Prediction Assignment

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6 7 2022

Summary

Setup

```
library(caret)
## Warning: package 'caret' was built under R version 4.0.5
## Loading required package: ggplot2
## Loading required package: lattice
library(dplyr)
##
## Attaching package: 'dplyr'
## The following objects are masked from 'package:stats':
##
##
       filter, lag
## The following objects are masked from 'package:base':
##
       intersect, setdiff, setequal, union
library(randomForest)
## randomForest 4.6-14
## Type rfNews() to see new features/changes/bug fixes.
## Attaching package: 'randomForest'
## The following object is masked from 'package:dplyr':
##
##
       combine
## The following object is masked from 'package:ggplot2':
##
##
       margin
```

Loading & Reading Data

```
trainingRaw <- read.csv("https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv")
testingRaw <- read.csv("https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv")</pre>
```

Data Exploration & Preprocessing

```
dim(trainingRaw)
## [1] 19622 160
dim(testingRaw)
## [1] 20 160
```

We can see that the training set consists of 19622 observations, while the testing set consists of only 20 observations. Each observation consists of 160 variables.

Let's look at the variables.

```
str(trainingRaw)
```

```
19622 obs. of 160 variables:
## 'data.frame':
##
  $ X
                           : int 1 2 3 4 5 6 7 8 9 10 ...
## $ user_name
                            : chr
                                  "carlitos" "carlitos" "carlitos" ...
                            : int 1323084231 1323084231 1323084231 1323084232 1323084232 1323084232
## $ raw_timestamp_part_1
## $ raw_timestamp_part_2
                            : int 788290 808298 820366 120339 196328 304277 368296 440390 484323 484
## $ cvtd_timestamp
                                  "05/12/2011 11:23" "05/12/2011 11:23" "05/12/2011 11:23" "05/12/20
                            : chr
                                  "no" "no" "no" "no" ...
## $ new_window
                            : chr
##
   $ num window
                           : int 11 11 11 12 12 12 12 12 12 12 ...
                          : num 1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.43 1.45 ...
## $ roll_belt
## $ pitch_belt
                          : num 8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.16 8.17 ...
## $ yaw_belt
                                  -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 ...
                           : num
## $ total_accel_belt
                            : int 3 3 3 3 3 3 3 3 3 ...
                                  ...
## $ kurtosis_roll_belt
                            : chr
                                  ...
## $ kurtosis_picth_belt
                            : chr
##
   $ kurtosis_yaw_belt
                            : chr
                                  ... ... ... ...
##
   $ skewness_roll_belt
                            : chr
                                  ... ... ... ...
## $ skewness_roll_belt.1
                            : chr
                                  ... ... ... ...
## $ skewness_yaw_belt
                            : chr
## $ max_roll_belt
                                  NA NA NA NA NA NA NA NA NA . . .
                            : num
## $ max_picth_belt
                                  NA NA NA NA NA NA NA NA NA ...
                            : int
                                  ...
## $ max_yaw_belt
                            : chr
                            : num NA NA NA NA NA NA NA NA NA ...
## $ min_roll_belt
## $ min_pitch_belt
                                  NA NA NA NA NA NA NA NA NA ...
                            : int
                                  ...
## $ min_yaw_belt
                            : chr
## $ amplitude_roll_belt
                            : num NA NA NA NA NA NA NA NA NA ...
                            : int NA NA NA NA NA NA NA NA NA ...
## $ amplitude_pitch_belt
```

```
"" "" "" ...
## $ amplitude_yaw_belt
                           : chr
## $ var_total_accel_belt
                           : num NA NA NA NA NA NA NA NA NA ...
## $ avg roll belt
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
                           : num \, NA NA NA NA NA NA NA NA NA ...
## $ stddev_roll_belt
## $ var_roll_belt
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ avg_pitch_belt
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ stddev pitch belt
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
##
   $ var_pitch_belt
                           : num
##
   $ avg_yaw_belt
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ stddev_yaw_belt
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ var_yaw_belt
                           : num
                                NA NA NA NA NA NA NA NA NA ...
## $ gyros_belt_x
                                 : num
## $ gyros_belt_y
                           : num
                                 0 0 0 0 0.02 0 0 0 0 0 ...
## $ gyros_belt_z
                                 -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 -0.02 0 ...
                           : num
## $ accel_belt_x
                                 -21 -22 -20 -22 -21 -21 -22 -22 -20 -21 ...
                           : int
## $ accel_belt_y
                           : int
                                 4 4 5 3 2 4 3 4 2 4 ...
## $ accel_belt_z
                                 22 22 23 21 24 21 21 21 24 22 ...
