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16th Workshop on Compiler-Driven Performance November 8, 2017

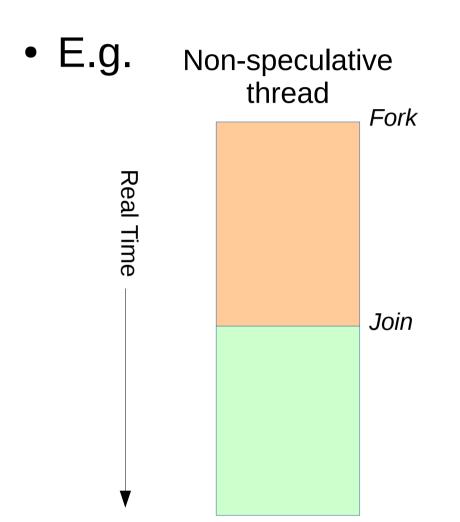
Credits

- Christopher J.F. Pickett, PhD
 - Java (SableSpMT), MLS, RVP
- Zhen Cao, PhD
 - C/C++/Fortran (MUTLS), opts
- MSc: Alexander Krolik, Haiying Xu
- IBM: Allan Kielstra
- Dozens of other TLS & TLS-related projects around the world!!

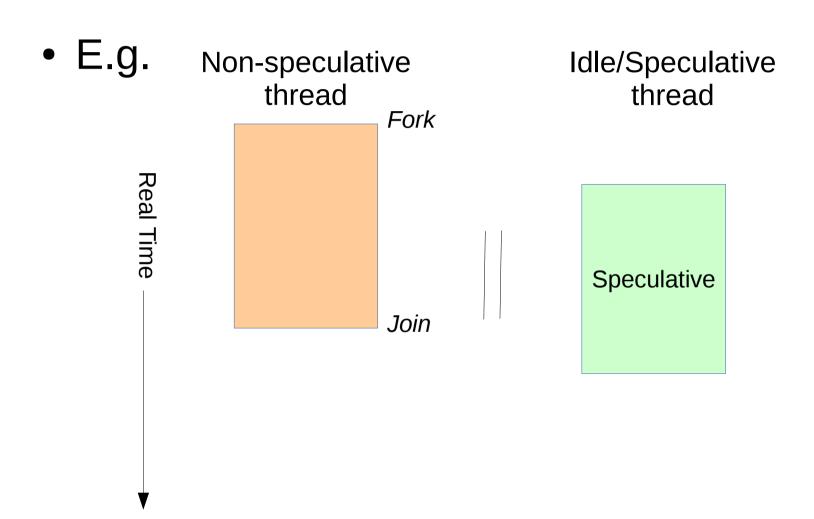
- Runtime optimization for sequential progs
- Use otherwise idle cores (threads)
- Fork (spawn) threads to execute in the future
- New threads start at the *Join* point
 - Code between Fork-Join, and after Join executed in parallel

• E.g. Non-speculative thread Real Time

Idle/Speculative thread

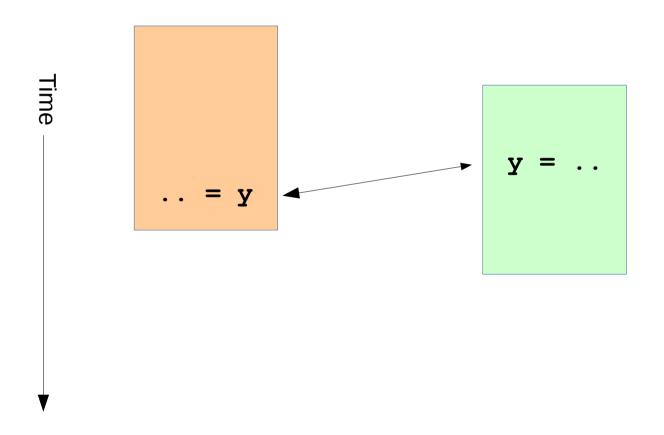


Idle/Speculative thread

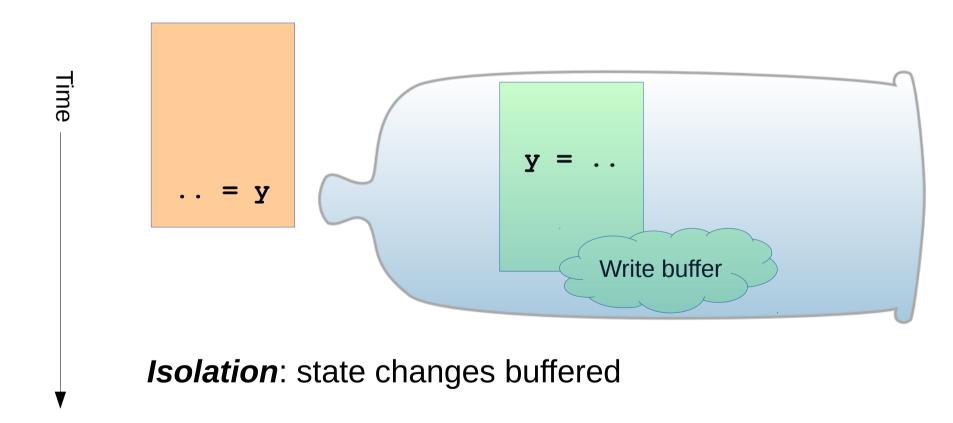


- Speculation
 - Not sure of program state (data) in the future
 - Not sure of exact control flow in the future
- Safety required!
 - Guarantee equivalence to sequential execution

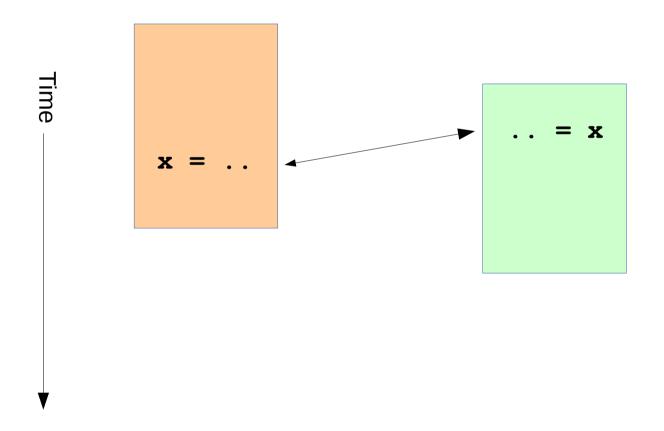
Safety: future should not affect the past



