



Meetup

Structure and
Interpretation
of Computer
Programs

Second Edition



Harold Abelson and
Gerald Jay Sussman
with Julie Sussman

Structure and Interpretation of Computer Programs

Chapter 5.1

Before we start ...



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Chapter 5.1

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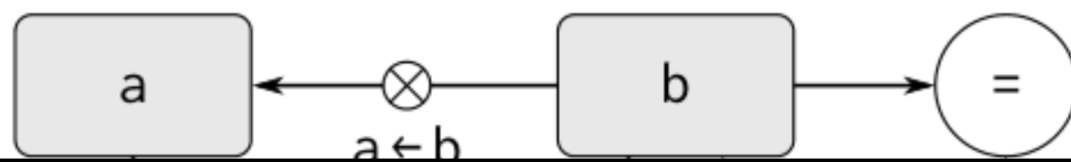
WE BEGAN THIS BOOK by studying processes and by describing processes in terms of procedures written in Lisp. To explain the meanings of these procedures, we used a succession of models of evaluation: the substitution model of **Chapter 1**, the environment model of **Chapter 3**, and the metacircular evaluator of **Chapter 4**. Our examination of the metacircular evaluator, in particular, dispelled much of the mystery of how Lisp-like languages are interpreted. But even the metacircular evaluator leaves important questions unanswered, because it fails to elucidate the mechanisms of control in a Lisp system

In this chapter we will describe processes in terms of the step-by-step operation of a traditional computer. Such a computer, or *register machine*, sequentially executes *instructions* that manipulate the contents of a fixed set of storage elements called *registers*. A typical register-machine instruction applies a primitive operation to the contents of some registers and assigns the result to another register. Our descriptions of processes executed by register machines will look very much like “machine-language” programs for traditional computers. However, instead of focusing on the machine language of any particular computer, we will examine several Lisp procedures and design a specific register machine to execute each procedure.

