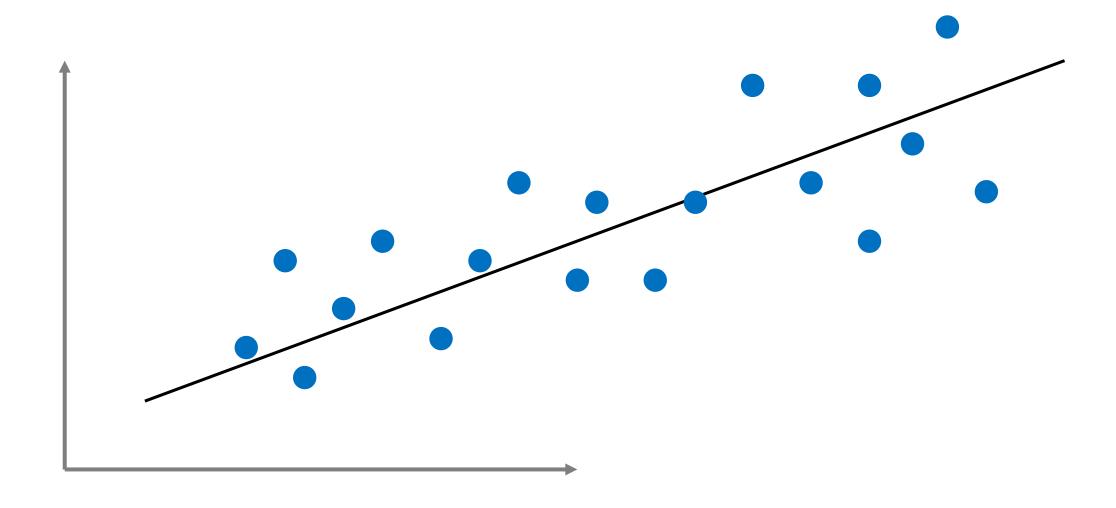
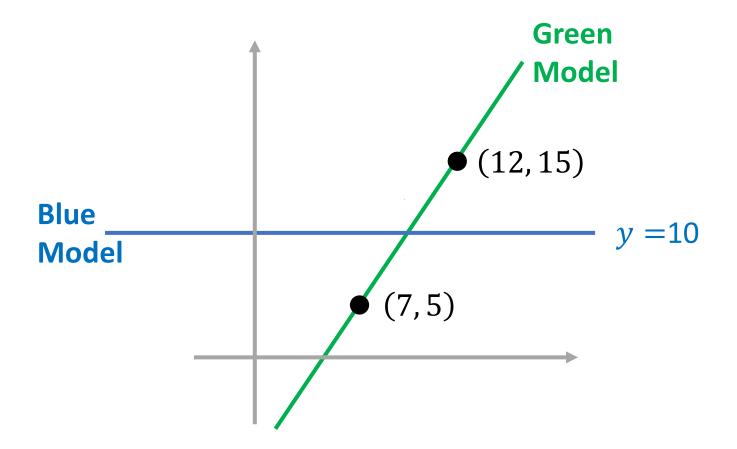
Linear models

