Artificial Intelligence

(Harvard CS182, Fall 2015)

Lecture Notes on Propositional Logic

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1 Introduction

One of the central goals of artificial intelligence is to be able to model human reasoning. We would expect a reasoning agent to be able to start with a set of knowledge and be able to draw conclusions about the statements relating to this input. This task seems quite far from our previous two units on search and constraint satisfaction, although we will see that it is closely related.

In the next few lectures we will explicitly discuss the task of reasoning about knowledge. We introduce a very simple form of a logic known as propositional logic, and show how it can be used

to encode sets of facts, known as knowledge bases. We then show how to use these knowledge bases to reason about new statements. To do this we will transform the logical representation into a form that again allows us to use the tools and language of search. We finish with a brief survey of the area of **planning**, which uses a logical representation to reason about sequences of events.

2 A Running Example: Medical Diagnosis

Consider the following flowchart distributed to help people with flu-like symptoms to perform self-diagnostics.

\AM@currentdocname .png		
		\ 73.60
.png		\AM@currentdocname .png
.png		
·hu8 —	nna	
	·hrig	

If we treat the state of a patient and the recommended action as a set of possible worlds, this chart can be seen as a knowledge base in propositional logic which will be the main focus of this note.

For simplicity let's cut down the number of possible symptoms to around 10. In English, we can roughly interpret these statements as saying:

- You may have the flu only if you have a cough in addition to a fever or are sweating.
- If you may have the flu and you have confusion or vomiting then call the emergency room.
- If you may have the flu but don't think it's an emergency, and you are over 65, then call the doctor.

It allows us to ask and answer formal questions about the structure of the world. For instance we might wonder:

• If I may have the flu does this mean that I am sweaty?

When we return to this example, we will see algorithms that allow us to answer these types of queries.

3 Propositional Logic

3.1 The Logic Framework

In this class we'll be considering a simple variant of **formal logic**. In this framework we assume that there is an underlying state of the world which is completely described by a **model** (used here in a formal sense). For now, we will treat the model m abstractly as some member of the set of all possible worlds \mathcal{M} . In the next section we will explicitly define the type of models of interest.

Logic allows us to make statements about the world, which we will call sentences. Under some worlds a sentence α may evaluate to true, and in others it may evaluate to false. In the first case (true), we say that the model **satisfies** the sentence. We use the notation $\mathcal{M}(\alpha)$ to specify all the subset of models that satisfy a given sentence.

We can also consider the relationship between two logical sentences α and β . If the statement α implies that β is true, we say α **entails** β and write this as $\alpha \models \beta$. The entailment relationship can be defined set-theoretically using models. Formally:

$$\alpha \models \beta \text{ iff } \mathcal{M}(\alpha) \subset \mathcal{M}(\beta),$$

That is α entails β is all models satisfied by α are also satisfied by β .

In practice we will very rarely be able to enumerate all the possible worlds in order to check entailment relations. However this provides an important vocabulary for thinking about the underlying assumptions of formal logic.

3.2 Syntax and Semantics of Propositional Logic

Now we look at specific variant of logic known as propositional logic. In propositional logic, we define a model as a mapping from atomic variables to true or false. That is we assume world consists of a set of proposition variables, and a model simply specifies whether each specific proposition is true or false in the current world, i.e. $m: \mathcal{P} \mapsto \{\top, \bot\}$.

3.3 Syntax and Semantics

Next we define a language for constructing sentences α about our propositional world. Unlike natural language, the sentence will come from a language with formally defined syntax and semantics. The following chart describes each of the symbols in the logic and their informal meaning.