                           : int
## $ magnet belt x
                           : int
                                 -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
## $ magnet_belt_y
                                599 608 600 604 600 603 599 603 602 609 ...
                           : int
## $ magnet belt z
                           : int
                                 -313 -311 -305 -310 -302 -312 -311 -313 -312 -308 ...
## $ roll_arm
                           : num
                                ## $ pitch_arm
                                22.5 22.5 22.5 22.1 22.1 22 21.9 21.8 21.7 21.6 ...
                           : num
## $ yaw_arm
                                 : num
## $ total accel arm
                                 34 34 34 34 34 34 34 34 34 ...
                           : int
## $ var_accel_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ avg roll arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ stddev_roll_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ var_roll_arm
                           : num
## $ avg_pitch_arm
                                NA NA NA NA NA NA NA NA NA ...
                           : num
## $ stddev_pitch_arm
                                 NA NA NA NA NA NA NA NA NA . . .
                           : num
## $ var_pitch_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ avg_yaw_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ stddev_yaw_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ var_yaw_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ gyros_arm_x
                                 : num
## $ gyros_arm_y
                                0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03 ...
                          : num
## $ gyros arm z
                          : num
                                 -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -0.02 ...
## $ accel_arm_x
                           : int
                                 ## $ accel_arm_y
                                 109 110 110 111 111 111 111 111 109 110 ...
                           : int
## $ accel_arm_z
                           : int
                                 -123 -125 -126 -123 -123 -122 -125 -124 -122 -124 ...
## $ magnet_arm_x
                                 -368 -369 -368 -372 -374 -369 -373 -372 -369 -376 ...
                           : int
## $ magnet_arm_y
                                 337 337 344 344 337 342 336 338 341 334 ...
                           : int
## $ magnet_arm_z
                           : int
                                 516 513 513 512 506 513 509 510 518 516 ...
## $ kurtosis_roll_arm
                           : chr
                                 ... ... ... ...
                                 ... ... ... ...
## $ kurtosis_picth_arm
                           : chr
## $ kurtosis_yaw_arm
                           : chr
                                 ... ... ... ...
##
   $ skewness_roll_arm
                           : chr
                                 ... ... ... ...
## $ skewness_pitch_arm
                           : chr
## $ skewness_yaw_arm
                           : chr
                                 0.01 \ 0.01 \ 0.01 \ 0.01
## $ max_roll_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
                                 NA NA NA NA NA NA NA NA NA ...
## $ max_picth_arm
                           : num
## $ max_yaw_arm
                           : int
                                 NA NA NA NA NA NA NA NA NA ...
## $ min_roll_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ min pitch arm
                           : num NA NA NA NA NA NA NA NA NA ...
```

```
## $ min_yaw_arm
                            : int NA NA NA NA NA NA NA NA NA ...
## $ amplitude_roll_arm
                            : num NA NA NA NA NA NA NA NA NA ...
                            : num NA NA NA NA NA NA NA NA NA ...
## $ amplitude_pitch_arm
## $ amplitude_yaw_arm
                            : int NA ...
## $ roll_dumbbell
                            : num 13.1 13.1 12.9 13.4 13.4 ...
## $ pitch dumbbell
                            : num -70.5 -70.6 -70.3 -70.4 -70.4 ...
## $ yaw dumbbell
                            : num -84.9 -84.7 -85.1 -84.9 -84.9 ...
                                   ...
## $ kurtosis_roll_dumbbell : chr
##
   $ kurtosis_picth_dumbbell : chr
                                   0.01 \ 0.01 \ 0.01 \ 0.01
                                   ... ... ... ...
## $ kurtosis_yaw_dumbbell
                             : chr
## $ skewness_roll_dumbbell : chr
                                   ... ... ... ...
## $ skewness_pitch_dumbbell : chr
                                   ... ... ... ...
## $ skewness_yaw_dumbbell
                            : chr
                                   NA NA NA NA NA NA NA NA NA ...
## $ max_roll_dumbbell
                            : num
## $ max_picth_dumbbell
                                   NA NA NA NA NA NA NA NA NA ...
                            : num
                                   ...
## $ max_yaw_dumbbell
                            : chr
## $ min_roll_dumbbell
                            : num NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_dumbbell
                                   NA NA NA NA NA NA NA NA NA ...
                            : num
                                   ...
## $ min_yaw_dumbbell
                            : chr
## $ amplitude roll dumbbell : num NA ...
##
    [list output truncated]
```