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```
(define (gcd a b)
  (if (= b 0)
      a
      (gcd b (remainder a b))))
```



register a). The source of data for a register can be another register (as in the $a \leftarrow b$ assignment), an operation result (as in the $t \leftarrow r$ assignment), or a constant (a built-in value that cannot be changed, represented in a data-path diagram by a triangle containing the constant).

An operation that computes a value from constants and the contents of registers is represented in a data-path diagram by a trapezoid containing a name for the operation. For example, the box marked rem

Figure 5.1: Data paths for a GCD machine.

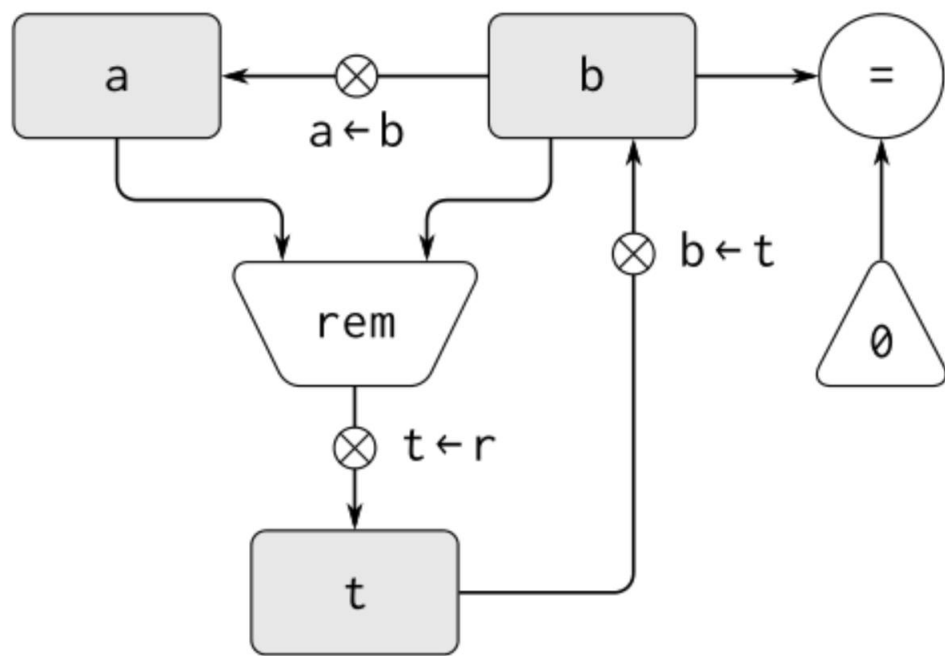


