

# Ardusplotit


Proof of concept for Arduino code injection



# Ardusploit: author



Help → About:

- Real job: security engineer and analyst @  SORINT<sub>SEC</sub>
- Hobby: everything technological related, with a special interest in security stuff
- I worked on a lot of open source projects, software and hardware related. I built a custom Arduino compatible board as a programmable GPS tracker (hereyouARE)
- Find details at: <http://enerduino.blogspot.com>

# Ardusplotit: The Project



## The idea: inject arbitrary code in an unknown sketch:

- Dump flash content
- Manipulate the dumped content (HEX file format)
- Inject the payload
- Reflash „injected“ dump

# Ardusploit: General thoughts



- AVR is not only Arduino. It is used in a lot of different products: home automation, industrial PCL, HID devices (Xbox controllers for example with AT43USB353M) and so on.
- AVR family product is very wide, with a lot of different chips with different features
- Atmel (now Microchip) did a great job in documenting all the features: if lost, just look for datasheets on the website

# Ardusploit: AVR architecture

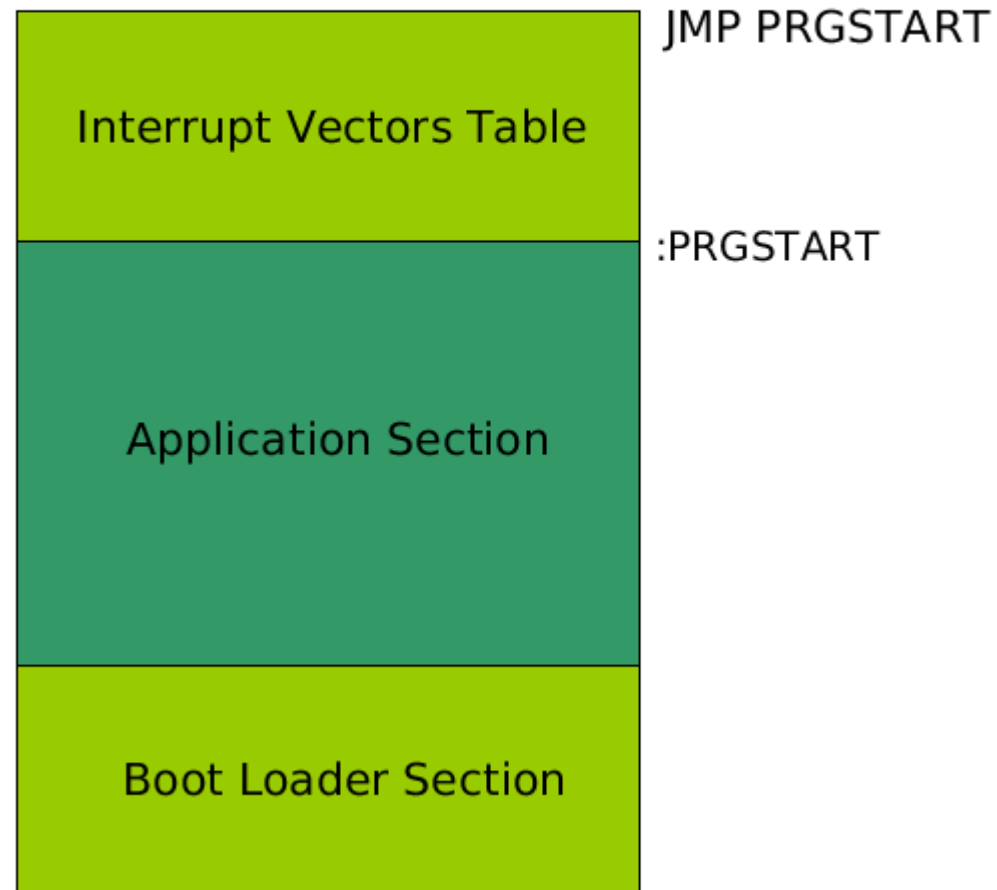


Feature of the AVR MCUs:

