### Mathematical Foundations of Data Science Assignment 5

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Chang Dong (a1807402)

#### 1. Consider the following augmented matrix:

$$\begin{bmatrix} x-2 & 0 & 0 & 3 \\ 0 & x^2-4 & 0 & x+2 \\ 0 & 0 & 1 & 4 \end{bmatrix}$$

Determine the number of solutions to this system for all possible values of  $x \in R$ , giving justification.

Answer:

$$A = \begin{bmatrix} x - 2 & 0 & 0 \\ 0 & x^2 - 4 & 0 \\ 0 & 0 & 1 \end{bmatrix}, b = \begin{bmatrix} 3 \\ x + 2 \\ 4 \end{bmatrix}$$

#### 1). No solution (meet either case):

#### Case 1:

when 
$$x - 2 = 0$$
, so  $x = 2$ , because  $0 \cdot x_1 \neq 3$ 

#### Case 2:

when 
$$x^2-4=0$$
, while  $x+2\neq 0$  , so  $x=2$  , because  $0\cdot x_2\neq x+2$ , where  $x+2\neq 0$ 

Thus, in all case, if x = 2, that can make this equation **no solution** 

#### 2). Have solution (meet all condition):

#### **Condition 1:**

when 
$$x - 2 \neq 0$$
, so  $x \neq 2$ 

Condition 2 (meet either case):

Case 1: when 
$$x^2 - 4 = 0$$
, while  $x + 2 = 0$ , so  $x = -2$ 

Case 2: or when 
$$x^2 - 4 \neq 0$$
, while  $x + 2 \neq 0$ , so  $x \neq \pm 2$ 

Thus, in condition 2,  $x \neq 2$ 

Thus, in all case, if  $x \neq 2$ , that can make this equation have solution

**Solution Set** 
$$(x_1, x_2, x_3) = \left[\frac{3}{x-2}, \frac{1}{x-2}, 4\right]^T$$
, when  $x \neq \pm 2$ 

**Solution Set** 
$$(x_1, x_2, x_3) = [\frac{3}{x-2}, t, 4]^T$$
,  $\forall t \in R$ , when  $x = -2$ 

# 2. Let $K = \begin{bmatrix} 2 & a & 1 \\ 0 & 1 & 1/a \\ 1 & 1 & 0 \end{bmatrix}$ for some $a \neq 0$ . Use row reduction to find $K^{-1}$ , showing all details of your row operations.

*Note:*  $E_{ij}(k)$  *is the math symbol refers to Elementary Row Transformation.* 

 $E_{ij}$ : Exchange two rows.

 $E_i(k)$ : Let row i times k.

 $E_{ij}(k)$ : Let k times row j add to row i.

Answer:

$$[K \mid I] = \begin{bmatrix} 2 & a & 1 & 1 & 0 & 0 \\ 0 & 1 & \frac{1}{a} & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{E_{13}} \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & \frac{1}{a} & 0 & 1 & 0 \\ 2 & a & 1 & 1 & 0 & 0 \end{bmatrix} \xrightarrow{E_{31}(-2)}$$

$$\left[\begin{array}{ccc|cccc}
1 & 1 & 0 & 0 & 0 & 1 \\
0 & 1 & \frac{1}{a} & 0 & 1 & 0 \\
0 & a-2 & 1 & 1 & 0 & -2
\end{array}\right]$$

$$\begin{bmatrix} 1 & 0 & 0 & \frac{1}{2} & -\frac{a}{2} & 0 \\ 0 & 1 & 0 & -\frac{1}{2} & \frac{a}{2} & 1 \\ 0 & 0 & 1 & \frac{a}{2} & -\frac{a^{2}}{2} + a & -a \end{bmatrix} = [I|K^{-1}]$$

Thus, 
$$K^{-1} = \begin{bmatrix} \frac{1}{2} & -\frac{a}{2} & 0\\ -\frac{1}{2} & \frac{a}{2} & 1\\ \frac{a}{2} & -\frac{a^2}{2} + a & -a \end{bmatrix}$$

#### 3. Consider the vectors

$$v_1 = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \ v_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \ v_1 = \begin{bmatrix} -1 \\ 3 \\ k \end{bmatrix}$$

(a) By solving  $c_1v_1 + c_2v_2 + c_3v_3 = 0$ , determine the unique value k for which  $\{v_1, v_2, v_3\}$  is a linearly dependent set.