Name	Syntax	Description
literal	P,Q	Reference to underlying propositions in ${\cal P}$
true	Т	Symbol for true
false	\perp	Symbol for false
not	\neg	$\neg P$ is true iff P is false in m
conjunction/and	\wedge	$P \wedge Q$ is true iff P and Q is true in m
disjunction/or	V	$P \lor Q$ is true iff P or Q is true in m
conditional	\Rightarrow	
biconditional	\Leftrightarrow	

AIMA also gives the full specification for the grammar, order of operations, and truth table of these symbols. It generally follows the standard mathematical standards for these symbols. For instance here is the definition of conditional:

P	Q	$P \Rightarrow Q$
\perp	\perp	()
\perp	T	
Т	\perp	
T	T	

3.4 Knowledge Base

Using a logical formalism we can define a knowledge base (KB) as a collection of conjoined (\land) sentences from the formalism. Implicitly our knowledge base *KB* defines the set of worlds $\mathcal{M}(KB)$ of interest.

Once we have a knowledge base, we can issue **queries** α consisting of logical statements about the knowledge base. In particular we will be interested in whether the knowledge base entails the question, i.e. $KB \models \alpha$.

The simplest way to do this would be to use **model checking**. Here we utilize the theory of entailment and check whether $\mathcal{M}(KB) \subset \mathcal{M}(\alpha)$. We could do this be constructing the two sets of models and confirming a subset relation, or by finding a contradiction.

3.5 Example: Medical Diagnostics

As a running example, we will consider the following flowchart distributed to help people with flu-like symptoms to perform informal self-diagnostics.

Now let us return to our diagnostics example. Recall that the diagram tells us the following relationship:

- You may have the flu only if you have a cough in addition to a fever or are sweating.
- If you may have the flu and you have confusion or vomiting then call the emergency room.
- If you may have the flu but don't think it's an emergency, and you are over 65, then call the doctor.

As noted above: If we treat the state of a patient and the recommended action as a set of possible worlds, this chart can be seen as a knowledge base in propositional logic. Here's what it looks like:

```
(((Fever \lor Sweaty) \land Cough)) \Leftrightarrow MayHaveFlu) \land \\ ((MayHaveFlu \land (Confusion \lor Vomiting) \Rightarrow Emergency) \land \\ ((MayHaveFlu \land \neg Emergency \land Over65) \Rightarrow CallDoctor)
```

The knowledge base contains 9 propositions:

Propositions	$\mathcal{M}(\mathit{KB})_1$	$\mathcal{M}(\mathit{KB})_2$	$\mathcal{M}(KB)_3$	
Cough		Т	Т	
SWEATY	\perp	T	\perp	
FEVER	\perp	\perp	T	
CONFUSION	\perp	\perp	\perp	
Vomiting	\perp		\perp	
Over65	\perp	\perp	\perp	
MAYHAVEFLU		Т	Т	
EMERGENCY	\perp	\perp	\perp	
CALLDOCTOR			Т	

Question 1 How many possible worlds exist, what is the size of $|\mathcal{M}|$?



We could in theory enumerate all models that satisfy this *KB*, however we will see that there are easier ways to do reasoning.

As an example consider a query α we might issue to this knowledge base,

• If I may have the flu does this imply that I am sweaty?

As an example, consider a query α we might issue to this knowledge base: "if I may have the flu does this imply that I am sweaty"?

Model checking method would enumerate all models that are consistent with the KB and the query. If $M(\alpha) \subset \mathcal{M}(KB)$ then it is entailed. Conversely, if we can find a model that is in $\mathcal{M}(KB)$ but violates the sentence they we can conclude the opposite.

Question 2 *Does KB* $\models \alpha$?



4 Inference

As an alternative to model-based reasoning we can instead perform reasoning based on **inferences**. Starting from a knowledge base KB we will attempt to transform the logical representation to find our goal sentence α . We can do this by applying a set of classical inference **rules**.