- Flash, EEPROM and SRAM are all integrated on the same chip
- Program instructions are stored in the Flash
- Size of the programs can vary from 32 to 64 KB (or 256KB), depending on the MCU model.  
**All the running code must reside on the flash**
- EEPROM is available for permanent data storing
- The MCU are all 8-bit, but the instruction set is built on instruction of one or two 16 bit words (JMP and CALL are two 16 bit words opcodes)
- Most of the instructions are 1 or 2 clock cycles; JMP and CALL requires 3 or 4 clock cycles instead

# Ardusploit: AVR architecture

## Flash Memory



# Ardusploit: AVR architecture



## Fuses

Fuses bits are a set of bits used by the MCU to store its initial configuration, like:

- Clock speed
- Watchdog timer
- Bootloader location

Fuses can be read with AVR toolchain utilities (avrdude)

# Ardusploit: AVR architecture



## Fuses

| Features   |   |
|--|---|
| Int. RC Osc. 8 MHz; Start-up time PWRDWN/RESET: 6 CK/14 CK + 65 ms; [CKSEL=0010 SUT=10]; default value |   |
| <input type="checkbox"/>   | Clock output on PORTB0; [CKOUT=0]                               |
| <input checked="" type="checkbox"/>  | Divide clock by 8 internally; [CKDIV8=0]                        |
| <input type="checkbox"/>   | Boot Reset vector Enabled (default address=\$0000); [BOOTRST=0] |
| Boot Flash section size=2048 words Boot start address=\$3800; [BOOTSZ=00] ; default value ▼            |   |
| <input type="checkbox"/>   | Preserve EEPROM memory through the Chip Erase cycle; [EESAVE=0] |
| <input type="checkbox"/>   | Watch-dog Timer always on; [WDTON=0]                            |
| <input checked="" type="checkbox"/>  | Serial program downloading (SPI) enabled; [SPIEN=0]             |
| <input type="checkbox"/>   | Debug Wire enable; [DWEN=0]                                     |
| <input type="checkbox"/>   | Reset Disabled (Enable PC6 as i/o pin); [RSTDISBL=0]            |
| Brown-out detection disabled; [BODLEVEL=111] ▼   |   |



# Ardusploit: AVR architecture



## **Bootloader**

When the AVR is powered or reset, it starts the boot sequence: depending on „Fuses“ status, it will start from address 0x0000 or with the bootloader

The bootloader sets an environment for the application code to execute. .It is used for:

- initialize the controller peripherals
- load selected user application
- start the code (execute)
- upload new code

**Avoid to mess up with bootloader code**

# Ardusploit: AVR architecture



```
sketch_may30a $  
void setup() {  
    // put your setup code here, to run once:  
  
}  
  
void loop() {  
    // put your main code here, to run repeatedly:  
  
}  
|
```

# Ardusploit: AVR architecture



## Interrupt Vector Table

The interrupt vector table is usually placed at the beginning of the flash. This is true for „Arduino“ devices, but it can also change, depending on:

- BOOTRST fuse bit
- IVSEL bit in MCU Control Register

From AVR datasheet:

| BOOTRST | IVSEL | Reset Address      | Interrupt Vectors Start Address |
|---------|-------|--------------------|---------------------------------|
| 1       | 0     | 0x0000             | 0x0002                          |
| 1       | 1     | 0x0000             | Boot Reset Address + 0x0002     |
| 0       | 0     | Boot Reset Address | 0x0002                          |
| 0       | 1     | Boot Reset Address | Boot Reset Address + 0x0002     |