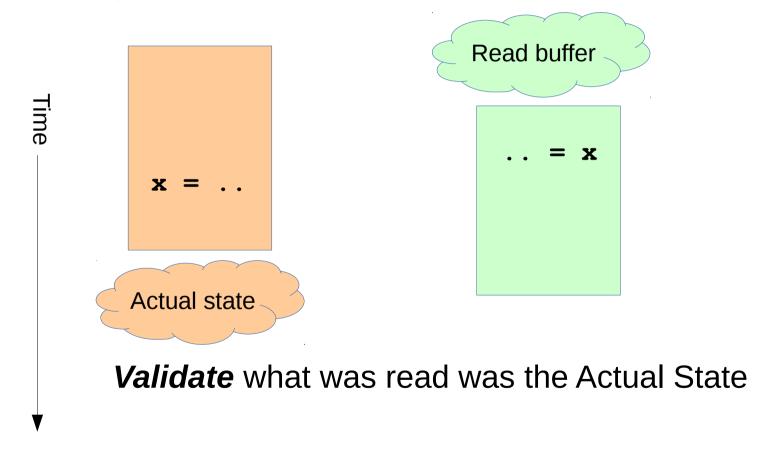
Safety: future should not affect the past



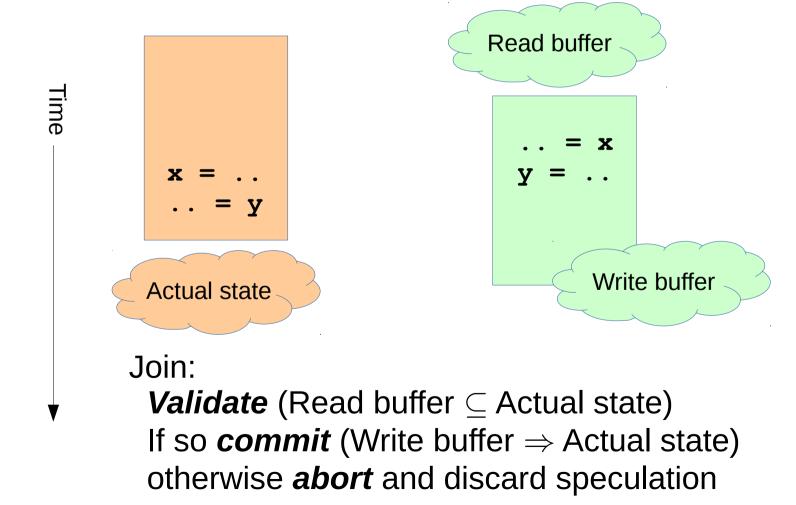
Safety: past should affect the future



Safety: past should affect the future



Both



Performance Factors

- Overhead in each step
 - Hardware support helps!
- Misspeculation (abort) is bad
 - Reduces parallelism
 - Wastes time

Design

- Various designs since 1990s [Franklin, "Multiscalar" 1993]
 - Mainly hardware [Jrpm, STAMPede, Mitosis, ...]
 - But some software
- Differ in opts, assumptions, benchmarks
 - Research focus on misspeculation, overhead

Comparison obscured by design choices

Choices, Choices, Choices

Speculative Targets

Thread Model

Versioning Model

Performance Model

Speculative Targets

- Core constraint
 - Fork > join
- Natural program divisions
 - Methods
 - Loop bodies
- Arbitrary
- (All equivalent via code-transformation)

- Suitable for method-rich contexts
 - OO programs
 - Java: [Chen & Olukuton, 1998]
- Fork: call-site
- Join: continuation

```
foo();
foo() {
    ...
}
```

- Suitable for method-rich contexts
 - OO programs
 - Java: [Chen & Olukuton, 1998]
- Fork: call-site
- Join: continuation

- Drawbacks
 - Method returns?

Return Value Prediction

Guess the return value!

- Consider history, simple patterns, partial state
 - Can be surprisingly accurate
- Predicting is key to MLS [Hu, Bhargava, John, 2003]

- Lots of work done in loops
 - Scientific programs, C/Fortran
- Fork: loop iteration entry
- Join: loop iteration end (start of next)

- Lots of work done in loops
 - Scientific programs
- Fork: loop iteration entry
- Join: loop iteration end
- Drawbacks
 - Loop-carried dependencies

Choices, Choices, Choices



Thread Model

- More than 1 speculative thread
- Which thread(s) can speculate?
 - Speculative or non-speculative or both
- How many children?

```
foo() {
    ...
    bar()
    ...
}
```

```
bar() {
    ...
    ping()
    ...
}
```

```
ping() {
...
}
```

```
foo() {
```

```
bar() {
    ...
    ping()
    ...
}
```

```
ping() {
...
}
```

```
foo() {
```

```
foo() {
    ...
    bar()
S1    ...
}
```

```
ping() {
...
}
```

```
foo() {
    ...
    bar()
S1    ...
}
```

```
ping() {
...
}
```

```
foo() {
    ...
    bar()
S1 ② ...
}
```

```
bar() {
    ...
    ping()
S2    ...
}
```

```
foo() {
    ...
    bar()
S1 ② ...
}
```

```
bar() {
...
ping()
s2 ...
}
```

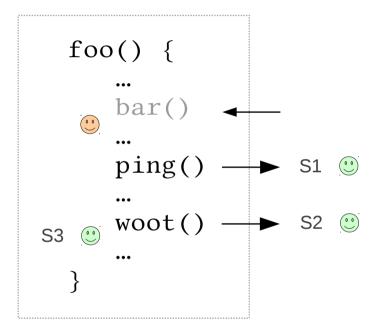
```
ping() {
...
}
```

```
foo() {
...
bar()
S1 ...
}
```

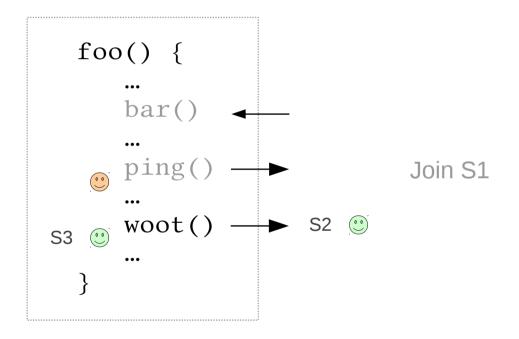
```
bar() {
    ...
    ping()
s2 **\omega**...
}
```

```
ping() {
...
}
```

```
foo() {
    ...
    bar()
    ...
    ping()
    ...
    woot()
    ...
}
```

