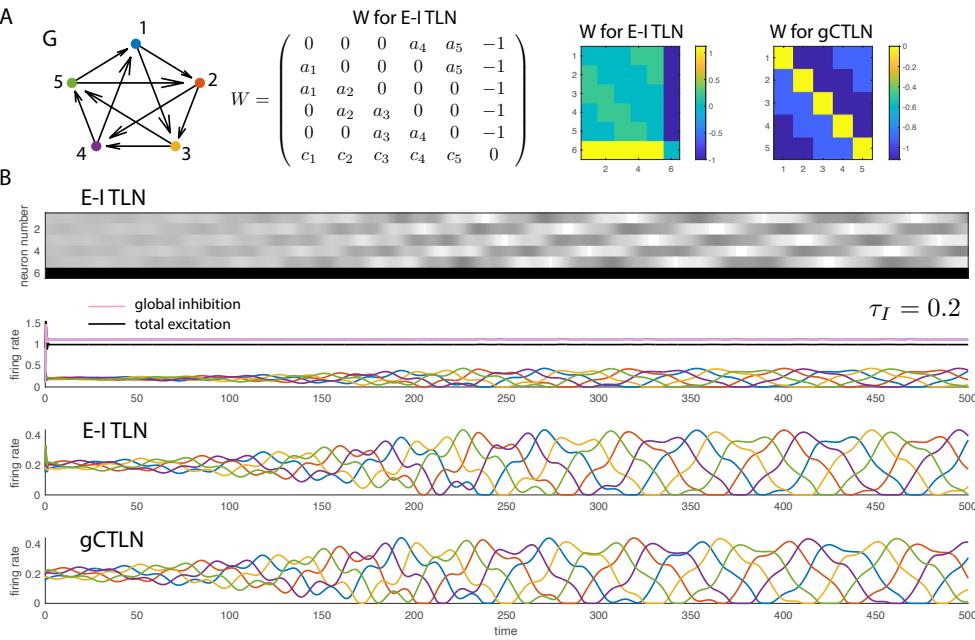
## Even “exotic” attractors like Gaudi and baby chaos look the same



# Even “exotic” attractors like Gaudi and baby chaos look the same



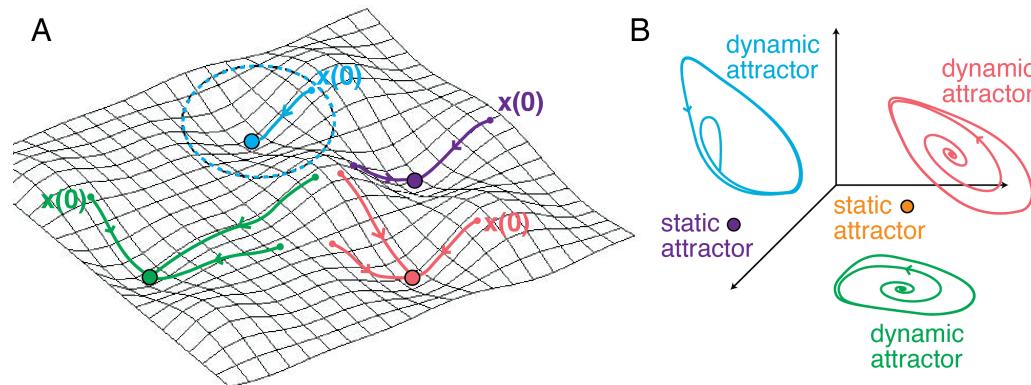
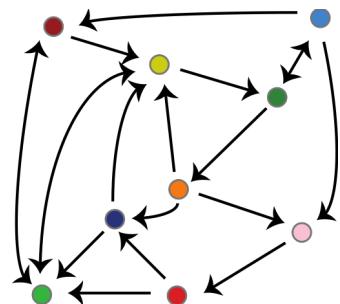
# Even “exotic” attractors like Gaudi and baby chaos look the same





We had many mathematical results, called “graph rules” on CTLNs.

Now many of those results also apply to E-I TLNs built from graphs!



Curto & Morrison, 2023 (review paper): Graph rules for recurrent neural network dynamics

# Domination Theorems

**Theorem 1 (2024)**

If  $j$  is a dominated node in  $G$ , then it drops out!

I.e., in any gCTLN, we have:

$$\text{FP}(G) = \text{FP}(G|_{[n] \setminus j})$$

Since E-I TLNs map to gCTLNs with the same fixed points, the domination theorems hold for E-I TLNs, too!

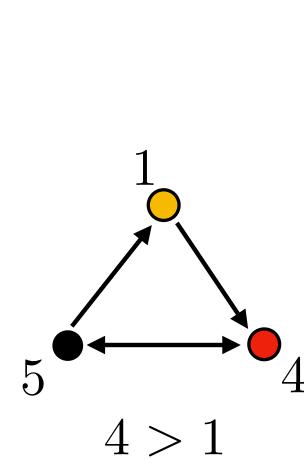
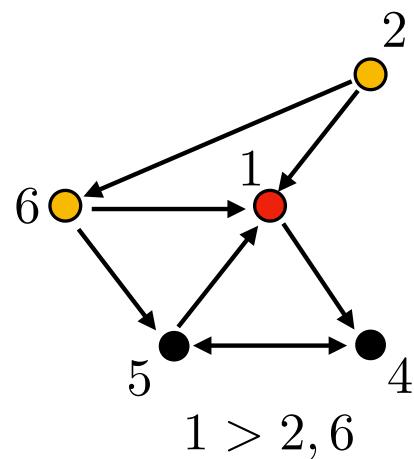
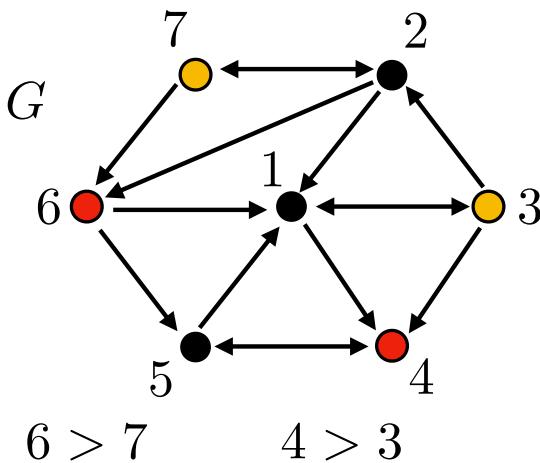
**Theorem 2 (2024)**

By iteratively removing dominated nodes, the final reduced graph

$G\text{-tilde}$  is unique. Moreover,

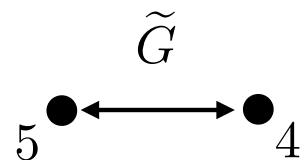
$$\text{FP}(G) = \text{FP}(\tilde{G})$$

**Example**

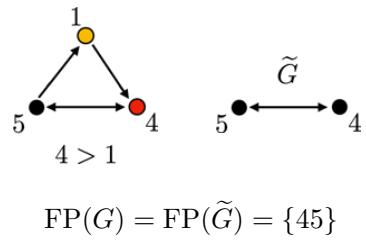
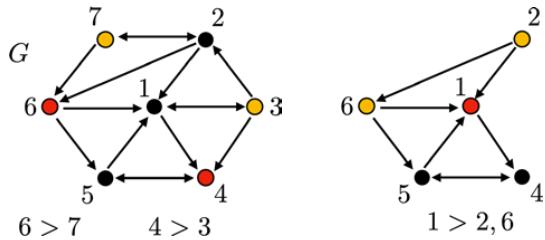


$$\text{FP}(G) = \{45\}$$

$$\text{FP}(\tilde{G}) = \{45\}$$

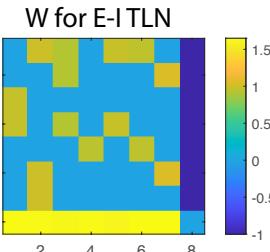
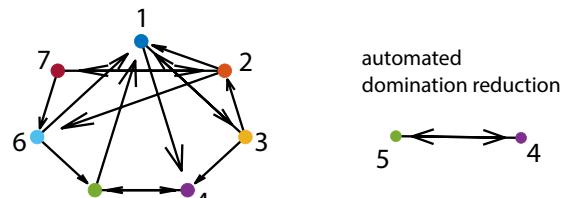