# Ardusplotit: AVR architecture



## Interrupt Vector Table Description

| Vector No. | Program Address <sup>(2)</sup> | Source       | Interrupt Definition  |
|------------|--------------------------------|--------------|---|
| 1          | \$0000 <sup>(1)</sup>          | RESET        | External Pin, Power-on Reset, Brown-out Reset, Watchdog Reset, and JTAG AVR Reset |
| 2          | \$0002                         | INT0         | External Interrupt Request 0  |
| 3          | \$0004                         | INT1         | External Interrupt Request 1  |
| 4          | \$0006                         | INT2         | External Interrupt Request 2  |
| 5          | \$0008                         | INT3         | External Interrupt Request 3  |
| 6          | \$000A                         | INT4         | External Interrupt Request 4  |
| 7          | \$000C                         | INT5         | External Interrupt Request 5  |
| 8          | \$000E                         | INT6         | External Interrupt Request 6  |
| 9          | \$0010                         | INT7         | External Interrupt Request 7  |
| 10         | \$0012                         | PCINT0       | Pin Change Interrupt Request 0  |
| 11         | \$0014                         | PCINT1       | Pin Change Interrupt Request 1  |
| 12         | \$0016 <sup>(3)</sup>          | PCINT2       | Pin Change Interrupt Request 2  |
| 13         | \$0018                         | WDT          | Watchdog Time-out Interrupt   |
| 14         | \$001A                         | TIMER2 COMPA | Timer/Counter2 Compare Match A  |
| 15         | \$001C                         | TIMER2 COMPB | Timer/Counter2 Compare Match B  |
| 16         | \$001E                         | TIMER2 OVF   | Timer/Counter2 Overflow   |

## Interrupt Vector Table Disassembly

```
00000000 <.sec1>:
0: 0c 94 35 00 jmp 0x6a ; 0x6a
4: 0c 94 5d 00 jmp 0xba ; 0xba
8: 0c 94 5d 00 jmp 0xba ; 0xba
c: 0c 94 5d 00 jmp 0xba ; 0xba
10: 0c 94 5d 00 jmp 0xba ; 0xba
14: 0c 94 5d 00 jmp 0xba ; 0xba
18: 0c 94 5d 00 jmp 0xba ; 0xba
1c: 0c 94 5d 00 jmp 0xba ; 0xba
20: 0c 94 5d 00 jmp 0xba ; 0xba
24: 0c 94 5d 00 jmp 0xba ; 0xba
28: 0c 94 5d 00 jmp 0xba ; 0xba
2c: 0c 94 5d 00 jmp 0xba ; 0xba
30: 0c 94 5d 00 jmp 0xba ; 0xba
34: 0c 94 5d 00 jmp 0xba ; 0xba
38: 0c 94 5d 00 jmp 0xba ; 0xba
3c: 0c 94 5d 00 jmp 0xba ; 0xba
40: 0c 94 26 02 jmp 0x44c ; 0x44c
44: 0c 94 5d 00 jmp 0xba ; 0xba
48: 0c 94 f4 01 jmp 0x3e8 ; 0x3e8
4c: 0c 94 ce 01 jmp 0x39c ; 0x39c
50: 0c 94 5d 00 jmp 0xba ; 0xba
```

# Ardusploit: AVR architecture



Different MCUs may have different behavior (compiler dependent):

- The position of the vector interrupt can be different (datasheets helps)
- The Interrupt Vector Table can be different: ATMEGA2560 use RJMP (16 bit opcode) instead of JMP (32 bit opcode)

# Ardusplotit: AVR architecture



## Entry Point

```
a4: 21 97      sbiw    r28, 0x01      ; 1
a6: fe 01      movw    r30, r28
a8: 0e 94 85 03 call    0x70a    ; 0x70a
ac: c4 33      cpi     r28, 0x34      ; 52
ae: d1 07      cpc     r29, r17
b0: c9 f7      brne    .-14          ; 0xa4
b2: 0e 94 70 02 call    0x4e0    ; 0x4e0
b6: 0c 94 90 03 jmp     0x720    ; 0x720
ba: 0c 94 00 00 jmp     0          ; 0x0
be: cf 92      push    r12
c0: df 92      push    r13
c2: ef 92      push    r14
c4: ff 92      push    r15
```

```
$ avr-objdump -j .sec1 -d -m avr5 --disassemble-zeroes <HEX file name>
```

