Subject parameter distribution:		rawPCov_2_1 rawPCov_2_2 rawPCov_3_2 rawPCov_4_2 rawPCov_5_2	rawPCov_3.1 rawPCov_3.2 rawPCov_3.3 rawPCov_4.3 rawPCov_5.3	rawPCov_4.1 rawPCov_4.2 rawPCov_4.3 rawPCov_4.4 rawPCov_5.4	rawPCov_5_1 rawPCov_5_2 rawPCov_5_3 rawPCov_5_4 rawPCov_5_5]
Initial latent state:	$\underbrace{\begin{bmatrix} \text{eta1} \\ \text{eta2} \end{bmatrix} (t_0)}_{\boldsymbol{\eta}(t_0)} \sim \text{N} \underbrace{\begin{bmatrix} \text{T0m_eta1} \\ \text{T0m_eta2} \end{bmatrix}}_{\text{T0MEANS}}, \underbrace{UcorSDtoCov} \left\{ \begin{bmatrix} 0.001 & 0 \\ 0 & 0.001 \end{bmatrix} \right\}}_{\text{T0VAR}}$				
Deterministic change:	$\underbrace{\begin{bmatrix} \text{eta1} \\ \text{eta2} \end{bmatrix}(t)}_{\boldsymbol{\eta}(t)} = \underbrace{\begin{pmatrix} \text{drift_eta1} & \text{drift_eta1_eta2} \\ \text{drift_eta2_eta1} & \text{drift_eta2} \end{pmatrix}}_{\text{DRIFT}} \underbrace{\begin{bmatrix} \text{eta1} \\ \text{eta2} \end{bmatrix}(t)}_{\boldsymbol{\eta}(t-1)} + \underbrace{\begin{bmatrix} 0 \\ 0 \end{bmatrix}}_{\text{CINT}}$	+			
Random change:	$\underbrace{UcorSDtoChol\left\{\begin{bmatrix} \text{diff_eta1} & 0 \\ \text{diff_eta2_eta1} & \text{diff_eta2}\end{bmatrix}\right\}}_{\text{DIFFUSION}}\underbrace{\begin{bmatrix} W_1 \\ W_2 \end{bmatrix}(t)}_{\mathbf{W}(t)}$				
Observations:	$\underbrace{\begin{bmatrix} \text{Stress} \\ \text{Stress2} \\ \text{Quality} \end{bmatrix}}_{\mathbf{Y}(t)}(t) = \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 0 \\ \text{stressLoading} & 1 \end{bmatrix}}_{\text{LAMBDA}}\underbrace{\begin{bmatrix} \text{eta1} \\ \text{eta2} \end{bmatrix}}_{\boldsymbol{\eta}(t)}(t) + \underbrace{\begin{bmatrix} \text{mm_Stress} \\ \text{mm_Quality} \end{bmatrix}}_{\text{MANIFESTMEANS}} + \underbrace{\underbrace{\begin{matrix} \boldsymbol{\tau} \\ \boldsymbol{\tau} \\ \textbf{manifestmeans} \end{matrix}}_{\text{MANIFESTMEANS}}$				
Observation noise:	$\underbrace{\begin{bmatrix} \text{mvarStress} & 0 & 0 \\ 0 & \text{mvarStress2} & 0 \\ 0 & 0 & \text{mvarQuality} \end{bmatrix}}_{\text{MANIFESTVAR}} \underbrace{\begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \end{bmatrix}}_{\epsilon(t)}(t)$				
System noise	Observation noise	`			

Note: UcorSDtoChol converts lower tri matrix of standard deviations and unconstrained correlations to Cholesky factor, UcorSDtoCov = transposed cross product of UcorSDtoChol, to give covariance, See Driver & Voelkle (2018) p11. Individual specific notation (subscript i) only shown for subject parameter distribution – pop. means shown elsewhere.

Observation noise

distribution:

 $\left[\epsilon_{j\in[1,2]}\right](t)\sim N(0,1)$

distribution per time $[W_{j\in[1,2]}](t) \sim N(0,1)$

step: