Ranging result

Request

Type: q(request)

Src: 0

Dest: node

Data: NULL

Type: r(result)

Src: node

Dest: 0

Data: direction

Type: r(result)

Src: node

Dest: 0

Data: direction

Type: q(request)

Src: 0

Dest: node

Data: NULL

AVR

ARM

NODE

Compass/ Range

Type: t(terminal)

Src: 0

Dest: anchor/node

Data: node/NULL

AVR

ARM

AVR

Matlab

ANCHOR

BASE