# Ardusplotit: AVR architecture

## Entry Chain

```
00000000 <.sec1>:  
0: 0c 94 35 00    jmp    0x6a    ; 0x6a  
4: 0c 94 5d 00    jmp    0xba    ; 0xba  
8: 0c 94 5d 00    jmp    0xba    ; 0xba
```

```
6a: 11 24          eor     r1, r1  
a6: fe 01          movw   r30, r28  
...  
ae: d1 07          cpc     r29, r17  
b0: c9 f7          brne   .-14          ; 0xa4  
b2: 0e 94 83 02    call   0x506    ; 0x506  
b6: 0c 94 a3 03    jmp     0x746    ; 0x746  
ba: 0c 94 00 00    jmp     0         ; 0x0
```

```
506: 78 94          sei  
508: 84 b5          in      r24, 0x24    ; 36  
50a: 82 60          ori     r24, 0x02      ; 2  
50c: 84 bd          out     0x24, r24     ; 36  
50e: 84 b5          in      r24, 0x24    ; 36  
510: 81 60          ori     r24, 0x01      ; 1  
512: 84 bd          out     0x24, r24     ; 36  
514: 85 b5          in      r24, 0x25    ; 37  
516: 82 60          ori     r24, 0x02      ; 2  
518: 85 bd          out     0x25, r24     ; 37  
51a: 85 b5          in      r24, 0x25    ; 37  
51c: 81 60          ori     r24, 0x01      ; 1  
51e: 85 bd          out     0x25, r24     ; 37
```

# Ardusplotit: dump flash



The dump of the MCU flash is done via the well-known AVR toolchain utilities:

```
avrdude -C/opt/arduino-1.8.2/hardware/tools/avr/etc/avrdude.conf -q -patmega328p -carduino  
-P/dev/ttyACM0 -b115200 -D -Uflash:r:/tmp/flash.hex:i
```

- -D        disable auto erase
- -q        quiet output
- -p        part no (MCU)
- -c        programmer
- -U        perform memory operation: read(r):filename:format (i=HEX)





# Ardusploit: disassemble dump



The dump can be disassembled with several tools:

- avr-objdump
- radare2
- IDA Pro
- AVR-Studio
- ...several other...



# Ardusplotit: manipulate dump

```
[+] Running for MCU: atmega328p with insert-flag: 1092C100
: 20 0000 00 D2C00000FEC00000FCC00000FAC00000F8C00000F6C00000F4C00000F2C00000 46
: 20 0020 00 F0C00000EEC00000ECC00000EAC00000E8C00000E6C00000E4C00000E2C00000 78
: 20 0040 00 E0C00000ABC20000DCC00000DAC00000D8C00000D6C00000D4C00000F6C10000 E4
: 20 0060 00 D0C0000065C200003AC20000CAC00000C8C00000C6C00000C4C00000C2C00000 2F
: 20 0080 00 C0C00000BEC00000BCC00000BAC00000B8C00000B6C00000B4C00000B2C00000 98
: 20 00A0 00 B0C00000AEC00000ACC00000AAC00000A8C00000A6C00000A4C00000A2C00000 F8
: 20 00C0 00 A0C000009EC000009CC000009AC0000098C0000096C0000094C0000092C00000 58
: 20 00E0 00 90C00000000002200250028002B002E003100340002010000050108010B010000 65
: 20 0100 00 2100240027002A002D003000330001010000040107010A010505050507050808 6F
```

: Line start  
20 Byte count (on the line)  
0000 Address  
00 Record type (00 Data, 01 EOF, ...).  
ABCD Data  
78 Checksum (two's complement of the least significant byte of the sum of all decoded byte values in the record preceding the checksum)



# Ardusplotit: ASM crash course (2 slides)



- Registers: we have 32 general purpose 8-bit registers (r0-r31). All logic and arithmetic ops operates on these. RAM is accessed with load and store operations
- Special Registers:
  - PC: 16- or 22 bit program counter (holds **next** instruction to be executed)
  - SP: 8- or 16 bit stack pointer
  - SREG: 8 bit status register
- Status bits:
  - 0: C → Carry Flag
  - 1: Z → Zero Flag
  - 2: N → Negative Flag
  - 3: V → Overflow Flag
  - 4: S → Sign Flag
  - 5: H → Half carry flag (BCD arithmetic)
  - 6: T → T bit copy (BST opcode)
  - 7: I → Interrupt flag



# Ardusplotit: ASM crash course (2 slides)



## Instruction syntax:

```
mov r10, r0           ; move content of r0 in r10
out 0x0b, r0          ; write the content of r0 in the specified port
```

It uses „Intel Syntax“, with destination before source.

