








Form Evaluasi Project Tahap Akhir (UAS)



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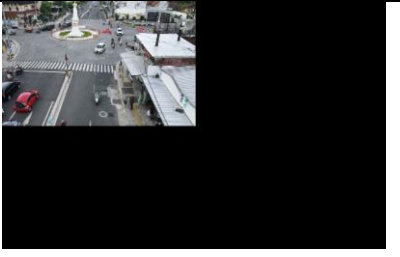
No	Fitur	Ada/Tidak	Code Fungsi / Algoritma Utama	Image Input	Image Output
1	Image Thresholding	Ada	<pre>def ImgThresHolding(img_input,coldepth): #solusi 1 #img_output=ImageOps.invert(img_input) #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() thresholdpic =img_input.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): if thresholdpic[i,j] < (127,127,127): pixels[i,j] = (0, 0, 0) elif thresholdpic[i,j] >= (127, 127, 127): pixels[i,j] = (255, 255, 255) if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output</pre>		



2	Image Negative	Ada	<pre> def ImgNegative(img_input,coldepth): #solusi 1 #img_output=ImageOps.invert(img_input) #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): r, g, b = img_input.getpixel((i, j)) pixels[i,j] = (255-r, 255-g, 255-b) if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
3	Image Brightness	Ada	<pre> def BrightnessUp(img_input, coldepth): #solusi 1 #img_output=ImageOps.invert(img_input) #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): r, g, b = img_input.getpixel((i, j)) pixels[i,j] = (150+r, 150+g, 150+b) if(r<0 and g<0 and b<0): r=0 g=0 b=0 if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") </pre>		 <p>Figure 1. Brightness Up</p>



		<pre>return img_output def BrightnessDown(img_input,coldepth): #solusi 1 #img_output=ImageOps.invert(img_input) #solusi 2 if coldepth!=24: img_input = img_input.convert("RGB") img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): r, g, b = img_input.getpixel((i, j)) pixels[i,j] = (r-100, g-100, b-100) if(r<0 and g<0 and b<0): r=0 g=0 b=0 if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output</pre>		 <p>Figure 2. Brightness Down</p>
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4	Image Rotation	Ada	<pre> def ImgRotate_90(img_input,coldepth,deg,direction): #solusi 1 #img_output=img_input.rotate(deg) #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[1],img_input.size[0])) pixels = img_output.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): if direction=="C": r, g, b = img_input.getpixel((j,img_output.size[0]-i-1)) else: r, g, b = img_input.getpixel((img_input.size[1]-j-1,i)) pixels[i,j] = (r, g, b) if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre> <hr/> <pre> def ImgRotate_180(img_input,coldepth,deg,direction): #solusi 1 #img_output=img_input.rotate(deg) #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): if direction=="C": r, g, b = img_input.getpixel((i,img_output.size[1]-j-1)) else: r, g, b = img_input.getpixel((img_input.size[0]-j-1,i)) pixels[i,j] = (r, g, b) if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: </pre>		
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			<pre> img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre> <hr/> <pre> def ImgRotate_270(img_input,coldepth,deg,direction): #solusi 1 #img_output=img_input.rotate(deg) #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[1],img_input.size[0])) pixels = img_output.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): if direction=="C": r, g, b = img_input.getpixel((img_output.size[1]-j-1,i)) else: r, g, b = img_input.getpixel((img_input.size[1]-j-1,i)) pixels[i,j] = (r, g, b) if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
5	Image Flipping	Ada	<pre> def ImgFlip(img_input,coldepth,deg,direction): #solusi 1 #img_output=img_input.rotate(deg) #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): if direction=="C": r, g, b = img_input.getpixel((img_output.size[0]-i-1,j)) </pre>		


			<pre> else: r, g, b = img_input.getpixel((img_input.size[0]-j-1,i)) pixels[i,j] = (r, g, b) if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
6	Image Zooming	Ada	<pre> def Img_Zoom(img_input,coldepth): #solusi 1 #img_output=ImageOps.invert(img_input) #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): r, g, b = img_input.getpixel((i*0.5, j*0.5)) pixels[i,j] = (r, g, b) if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
7	Image Shrinking	Ada	<pre> def ImgZoomout(img_input,coldepth): #solusi 1 #img_output=ImageOps.invert(img_input) #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): </pre>		