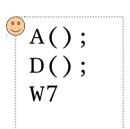


```
foo() {
...
bar()
...
ping() → □ Join S1
...
s3 ② woot() → S2 ②
...
}
```

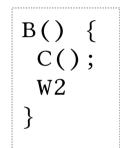


```
foo() {
    ...
    bar()
    ...
    ping() → Join S1
    ...
    woot() → S2 ② Join S2
    ...
}
```





```
A() {
B();
W3
}
```

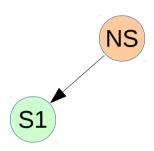


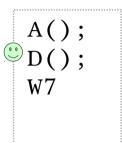
```
C() {
  W1
}
```

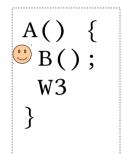
```
D() {
   E();
   W6
}
```

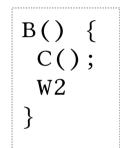
```
E() {
 F();
 W5
}
```

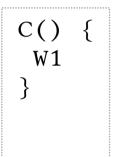
```
F() {
    W4
}
```







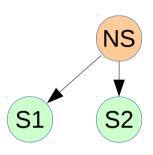


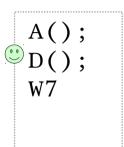


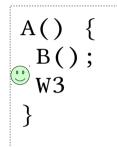
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    W6
}
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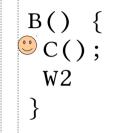
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 W5
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```

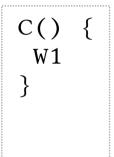
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F() {
    W4
}
```







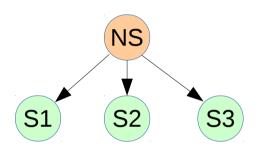


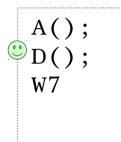


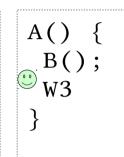
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    W6
}
```

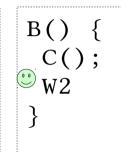
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 W5
}
```

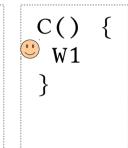
```
F() {
    W4
  }
```







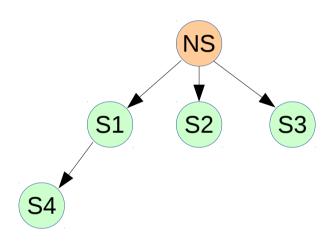


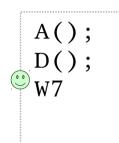


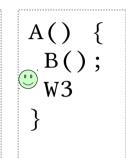
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   W6
}
```

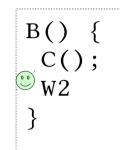
```
E() {
 F();
 W5
}
```

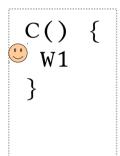
```
F() {
    W4
}
```



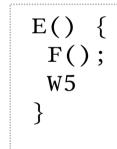




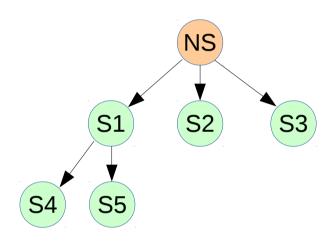


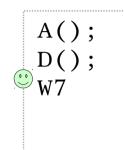


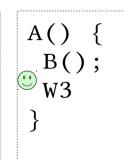
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W6
}
```

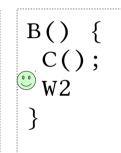


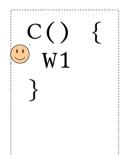
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F() {
W4
}
```



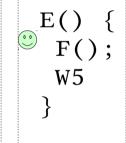




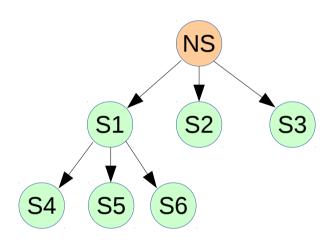


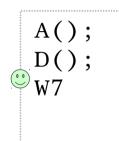


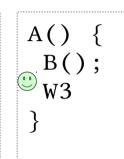
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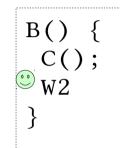


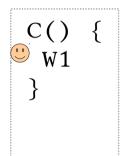
```
F() {
    W4
}
```



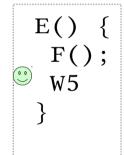


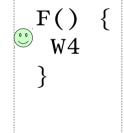






```
D() {
    E();
    W6
}
```





 Mixed A(); NS W1 S2 S3 W4 **S1** W2 W3 D() { F(); S5 S6 W7 W6 W5

Out-of-order

e.g., early SableSpMT

Non-spec allowed n children, spec not allowed

In-order

e.g., SpLSC/SpLIP, BOP

Everyone allowed 1 child

Mixed

e.g., MUTLS

- Everyone allowed n children
 - Immediate children out-of-order

(Anti-)Synergy with where to speculate

```
for (...) {
    ...
}

for (...) {
    ...
}

for (...) {
    ...
}
```

Out-of-order limits speedup to 2

(Anti-)Synergy with where to speculate

Out-of-order limits speedup to 2

• (Anti-)Synergy with where to speculate

```
foo() {
    if (..)
    foo()
    work
}
```

Head-recursion & in-order

• (Anti-)Synergy with where to speculate

```
foo() {
   if (..)
   foo() {
   if (..)
   foo()
   work
   work
}
```

Head-recursion & in-order

(Anti-)Synergy with where to speculate

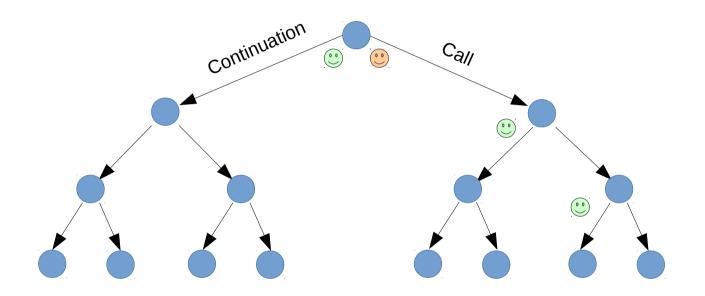
```
foo() {
    work
    if (..)
    foo()
}
```