Opcodes are documented in AVR site:

DEC

16-bit Opcode:

|      |      |      |      |
|------|------|------|------|
| 1001 | 010d | dddd | 1010 |
|------|------|------|------|



# Ardusplotit: inject code

Prepare the payload. The blink sample. This may differ for each MCU:

```
sbi    0x04, 7      ; Set port as output
in     r24, 0x24    ; Turn LED on
andi   r24, 0x7F
out    0x24, r24
sbi    0x05, 7
ldi    r18, 0xFF    ; DELAY
ldi    r24, 0xE1
ldi    r25, 0x04
subi   r18, 0x01
sbci   r24, 0x00
sbci   r25, 0x00
brne   .-8
rjmp   .+0
in     r24, 0x24    ; Turn LED off
andi   r24, 0x7F
out    0x24, r24
cbi    0x05, 7
ldi    r18, 0xFF    ; DELAY
ldi    r24, 0xE1
ldi    r25, 0x04
subi   r18, 0x01
sbci   r24, 0x00
sbci   r25, 0x00
brne   .-8
rjmp   .+0
```



# Ardusplotit: inject code

Prepare the payload. Serial output for 328p:

```
ldi    r24, 0x41      ; 65 'A'
ldi    r18, 0x00
ldi    r19, 0x2C
cli
sbi    0x0a, 1        ; DDRD (pin 0-7 set Tx)
cbi    0x0b, 1        ; PORTD (clear bit Tx, setting it as out)
in     r0, 0x0b
ldi    r25, 0x03
mov    r18, r19      ; loop
dec    r18
brne   .-4           ; -4 bytes (dec r18)
bst    r24, 0
bld    r0, 1
lsr    r25
ror    r24
out    0x0b, r0      ;
brne   .-18          ; -18 bytes (loop)
```



# Ardusplotit: inject code

## Available payloads in the script.

```
# Payload. Must ends with RETI (opcode 1895)

payloadDictionary_blink = {
  # Blink 0.1sec payload for atmega328p
  'atmega328p': '1F920F920FB60F9211242F933F934F935F938F939F93AF93BF93EF93FF93259A80E092EEA4E0B0E02B2F4A2F592F2D9A815090

  # Blink 0.1sec payload for atmega32u4
  'atmega32u4': '1F920F920FB60F9211242F933F934F935F938F939F93AF93BF93EF93FF933F9A479A8FEF91EE24E0815090402040E1F700C088

  # Blink 0.1sec payload for atmega2560
  'atmega2560': '1F920F920FB60F9211242F933F934F935F938F939F93AF93BF93EF93FF93279A84B58F7784BD2F9A2FEF81EE94E02150804090
}

payloadDictionary_hello = {
  # "Hello World" payload for atmega328p
  'atmega328p':
  '0F922F933F938F939F9388E420E03CE2F894519A59980BB093E0232F2A95F1F780FB01F8969587950BB8B9F785E620E03CE2F894519A59980BB0
78FE620E03CE2F894519A59980BB093E0232F2A95F1F780FB01F8969587950BB8B9F782E720E03CE2F894519A59980BB093E0232F2A95F1F780FB
}
```



