## Tianxin Hu

Block 835 Jurong West Street 81, #04-35, Singapore 640835 | +65-83125553 | +86-13191066031

TIANXIN001@e.ntu.edu.sg | ccwssplus.htx@gmail.com | Google Scholar | github.com/ccwss-maker

### **Educational Background**

### Nanyang Technological University (Master of Science)

Aug 2024 – Present

- School: Electrical and Electronic Engineering
- Major: Computer Control & Automation
- Dissertation: Minimizing Swept Area for AGVs in Singapore Seaport
- GPA: 92.00/100

#### Wuhan University of Science and Technology (Bachelor of Engineering)

Sept 2020 - Jun 2024

- School: Automobile and Traffic Engineering
- Major: Vehicle Engineering (Industrial Planning)
- GPA: 88.30/100 (Class Ranking: 3/32 Department Ranking: 8/157)

### **Academic Experience**

#### AIBOT Technology Pte. Ltd. — Autonomous Navigation System Development

Jul 2025 - Present

- Supervisor: Professor Lihua Xie, Dr. Shenghai Yuan
- Position: Navigation Module Lead
- **Responsibilities:** Developed the full-stack navigation module for the company's autonomous mobile robot, responsible for cross-floor navigation, elevator interface integration, and dynamic obstacle avoidance within residential and commercial environments
- ✓ Achievements: Achieved fully autonomous navigation and delivery within multi-story residential complexes

## Research Student — NTU Internet of Things Lab & Center for Advanced Robotics Technology and Innovation (CARTIN)

Aug 2024 - Present

- Supervisors: Professor Lihua Xie, Dr. Shenghai Yuan
- **Research Focus:** Developed optimization-based motion planning methods for multi-axle autonomous vehicles to minimize swept volume during turning maneuvers and reduce tire wear under dynamic constraints
- ✓ **Achievements:** Published five papers on vehicle planning and control (three under review) [J1-J5]

# Xin Chi Technology — Research and Development of Autonomous Driving System for Multi-Axle Heavy-Duty Transport Vehicles

Jun 2022 - Jun 2024

- Supervisor: Senior Engineer Xiangrong You
- Position: Technical Director & Corporate Legal Representative
- **Responsibilities:** Led R&D of autonomous driving systems for heavy-duty vehicles, covering mathematical modeling, ROS architecture, microcontroller development, and both simulation and prototype validation
- ✓ Achievements: Contributed to multiple patents [P1–P4] and received several national awards [A1–A5]

## Research and Development of Autonomous Driving System for Formula Racing

Feb 2021 - Jun 2024

- Supervisors: Associate Professor Chao Deng, Dr. Junyi Zou
- Position: Leader of the Unmanned Group
- **Responsibilities:** Led the development of the autonomous driving system for Formula Student Autonomous China (FSAC), covering visual detection, mapping, planning, and tracking
- ✓ Achievements: Received the FSAC Third Prize and Best Rookie Award [A6], and published a paper on it [J6]

#### **Publications**

## [J1] Energy-Constrained Navigation for Planetary Rovers under Hybrid RTG-Solar Power (Under Review)

Sep 2025

An International Conference about Robotics

**Tianxin Hu**, Weixiang Guo, Ruimeng Liu, Xinhang Xu, Rui Qian, Jinyu Chen, Shenghai Yuan, Lihua Xie DOI: 10.48550/arXiv.2509.15062