Figure 5.1: Data paths for a GCD machine.

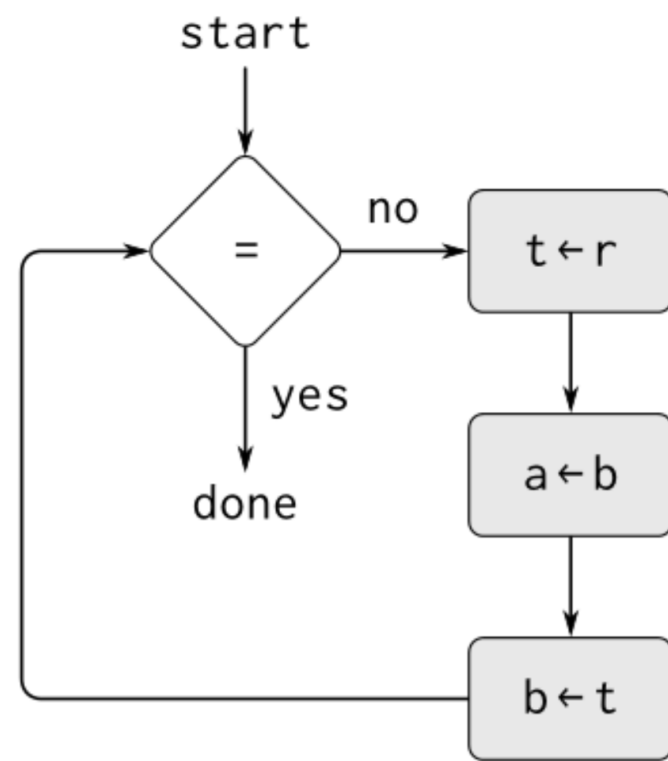


Figure 5.2: Controller for a GCD machine.

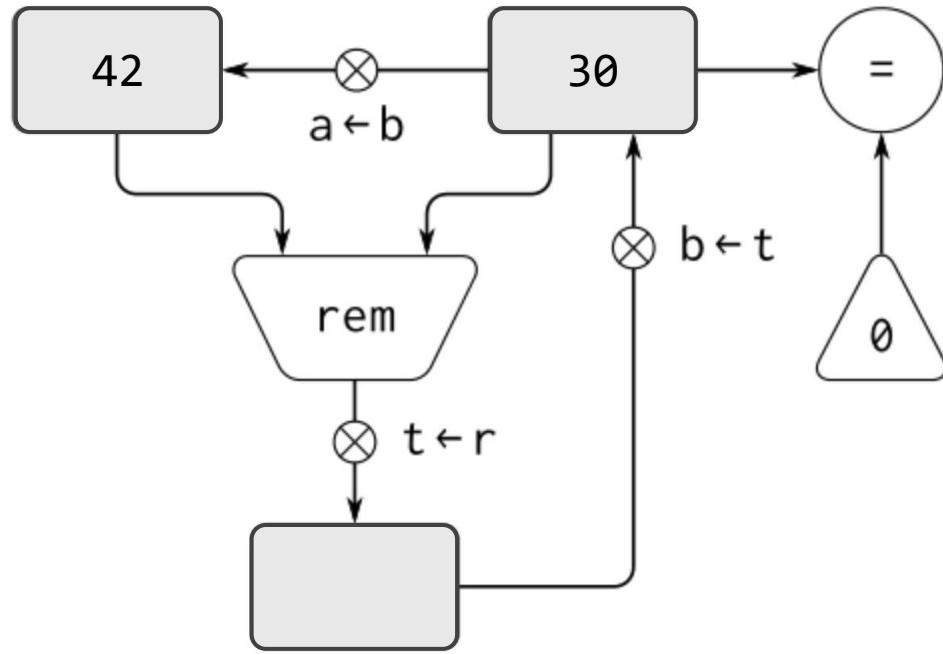


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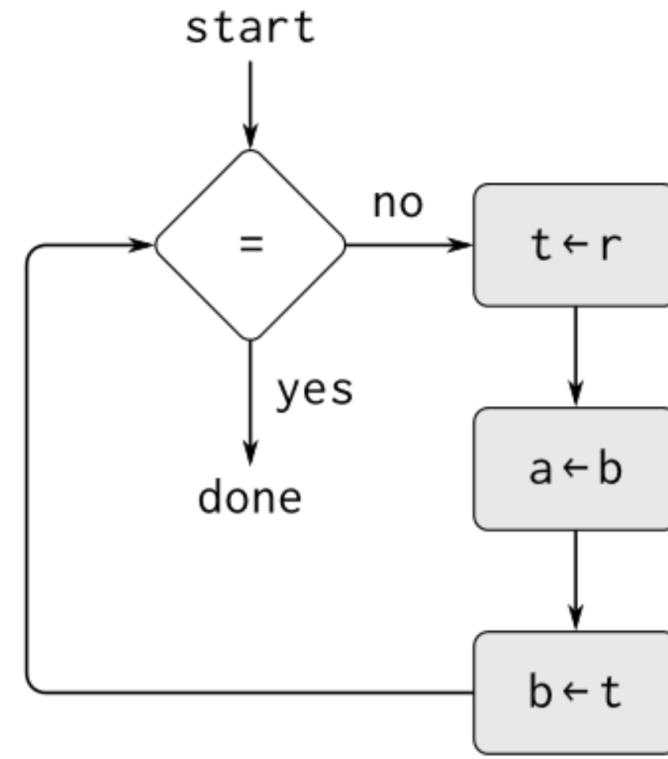


Figure 5.2: Controller for a GCD machine.

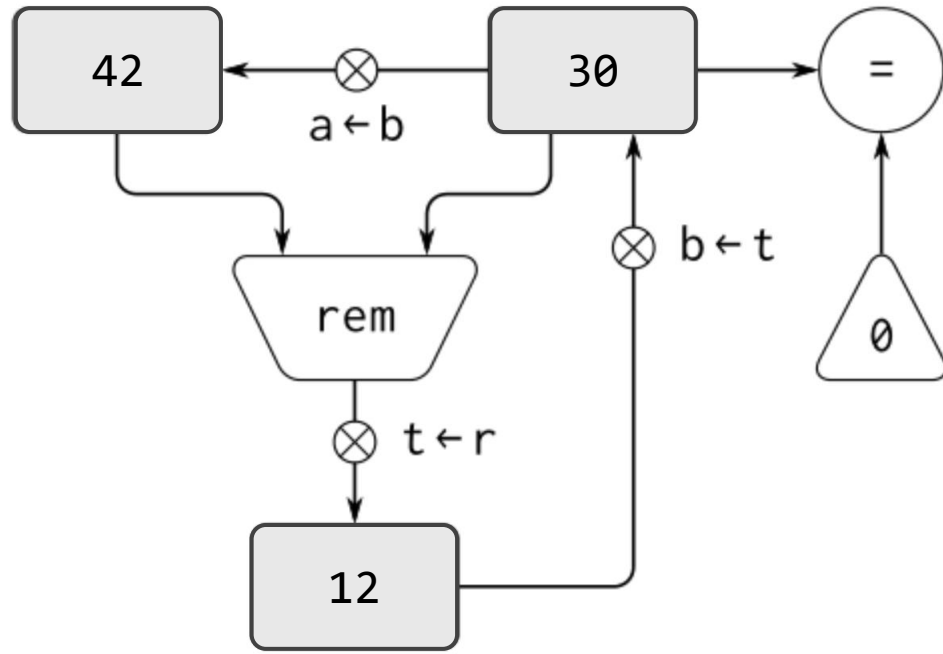


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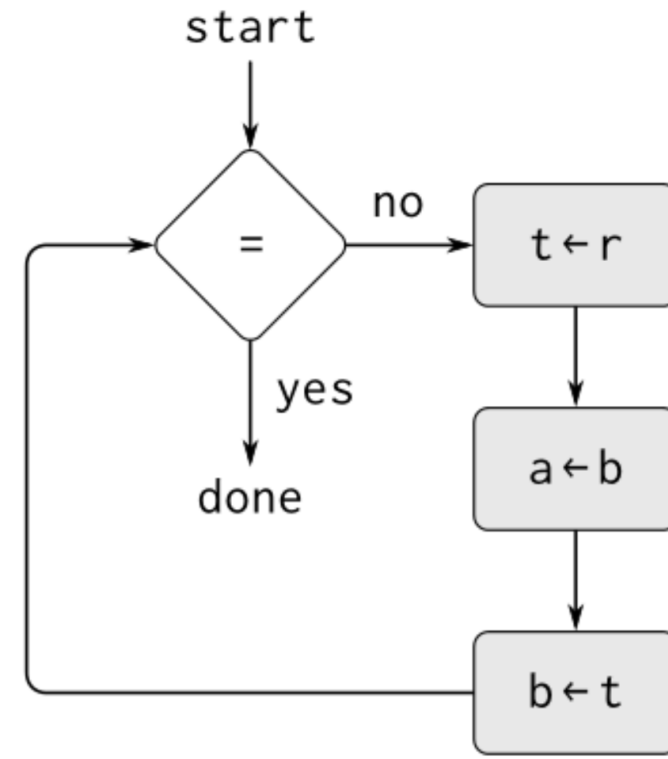


Figure 5.2: Controller for a GCD machine.

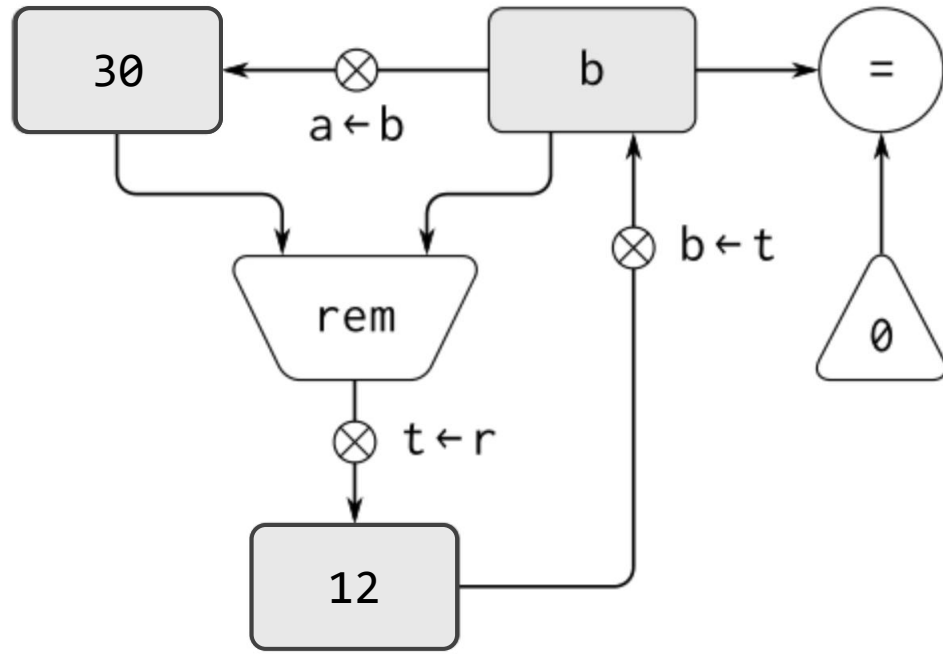


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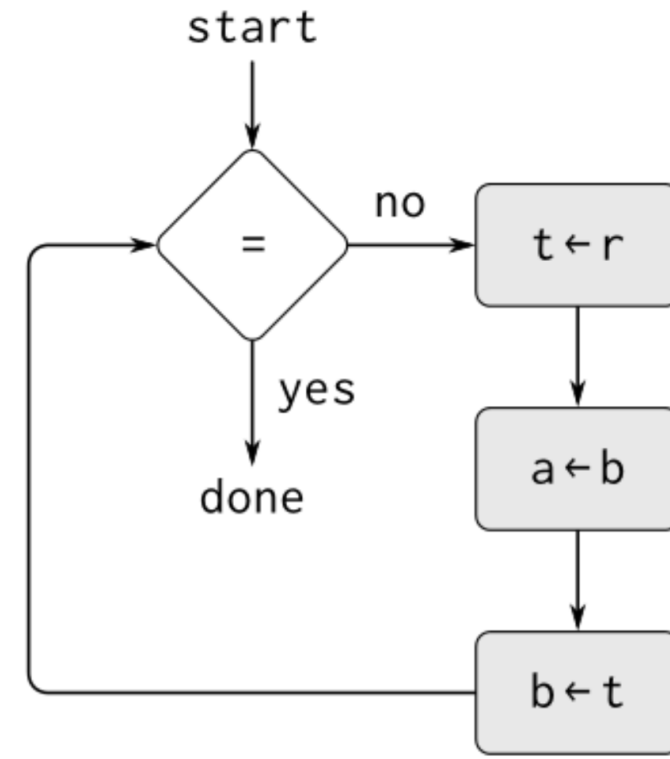


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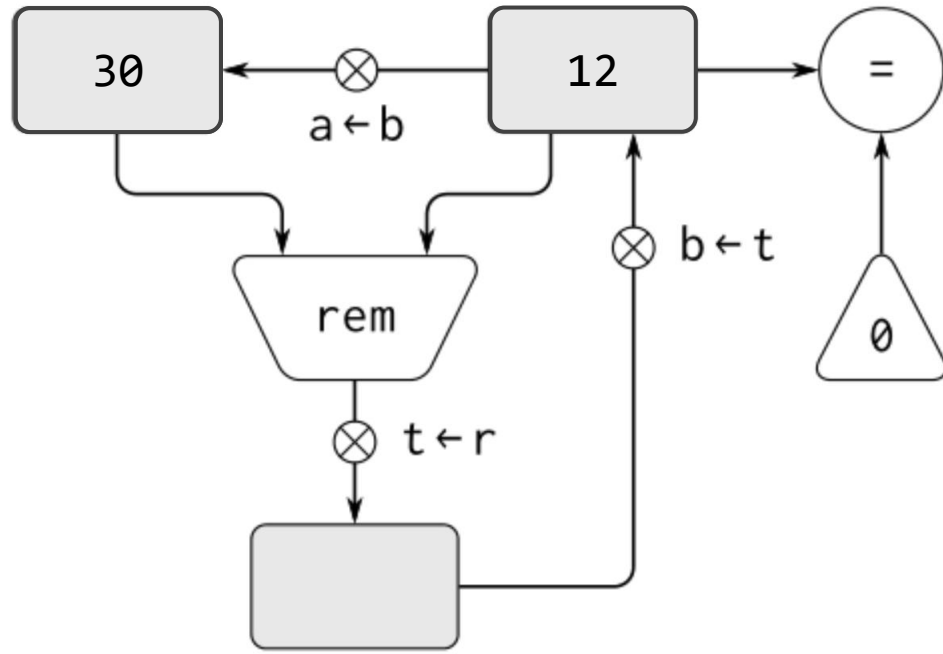