# Ardusplotit: inject code



If the timer interrupt vector is in use, the script detect it and appends the code (prepend to tell the true) at the existing one:

```
251 #
252 # Check if Timer interrupt is already used
253 #
254 def isTimerUsed(vectorJump, prog, mcu):
255
256     # Find instruction pointed by the vector address
257     p = BitArray('0x' + prog[vectorJump:vectorJump+4])
258     p.byteswap() # Correct endianness
259
260     if mcu == 'atmega2560':
261         # ATMEGA2560 uses rjmp, so requires specific check
262         b = BitArray(p)
263         # Get the offset of rjmp
264         offset = re.match('110[10](.....)', b.bin).group(1)
265         o = BitArray('bin:12=' + offset)
266         # Read the instruction at offset
267         i = vectorJump + (o.int * 4) + 4
268         opcode = prog[i+2:i+4] + prog[i:i+2]
269         # Get again the offset of the rjmp
270         b = BitArray('0x' + opcode)
271         offset = re.match('110[10](.....)', b.bin)
272         if offset:
273             o = BitArray('bin:12=' + offset.group(1))
274             # Check if the jmp go back to 0, if so the vector is not used
275             if (abs(o.int * 4) - (i + 4)) == 0:
276                 return False
277         else:
278             # Extract the opcode
279             opcode = prog[p.int*4:(p.int+2)*4]
280
281             # Check if pointed opcode is 0C940000 (JMP 0), if so the vector is not used
282             if opcode == '0C940000':
283                 return False
284
285     return True
```





# Ardusplotit: inject code

```
6 void loop() {  
7   // put your main code here, to run repeatedly:  
8   int a = 0;  
9  
10  asm volatile("nop\nnop\nnop\nnop");  
11  
12  a += 1;  
13  
14  asm volatile("nop\nnop\nnop\nnop");  
15 }
```

avr-objdump

```
7  
8 27e: c0 e0      ldi r28, 0x00 ; 0  
9 280: d0 e0      ldi r29, 0x00 ; 0  
10 282: 00 00      nop  
11 284: 00 00      nop  
12 286: 00 00      nop  
13 288: 00 00      nop  
14 28a: 00 00      nop  
15 28c: 00 00      nop  
16 28e: 00 00      nop  
17 290: 00 00      nop  
18 292: 20 97      sbiw r28, 0x00 ; 0  
19
```

# Ardusploit: inject code - Timers



MCUs usually have 3 Timer Interrupts:

- Timer0 (8 bit): used by delay(), millis() and micros() functions
- Timer1 (16 bit): used by Servo library
- Timer2 (8 bit): another timer like the Timer0
- Timer3,4,5 (16 bit): available on ATMega 2560 board



# Ardusploit: inject code - Timers



Timers are increased at each clock tick.

In CTC mode, the interrupt is triggered when the timer reaches a specific value.

By choosing the match value and the speed you can control the frequency of the interrupt.



# Ardusploit: inject code - Timers



Timer speed:

At 16Mhz, we have a tick every 0,000000063 sec.

Assuming 16 bit timer (65535) you can have a trigger every 0,004 sec (~4ms)

You can control the speed with prescaler (1, 8, 64, 256 or 1024)



# Ardusplot: inject code - Timers

## Prescaler:

Prescaler can be set via the proper control register, in this case TCCR1B (Timer1) and CSxx bits:

| Bit           | 7     | 6     | 5 | 4     | 3     | 2    | 1    | 0    |        |
|---------------|-------|-------|---|-------|-------|------|------|------|--------|
|               | ICNC1 | ICES1 | – | WGM13 | WGM12 | CS12 | CS11 | CS10 | TCCR1B |
| Read/Write    | R/W   | R/W   | R | R/W   | R/W   | R/W  | R/W  | R/W  |        |
| Initial Value | 0     | 0     | 0 | 0     | 0     | 0    | 0    | 0    |        |