An inference rule takes a set of premises and returns a new sentence as a conclusion:

We can extend the set of knowledge by applying inference rules to the current data. For instance the simplest inference **modus ponens** or implication elimination adds the conclusion of a conditional:

$$\frac{\alpha \Rightarrow \beta \quad \alpha}{\beta}$$

Another is simply eliminating a conjuntion:

$$\frac{\alpha \wedge \beta}{\alpha}$$

We can also express DeMorgan's laws as inferences:

$$\frac{\neg(\alpha \land \beta)}{\neg\alpha \lor \neg\beta}$$

4.1 Search and Inference

Using these rules we can define a search problem. This brings us back to our trusty search specification.

Name	Туре	Description
State		
Initial state		
Actions		
Result		
Goal		

There are two desirable properties of inference rules.

Definition 1 A rule is **sound** if it is truth preserving, i.e. it does not change the set of models.

Definition 2 A set of rules is **complete** if they are guaranteed to find a solution, when used with a complete search algorithm

AIMA gives a set of sound rules for propositional logic and an informal assertion that they are complete. However there is much simpler cleaner inference strategy for dealing with propositional logic.

5 Resolution

An even better method than searching with inference rules to is to use resolution. Instead of trying to produce the query, resolution instead aims to find a **proof by contradiction**. It first assumes the negation of the query, and then tries to find a contradiction. Formally, define any sentence α as **satisfiable** if there exists a model for which it is true, i.e. $\mathcal{M}(\alpha)$ is not empty. We can then find entailment using the rule:

$$\alpha \models \beta$$
 iff $(\alpha \land \neg \beta)$ is unsatisfiable

For **resolution**, for a query α and knowledge base KB, we first construct $KB \wedge \neg \alpha$ and then search for a proof of unsatisfiability.

5.1 Resolution for Propositional Logic

Our aim for resolution will be to produce a contradiction of the form $p \land \neg p$, where p is a literal. We will do this by adding more sentences to the KB until we discover a contradiction or run out of inference rules to apply.

Consider a sentence in the KB consisting of a disjunction of possibly negated literals $l_1 \vee ... \vee l_k$. We call this a **clause**. If we also know from the KB that any of the literals are false, i.e. $\neg l_i$, we can remove it from the list, producing a smaller disjunctive clause. This is called a **unit resolution**:

$$\frac{l_1 \vee \ldots \vee l_k \quad \neg l_i}{l_1 \vee \ldots \vee l_{i-1} \vee l_{i+1} \vee \ldots \vee l_k}.$$

However we don't need to just do unit resolutions, if there is a another clause $m_1 \vee ... \vee m_n$ that contains the negation of any literal in l then we can soundly resolve the two clauses. This is called **general resolution**:



The key idea of propositional resolution is that if the KB only consists of clauses, then general resolution is the only inference rule needed to produce a complete inference algorithm.

- Soundness: The resolution rule is truth preserving
- Completeness: It is always able to find a proof.

But what about all the other elements besides disjunction (\vee) and literal negation (\neg)? Well it turns out we can apply a transformation that removes these elements from the problem entirely.

5.2 Conjunctive normal form

Conjunctive normal formal (CNF) is a general representation for propositional logic, that consists only of conjoined clauses with propositions or negative propositions. While much more difficult to read than general propositional logic, it can represent all possible propositional sentences. To convert a sentence in propositional logic to CNF we apply the following 4 transformations.

- 1. Biconditional Elimination: Replace $\alpha \Leftrightarrow \beta$ with $(\alpha \Rightarrow \beta) \land (\beta \Rightarrow \alpha)$
- 2. Conditional Elimination: Replace $\alpha \Rightarrow \beta$ with $\neg \alpha \lor \beta$.
- 3. Move ¬ inward. Demorgan's rules

$$\neg(\alpha \land \beta) \triangleq (\neg\alpha \lor \neg\beta)$$
$$\neg(\alpha \lor \beta) \triangleq (\neg\alpha \land \neg\beta)$$

4. Distribute \vee over \wedge .

$$\alpha \vee (\beta \wedge \gamma) \triangleq (\alpha \vee \beta) \wedge (\alpha \vee \gamma)$$

The final form of the KB will now be a conjunction of disjunctive clauses. That is a conjunction of phrases each containing only \vee and \neg applied to atomic propositions.