			<pre> r, g, b = img_input.getpixel((i, j)) pixels[i*0.5,j*0.5] = (r, g, b) if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
8	Mean Filtering	Ada	<pre> def ImgMean(img_input, coldepth): if coldepth!=24: img_input = img_input.convert("RGB") kernel = 3 task1=[] task2=[] task3=[] index = kernel // 2 img_output = Image.new('RGB', (img_input.size[0], img_input.size[1])) pixels = img_output.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): for z in range(kernel): if i + z - index < 0 or i + z - index > img_input.size[0] - 1: for c in range (kernel): task1.append(0) task2.append(0) task3.append(0) else: if j + z - index < 0 or j + index > img_input.size[1] - 1: task1.append(0) task2.append(0) task3.append(0) else: for k in range (kernel): r,g,b = img_input.getpixel((i+z-index,j+k-index)) task1.append(r) task2.append(g) task3.append(b) # menghitung temp pixels[i,j] = (round((sum(task1))/len(task1)), round((sum(task2))/len(task2)), round((sum(task3))/len(task3))) </pre>		

			<pre> task1=[] task2=[] task3=[] if coldepth == 1: img_output = img_output.convert("1") elif coldepth == 8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
9	Median Filtering	Ada	<pre> def imgmedian(img_input,coldepth): if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1]), "white") pixels = img_output.load() mask = [(0,0)] * 9 for i in range(1, img_output.size[0]-1): for j in range(1, img_output.size[1] - 1): mask[0] = img_input.getpixel((i-1,j-1)) mask[1] = img_input.getpixel((i-1,j)) mask[2] = img_input.getpixel((i-1,j+1)) mask[3] = img_input.getpixel((i,j-1)) mask[4] = img_input.getpixel((i,j)) mask[5] = img_input.getpixel((i,j+1)) mask[6] = img_input.getpixel((i+1,j-1)) mask[7] = img_input.getpixel((i+1,j)) mask[8] = img_input.getpixel((i+1,j+1)) mask.sort() pixels[i,j] = (mask[4]) if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
10	Edge Detection Pilihan 1	Tidak			
11	Edge Detection Pilihan 2	Tidak			
12	Gaussian Filtering	Tidak			


13	Erosi	Ada	<pre> def Imgerosi(img_input,coldepth,direction): #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() for i in range(1, img_output.size[0]-1): for j in range(1,img_output.size[1]-1): masukan = [img_input.getpixel((i-1, j-1)), img_input.getpixel((i-1, j)), img_input.getpixel((i-1, j+1)), img_input.getpixel((i, j-1)), img_input.getpixel((i, j)), img_input.getpixel((i, j+1)), img_input.getpixel((i+1, j-1)), img_input.getpixel((i+1, j)), img_input.getpixel((i+1, j+1))] erosi_min = min (masukan) erosi_max = max (masukan) if direction == "min": pixels[i,j] = erosi_min else: pixels[i,j] = erosi_max if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
14	Dilasi	Ada	<pre> def Imgdilasi(img_input,coldepth,direction): #solusi if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() for i in range(1,img_input.size[0]-1): for j in range(1, img_output.size[1]-1): masukan= [img_input.getpixel((i-1, j-1)), img_input.getpixel((i-1, j)), img_input.getpixel((i-1, j+1)), img_input.getpixel((i, j-1)), img_input.getpixel((i, j)), </pre>		