A

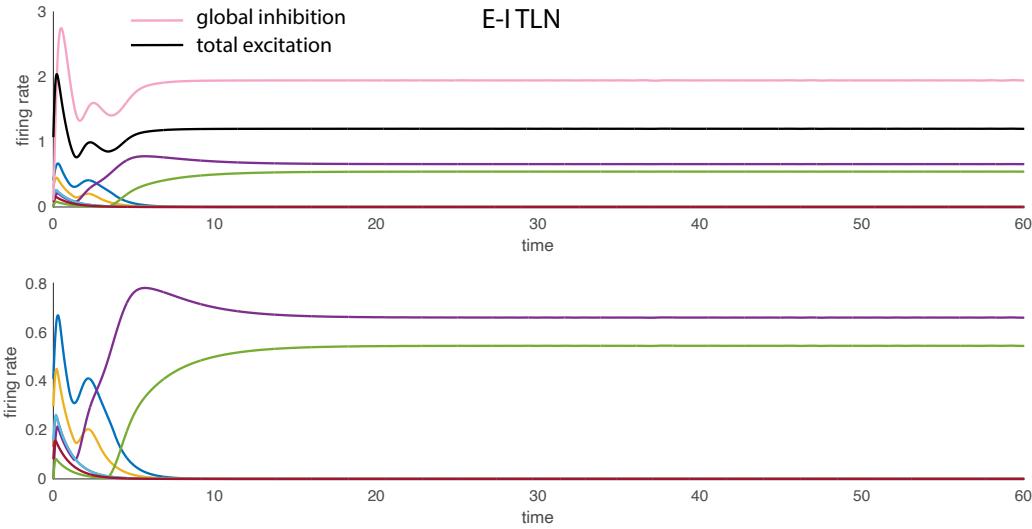


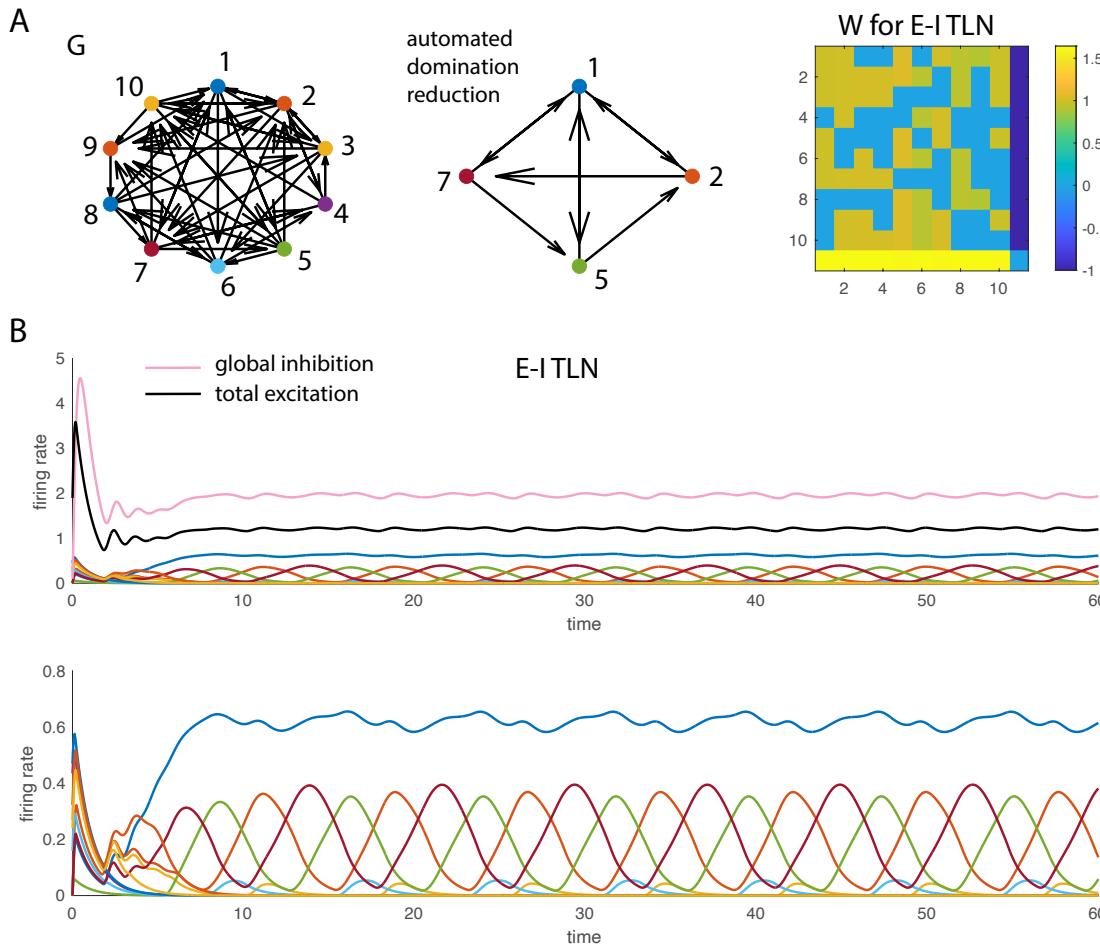
Since E-I TLNs map to gCTLNs with the same fixed points, the domination theorems hold for E-I TLNs, too!

B



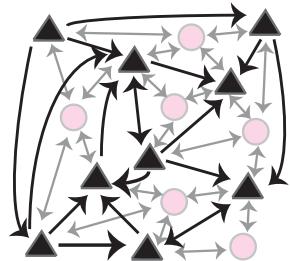
C



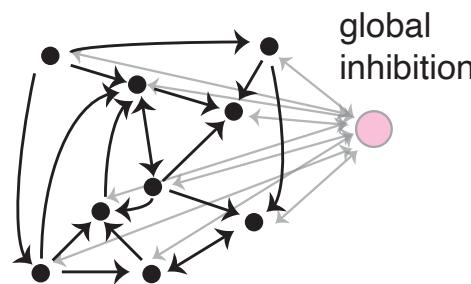


Since E-I TLNs map to gCTLNs with the same fixed points, the domination theorems hold for E-I TLNs, too!

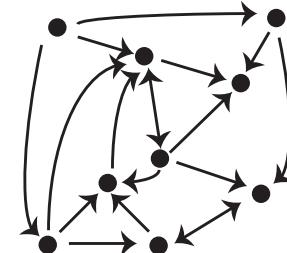
A excitatory neurons  
in a sea of inhibition



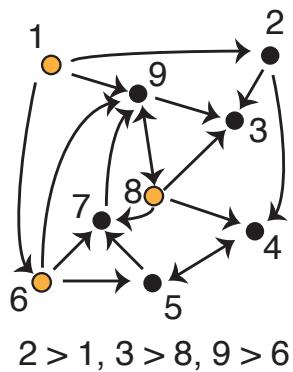
B E-I network



C graph G

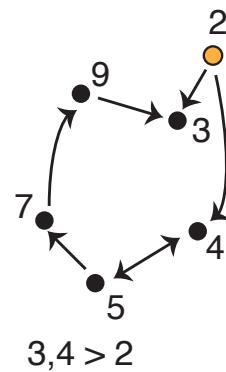


D domination in G



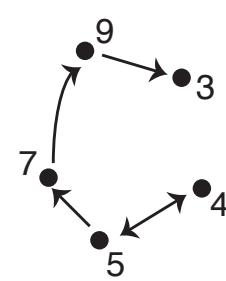
$2 > 1, 3 > 8, 9 > 6$

E partial reduction



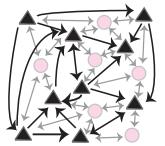
$3,4 > 2$

F reduced graph  $\tilde{G}$

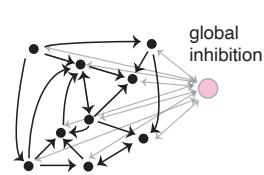


$FP(G) = FP(\tilde{G}) = \{3,45\}$

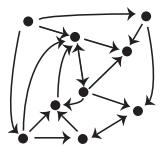
A excitatory neurons  
in a sea of inhibition