[J2] STARC: See-Through-Wall Augmented Reality Framework for Human-Robot Collabora-Sep 2025 tion in Emergency Response (Under Review) An International Conference about Robotics Shenghai Yuan, Weixiang Guo, Tianxin Hu, Yu Yang, Jinyu Chen, Rui Qian, Zhongyuan Liu, Lihua Xie DOI: 10.48550/arXiv.2509.15507 [J3] CleanUpBench: Embodied Sweeping and Grasping Benchmark (Under Review) Aug 2025 An International AI conference Wenbo Li, Guanting Chen, Tao Zhao, Jiyao Wang, Tianxin Hu, Yuwen Liao, Weixiang Guo, Shenghai Yuan DOI: 10.48550/arXiv.2508.05543 [J4] Swept Volume-Aware Trajectory Planning and MPC Tracking for Multi-Axle Swerve-May 2025 **Drive AMRs** *IEEE International Conference on Robotics and Automation (ICRA 2025)* Tianxin Hu, Shenghai Yuan, Ruofei Bai, Xinhang Xu, Yuwen Liao, Fen Liu, Lihua Xie DOI: 10.1109/ICRA55743.2025.11127914 [J5] Tire Wear-Aware Trajectory Tracking Control for Multi-Axle Swerve-Drive Autonomous June 2025 **Mobile Robots** Journal of Automation and Intelligence Tianxin Hu, Xinhang Xu, Thien-Minh Nguyen, Fen Liu, Shenghai Yuan, Lihua Xie DOI: 10.1016/j.jai.2025.05.003 [J6] Improvement of YOLOv5 Algorithm for Formula Racing Based on TensorRT under ROS May 2023 Platform Agricultural Equipment & Vehicle Engineering Tianxin Hu, Chao Deng, Junjie Ma, Wang Liu DOI: 10.3969/j.issn.1673-3142.2023.05.004 **Patents** [P1] (Granted) Multi-axle all-wheel steering vehicle vector-division correction method and Sep 2025 Tianxian Hu, Xiangrong You, Dongmei Wang, Xinhe Long, Xinyu Wang, Shuang Liu, Yutong Fu, Xinyao Wang, Lefeng Wei, Baizhen Zhang Patent No.: CN116534005B [P2] (Granted) A system and method for automatically correcting the deviation of a beam Jul 2023 transport vehicle in a tunnel Xiangrong You, Enze Jin, Dongmei Wang, Yuran Huang, Tianxian Hu, Shuai Zhu, Beijia Zhang Patent No.: CN114633801B [P3] (Pending) Energy-saving system and method for beam transport vehicle based on trav-Feb 2024 eling pressure control Wei Li, Xiangrong You, Dongmei Wang, Xinhe Wang, Peng Cheng, Yuming Liu, Shuang Hu, Tianxian Hu, Xinyao Wang, Lefeng Wei, Baizhen Zhang Application No.: CN117508238A [P4] (Pending) Method, system and equipment for planning obstacle avoidance path of Dec 2023 multi-shaft all-wheel steering beam transporting vehicle Xiangrong You, Yucheng Yin, Liwei Wang, Dongmei Wang, Tianxian Hu, Shuang Liu, Xinyao Wang, Lefeng Wei, Baizhen Zhang Application No.: CN117168481A Awards [A1] (International Level) Bronze Award of the 9th China International College Students Apr 2024 **Innovation Competition** Organizing Committee of China College Students "Internet+" Competition [A2] (National Level) The First Prize of the 18th "Challenge Cup" National Undergraduate Oct 2023 **Curricular Academic Science and Technology Works** China Association for Science and Technology, Ministry of Education of the PRC, Chinese Academy of Social

[A3] (International Level) Bronze Award of the 8th China College Students "Internet+" In-

Organizing Committee of China College Students "Internet+" Competition

novation and Entrepreneurship Competition

Apr 2023

Sciences

[A4] (National Level) Second Prize of the 15th China College Student Computer Design

Ompetition

Jul 2022

Organizing Committee of Chinese College Student Computer Design Competition

[A5] (National Level) Second Prize of the 15th Energy Saving and Emission Reduction Competition

China College Student Energy Conservation and Emission Reduction Social Practice and Technology Competition

China College Student Energy Conservation and Emission Reduction Social Practice and Technology Competition Committee

[A6] (National Level) Third Prize and Best Rookie Award of Formula Student Competition
China Society of Automotive Engineers, Organizing Committee of FSAC

Oct 2022

## **Technical Expertise**

**Programming:** C, C++, Python, XML (URDF/Launch)

Robotics & Simulation: ROS/ROS2, Gazebo Classic & GZ Sim, RViz, URDF/SDF modeling

Embedded Systems: NVIDIA Jetson (AGX Xavier, Orin NX), STM32, ESP8266, 8051; FreeRTOS, LVGL, U8G2

Hardware Design: Altium Designer, Proteus; multilayer PCB design and soldering

Modeling, Simulation & CAD: MATLAB, COMSOL, SolidWorks, CATIA, Blender, AutoCAD