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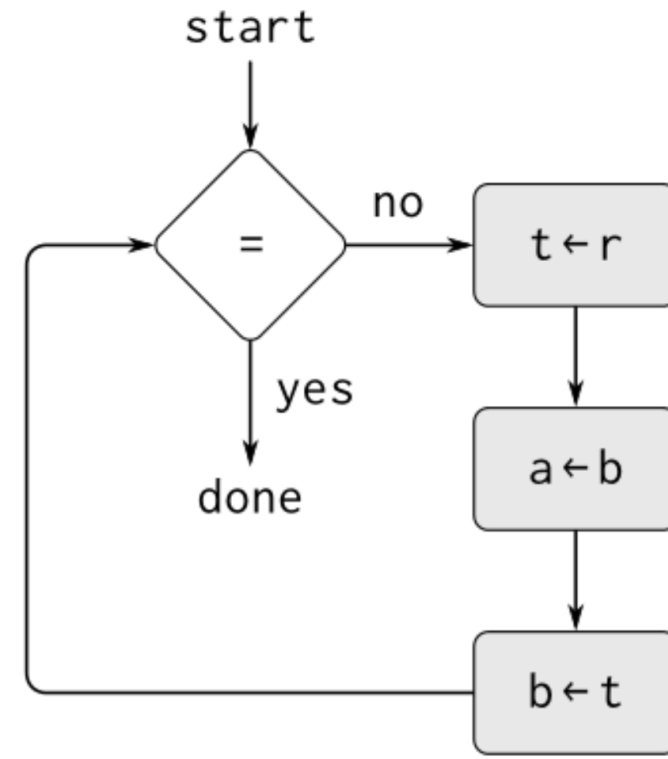


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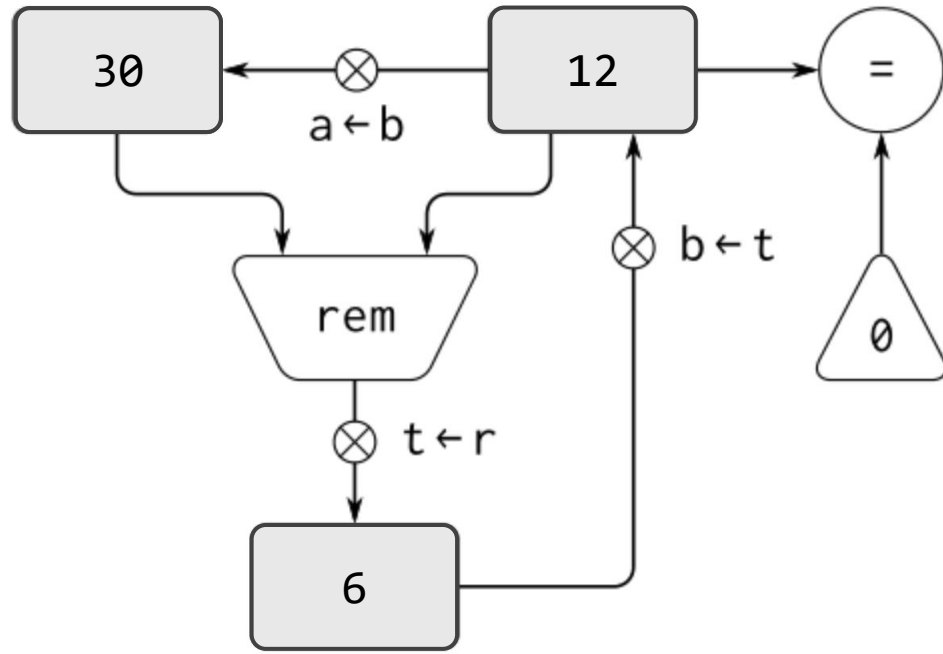


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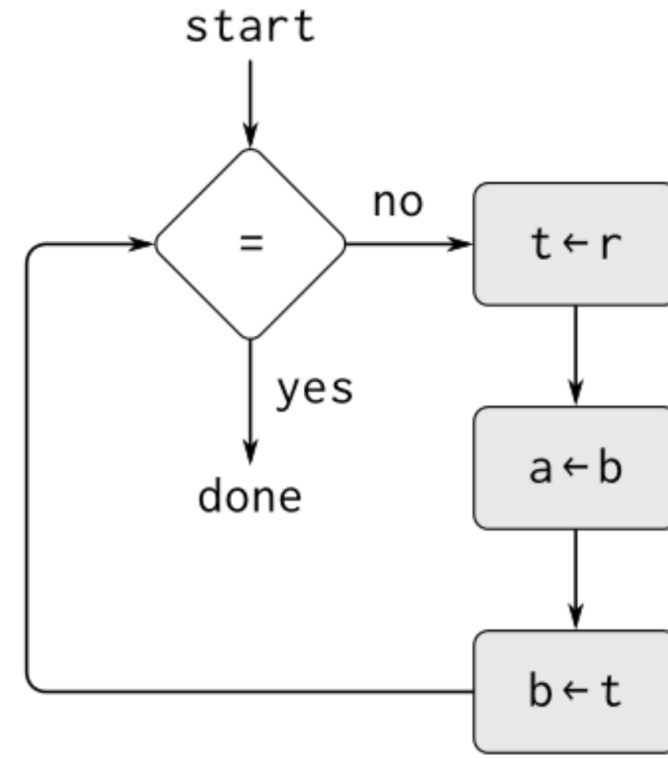


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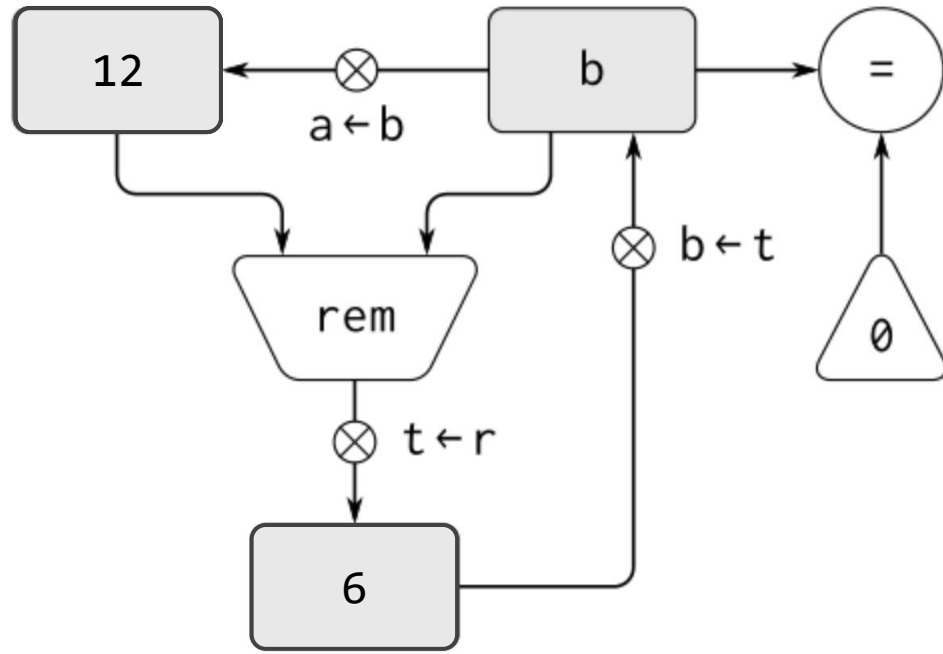


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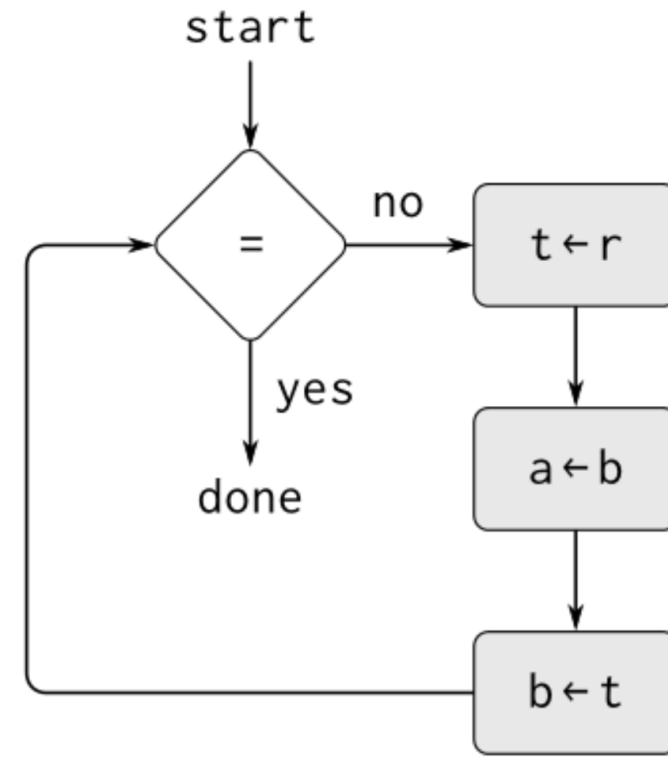


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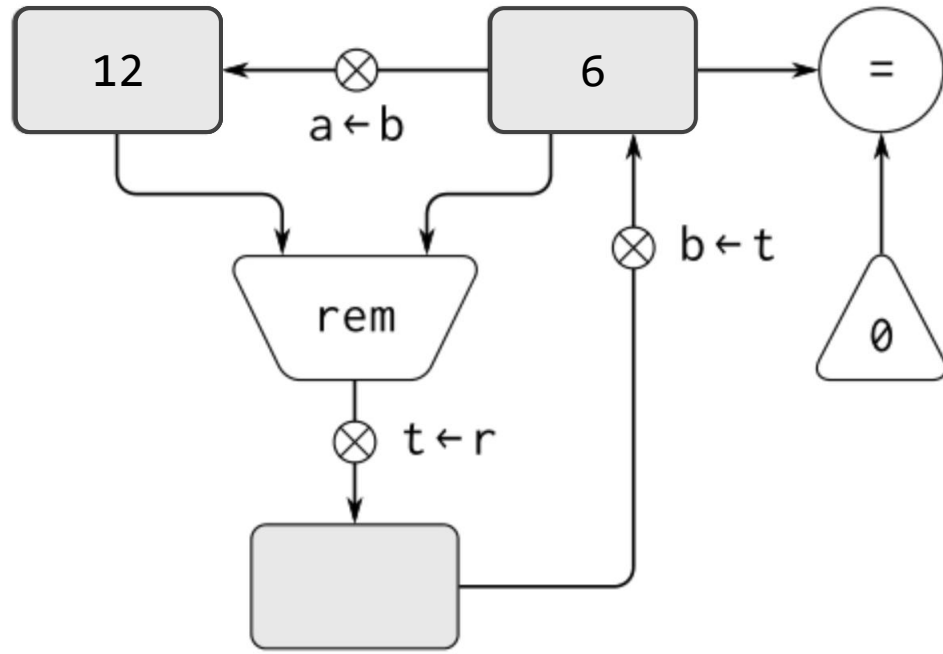


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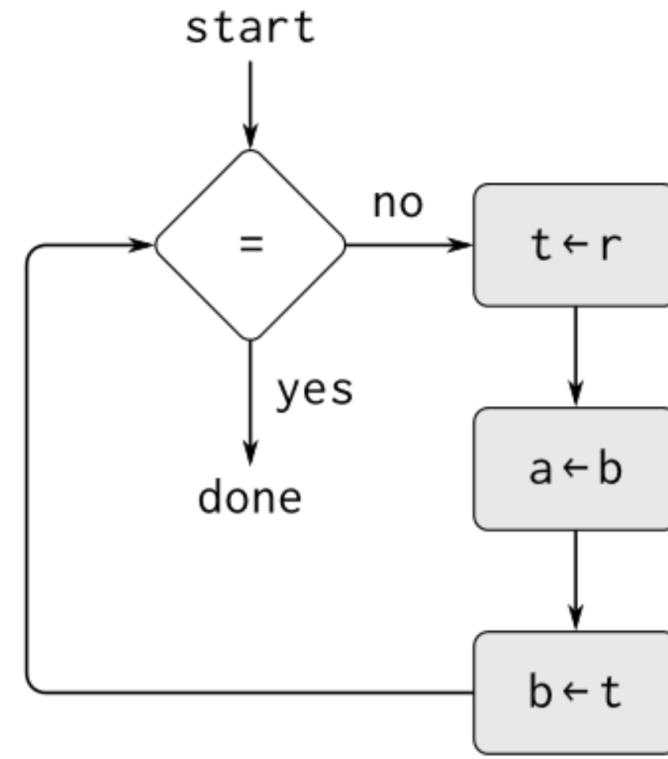