Tail-recursion & out-of-order

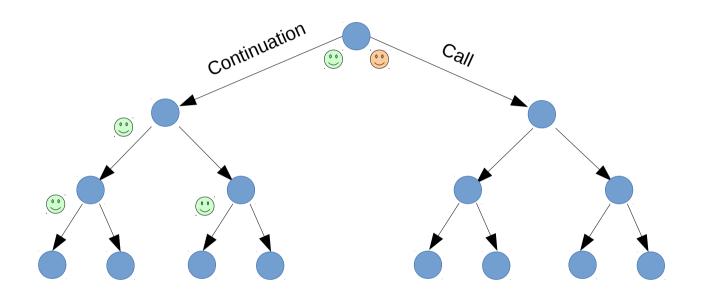
• (Anti-)Synergy with where to speculate

```
foo() {
    work
    if (..)
    foo()
    foo()
}
```

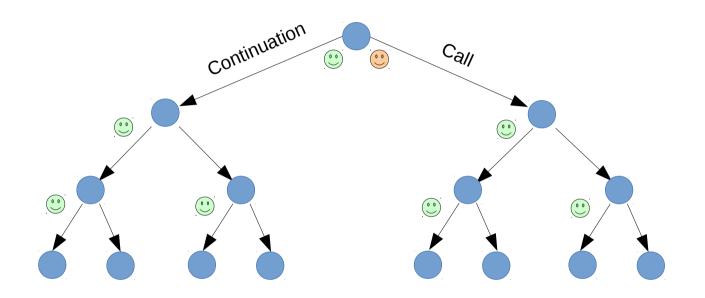
Tail-recursion & out-of-order



Out-of-Order



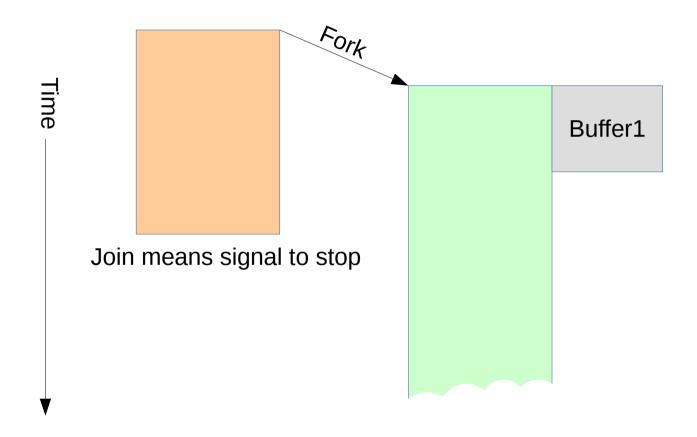
In-Order



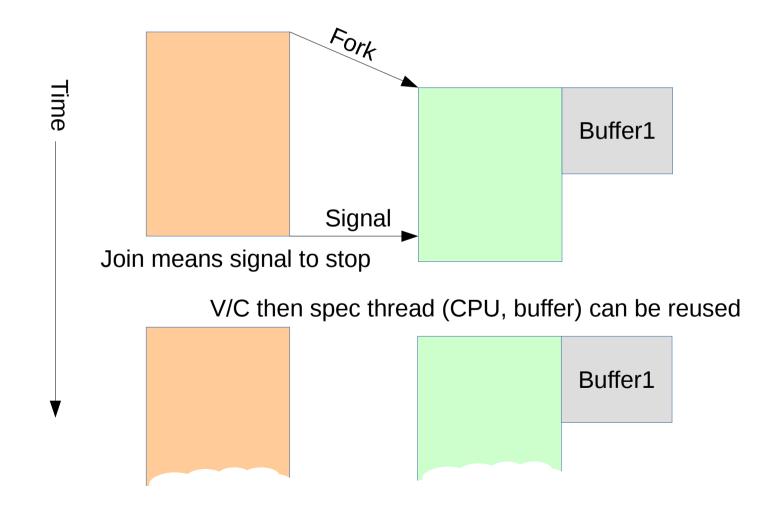
Thread Model

- Spec threads execute until joined
- Spec threads managed by non-spec
 - Resources recycled after join