We have a lot of variables (160), so we obviously have to reduce that number. Also, a lot of variables seem to be NA, so we decide to simply omit all variables with NA values. Note that this is a very simply imputation method and more advanced methods could be tried instead.

```
training <- trainingRaw[, colSums(is.na(trainingRaw)) == 0]
testing <- testingRaw[, colSums(is.na(testingRaw)) == 0]</pre>
```

Now let's take another look.

```
dim(training)
## [1] 19622 93
dim(testing)
```

```
## [1] 20 60
```

That's better, but there are still too many variables. Let's remove some more columns.

```
y <- training$classe

training <- training[, sapply(training, is.numeric)]

testing <- testing[, sapply(testing, is.numeric)]

training <- training %>% select(-X, -raw_timestamp_part_1, -raw_timestamp_part_2, -num_window)
testing <- testing %>% select(-X, -raw_timestamp_part_1, -raw_timestamp_part_2, -num_window, -problem_interaining$classe <- y</pre>
```

```
dim(training)
## [1] 19622 53
dim(testing)
## [1] 20 52
```

Data Preparation

We now want to split our training data into a train and a validation set.

```
set.seed(42)
inTrain <- createDataPartition(training$classe, p = .7, list = FALSE)

train <- training[inTrain,]
val <- training[-inTrain,]</pre>
```

Model Fit

Let's now use a random forest classifier for our training data. The random forest classifier was chosen because in the lectures we were told that they perform very good out of the box for most cases. We use 5 fold cross validation and 100 trees.

```
rf <- train(classe ~ ., data = train, method="rf", trControl = trainControl(method = "cv", 5), ntree=10
rf

## Random Forest
##
## 13737 samples
## 52 predictor</pre>
```

```
##
       5 classes: 'A', 'B', 'C', 'D', 'E'
## No pre-processing
## Resampling: Cross-Validated (5 fold)
## Summary of sample sizes: 10990, 10990, 10990, 10989, 10989
## Resampling results across tuning parameters:
##
##
     mtry Accuracy
                      Kappa
##
     2
           0.9894447 0.9866460
     27
           0.9913372 0.9890411
##
##
     52
           0.9835480 0.9791847
##
## Accuracy was used to select the optimal model using the largest value.
## The final value used for the model was mtry = 27.
```

On the test set we a get a very high accuracy.

```
valPrediction <- predict(rf, val)</pre>
cf <- confusionMatrix(valPrediction, as.factor(val$classe))</pre>
## Confusion Matrix and Statistics
##
##
             Reference
## Prediction
                  Α
                       В
                            C
                                  D
                                       Ε
            A 1670
                       3
                                  0
                                       0
##
                            0
##
            В
                  3 1133
                            6
                                  0
                                       0
##
            С
                  1
                       3 1020
                                  9
##
            D
                  0
                       0
                            0
                                954
                                       5
            Е
##
                       0
                            0
                                  1 1077
##
## Overall Statistics
##
##
                   Accuracy: 0.9947
##
                     95% CI: (0.9925, 0.9964)
##
       No Information Rate: 0.2845
       P-Value [Acc > NIR] : < 2.2e-16
##
##
##
                      Kappa: 0.9933
##
##
    Mcnemar's Test P-Value : NA
##
## Statistics by Class:
##
##
                         Class: A Class: B Class: C Class: D Class: E
## Sensitivity
                           0.9976
                                     0.9947
                                               0.9942
                                                        0.9896
                                                                  0.9954
                                     0.9981
                                               0.9973
                                                        0.9990
                                                                  0.9998
## Specificity
                           0.9993
## Pos Pred Value
                           0.9982
                                     0.9921
                                              0.9874
                                                        0.9948
                                                                  0.9991
## Neg Pred Value
                           0.9991
                                     0.9987
                                               0.9988
                                                        0.9980
                                                                  0.9990
## Prevalence
                           0.2845
                                     0.1935
                                               0.1743
                                                        0.1638
                                                                  0.1839
                                                        0.1621
                                                                  0.1830
## Detection Rate
                           0.2838
                                     0.1925
                                               0.1733
## Detection Prevalence
                           0.2843
                                     0.1941
                                               0.1755
                                                        0.1630
                                                                  0.1832
## Balanced Accuracy
                           0.9984
                                     0.9964
                                               0.9957
                                                        0.9943
                                                                  0.9976
```

And we also get a very high accuracy on the validation set.

Now let's look at the out of sample error.

```
outOfSampleError
outOfSampleError
```

```
## Accuracy
## 0.00526763
```

Predict Test Data

Finally, we use our classifier to predict the test data.

testPrediction <- predict(rf, testing)</pre>

testPrediction

[1] B A B A A E D B A A B C B A E E A B B B

Levels: A B C D E