

# SugarTrail Code Introduction

## 1 Phase 1: Signature Test

- Location:
  - Getting Data: \sugar\cluster\reading\_testing
  - Analysis: \sugar\cluster\analysis\lab\_signature
- Fig:
  - Stable reading for one node
  - Disturbed reading for one node
  - Relatively stable signature for one node
- Run: \sugar\cluster\analysis\lab\_signature\sig\_analysis.m

## 2 Phase 2: Distribution Table/Curve generate

- Location: \sugar\cluster\distribution
- Fig:
  - Relation of ranging distance and real distance
- Run:

## 3 Phase 3: Hallway Test

- Location: \sugar\cluster\hallway\_simulation
- Fig:
  - Cluster
  - Navigation
  - Base number and performance
  - Cluster size threshold and performance
- Run: main.c

## 4 Phase 4 : Lab(Field Test)

- Location: \sugar\cluster\lab\_field\_test
- Fig: None
- Run: main.c

## 5 Phase 5: Lab(Database Test)

- Location: \sugar\cluster\lab\_database
- Fig:
  - Clustering(path\_length = 10000)
  - Navigaion
- Run:
  - p1\_collect\_readings.m (collecting data, done, don't run again)
  - p2\_data\_process.m (generate proper data structure for later, done, don't run again)
  - p3\_generate\_cluster.m
  - p4\_match\_area\_to\_cluter.m
  - p5\_testing.m
  - p6\_kmeans.m

## 6 Phase 6: Supermarket Experiment

- Location: \sugar\cluster\supermarket\_exp
- Supermarket layout: supermarket.skp
- Data:
  - Raw Data: \sugar\cluster\supermarket\_exp\step3\raw\_data\
  - Complete Data and Documentation: \sugar\cluster\supermarket\_exp\step3\complete\_data\
- Fig:
  - Compass Direction
  - Clustering(path\_length = 10000)
  - Navigation
- Run:
  - p1\_collect\_readings.m (collecting data, done, don't run again)
  - p2\_data\_process.m (generate proper data structure for later, done, don't run again)
  - draw\_compass\_direction.m
  - p3\_generate\_cluster.m
  - p4\_testing.m
- Code for analysis: \sugar\cluster\supermarket\_exp\analysis
  - .m files:
    - \* angle\_convert.m : convert direction information into angle
    - \* dijkstra.m : Dijkstra Algorithm
    - \* direction\_convert.m : convert current reading into direction info based on the reading at that point
    - \* draw\_cluster.m : draw the clusters, should be updated with translucent style soon
    - \* draw\_compass\_direction.m : draw the magnetic field based on compass reading in supermarket

- \* `get_cluster_sig.m` : get the cluster which the signature belongs to, used to implemented by choosing the minimum eclidean distance, but with the using of sub-set in signature, we change it to use possibility also, but it does not work well with the later one, cannot select correct cluster often.
  - \* `get_next_point.m` : used in the "training part", when the training paths are generated, it will give out the next point in path, based on random walk and the data from supermarket.
  - \* `get_next_step.m` : used in the "testing part", when the guiding paths are generated, it will give out the next step location in navigation, based on guiding info and the data from supermarket.
  - \* `guide.m` : the main part of guiding
  - \* `is_blocked.m` : check whether if the path of current point and next point is blocked by environment.
  - \* `navigate.m` : called in `testing.m` for navigation from one point to another
  - \* `possibility.m` : give out the possibility of one ready belongs to certain cluster.
  - \* `valid_sig.m` : check whether the signature reading is valid and how many valid info is in one signature.
- .mat files:
- \* `2feet_grid.mat` : real supermarket readings, ranging with different anchors and compass reading at each point of the grid
  - \* `processed_data.mat` : the data processed from raw data.
  - \* `distribution_table.mat` : calculate the possibility of one reading belongs to the cluster with certain center
  - \* `environment_info.mat` : racks' edges info, for obstacle detection