In this exercise you will implement a class representing a terrain in the form of a rectangular grid. The cells of the grid are indexed with pairs of integers, where (0,0) represents the lower left cell of the grid, and (m-1,n-1) represents the top right cell of the grid, where m is the width and n is the height of the grid. For example, a grid of width 4 and height 3 is indexed in the following way:

Some of the cells of the grid are blocked by obstacles. We are interested in determining whether there is a path to reach a given goal cell from a given start cell by moving one cell at a time in each of the four cardinal directions: North, East, West, South, and never entering a blocked cell or stepping outside of the grid. You will write functions that compute and output such a path if one exists, or otherwise report that there is none.

In the example above, suppose that cells (3,0), (3,2), (0,1) and (1,1) are blocked. We will represent grids in a textual form, denoting blocked cells with \mathbf{x} , and denoting cells that are not blocked by \mathbf{o} . Thus, the grid with these blocked cells is represented as:

If the start cell is (0,0) and the goal is (0,2), then a path from start to goal is

$$(0,0), (1,0), (2,0), (2,1), (2,2), (1,2), (0,2).$$

We can represent this path in our textual representation as follows:

Here, **s** denotes the start, **g** denotes the goal, and the * symbols denote the cells visited in this path from start to goal. Note that the letters **s** and **g** overwrite the * symbols from the corresponding cells of the path. If the start and the goal are the same cell, then the cell should be marked with **g**.

Alternatively, we can represent this path as a sequence of directions as follows:

Move from (0,0) to (2,0).

Turn North.

Move from (2,0) to (2,2).

Turn West.

Move from (2,2) to (0,2).

You have arrived at your destination.

You will have to implement functions for reading the description of a grid from a given file and computing a path for the start to the goal location in the grid, or determining that there is no such path. Recall that a path should not enter blocked cells or exit the grid. You will also have to implement functions for outputting a computed path, in each of the two formats above: as the textual representation on the grid, and as a sequence of move and turn directions. Finally, you also have to implement functions for getting and changing the state of the grid (blocked cells, and start and goal locations).

A detailed description of the functions of the class is given in Grid.h.