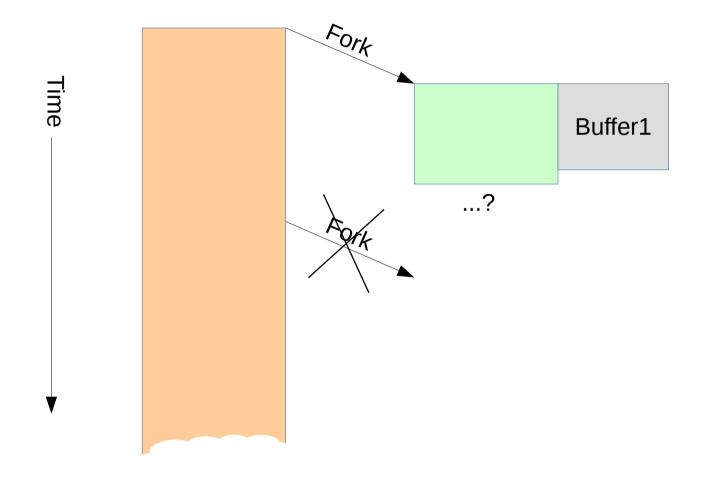
Joining implies reusability



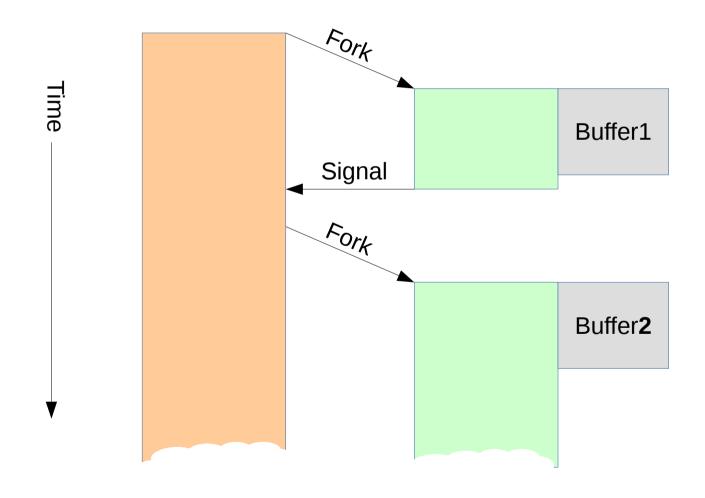
Joining implies reusability



• Spec thread is short - idle



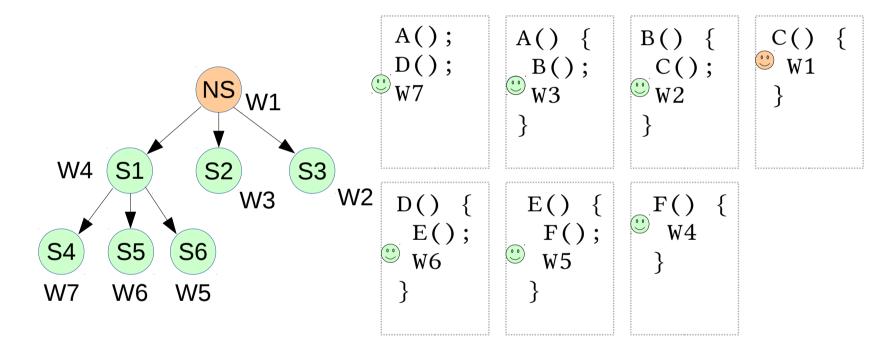
Let spec thread declare itself reusable

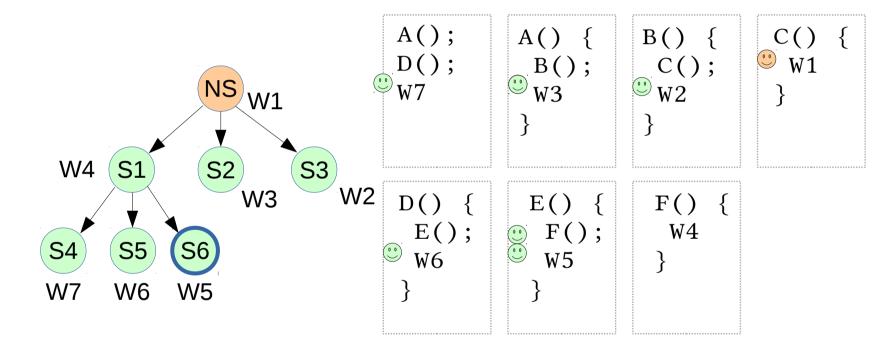


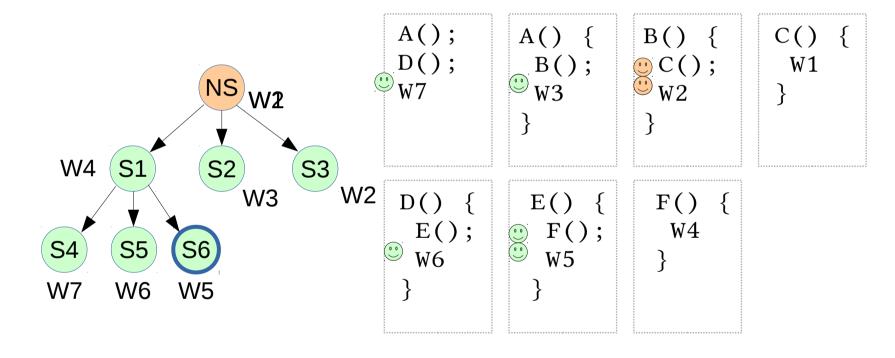
- Threads repurposed before join
 - More threads available for later spec
- More complicated buffer mgmt
 - More than 1 buffer per thread

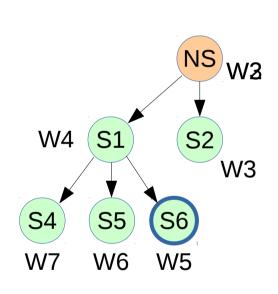
Thread Model

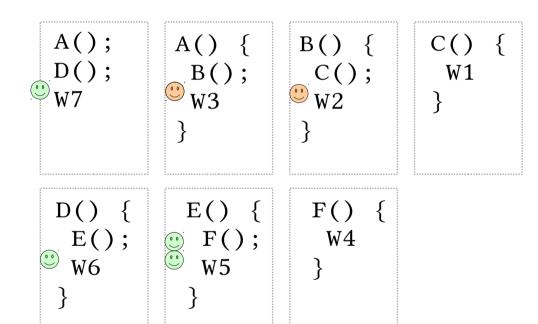
- In-order, mixed => nested speculation
 - Degrees/levels of speculation
- Commit design choices
 - Who can join with whom



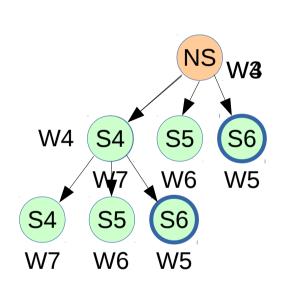


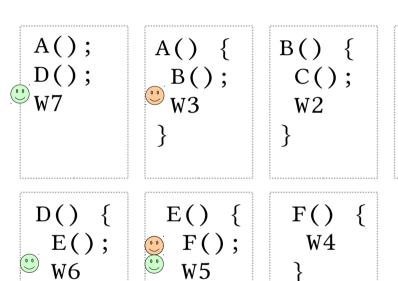






Sequential commit





C() {

W1

- Sequential commit simplifies buffer mgmt
 - Always copy from spec buffer to main memory
 - Commit must precede buffer reuse
- Non-seq commit
 - More complex
 - merged validation reqs
 - buffer size may grow with each commit
 - extra sync (spec/spec as well as non-spec/spec)