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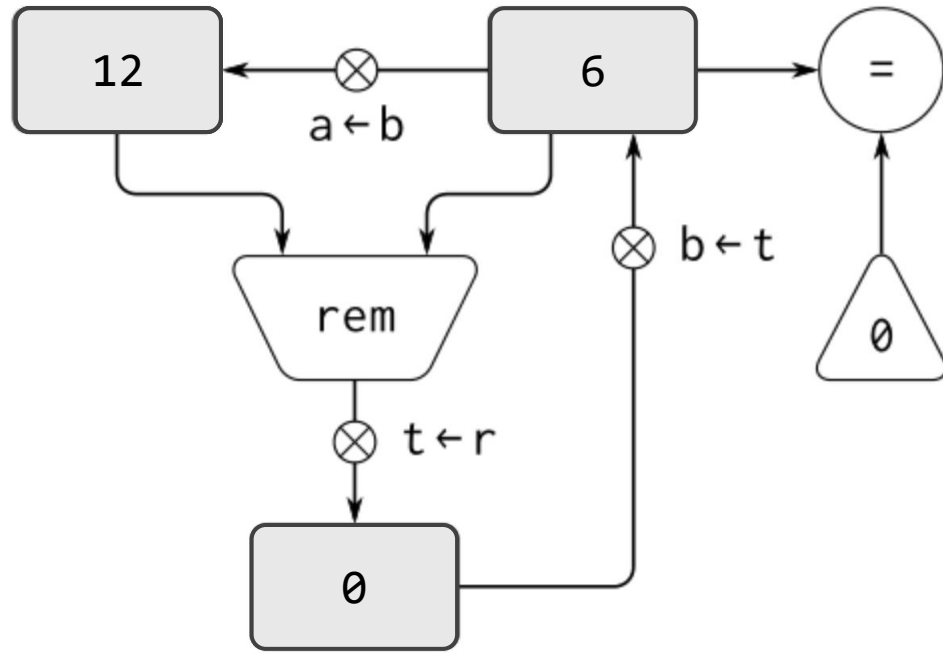


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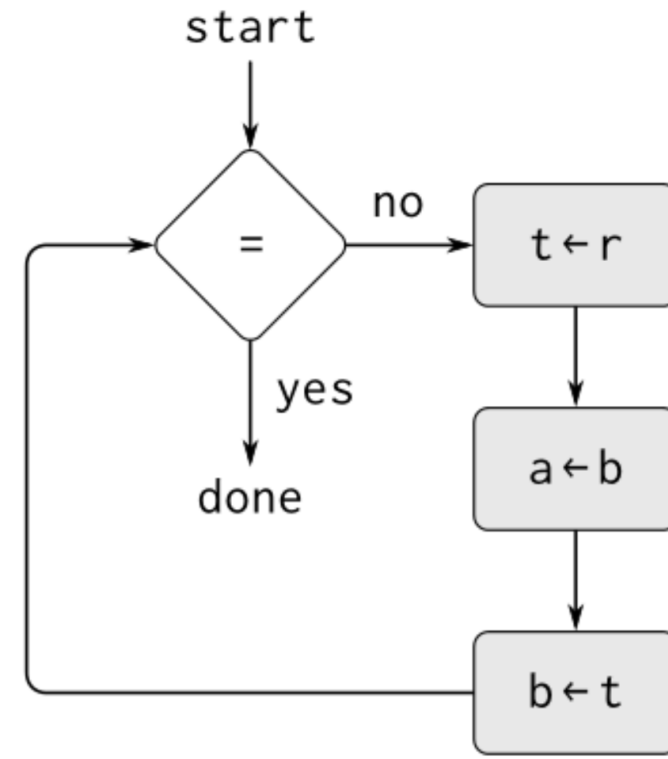


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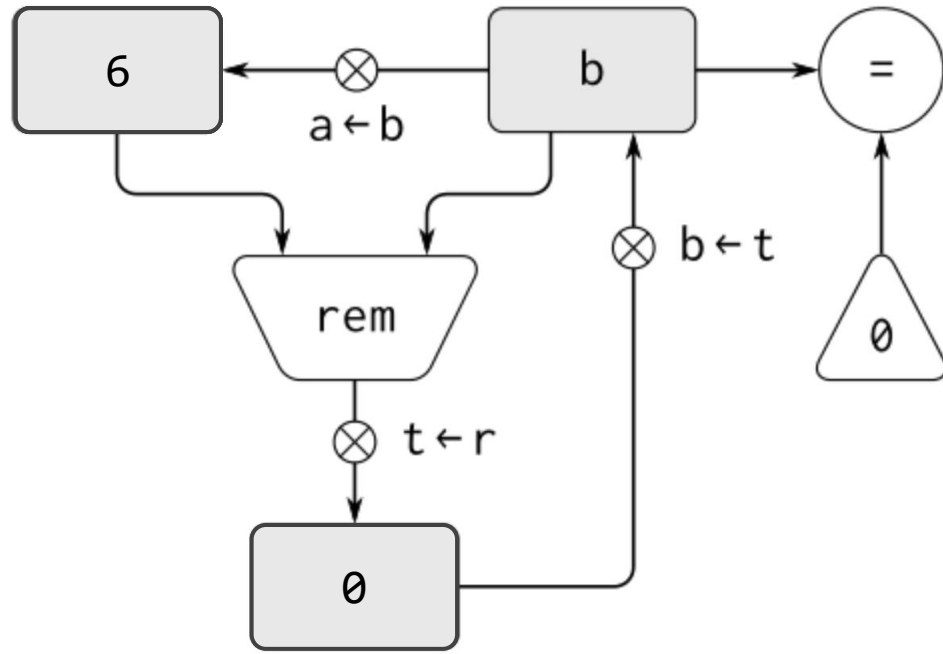


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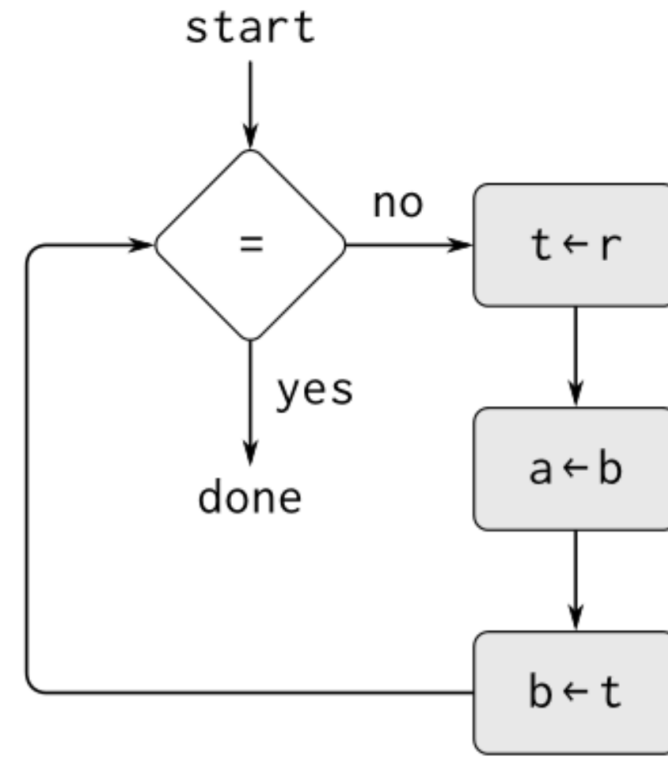


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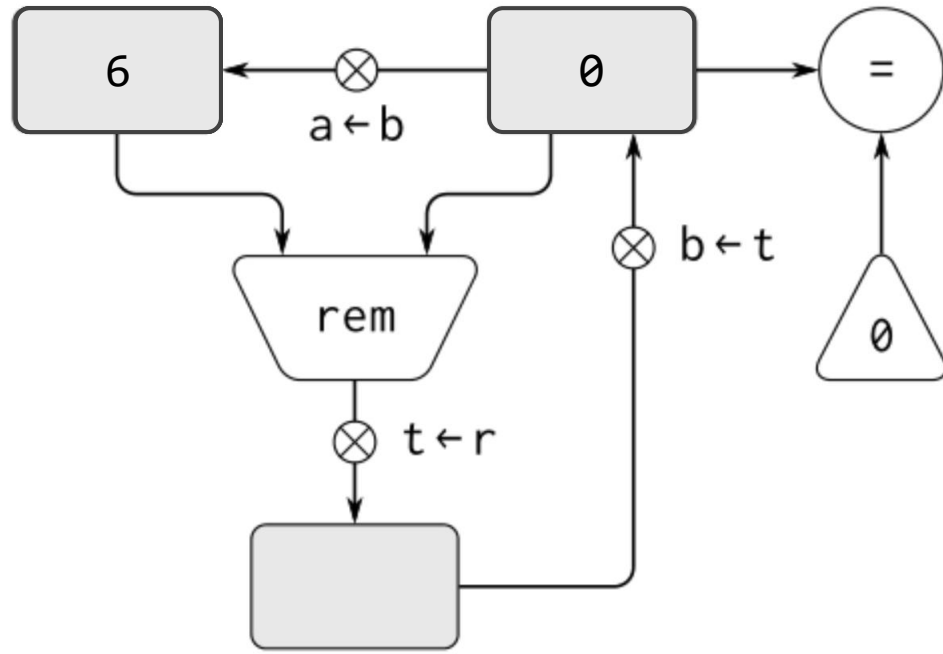


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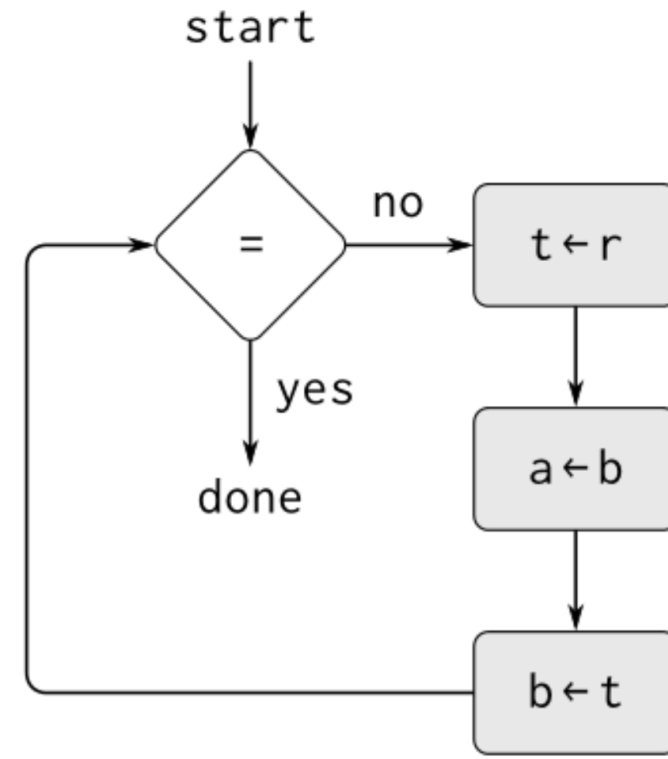


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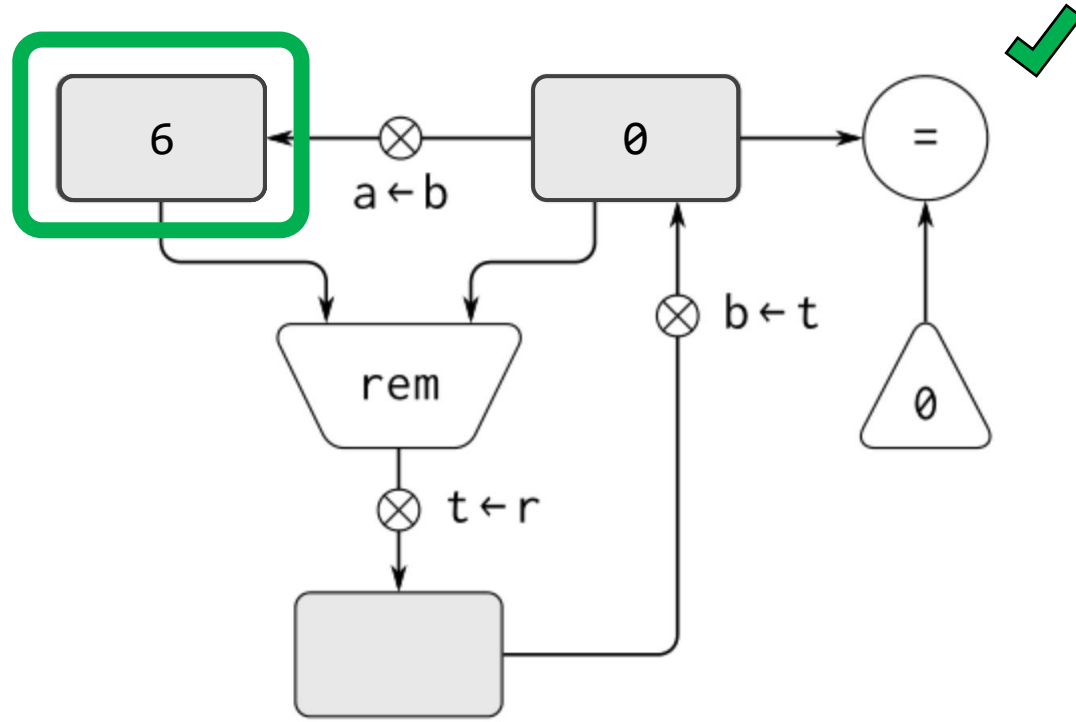