Answer:

We can use **Row Echelon Form(REF)** to determine the **Rank** of  $[v_1, v_2, v_3] < 3$ , that make  $v_1, v_2, v_3$  are linearly dependent.

$$[v_1, v_2, v_3] = \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 3 \\ 2 & 0 & k \end{bmatrix} \xrightarrow{E_{31}(-2)} \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 3 \\ 0 & -2 & k+2 \end{bmatrix} \xrightarrow{E_{32}(2)} \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 3 \\ 0 & 0 & k+8 \end{bmatrix}$$

We don't need to use **Elementary Row Operations** to make the matrix into the **RREF**, just making **REF** like this is enough to determine the **Rank** of this matrix.

So we can draw the conclusion that when k = -8, the **Rank** of this matrix must < 3, which makes  $\{v_1, v_2, v_3\}$  is a linearly dependent set.

#### (b) For the value of k above, write one of the vectors as a linear combination of the others.

Answer:

From 3(a) we know that:

$$\{v_1, v_2, v_3\} = \{ \begin{bmatrix} 1\\0\\2 \end{bmatrix}, \begin{bmatrix} 1\\1\\0 \end{bmatrix}, \begin{bmatrix} -1\\3\\-8 \end{bmatrix} \}$$

We know that  $v_3 = k_1 \cdot v_1 + k_2 \cdot v_2$ , because  $v_i$  ( $\forall i \in \{1, 2, 3\}$ ) can be represented by the linear combination of the other vectors  $v_i$  and  $v_k$  ( $j, k \in \{1, 2, 3\}$ , and  $i \neq j \neq k$ )

So we have 
$$\begin{bmatrix} -1 \\ 3 \\ -8 \end{bmatrix} = \begin{bmatrix} k_1 \\ 0 \\ 2k_1 \end{bmatrix} + \begin{bmatrix} k_2 \\ k_2 \\ 0 \end{bmatrix} = \begin{bmatrix} k_1 + k_2 \\ k_2 \\ 2k_1 \end{bmatrix}$$

$$2k_1 = -8$$
,  $k_2 = 3$ ,  $k_1 + k_2 = -1$ 

So we have  $k_1 = -4$ ,  $k_2 = 3$ , that make  $v_3 = -4v_1 + 3v_2$ 

## **4.** Find the eigenvalues and eigenspaces of $A = \begin{bmatrix} 8 & 2 \\ -2 & 3 \end{bmatrix}$ , showing all working.

Answer:

We can solve this equation  $|\lambda I - A| = 0$  to find the eigenvalues  $\lambda_i$  of A

$$|\lambda I - A| = \det \begin{bmatrix} \lambda - 8 & -2 \\ 2 & \lambda - 3 \end{bmatrix} = 0$$

$$(\lambda - 8)(\lambda - 3) + 4 = \lambda^2 - 11\lambda + 28 = (\lambda - 4)(\lambda - 7) = 0$$

So **eigenvalues** of A are  $\lambda_1 = 4$  and  $\lambda_2 = 7$ 

when 
$$\lambda = 4$$
,  $[\lambda I - A] = \begin{bmatrix} -4 & -2 \\ 2 & 1 \end{bmatrix} \xrightarrow{E_{12}(2)} \begin{bmatrix} 0 & 0 \\ 2 & 1 \end{bmatrix}$ , so  $2x_1 + x_2 = 0$ , eigenvector  $v_1 = (x_1, x_2) = [t, -2t]^T$ ,  $t \in R$ 

when  $\lambda = 7$ ,  $[\lambda I - A] = \begin{bmatrix} -1 & -2 \\ 2 & 4 \end{bmatrix} \xrightarrow{E_{21}(2)} \begin{bmatrix} -1 & -2 \\ 0 & 0 \end{bmatrix}$ , so  $-x_1 - 2x_2 = 0$ , eigenvector  $v_2 = (x_1, x_2) = [2t, -t]^T$ ,  $t \in R$ 

In summary, the eigenvalues  $\lambda = 4$  correspondes to the eigenspace  $E_4 = \{\begin{bmatrix} 1 \\ -2 \end{bmatrix} t | t \in R \}$ , and the eigenvalues  $\lambda = 7$  correspondes to the eigenspace  $E_7 = \{\begin{bmatrix} 2 \\ -1 \end{bmatrix} t | t \in R \}$