Table 14-6. Clock Select Bit Description

| CS12 | CS11 | CS10 | Description   |
|------|------|------|---|
| 0    | 0    | 0    | No clock source (Timer/Counter stopped).                |
| 0    | 0    | 1    | $\text{clk}_{\text{IO}}/1$ (no prescaling)              |
| 0    | 1    | 0    | $\text{clk}_{\text{IO}}/8$ (from prescaler)             |
| 0    | 1    | 1    | $\text{clk}_{\text{IO}}/64$ (from prescaler)            |
| 1    | 0    | 0    | $\text{clk}_{\text{IO}}/256$ (from prescaler)           |
| 1    | 0    | 1    | $\text{clk}_{\text{IO}}/1024$ (from prescaler)          |
| 1    | 1    | 0    | External clock source on T1 pin. Clock on falling edge. |
| 1    | 1    | 1    | External clock source on T1 pin. Clock on rising edge.  |

# Ardusploit: inject code - Timers



The interrupt is triggered when the ticks reach the value in „Compare Match Register“.

To compute the value:

Clock Speed/Prescaler Speed/Frequency

Example, if we use a 16Mhz MCU, 256 prescaler and 2Hz (2 per sec):

$$16,000,000/256/2 = 31,250$$



# Ardusplotit: inject code

Sets up the timer interrupt (TIMER1\_COMPA):

```
noInterrupts();           // disable all interrupts
TCCR1A = 0;
TCCR1B = 0;
TCNT1  = 0;

OCR1A = 31250;             // compare match register: 16000000/256/2
TCCR1B |= (1 << WGM12);   // sets CTC mode
TCCR1B |= (1 << CS12);     // sets 256 prescaler
TIMSK1 |= (1 << OCIE1A);  // enable timer compare interrupt
interrupts();
```

```
cli
sts    0x0080, r1
ldi    r30, 0x81
ldi    r31, 0x00
st     Z, r1
sts    0x0085, r1
sts    0x0084, r1
ldi    r24, 0x12
ldi    r25, 0x7A
sts    0x0089, r25
sts    0x0088, r24
ld     r24, Z
ori    r24, 0x08
st     Z, r24
ld     r24, Z
ori    r24, 0x04
st     Z, r24
ldi    r30, 0x6F
ldi    r31, 0x00
ld     r24, Z
ori    r24, 0x02
st     Z, r24
sei
```



# Ardusploit: inject code

Find free space to inject the code in HEX file:

- Avoid bootloader area
- Look for unused space (0xFF). The script tries to find this proper aligned space
- If not available we have two options: we don't actually have space, or it has been „overwritten“ with something different than 0xFF