Choices, Choices, Choices

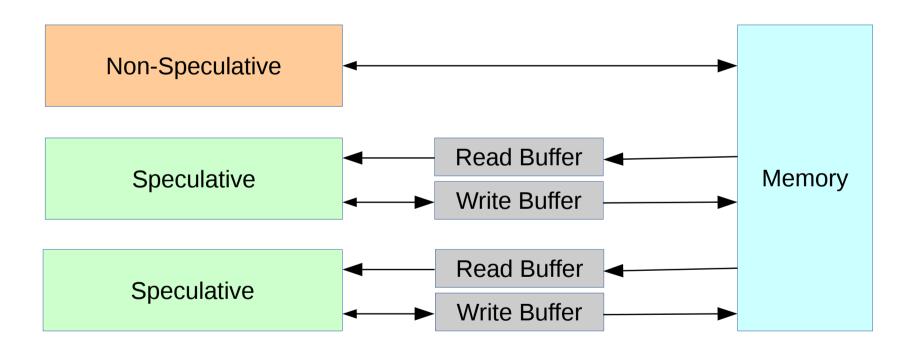


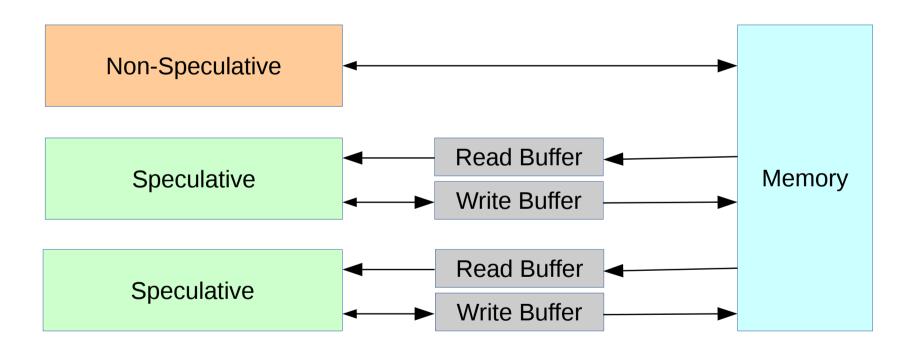
Version Control

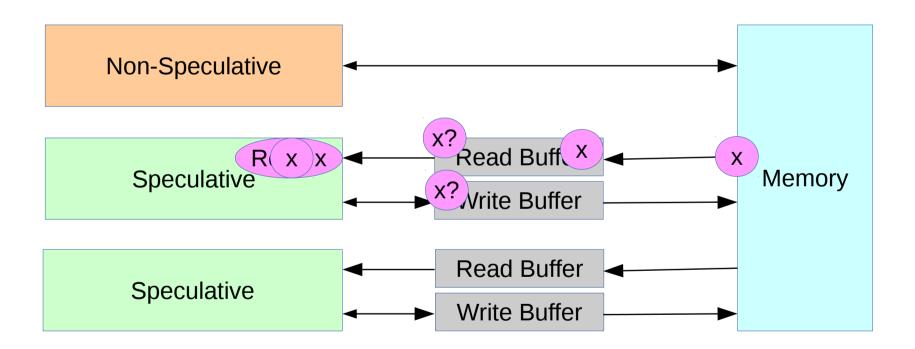
Multiple ways we can ensure state correctness

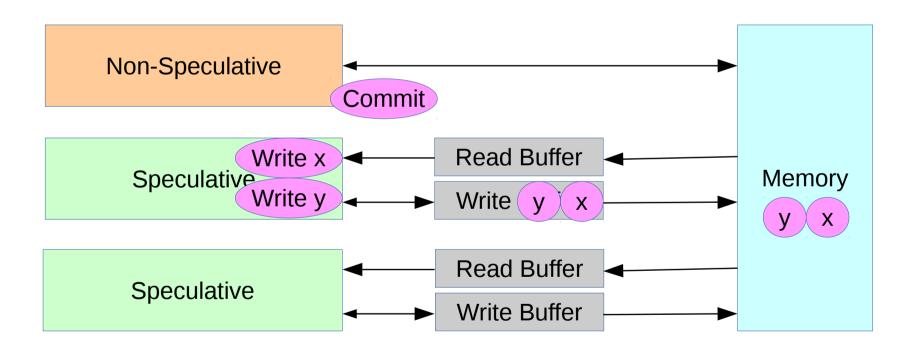
- Lazy scheme
 - Validation checks for RAW violations
 - Spec maintains a read buffer
 - Reading a stale value is detected
 - Isolation obviates WAR and WAW worries
 - Spec maintains a write buffer
 - Writes from the future postponed until ready