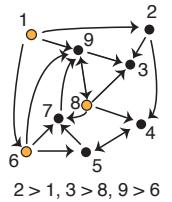
B E-I network



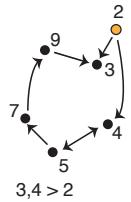
C graph G



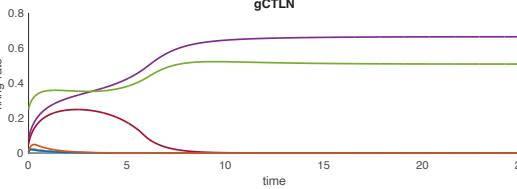
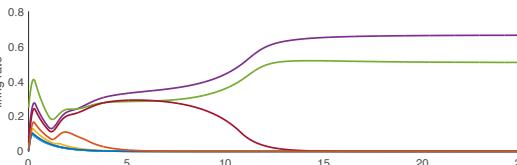
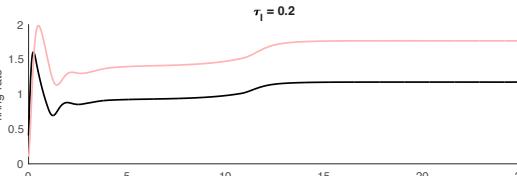
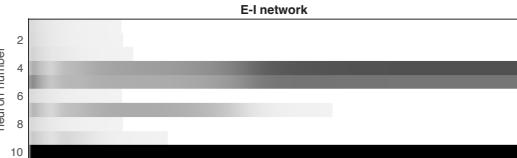
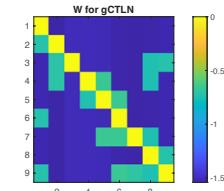
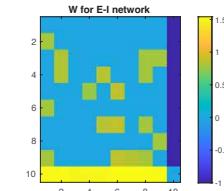
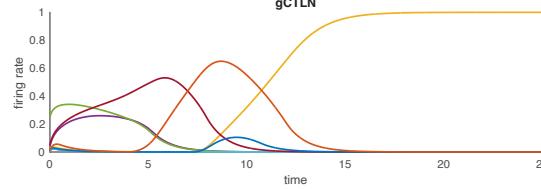
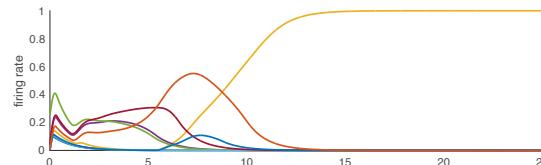
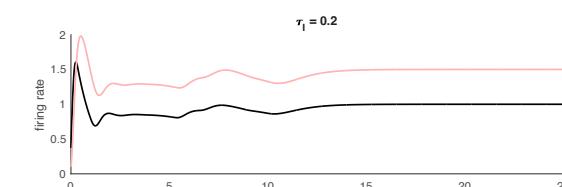
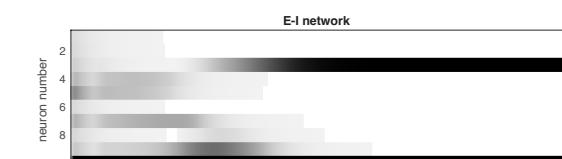
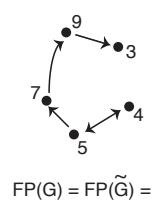
D domination in G



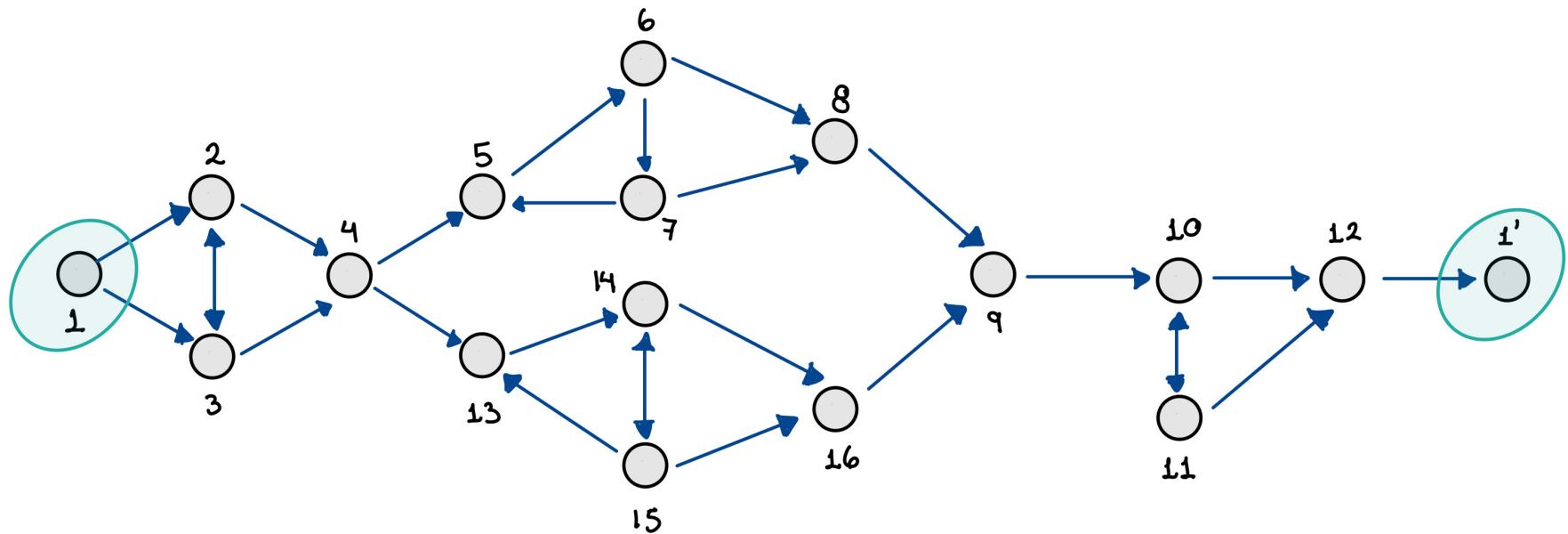
E partial reduction



F reduced graph  $\tilde{G}$

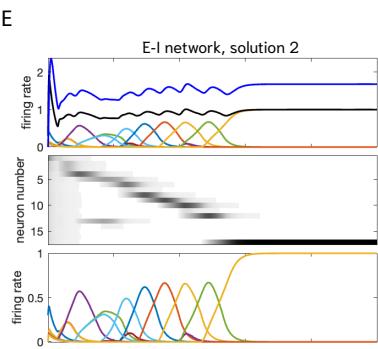
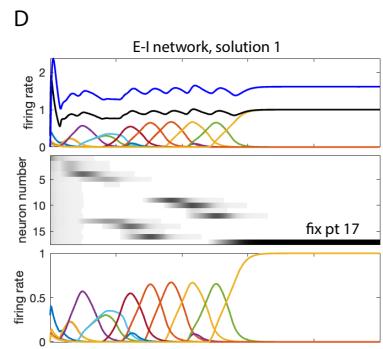
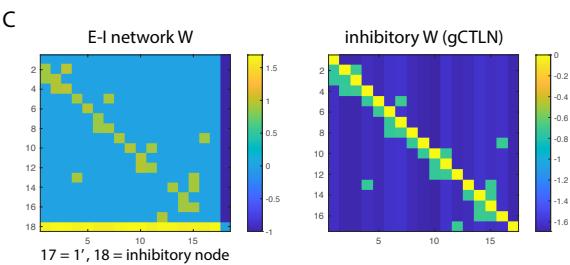
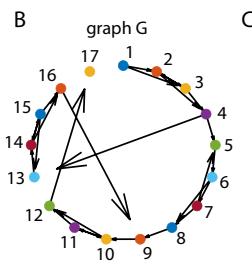
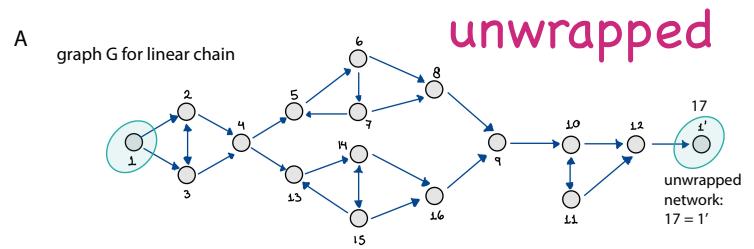