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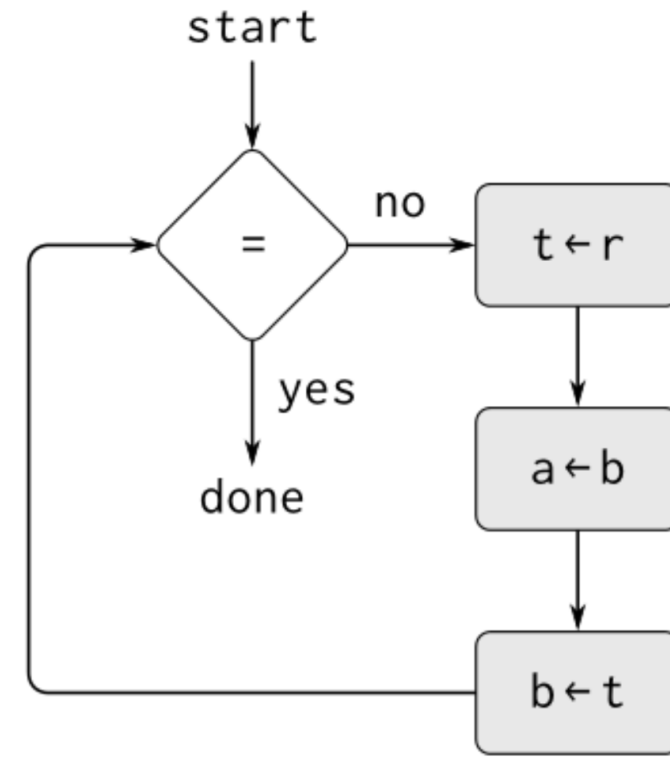
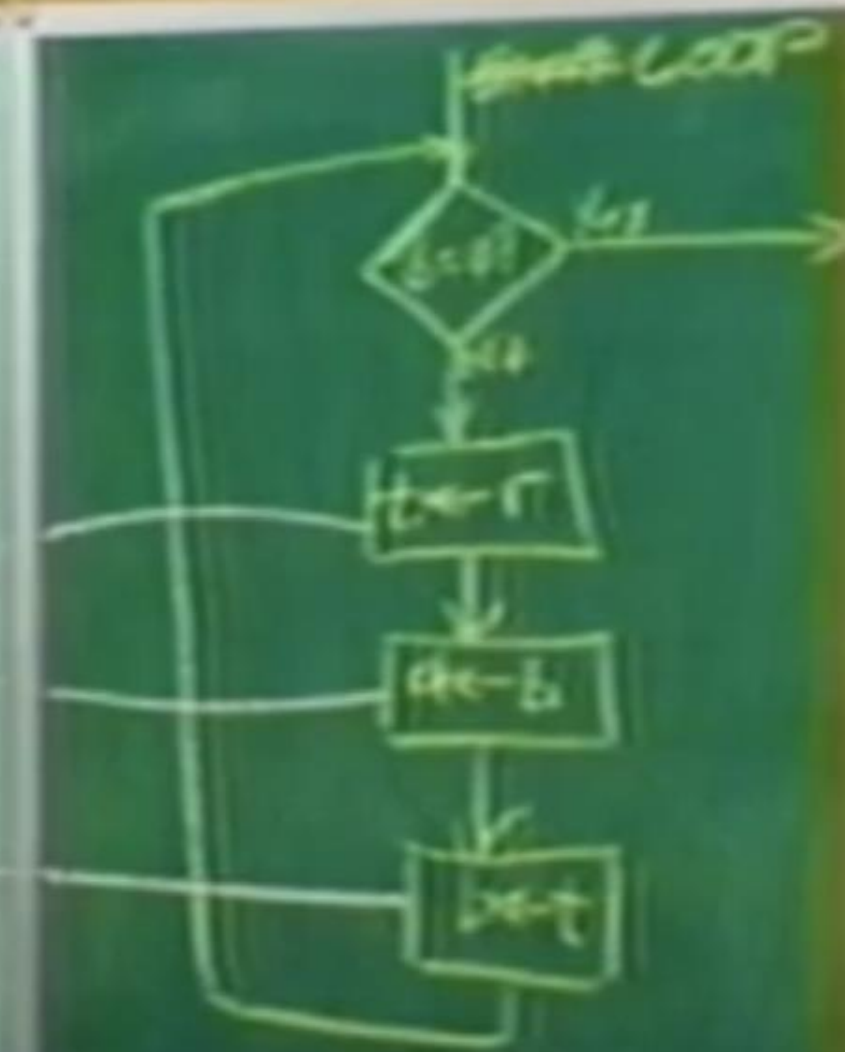




Figure 5.2: Controller for a GCD machine.

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DATA



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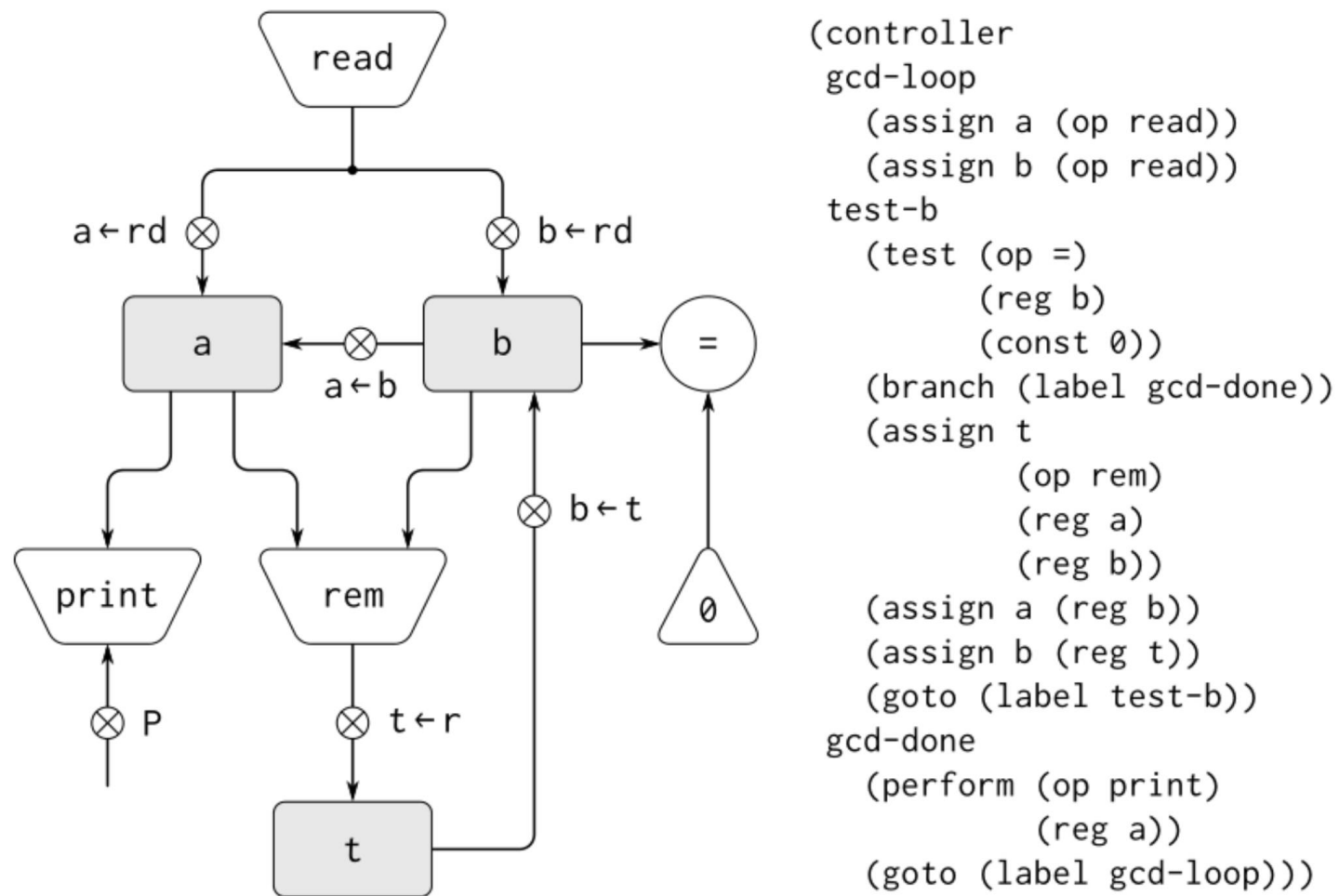



Figure 5.4: A GCD machine that reads inputs and prints results.

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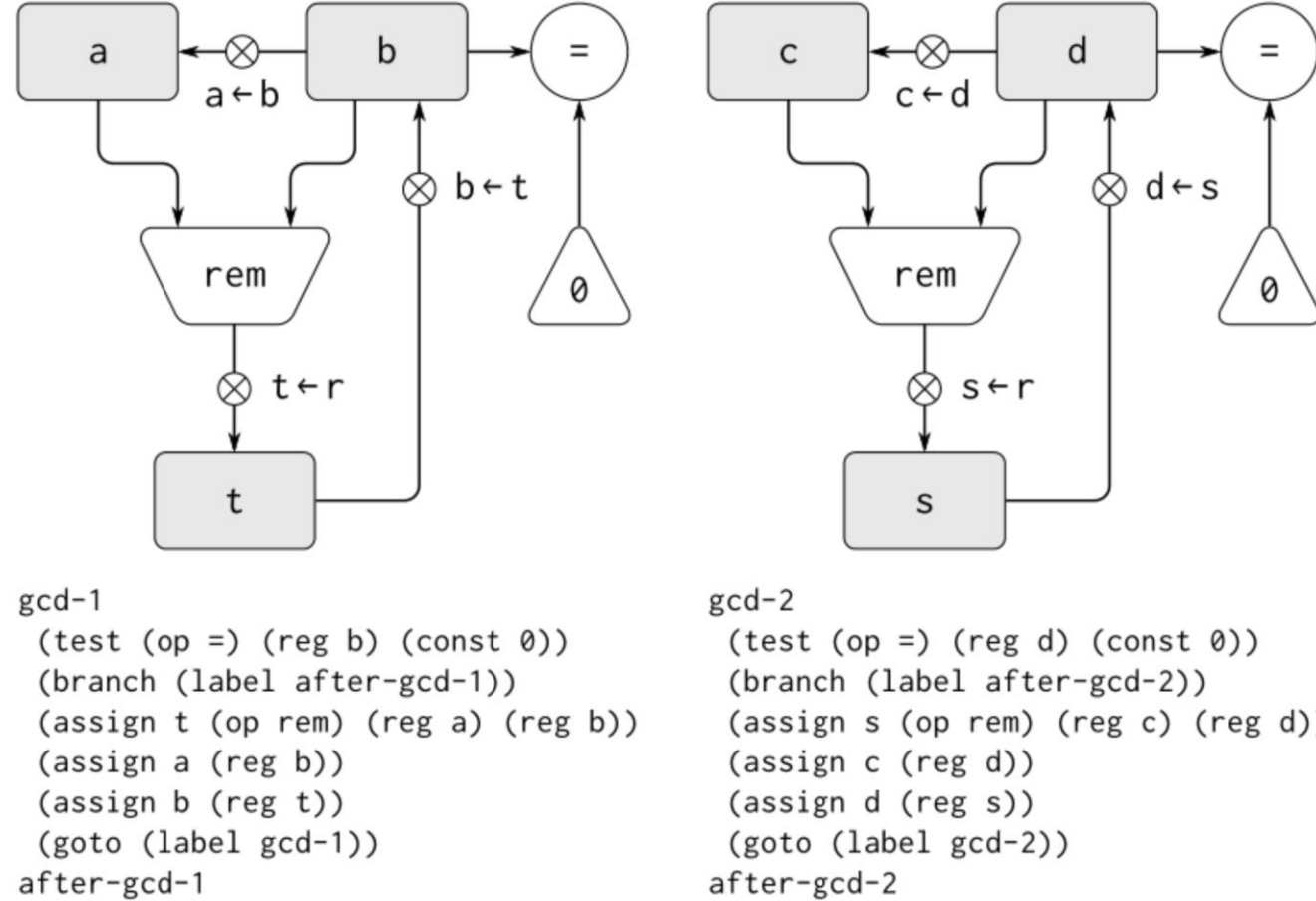


Figure 5.7: Portions of the data paths and controller sequence for a machine with two GCD computations.

Figure 5.8: ↓ Portions of the controller sequence for a machine that uses the same data-path components for two different GCD computations.

gcd-1