Example Let's convert the medical KB into CNF:

• Original

```
(((Fever \lor Sweaty) \land Cough) \Leftrightarrow MayHaveFlu) \land \\ ((MayHaveFlu \land (Confusion \lor Vomiting) \Rightarrow Emergency) \land \\ ((MayHaveFlu \land \neg Emergency \land Over65 \Rightarrow CallDoctor)
```

• Step 1 Biconditional

• Step 2 Conditional

٥

• Step 3 De Morgan's Laws

```
 (\neg MayHaveFlu \lor ((Fever \lor Sweaty) \land Cough)) \land \\ ((\neg Fever \land \neg Sweaty) \lor \neg Cough) \lor MayHaveFlu) \land \\ ((\neg MayHaveFlu \lor (\neg Confusion \land \neg Vomiting) \lor Emergency) \land \\ ((\neg MayHaveFlu \lor Emergency \lor \neg Over65 \lor CallDoctor)
```

• Step 4 Redistribute

```
(\neg MAYHAVEFLU \lor FEVER \lor SWEATY) \land \\ (\neg MAYHAVEFLU \lor COUGH) \land \\ (\neg FEVER \lor COUGH \lor MAYHAVEFLU) \land \\ (\neg SWEATY \lor COUGH \lor MAYHAVEFLU) \land \\ (\neg CONFUSION \lor \neg MAYHAVEFLU \lor EMERGENCY) \land \\ (\neg VOMITING \lor \neg MAYHAVEFLU \lor EMERGENCY) \land \\ (\neg MAYHAVEFLU \lor EMERGENCY) \lor (\neg MAYHAVEFLU \lor EMERGENCY) \land \\ (\neg MAYHAVEFLU \lor EMERGENCY) \lor \neg OVER65 \lor CALLDOCTOR)
```

One step of general resolution then yields:

 \neg MayHaveFlu \lor Fever \lor Sweaty $(\neg$ Sweaty \lor Cough \lor MayHaveFlu)

5.3 Resolution Algorithm

This brings us to the full resolution algorithm for inference.

- Create a new KB by adding $\neg \alpha$, i.e. $KB \land \neg \alpha$
- Convert to CNF.
- Repeatedly apply resolution.
 - If there are no new clauses to resolve, the KB does not entail α .
 - If there an empty clause is produce, we have a contradiction and KB does entail α .

We can show that given enough time this algorithm will either find a contradiction or find no new clauses to resolve. This gives a simple complete algorithm propositional logic.

However, there is a big *but* here. We have not discussed at all the complexity of this approach. This problem of determining whether a propositional statement is satisfiable is known as SAT. If you took CS-121 you know that a variety of this problem 3-SAT is perhaps the most famous problem in computer science. This is one of Karp's original 21 problems, and one of the first problems to be proven NP-Complete. Therefore for general logic we can't hope to find efficient solutions. That being said there are many cases where variants of resolution and goal directed search are able to find solutions to real-world versions.

6 Planning

So far we have discussed logic in the context of inference in a static world. In practice though the underlying model may be in constant flux. In planning we explicitly incorporate **actions** that change the underlying model. In many ways this is similar to the actions that occur in search. However, planning will utilize propositional logic to explictly declare exactly which actions are applicable in each state and how they update the state of the world.

The upside of this extra information is that it will allow us to use general purpose planners to perform search. These planners can take advantage of the logical representation to generate effective heuristics for the planning search problem without requiring domain knowledge.

6.1 Closed-World Assumption

Before discussing planning, we need to make one change to our current assumptions about the semantics of propositional logic, known as the closed-world assumption. So far, we have been assuming that all propositions in the world are explicitly included in the knowledge base. In the closed-world assumption we allow there to be arbitrary additional propositions, but that they are assumed to be false in all models .