			<pre> img_input.getpixel((i, j+1)), img_input.getpixel((i+1, j-1)), img_input.getpixel((i+1, j)), img_input.getpixel((i+1, j+1)) dilasi_min = min (masukan) dilasi_max = max (masukan) if direction == "max": pixels[i,j] = dilasi_max else: pixels[i,j] = dilasi_min if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
15	Opening	Ada	<pre> def ImgOpening(img_input,coldepth,direction): #solusi 2 if coldepth!=24: img_input = img_input.convert("RGB") img_output Image.new('RGB',(img_input.size[0],img_input.size[1]),"white") pixel = img_input.load() pixels = img_output.load() for i in range(1,img_input.size[0]-1): for j in range(1, img_output.size[1]-1): masukan= [img_input.getpixel((i-1, j-1)), img_input.getpixel((i-1, j)), img_input.getpixel((i-1, j+1)), img_input.getpixel((i, j-1)), img_input.getpixel((i, j)), img_input.getpixel((i, j+1)), img_input.getpixel((i+1, j-1)), img_input.getpixel((i+1, j)), img_input.getpixel((i+1, j+1))] opening_min = min (masukan) opening_max = max (masukan) if direction == "open": pixels[i,j] = opening_min and opening_max else: pixels[i,j] = pixel[i,j] if coldepth==1: </pre>	=	

			<pre> img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
16	Closing	Ada	<pre> def ImgClosing(img_input,coldepth,direction): #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output Image.new('RGB',(img_input.size[0],img_input.size[1]),"white") pixel = img_input.load() pixels = img_output.load() for i in range(1,img_input.size[0]-1): for j in range(1, img_output.size[1]-1): masukan= [img_input.getpixel((i-1, j-1)), img_input.getpixel((i-1, j)), img_input.getpixel((i-1, j+1)), img_input.getpixel((i, j-1)), img_input.getpixel((i, j)), img_input.getpixel((i, j+1)), img_input.getpixel((i+1, j-1)), img_input.getpixel((i+1, j)), img_input.getpixel((i+1, j+1))] closing_min = min (masukan) closing_max = max (masukan) closing= closing_max and closing_min if direction == "close": pixels[i,j] = closing else: pixels[i,j] = pixel[i,j] if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>	=	

17	RGB to Grayscale	Ada	<pre> def ImgGreyscale(img_input,coldepth): #solusi 1 #img_output=ImageOps.invert(img_input) #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() threshold = img_input.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): r, g, b = img_input.getpixel((i, j)) pixels[i,j] = (r, r, r) if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
18	RGB to HSV/HLS Conversion	Tidak			

FITUR TAMBAHAN :

No	Fitur	Ada/Tidak	Code Algoritma	Image Input	Image Output
1	Image Blending	Ada	<pre> def ImgBlending(img_input,coldepth,img2,x,y,value): #solusi 1 #img_output=ImageOps.invert(img_input) #solusi 2 if coldepth!=24: img_input = img_input.convert('RGB') img2 = img2.open("C:/Users/M.S.I/Downloads/Undiksha Material/praktikum1/Foto/Foto2.jpg") img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() lebar=img2.size[0] tinggi=img2.size[1] </pre>		

			<pre> value2=10-value for i in range(img_output.size[0]): for j in range(img_output.size[1]): r, g, b = img_input.getpixel((i,j)) if i>=lebar+x or j>=tinggi+y or i<x or j<y: r2=r g2=g b2=b else: r2, g2, b2 = img2.getpixel((i-x, j-y)) pixels[i,j] = (int((r*value2+r2*value)/10), int((g*value2+g2*value)/10), int((b*value2+b2*value)/10)) img_output = img_output.convert("RGB") return img_output </pre>		
2	Image Logarithmic	Tidak			
3	Image Translation	Ada	<pre> def ImgTranslation(img_input,coldepth): #solusi 1 #img_output=ImageOps.invert(img_input) #solusi 2 if coldepth!=25: img_input = img_input.convert('RGB') img_output = Image.new('RGB',(img_input.size[0],img_input.size[1])) pixels = img_output.load() for i in range(img_output.size[0]): for j in range(img_output.size[1]): r, g, b = img_input.getpixel((i, j)) pixels[i-50,j-50] = (r, g, b) if coldepth==1: img_output = img_output.convert("1") elif coldepth==8: img_output = img_output.convert("L") else: img_output = img_output.convert("RGB") return img_output </pre>		
4	Edge Detection Pilihan 3	Tidak			
5	Edge Detection Pilihan 4	Tidak			
6	Edge Detection Pilihan 5	Tidak			

7	Top Hat	Tidak			
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PRINT SCREEN ANTARMUKA UTAMA :