```
(test (op =) (reg b) (const 0))  
(branch (label after-gcd-1))  
(assign t (op rem) (reg a) (reg b))  
(assign a (reg b))  
(assign b (reg t))  
(goto (label gcd-1))
```

after-gcd-1

...

gcd-2

```
(test (op =) (reg b) (const 0))  
(branch (label after-gcd-2))  
(assign t (op rem) (reg a) (reg b))  
(assign a (reg b))  
(assign b (reg t))  
(goto (label gcd-2))
```

after-gcd-2





Figure 5.9: ↓ Using a continue register to avoid the duplicate controller sequence in [Figure 5.8](#).

```
gcd
  (test (op =) (reg b) (const 0))
  (branch (label gcd-done))
  (assign t (op rem) (reg a) (reg b))
  (assign a (reg b))
  (assign b (reg t))
  (goto (label gcd))
gcd-done
  (test (op =) (reg continue) (const 0))
  (branch (label after-gcd-1))
  (goto (label after-gcd-2))
  ...
;; Before branching to gcd from the first place where
;; it is needed, we place 0 in the continue register
  (assign continue (const 0))
  (goto (label gcd))
after-gcd-1
  ...

;; Before the second use of gcd, we place 1
;; in the continue register
  (assign continue (const 1))
  (goto (label gcd))
after-gcd-2
```


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```
(assign <register-name> (reg <register-name>))  
(assign <register-name> (const <constant-value>))  
(assign <register-name>  
      (op <operation-name>  
        <input1> ... <inputn>))  
(perform (op <operation-name>) <input1> ... <inputn>))  
(test (op <operation-name>) <input1> ... <inputn>))  
(branch (label <label-name>))  
(goto (label <label-name>))
```