For instance in the medical diagnosis example, we might pose a closed world query of the form:

IsDoctor ∨ Coughing

Which would not be implied since ISDOCTOR is not in the knowledge-base and is assumed to be false and COUGHING may or may not be true.

We can take this a step further and make **lifted** literals for an occupation. Say for any occupation *a* is the following statement implied:

Is(a) ∨ Coughing

Don't let the function notation confuse you here, we can think of there being many different propositions Is(Doctor), Is(Lawyer), Is(Policeman), etc. Each of these is just an atomic proposition like ISDOCTOR. Since none of them are seen, they are assumed to be \bot .

6.2 Planning As Search

A planning problem fits under our standard definition of search. Note though that unlike in the last section, we are not trying to tell if a query is entailed from a knowledge base.

Instead in planning our state will consist of complete models. We start with an explicit model of the world, and at each step we apply actions that update the model until we reach a model that satisfies the goal condition. The ACTIONS function and the goal test will be based on whether the model satisfies a logical condition.

Name	Туре	Description
State	\mathcal{M}	A model specified with the closed world assumption
Initial state		An explicit model, specified as a conjunction of literals.
Actions		The list of actions that match the explicit pre-conditions (see below)
Result		A model transformed by the action's effects (see below).
Goal		Does the model satisfy a logical goal condition?

6.3 Actions

The core of planning is a set of actions which modify the current state of the world. AIMA uses the example of an airline logistics system that moves goods from one city to the next. As part of the system there may be an action like the following:

```
Action ( LOAD(c, p, a),

Precond : AT(c, a) \wedge AT(p, a) \wedge CARGO(c) \wedge PLANE(p) \wedge AIRPORT(a)

Effect : \negAT(c, a) \wedge IN(c, p))
```

where this is an implied for all c, p, a. We read this as follows: for cargo c, plane p, and airport a, if the cargo and place are at airport a, then this action can be applied to take remove cargo from airport a and put it on plane p. If current state of the world is:

```
CARGO(Elephant) \land PLANE(767) \land AT(Elephant, JFK) \land AT(767, JFK) \land HASEARS(Elephant)
```

Then this action could be applied to transform the state to

$$CARGO(Elephant) \land PLANE(767) \land IN(Elepant, 767) \land AT(767, JFK) \land HASEARS(Elephant)$$

In general we interpret actions to mean if the current model state satisfies the precondition α , then the action is **applicable** and we can update the state model with effect β .

In the planning language described in AIMA, PDDL, all states, effects and goal tests are assumed to be conjunctions of (possibly negated) literals. This makes it quite simple to match the preconditions and goal states as well as keep track of the world.

6.4 World Updates

Let us now be a bit more explicit about what it means to update the world. The effect gives a list of literals that must occur in the new world.

Since we are using the closed-world assumption, the current state can be represented as simply a list of positive literals (since all others are assumed to be false). Each positive effect is simply added to the list, and negative effects are removed. In practice this can be implemented as a set operation where the result of an action is:

$$RESULT(s, a) = (s \setminus DEL(a)) \cup ADD(a)$$

Additionally, because actions are generic functions over all arguments of their input, it is required that every variable have some precondition. This effectively **grounds** the action by the current model. Without this condition there could be potentially unbounded actions where say any lifted literal say AT(*Elepant*, *JFK*), AT(*Elepant*, *OHare*), or even AT(*Elepant*, *Elephant*) could be produced as an effect.

6.5 Full Example:

As a simple example of planning, we consider the famous wolf, goat, and cabbage problem dating from the 9th century. The problem states:

A man has to cross a stream in a boat that can hold himself and only one other object. He needs to transport a wolf (lion, jackal), a goat (sheep), and a cabbage (bundle of hay, pumpkin). He must be sure that when he is out in the boat the wolf does not eat the goat and the goat does not eat the cabbage.