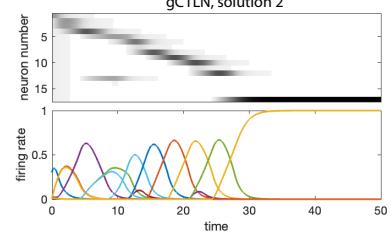
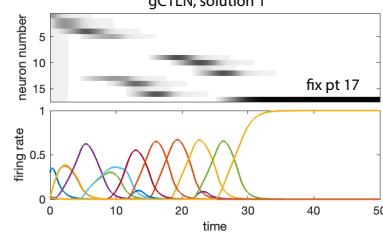
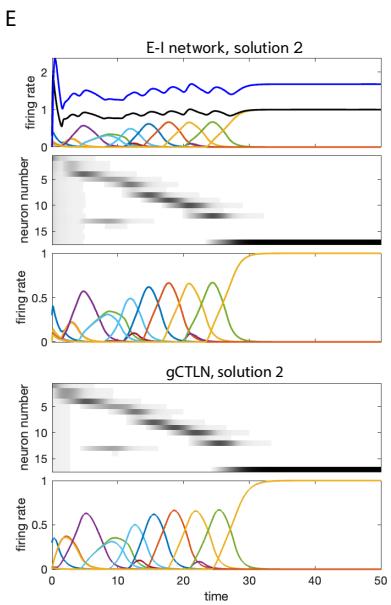
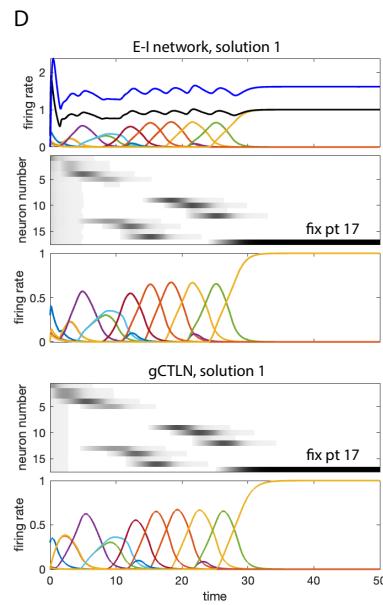
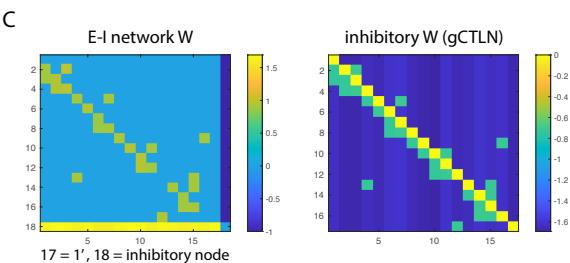
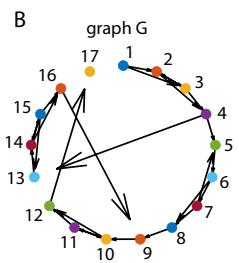
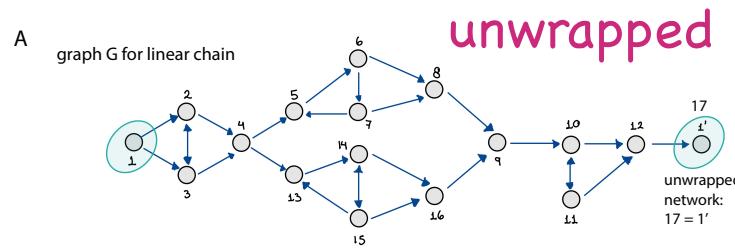
## Cyclic chain example

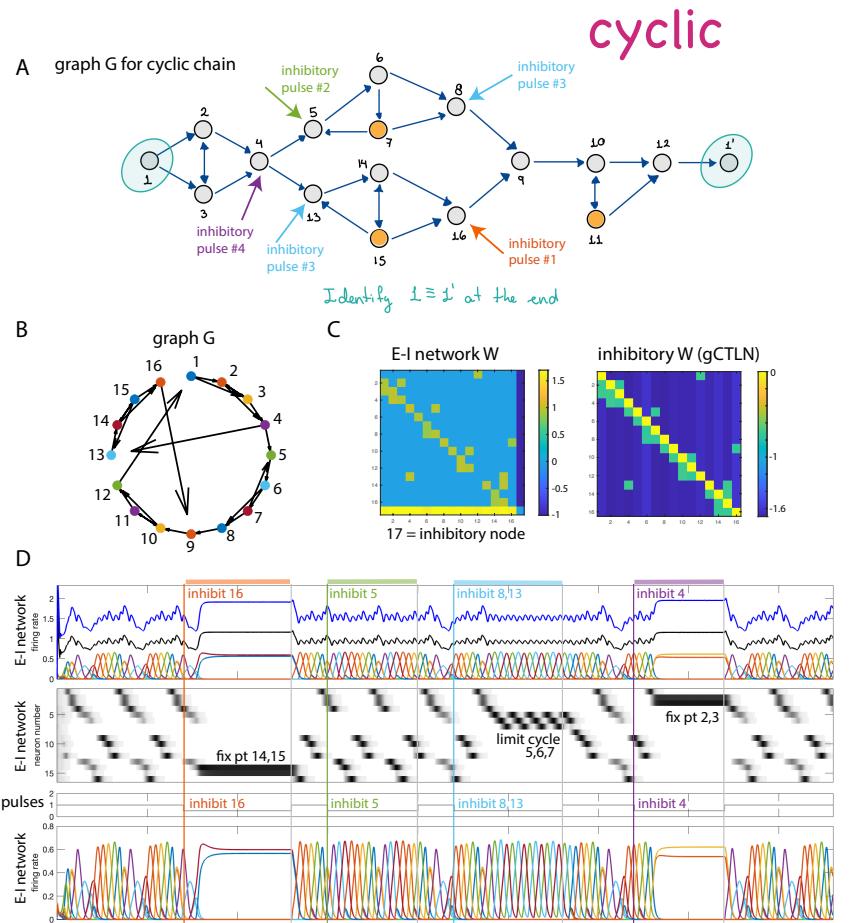
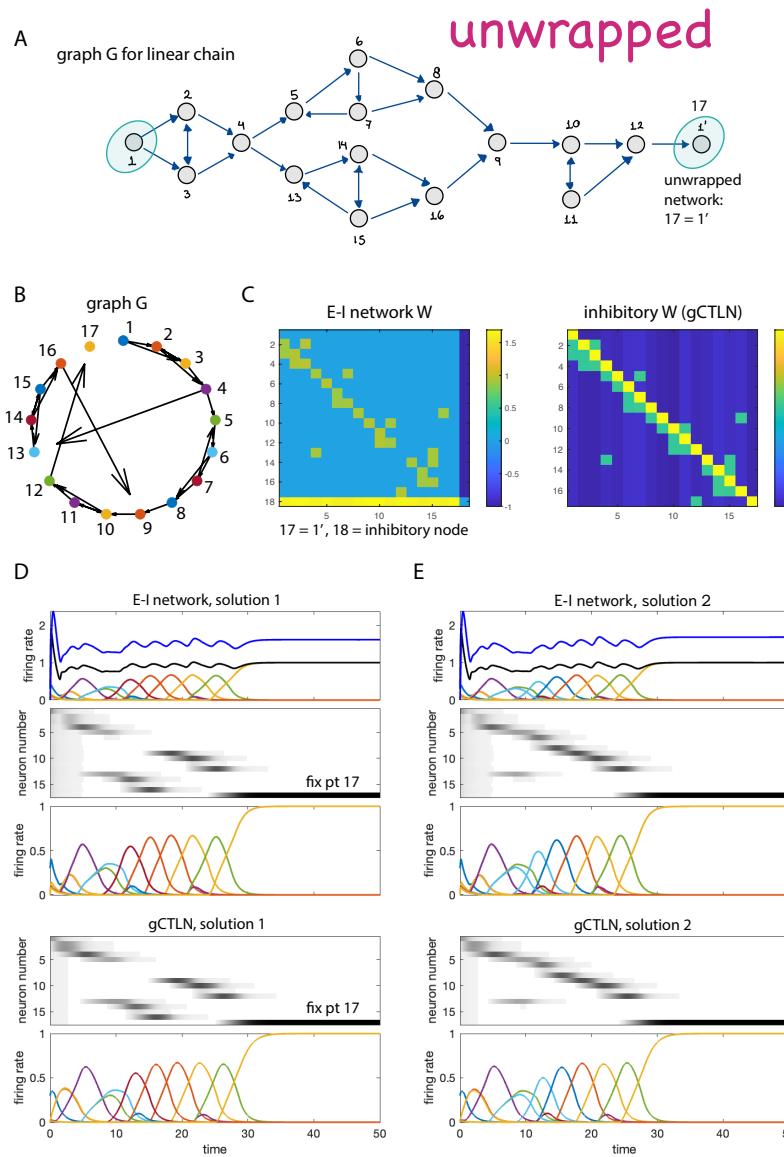