Linear regression



Error definition



$$y_i = Instance$$

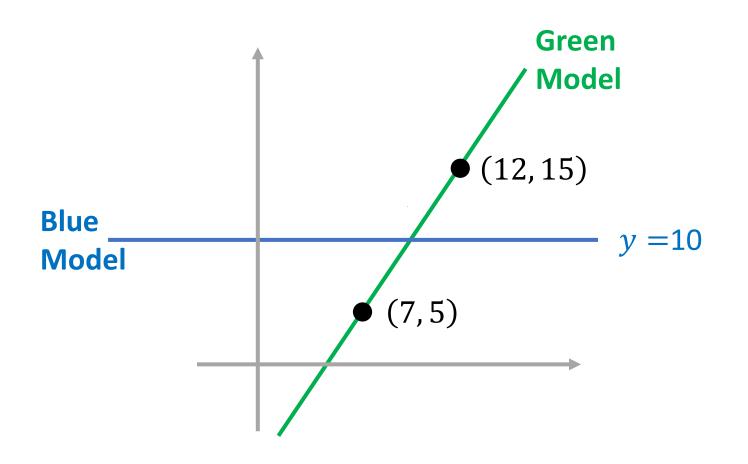
 $\hat{y}_i = Model$

$$\varepsilon \propto \hat{y}_i - y_i$$

$$\varepsilon = 0$$

$$\varepsilon = 0$$

Error definition



$$\varepsilon \propto \hat{y}_i - y_i$$

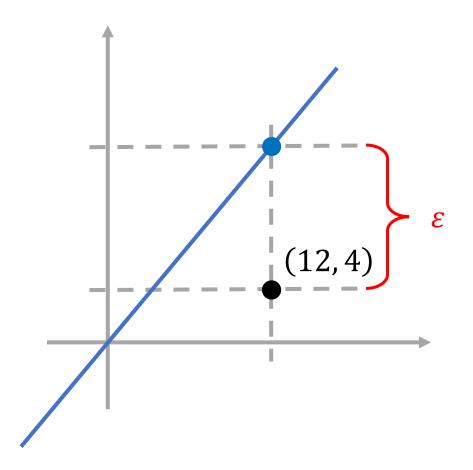
$$\varepsilon = 0$$

$$\varepsilon = 0$$

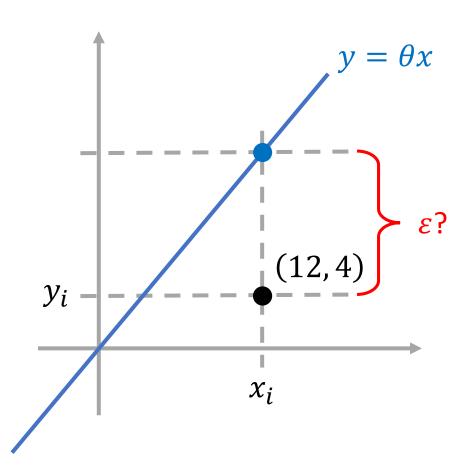
Solution:

$$\varepsilon \coloneqq \sum_{i=1}^{m} (\hat{y}_i - y_i)^2$$

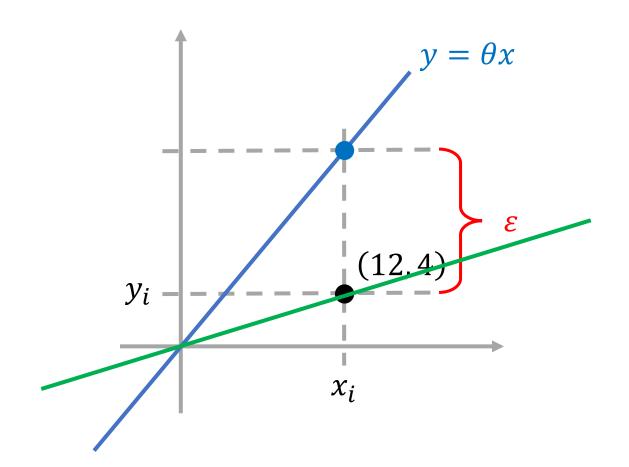
$$y = \theta x$$
 $m = 1$



$$y = \theta x$$
 $m = 1$



$$y = \theta x$$
 $m = 1$



$$\varepsilon = (y - 4)^2$$

$$= (12\theta - 4)^2$$

$$= (x_i\theta - y_i)^2$$

$$\frac{d\varepsilon}{d\theta} = 0 \qquad \Rightarrow \qquad \theta = 4/12 = y_i/x_i$$