We formulate this as a planning problem. (Generally the AIMA description requires that preconditions should only be positive or negative literals, for simplicity here we allow a negative conjunction).

```
Init \qquad \mathsf{ON}(\mathsf{Left},\mathsf{Wolf}) \land \mathsf{ON}(\mathsf{Left},\mathsf{Goat}) \land \mathsf{ON}(\mathsf{Left},\mathsf{Cabbage}) \land \mathsf{ON}(\mathsf{Left},\mathsf{Boat}) \\ \land \mathsf{ACROSS}(\mathsf{Left},\mathsf{Right}) \land \mathsf{ACROSS}(\mathsf{Right},\mathsf{Left}) \\ \textit{Action} \qquad ( \quad \mathsf{MOVE}(s,s',a), \\ \mathsf{Precond} : \mathsf{ACROSS}(s,s') \land \mathsf{ON}(s,\mathsf{Boat}) \land \mathsf{ON}(s,a) \land \\ \neg(\mathsf{ON}(s',\mathsf{Wolf}) \land \mathsf{ON}(s',\mathsf{Goat})) \land \neg(\mathsf{ON}(s',\mathsf{Goat}) \land \mathsf{ON}(s',\mathsf{Cabbage})), \\ \mathsf{Effect} : \neg \mathsf{ON}(s,\mathsf{Boat}) \land \neg \mathsf{ON}(s,a) \land \mathsf{ON}(s',\mathsf{Boat}) \land \mathsf{ON}(s',a)) \\ \textit{Action} \qquad ( \quad \mathsf{MOVE-EMPTY}(s,s'), \\ \mathsf{Precond} : \mathsf{OTHERSIDE}(s,s') \land \mathsf{ON}(s,\mathsf{Boat}) \land \\ \neg(\mathsf{ON}(s',\mathsf{Wolf}) \land \mathsf{ON}(s',\mathsf{Goat})) \land \neg(\mathsf{ON}(s',\mathsf{Goat}) \land \mathsf{ON}(s',\mathsf{Cabbage})), \\ \mathsf{Effect} : \neg \mathsf{ON}(s,\mathsf{Boat}) \land \mathsf{ON}(s',\mathsf{Boat})) \\ \mathsf{Goal} \qquad \mathsf{ON}(\mathsf{Right},\mathsf{Wolf}) \land \mathsf{ON}(\mathsf{Right},\mathsf{Goat}) \land \mathsf{ON}(\mathsf{Right},\mathsf{Cabbage}) \\ \end{aligned}
```

XKCD finds this version of the problem a little silly. Figure ?? gives their interpretation. Here is the path that they take for this problem.

```
s_0 = \text{ON}(\text{Left}, \text{Wolf}) \land \text{ON}(\text{Left}, \text{Goat}) \land \text{ON}(\text{Left}, \text{Cabbage}) \land \text{ON}(\text{Left}, \text{Boat})
a_0 = \text{MOVE}(\text{Left}, \text{Right}, \text{Goat})
s_1 = \text{ON}(\text{Left}, \text{Wolf}) \land \text{ON}(\text{Right}, \text{Goat}) \land \text{ON}(\text{Left}, \text{Cabbage}) \land \text{ON}(\text{Right}, \text{Boat})
a_1 = \text{MOVE-EMPTY}(\text{Right}, \text{Left})
s_1 = \text{ON}(\text{Left}, \text{Wolf}) \land \text{ON}(\text{Right}, \text{Goat}) \land \text{ON}(\text{Left}, \text{Cabbage}) \land \text{ON}(\text{Left}, \text{Boat})
a_2 = \text{MOVE}(\text{Left}, \text{Right}, \text{Cabbage})
s_2 = \text{ON}(\text{Left}, \text{Wolf}) \land \text{ON}(\text{Right}, \text{Goat}) \land \text{ON}(\text{Right}, \text{Cabbage}) \land \text{ON}(\text{Right}, \text{Boat})
a_2 = \text{MOVE}(\text{Right}, \text{Left}, \text{Cabbage})
```

