$\underbrace{\left[\text{ly}\right]\left(t_{0}\right)}_{\boldsymbol{\eta}\left(t_{0}\right)} \sim \text{N} \left[\underbrace{\left[\text{T0m.ly}\right]}_{\boldsymbol{Q}}, \underbrace{\textit{UcorSDtoCov}\left\{\left[0.01\right]\right\}}_{\boldsymbol{Q^{*}}_{t0}}\right]$ latent state: Deterministic change:

 $\sim tform \left\{ N \left(\begin{bmatrix} raw_T0m_ly \\ raw_mm_y \end{bmatrix}, \begin{bmatrix} rawPCov_1_1 \\ rawPCov_2_1 \end{bmatrix} \right) \right\}$

Observations:
$$\underbrace{\left[\mathbf{y}\right](t)}_{\mathbf{Y}(t)} = \underbrace{\left[1\right]}_{\mathbf{\Lambda}} \underbrace{\left[\mathbf{l}\mathbf{y}\right](t)}_{\boldsymbol{\eta}(t)} + \underbrace{\left[\mathbf{mm}_{-}\mathbf{y}\right]}_{\boldsymbol{\tau}}$$

Observation noise:
$$\underbrace{\begin{bmatrix} 0.2 \end{bmatrix}}_{\Theta} \underbrace{\begin{bmatrix} \epsilon_1 \end{bmatrix}(t)}_{\epsilon(t)}$$

Subject

parameter distribution:

Initial

Random

change:

System noise Observation noise distribution per time $\Delta \big[W_{j \in [1,1]}\big](t-u) \sim \mathrm{N}(0,t-u)$ $[\epsilon_{i \in [1,1]}](t) \sim N(0,1)$ distribution: step:

 $\underbrace{UcorSDtoChol\left\{\left[\text{diff_ly}\right]\right\}}_{}\underline{d\left[W_{1}\right]\left(t\right)}$

Note: UcorSDtoChol converts lower tri matrix of standard deviations and unconstrained correlations to Cholesky factor, UcorSDtoCov = transposed cross product of UcorSDtoChol, to give covariance, See Driver & Voelkle (2018) p11.

Individual specific notation (subscript i) only shown for subject parameter distribution – pop. means shown elsewhere.