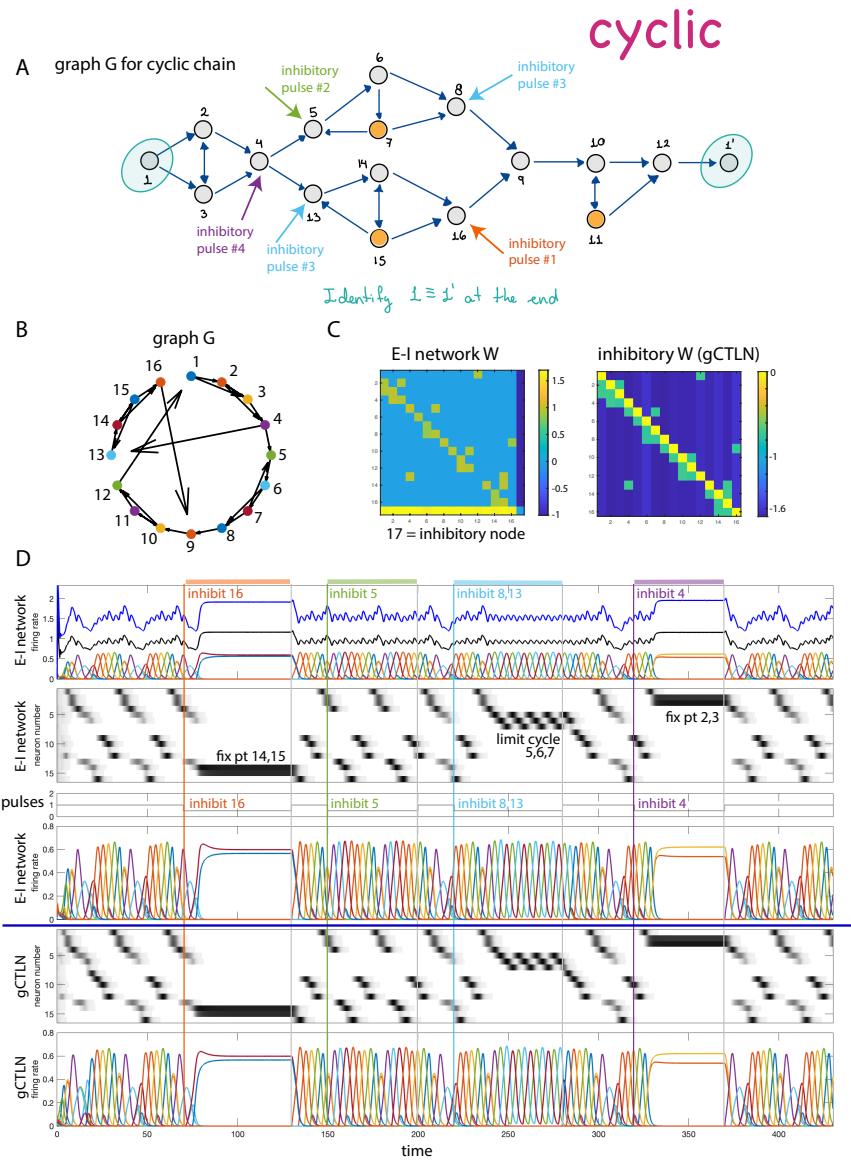
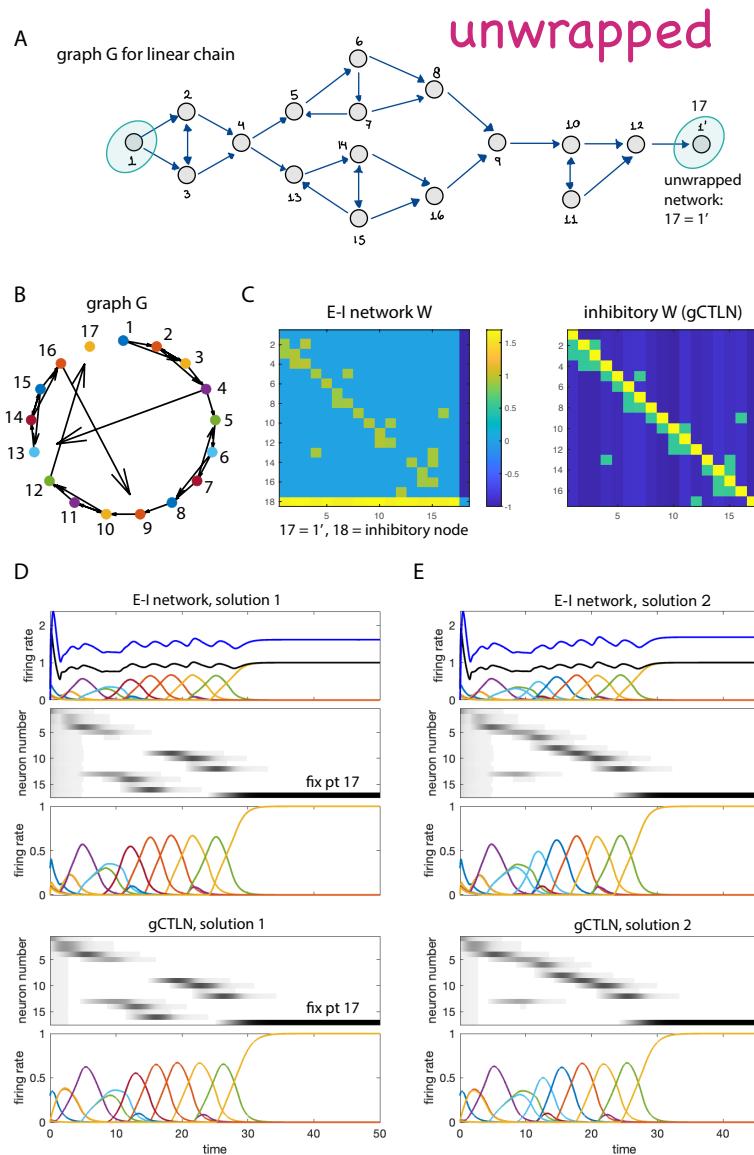
Identify  $1 \equiv 1'$  at the end

Domination reduction cannot be done, and the network activity will loop around.

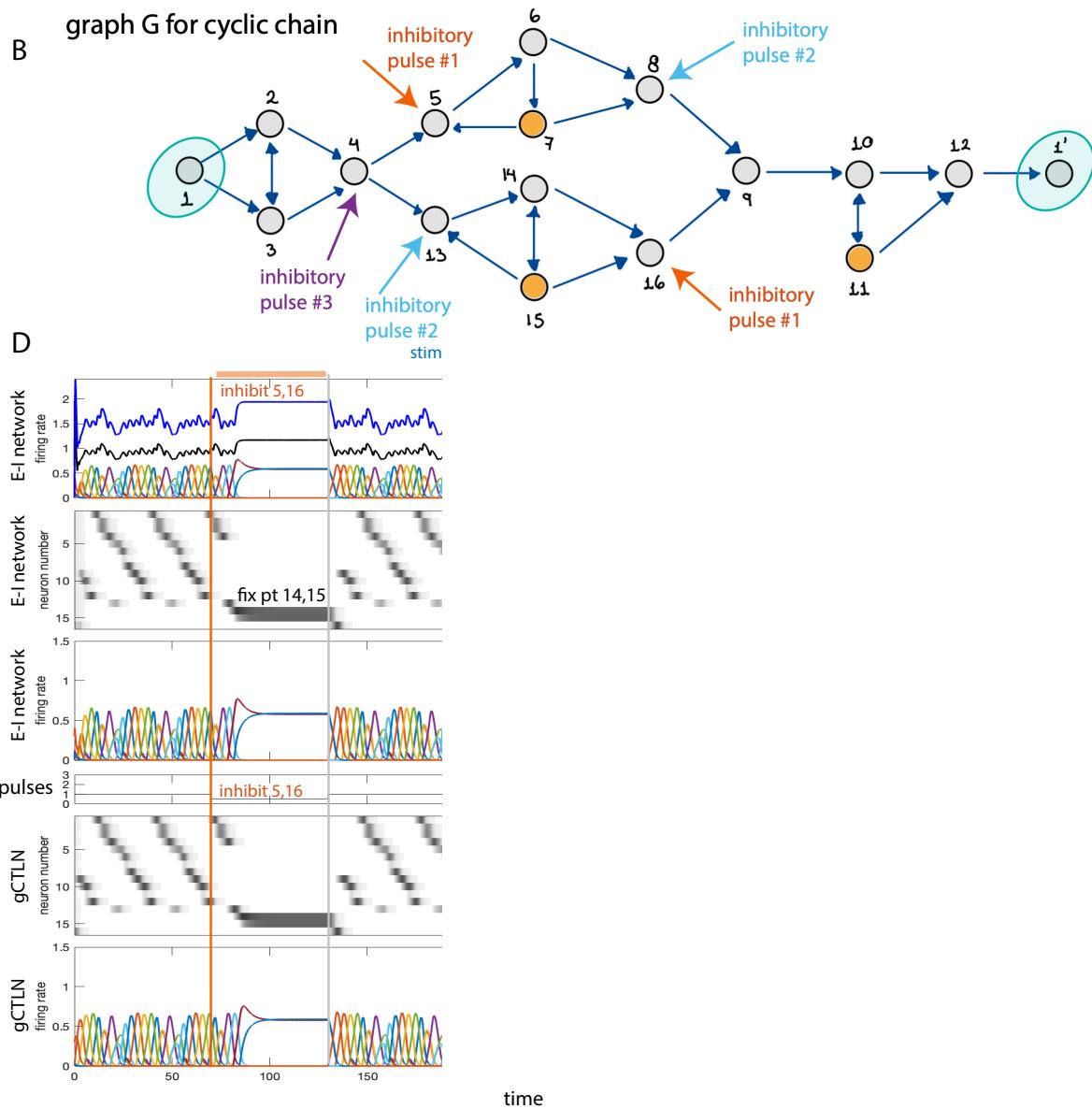






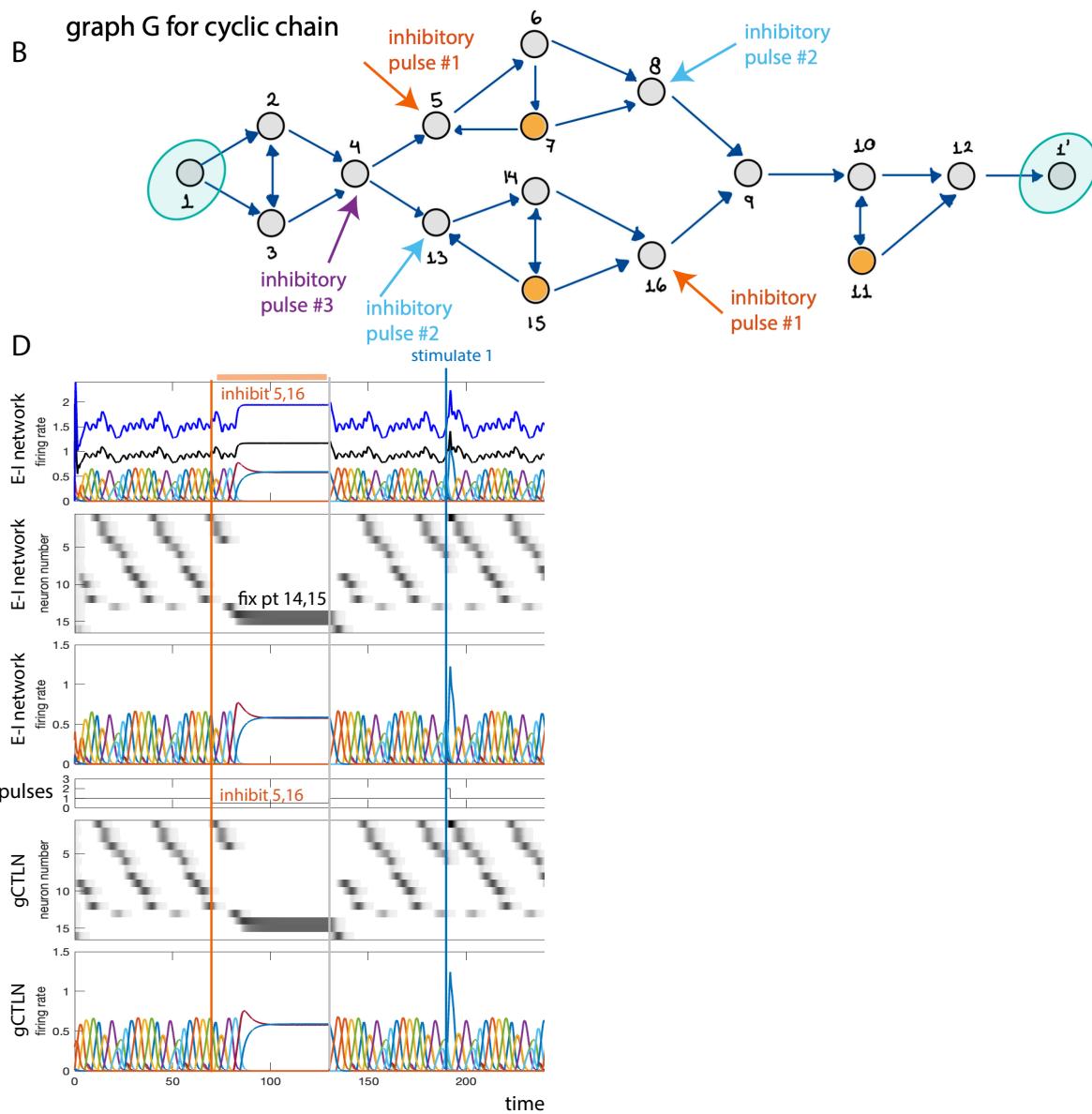


inhibitory pulses  
= stop signs



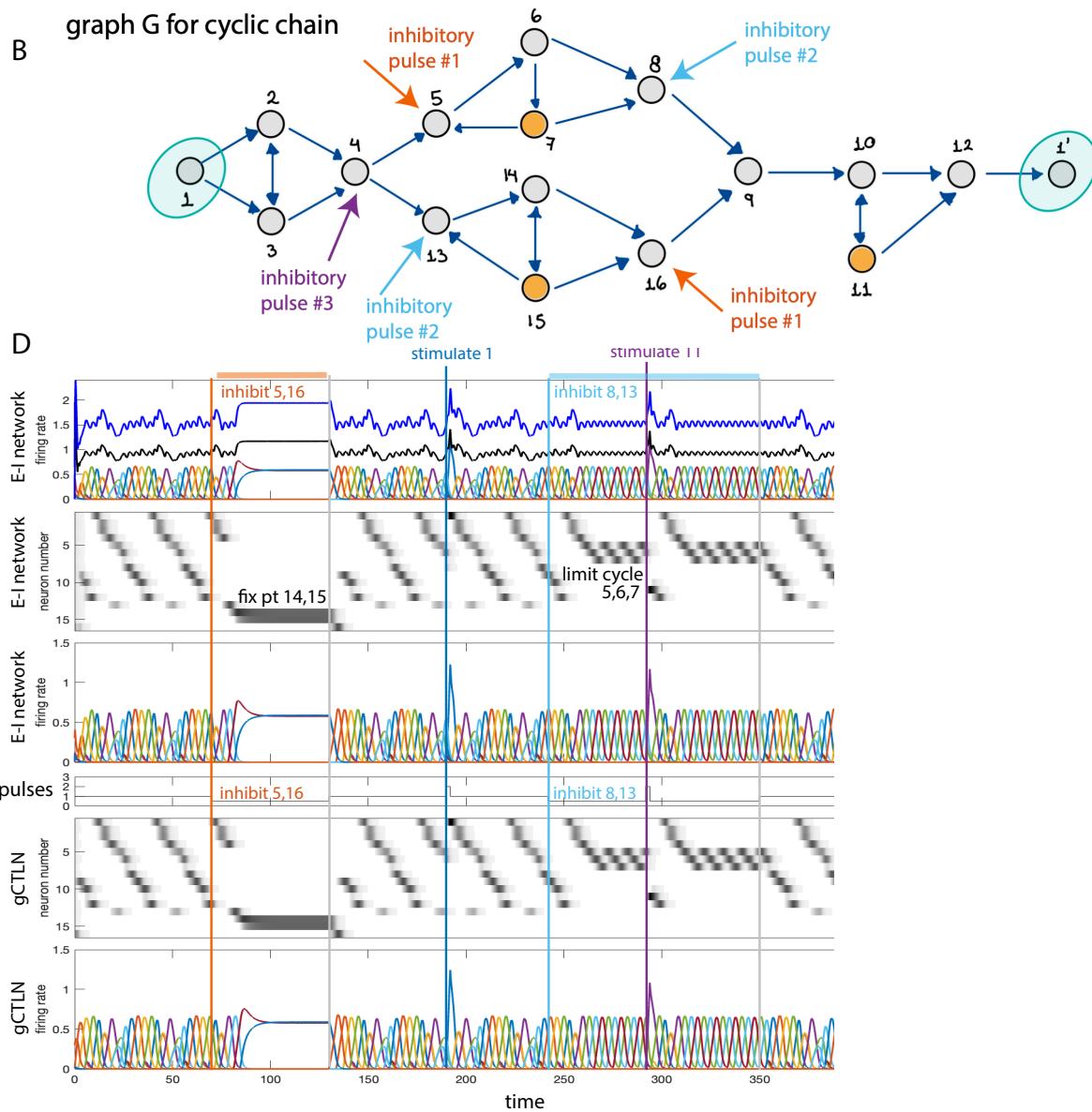
inhibitory pulses  
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excitatory pulses  
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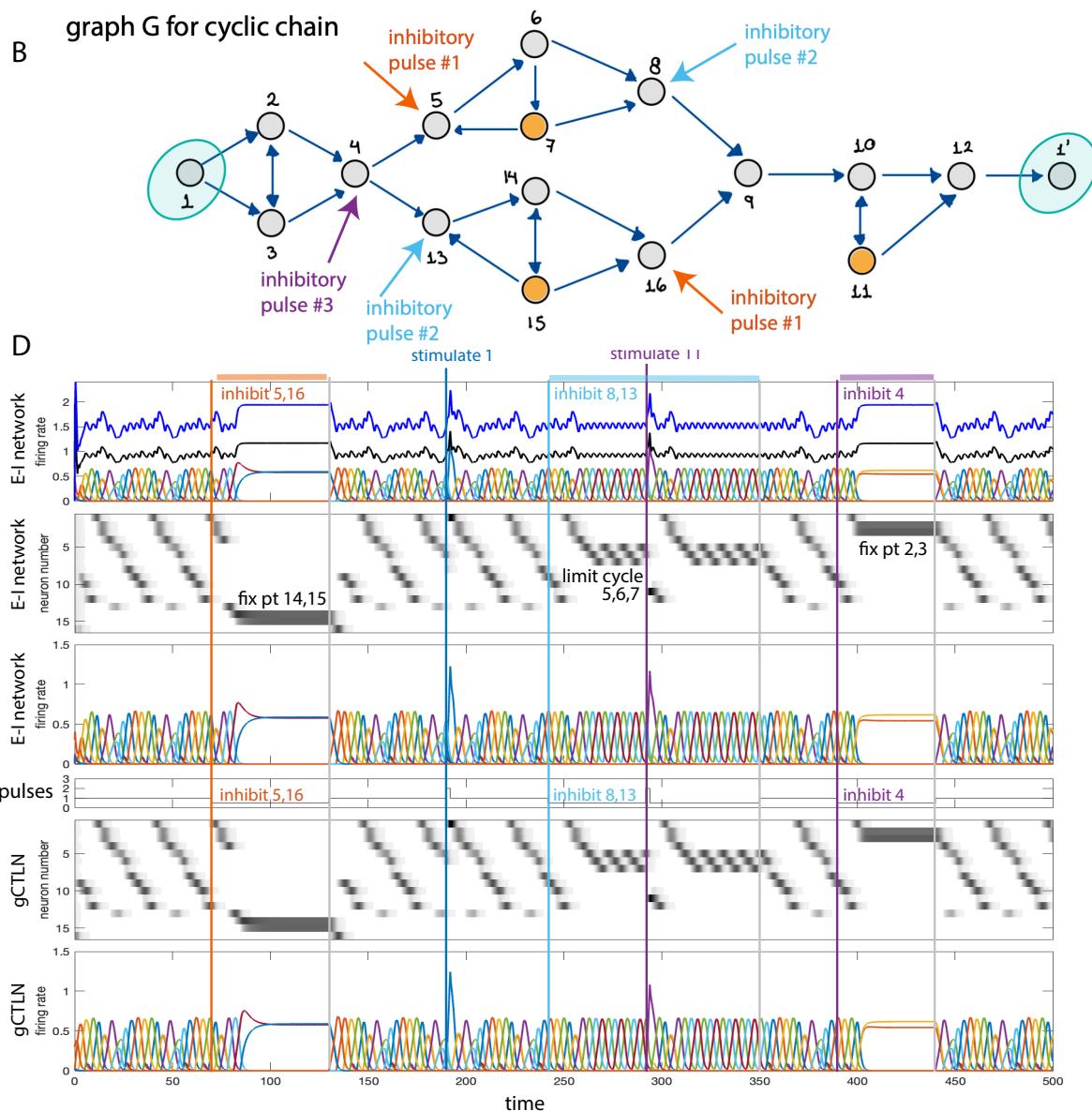
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excitatory pulses  
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# Thank you!