$$\therefore y = \frac{4}{12}x$$

$$y = f(\theta)$$

$$\varepsilon = g(y) \Rightarrow \varepsilon = h(\theta)$$

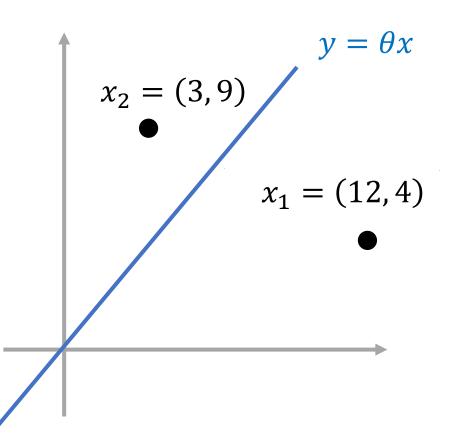
$$y = \theta x$$
 $m = 1$

 x_i

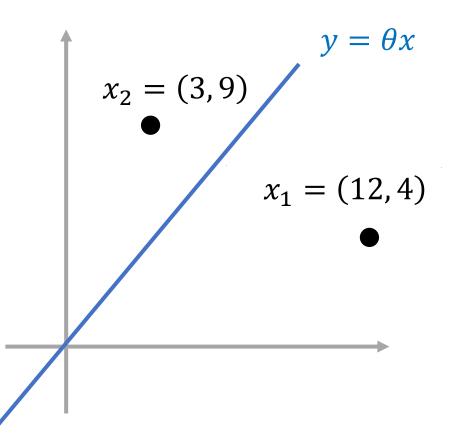
plt.show()

>_ Code $\therefore y = \frac{4}{12}x$

$$y = \theta x$$
 $m = 2$

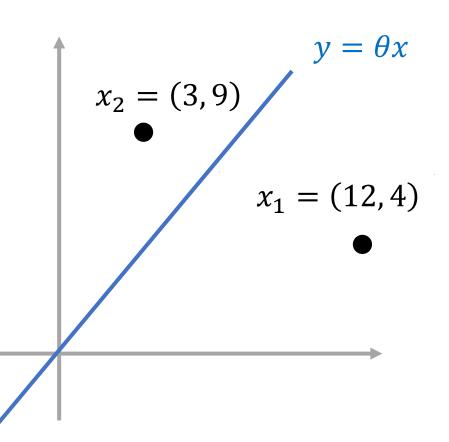


$y = \theta x$ m = 2



$$\varepsilon = (\theta x_1 - y_1)^2 + (\theta x_2 - y_2)^2$$

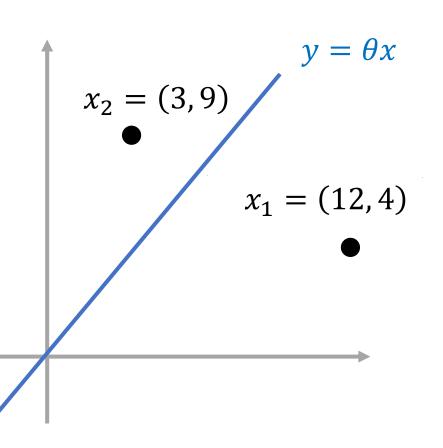
$y = \theta x$ m = 2



$$\varepsilon = (\theta x_1 - y_1)^2 + (\theta x_2 - y_2)^2$$

$$\frac{d\varepsilon}{d\theta} = 0 \quad \Rightarrow \quad \theta = \frac{x_1 y_1 + x_2 y_2}{x_1^2 + x_2^2}$$

$y = \theta x$ m = 2

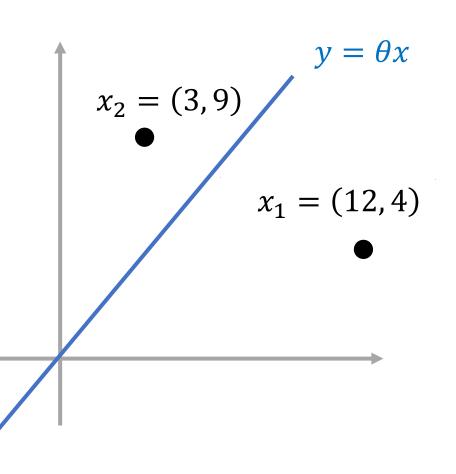


$$\varepsilon = (\theta x_1 - y_1)^2 + (\theta x_2 - y_2)^2$$

$$\frac{d\varepsilon}{d\theta} = 0 \quad \Rightarrow \quad \theta = \frac{x_1 y_1 + x_2 y_2}{x_1^2 + x_2^2}$$