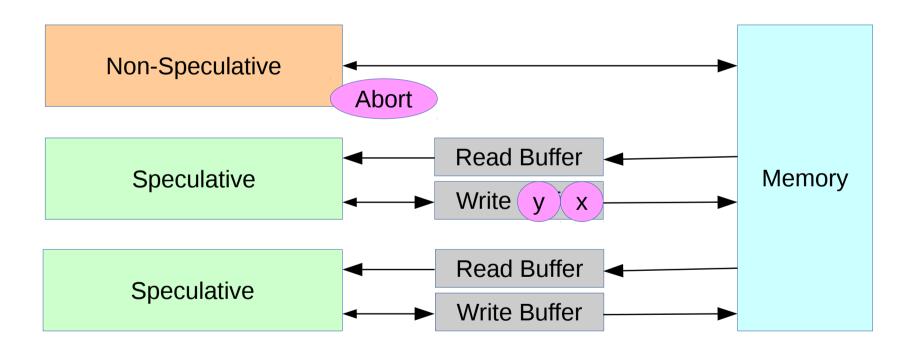
e.g., SableSpMT, SpLSC, Lector









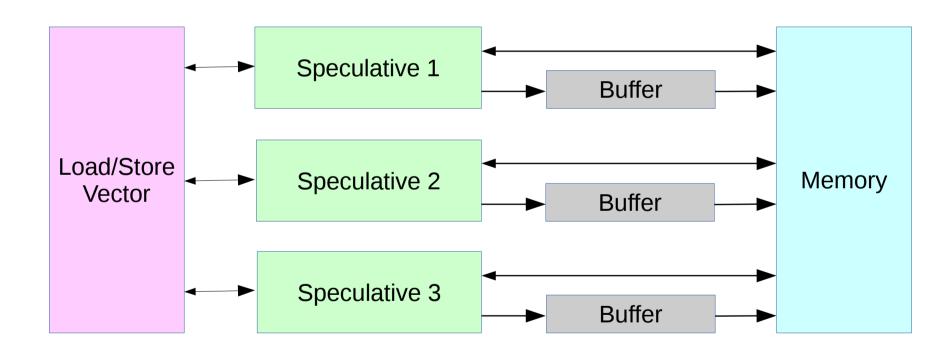


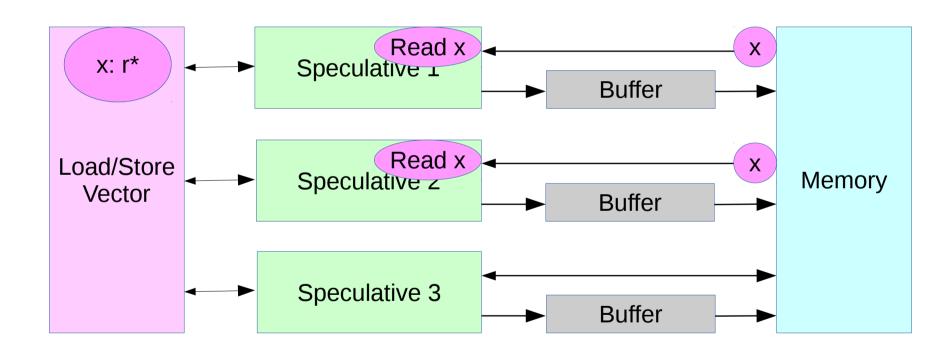
Version Control

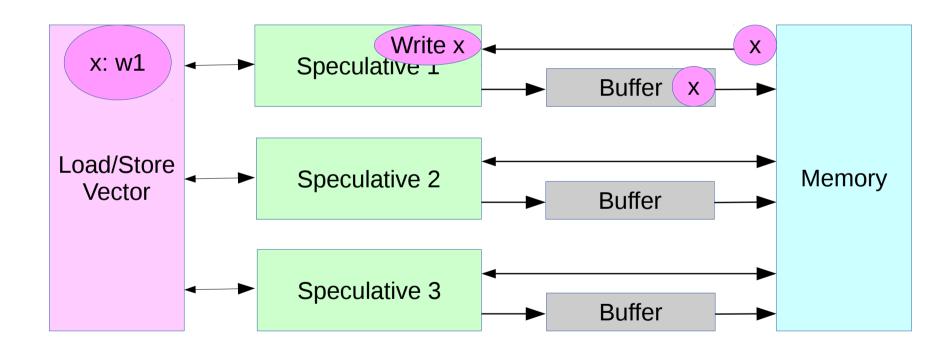
- Lazy
 - Abort is cheap
 - Validation/Commit is expensive
 - Big buffers, lots of memory traffic
- Spec should be likely to succeed
 - We are avoiding misspeculation
 - Better would be
 - Abort is expensive
 - Validation/Commit is cheap

Version Control

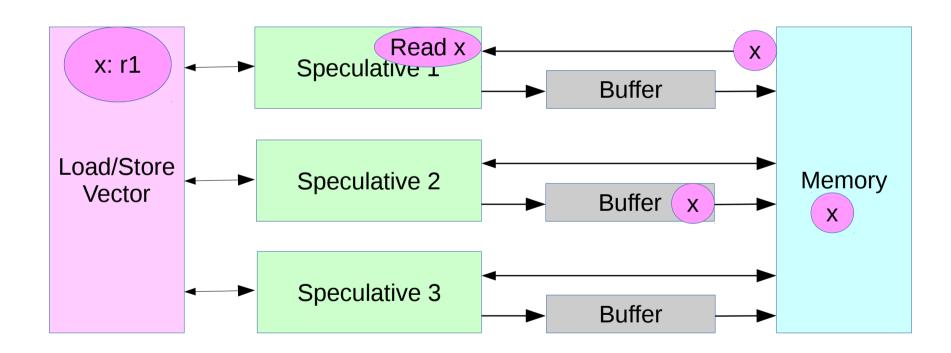
- *Eager* scheme
 - Threads write to memory directly
 - Maintain a shadow/prior-version buffer for undo
 - No privileged non-spec
- Eager avoids commit overhead
 - Trades for more expensive undo
 - More complex version management





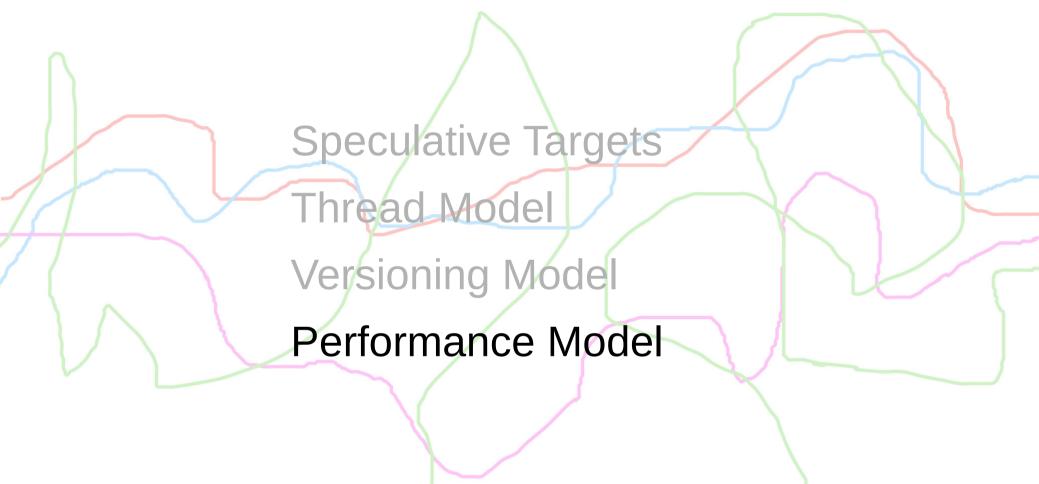


- Load/Store vector tracks current version
 - Who wrote, who read
 - Thread id's for order decisions
- RAW error
 - Writer rolls back reader(s)
- WAR
 - Reader rolls back writer
- WAW
 - Writer rolls back previous writer



- V/C amortized, effectively parallelized
- Drawbacks
 - Version checks
 - Sensitive to WAR and WAW errors
 - Rollback much more complicated
- No progress guarantee

Choices, Choices, Choices



Performance Model

- Resource limitations another concern
 - Forward-dependence in fork choices

```
foo() {
    ping();
    woot();
}
bar();
```

```
foo() {
    ping();
    woot();
}
bar();
```

Is (foo || bar) better than (ping || woot)?