Katie Morrison



Caitlyn Parmelee



Chris Langdon



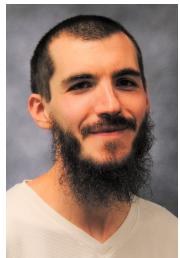
Nicole Sanderson



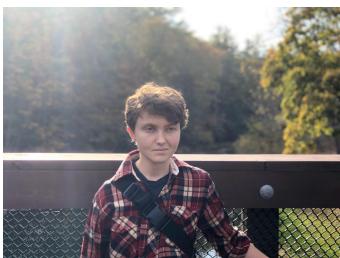
Safaan Sadiq



Jency (Yuchen) Jiang



Jesse Geneson



Caitlin Lienkaemper



Juliana Londoño  
Alvarez



Zelong Li



Vladimir Itskov



Anda Degeratu



Johns Hopkins University Applied Physics Laboratory,  
Research & Exploratory Development Department



# Domination - New Theorems - a word about the proofs

## 3. Proof of Theorem 1.5 Theorem 1

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need some more lemmas...

**Lemma 3.6.** Let  $G$  be a graph with vertex set  $[n]$ . For any gCTLN on  $G$ ,

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## Proof of Theorem 1

*Proof of Theorem 1.5.* Suppose  $j$  is a dominated node in  $G$ , and let  $(W, b)$  be an associated gCTLN. By Lemma 3.5, we know that  $y_j^* \leq 0$  at every fixed point  $(W, b)$ . It follows that  $j \notin \sigma$  for all  $\sigma \in \text{FP}(G)$ . Hence,

$$\text{FP}(G) \subseteq \text{FP}(G|_{[n] \setminus j}).$$

It remains to show that  $\text{FP}(G|_{[n] \setminus j}) \subseteq \text{FP}(G)$ . By Lemma 3.6, this is equivalent to showing that for each  $\sigma \in \text{FP}(G|_{[n] \setminus j})$ ,  $\sigma \in \text{FP}(G|_{\sigma \cup j})$ .

Suppose  $\sigma \in \text{FP}(G|_{[n] \setminus j})$ , with corresponding fixed point  $x^*$ . In this setting, we are not guaranteed that  $y_j^* = y_j(x^*) \leq 0$ , as  $x^*$  is not necessarily a fixed point of the full network. To see whether  $\sigma \in \text{FP}(G|_{\sigma \cup j})$ , it suffices to check the “off”-neuron condition for  $j$ : that is, we need to check if  $y_j^* \leq 0$  when evaluating (3.1) at  $x^*$ .

Recall now that there exists a  $k \in [n] \setminus j$  such that  $k$  graphically dominates  $j$ . It is also useful to evaluate  $y_k^*$  at  $x^*$ . Following the beginning of the proof of Lemma 3.2, we see that simply from the fact that  $\text{supp}(x^*) = \sigma$ , we obtain

$$y_j^* + W_{kj}x_j^* \leq y_k^* + W_{jk}x_k^*.$$

However, we cannot assume  $x_j^* = [y_j^*]_+$ , since we are not necessarily at a fixed point of the full network  $(W, b)$ . We know only that  $x_j^* = 0$  and  $x_k^* = [y_k^*]_+$ , as the fixed point conditions are satisfied in the subnetwork  $(W_{[n] \setminus j}, b_{[n] \setminus j})$  that includes  $k$ . This yields,

$$y_j^* \leq y_k^*(1 + W_{jk}) \leq 0,$$

where the second inequality stems from the fact that  $W_{jk} < -1$ . So, as it turns out, we see that  $y_j^* \leq 0$  not only for fixed points of  $(W, b)$ , but also for fixed points from the subnetwork  $(W_{[n] \setminus j}, b_{[n] \setminus j})$ . We can thus conclude that  $\text{FP}(G|_{[n] \setminus j}) \subseteq \text{FP}(G)$ , completing the proof.  $\square$

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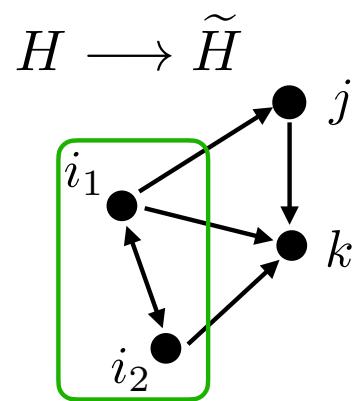
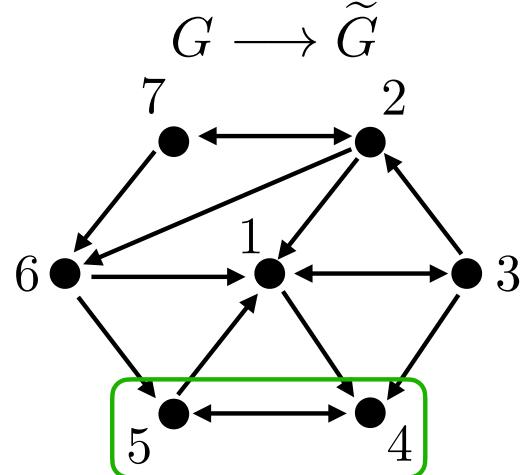
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# Can domination be useful for connectome analysis?

