

# -Studying group-W1

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## Abstract

Reading Notes for Week 1, "Introduction to Machine Learning"

## 1 Terminologies

- Machine Learning: Algorithms + statistical models  $\rightarrow$  computer systems performing tasks based on patterns and inference
- Supervised Learning: Training with data labeled by classification and regression
- Unsupervised Learning: Training without data labeled by clustering.<sup>1</sup>
- Hypothesis Space: A set of functions  $\{f|f : S_{input} \rightarrow S_{output}\}$
- Occam's razor: Simple models are better when having same outcome

## 2 Model Evaluation

### 2.1 Empirical Error

The error resulted from data training. Error rate is defined as :  $\frac{N_{errors}}{N_{total}}$ . Notice the difference between empirical error and generalization error

### 2.2 Learning State

Overfitting : the state that the model takes too many features of the testing data, which can not be used in general ways. Underfitting : the state of taking too few features. Solution of overfitting is adding weight-decay, and for underfitting we add more branches to the decision tree, or increase the rounds of learning.

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<sup>1</sup>clustering: dividing training set into groups. Each subset owns some intrinsic attributes

## 2.3 Cross Validation

Dividing data into  $k$  subsets (mutually exclusive) and randomly choose one for testing set, the other as training set. Usually we choose  $k = 10$ .

## 2.4 Hold-Out

How many data should we use in training while the other use in testing? There is a dilemma that more training data might receive better model, less accurate in testing, however. Usually, we take  $\frac{2}{3}$  -  $\frac{4}{5}$  data for training.

## 2.5 Bootstrapping

See "Appendix 1" for algorithm. Randomly choosing one sample from the dataset into the training set, and repeat for  $|S_{sample}|$  times. Those samples which are not chosen will be the testing set. The following equation shows that about 36.8% of data will be in the testing set.

$$\lim_{m \rightarrow \infty} (1 - \frac{1}{m})^m = \frac{1}{e} \approx 0.368$$

# 3 Performance measure

## 3.1 Mean squared error

In statistic, there are two kinds of Mean squared error.

- Discrete

$$E(f; D) = \frac{1}{m} \sum_{i=1}^m (f(x_i) - y_i)^2$$

- Continuous

$$E(f; D) = \int_{x \in D} (f(x) - y)^2 p(x) dx$$

## 3.2 Bias-variance decomposition

Notice that  $y_D$  stands for the label in dataset, and  $y$  stands for the real label of  $x$ . (The difference between the two leads to noise)

- Expectation of the learning algorithm

$$\bar{f}(x) = E_D[f(x; D)]$$

- Variance

$$var(x) = E_D[(f(x; D) - \bar{f}(x))^2]$$

- Noise

$$\epsilon^2 = E_D[(y_D - y)^2]$$

- Bias(Difference between expected output and actual label)

$$bias^2(x) = (\bar{f}(x) - y)^2$$

By the above equations, we can get the Bias-variance decomposition:

$$E(f; D) = bias^2(x) + var(x) + \epsilon^2$$

## 4 Decision Tree

See "Appendix 2" for Algorithm. It is a way to decide the attribute sequence to classify a data.

- Information entropy: Similar to Thermodynamics. Quantify whether a feature is decisive.

$$Ent(D) = - \sum_{k=1}^{|y|} p_k \log_2 p_k$$

- Information Gain: Evaluate the target attribute a

$$Gain(D, a) = Ent(D) - \sum_{v=1}^V \frac{|D^v|}{|D|} Ent(D^v)$$

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## References

- [1] Murphy, K. P. (2012). Machine learning: a probabilistic perspective. MIT press.
- [2] Goodfellow, I., Bengio, Y., Courville, A. (2016). Deep learning. MIT press.

## Appendix 1

Bootstrapping [1] Bootstrapping  $D$  Input: Dataset  $D$  Output: Training Set  $T$   
 $m \leftarrow D.size()$   $T \leftarrow \phi$   $i$  in range  $m$   $x = random(D)$ ;  $T.add(x)$   $T$

## Appendix 2

Decision Tree [1] TreeGenerate  $D, A$   
 Input: Training Set  $D = \{(x_i, y_i)\}$ ; Attribute Set  $A = \{y_i\}$

Create new node  $N$  All tuples in  $D$  are of same Attribute  $C$   $N \leftarrow$  leaf node labeled with  $C$   $A = \phi$  tuples in  $D$  have same values over  $A$   $N \leftarrow$  a leaf node labeled with the majority attribute in  $D$  Calculating Information Gain to select the best splitting criterion  $a_*$   $N \leftarrow a_*$   $a_*^v$  in  $a_*$  Add a new branch after node  $N$  with node  $M$  let  $D_v$  be a subset containing all tuples satisfying  $a_*^v$  in  $D$   $D_v = \phi$   $M \leftarrow$  a leaf node labeled with the majority attribute in  $D$   $M \leftarrow \text{TREEGENERATE}(D_v, A - \{a_*\})$

## References