Matrix form for fast vectorized computations

$$y = \theta x$$
 $m = 2$



$$\varepsilon = (\theta x_1 - y_1)^2 + (\theta x_2 - y_2)^2$$

$$\frac{d\varepsilon}{d\theta} = 0 \quad \Rightarrow \quad \theta = \frac{x_1 y_1 + x_2 y_2}{x_1^2 + x_2^2}$$

Matrix form for fast vectorized computations

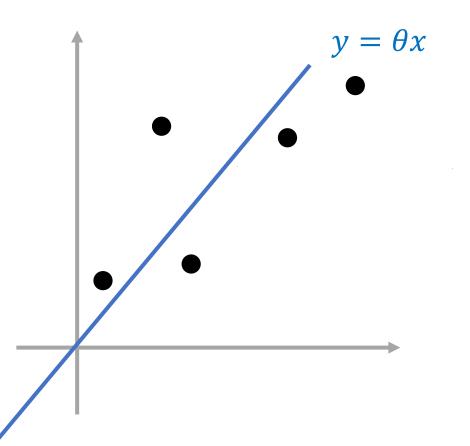
$$y = \theta x$$
 $m = 2$

$$\theta = \frac{(x_1, x_2)^T {y_1 \choose y_2}}{(x_1, x_2)^T {x_1 \choose x_2}} = x^T y / x^T x$$
>_ Code

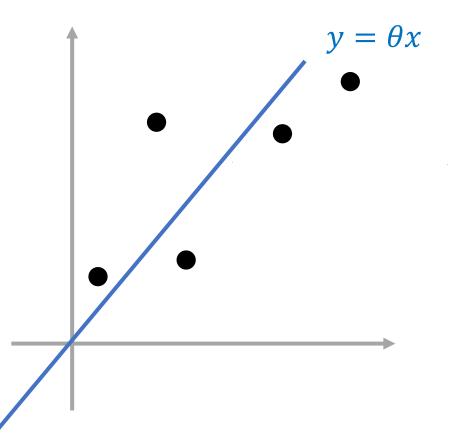
```
x_2 = (3, 9) /
               y = \theta x
```

```
import numpy as np
           import matplotlib.pyplot as plt
x_1 = (12,4)  xi = np.array([3, 12]) # data points o o o
            yi = np.array([9, 4])
            theta = sum(xi * yi) / sum(xi**2)
            plt.scatter(xi,yi)
            # model
            x = np.linspace(min(xi), max(xi), num = 5)
            y = theta * x
            plt.plot(x, y)
            plt.axis('equal')
            plt.show()
```

$$y = \theta x$$
 m

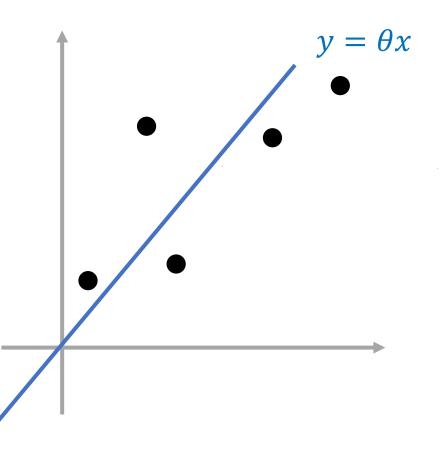


$$y = \theta x$$
 m



$$\varepsilon = (\theta x_1 - y_1)^2 + (\theta x_2 - y_2)^2 + (\theta x_m - y_m)^2$$

$$y = \theta x$$
 m



$$\varepsilon = (\theta x_1 - y_1)^2 + (\theta x_2 - y_2)^2 + (\theta x_m - y_m)^2$$

$$\frac{d\varepsilon}{d\theta} = 0 \quad \Rightarrow \quad \theta = \frac{\sum_{i=1}^{m} x_i y_i}{\sum_{i=1}^{m} x_i^2}$$

Matrix form for fast vectorized computations

$$\begin{pmatrix} \vdots \\ \vdots \\ \chi_m \end{pmatrix} \qquad \mathbf{y} \coloneqq \begin{pmatrix} \chi_1 \\ \vdots \\ \chi_m \end{pmatrix}$$

$$\Rightarrow \theta = x^T y / x^T x$$

Your turn

 $y = A\sin(x)$