Every graph has a unique domination reduction:  $G \longrightarrow \tilde{G}$

Two graphs with the same reduction are in the same domination equivalence class.

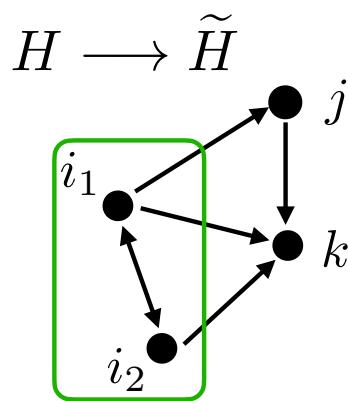
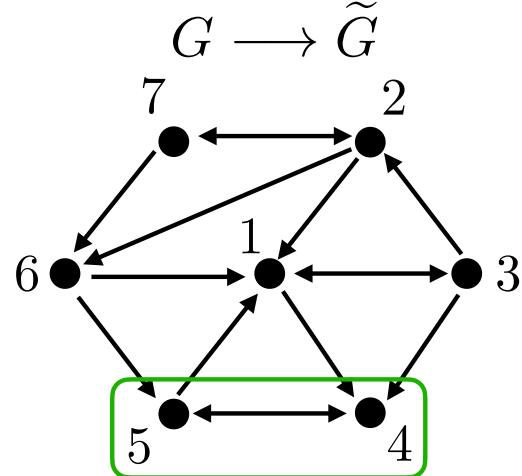


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1. Are overrepresented graphical motifs more likely to be reducible or irreducible?
2. Which motifs are domination-equivalent?
3. What about larger portions of the connectome: do they reduce via domination?

# Very preliminary analysis

## Graph motifs team at JHU

Jordan Matelsky (also at Penn)

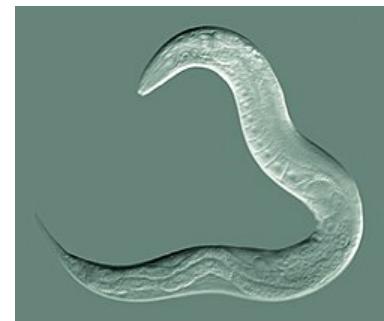
Patricia Rivlin

Michael Robinette

Erik Johnson

Brock Wester

Johns Hopkins University Applied Physics Laboratory,  
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C. elegans E-E network:

G has 143 nodes

reduced G: 104 nodes

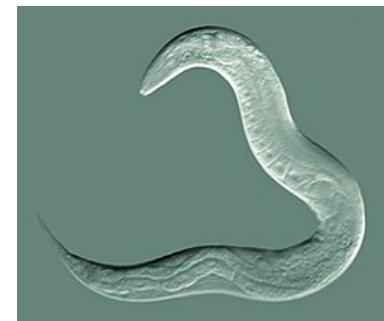


We first strip out everything but chemical synapses, then tag neurons by their small-molecule neurotransmitters—acetylcholine/glutamate as excitatory, GABA as inhibitory—next we grab the induced subgraph of neurons that fire ACh/Glu but no GABA. That's our 'excitatory' network. And yes—it's just a conservative, transmitter-based proxy for valence; real C. elegans synaptic polarity is far messier (receptors, modulators, co-transmission, gap junctions, etc.) All blame goes to Jordan Matelsky, Carina did nothing wrong.

Joaquín Castañeda Castro

## Very preliminary analysis

Is a reduction from 143  $\rightarrow$  104 nodes common or rare in a random graph with matching edge probability?



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## Very preliminary analysis

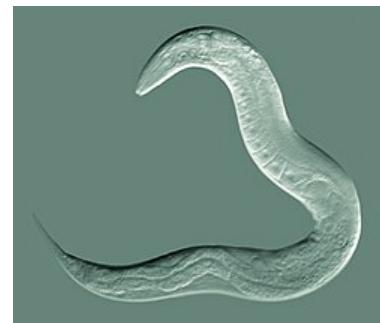
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1 million E-R random graphs with matching  $p = 0.054$

Distribution of domination reductions:

- 143 nodes: 782,590
- 142 nodes: 189,951
- 141 nodes: 24,951
- 140 nodes: 2,307
- 139 nodes: 185
- 138 nodes: 15
- 137 nodes: 1

VERY RARE!!



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C. elegans E-E network reduction:

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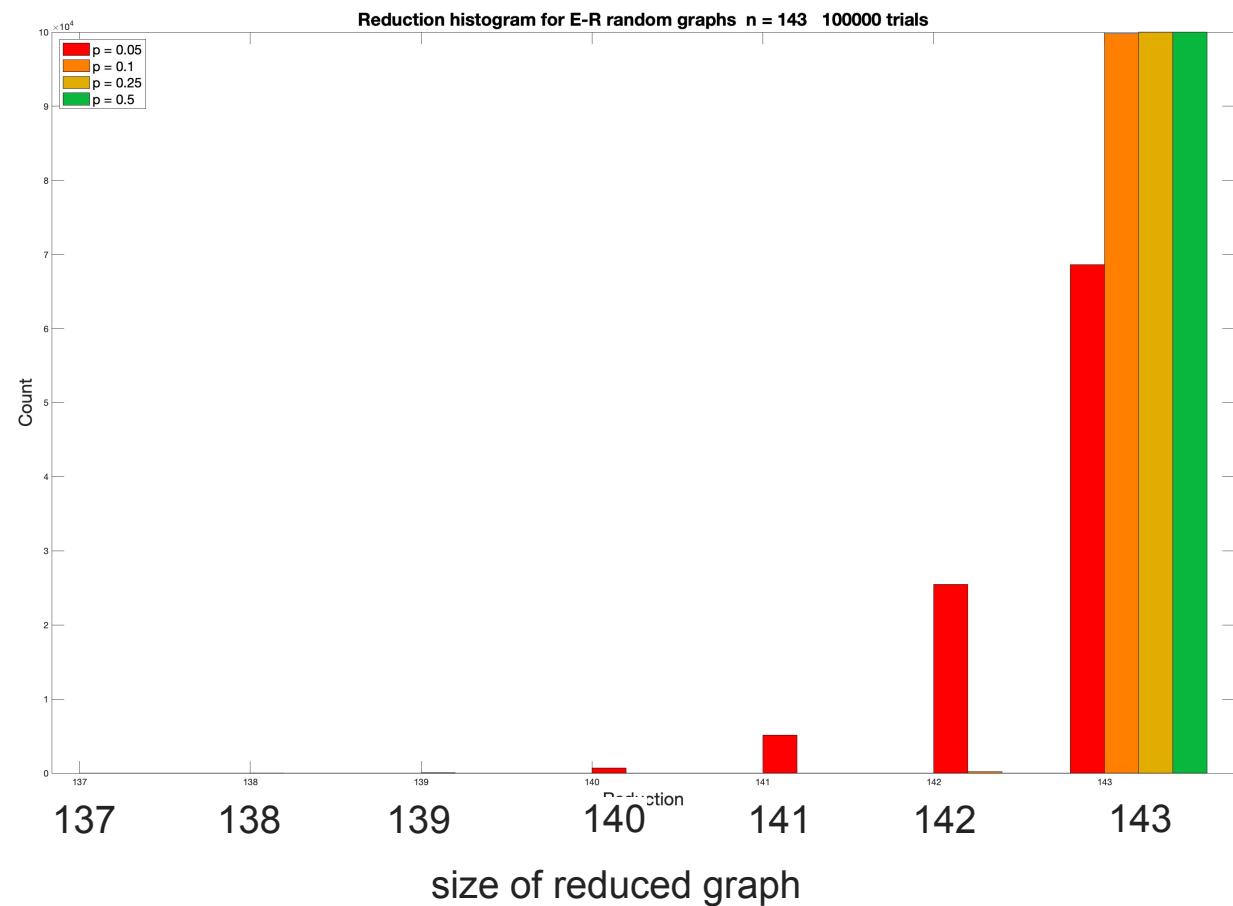
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Reduction sizes of E-R random graphs of size  $n=143$  with  $p = 0.05, 0.1, 0.25, 0.5$



## Back to our motivating questions and ideas:

1. How does connectivity shape dynamics?
2. The relationship between connectivity and neural activity depends on the dynamical system you associate to the connectome.
3. By studying neuroscience-inspired (nonlinear!) dynamical systems on graphs, we can generate hypotheses about the dynamic meaning/role of various network motifs.

Domination is a graph property that comes out of the nonlinear dynamics, it is not something that graph theorists or network scientists were already paying attention to.