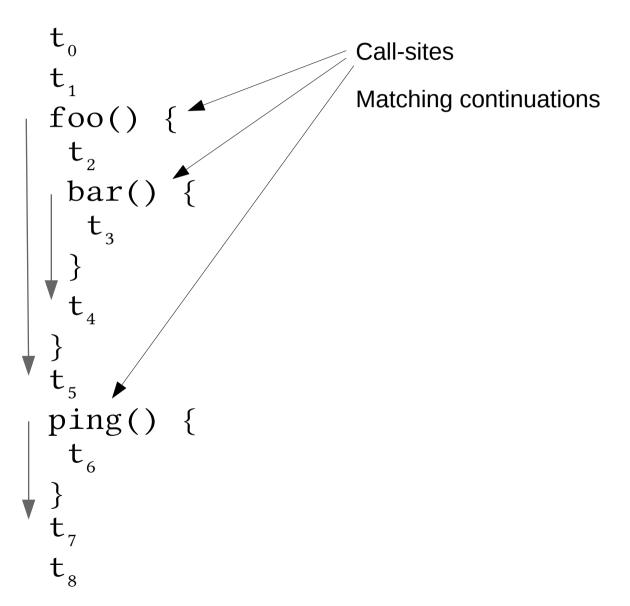
Performance Model

- Can we determine potential benefit?
 - Toward an ahead-of-time model
- Data dependencies unknown
 - Assume best case
- Dynamic control flow unknown
 - Start with traces (post-facto)

```
foo() {
 bar() {
ping() {
```

```
Sequential code chunks
foo(
 bar(
ping() {
```

```
Call-sites
foo()
 \mathsf{t}_{_2}
 bar()
    t_3
ping() {
t_8
```



```
foo() {
 bar() {
ping() {
```

We have n>0 threads

Each call-site implies a fork choice

Split trace into pieces

Call, continuation

How many threads?

In-order: call (1), cont (n-1)
Out-of-order: call(n-1), cont(1)

Mixed: call(m), cont(n-m) over 0<m<n

Post-join: where do we pick up again?

How far did spec get before joining? How far can we get before joining?

```
foo() {
 bar() {
ping() {
```

```
foo() {
 bar() {
ping() {
```

```
foo() {
    bar() {
   ping() {
```

Determine how long the call takes

```
foo() {
    bar() {
   ping() {
```

Determine how long the call takes

```
foo() {
 → bar() {
   ping() {
```

Determine how long the call takes

Recursively process body

```
foo() {
 -> bar() {
  -> t<sub>3</sub>
    ping() {
```

Determine how long the call takes

Recursively process body

```
foo() {
    bar() {
   ping() {
```

Determine how long the call takes

Recursively process body

```
foo() {
 bar() {
ping() {
```

Determine how long the call takes

Recursively process body

```
foo() {
 bar() {
ping() {
```

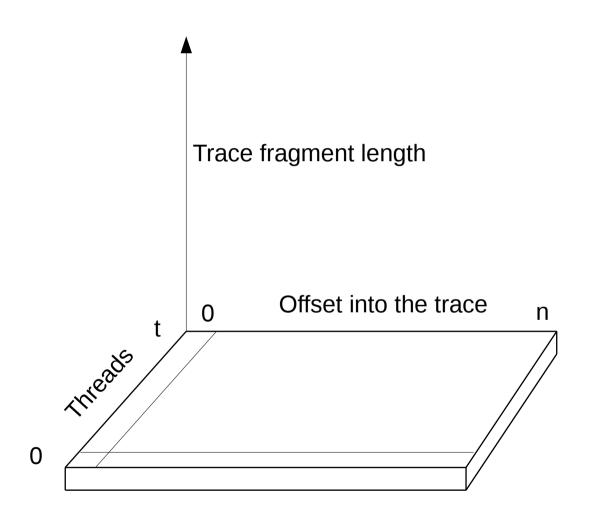
Total time: 6

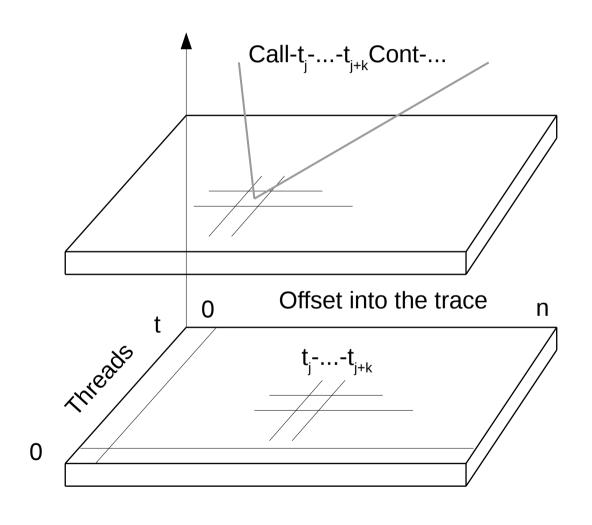
- Full model considers all partitionings of
 - T = S;(A|B);C
 - A,B,C recursively parallelized
- Misspeculation, ...
- Expensive!
 - Based on finding all possible traces (timings)

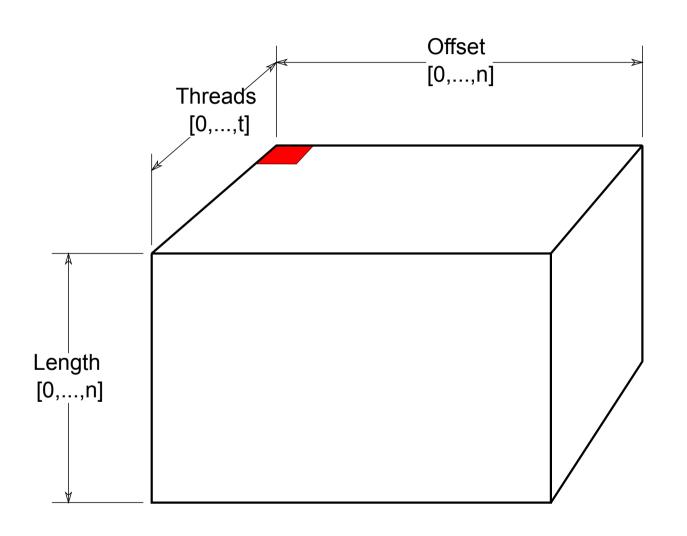
- Only interested in best-possible perf
- Lots of recursive calculations

- Dynamic programming model helps
 - Break down into a merge of smaller problems

- Processing a partial trace from an offset
 - $T = t_i...t_i$
- Find best performance given a thread budget
- Recursive:
 - Make a step, reduce to a small trace
 - Look at memoized perf of smaller traces
- Base case: each trace unit does 1 work







- Limitations
 - Trace-based
 - Unit work size
 - Loop-speculation?
 - Represent cyclic properties?
- Most interesting for showing it is possible

Conclusion

- Plenty of room for component optimizations
- But also major design choices
- Different progs respond differently
 - Adaptive, hybrid forms
- Modelling an interesting direction

Thank You for Listening