The use of registers to hold labels was introduced in [Section 5.1.3](#):

```
(assign <register-name> (label <label-name>))  
(goto (reg <register-name>))
```

Instructions to use the stack were introduced in [Section 5.1.4](#):

```
(save <register-name>)  
(restore <register-name>)
```

The only kind of *<constant-value>* we have seen so far is a number, but later we will use strings, symbols, and lists. For example,

```
(const "abc") is the string "abc",  
(const abc) is the symbol abc,  
(const (a b c)) is the list (a b c),  
and (const ()) is the empty list.
```


Structure & Interpretation of Computer Programs

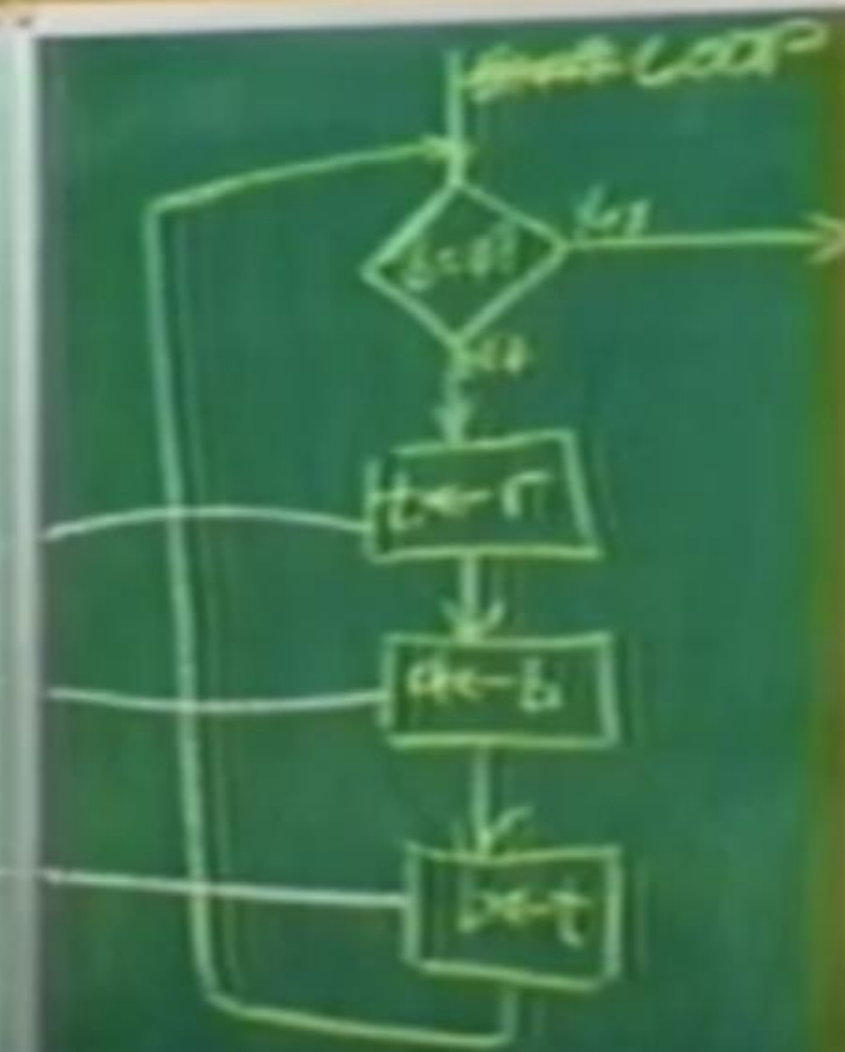
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