# Ardusplotit: inject code

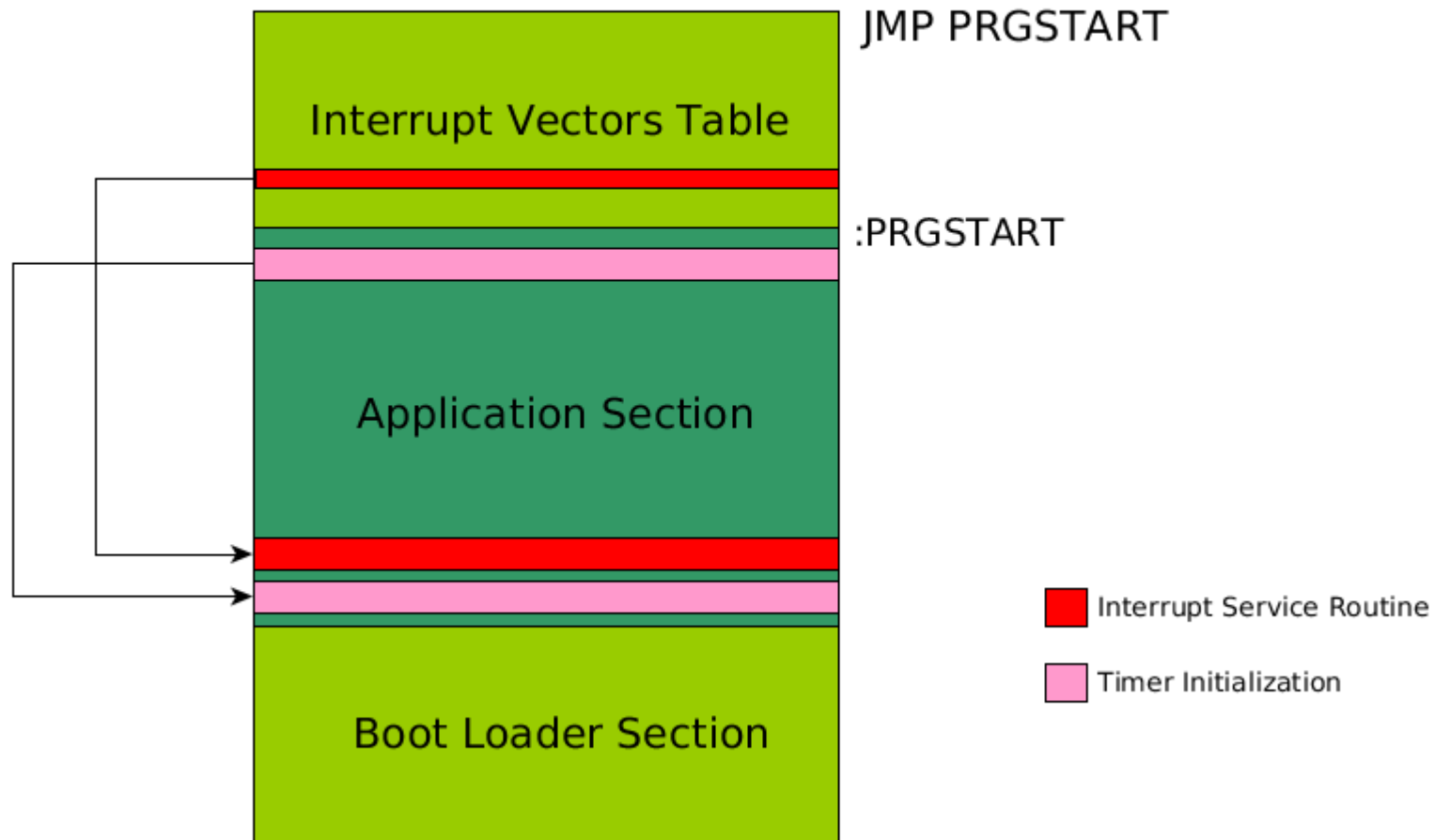
Prepare the hex file to be written back:

```
if timerUsed == False:
    if mcu == 'atmega2560':
        prog = prog[:isrJump] + '0C94' + fixedAddrPayload.hex + prog[isrJump + 8:insertPoint + 8] + '0C94' + fixedAddrInit
    else:
        prog = prog[:isrJump] + fixedAddrPayload.hex + prog[isrJump + 4:insertPoint + 8] + '0C94' + fixedAddrInit.hex + pr
else:
    if mcu == 'atmega2560':
        # Do not modify the entry point, just rely on existing ISR initialization
        prog = prog[:isrJump] + '0C94' + fixedAddrPayload.hex + prog[isrJump + 8:]
    else:
        # Do not modify the entry point, just rely on existing ISR initialization
        prog = prog[:isrJump] + fixedAddrPayload.hex + prog[isrJump + 4:]
```



# Ardusploit: Injected Flash

## Flash Memory



# Ardusploit: ardusploit.py



What ardusplot.py can do for you:

- It gives you some sample payloads, ready to be modified
- It has a ready and usable Interrupt initialization routine
- It finds free space in the Flash to place payload and Interrupt Initialization routine
- It place the code and takes care of the „replaced“ code, relocating the instructions
- It automatically manages the presence of an existing ISR, managing and placing all the needed opcodes
- It fully prepares the HEX file to be written back to the Flash



# Ardusploit: Options



## Available script options:

ardusplot.py -f <inputfile>

- v verbose output
- d dry-run, do not apply any modification
- m specify MCU to work with (default: atmega328p)
- t type of payload to inject (default: blink)
- i insert-flag, the instructions after which inject the code
- p hex payload address, no validation will be performed  
(automatically computed if omitted)
- P hex init payload address, no validation will be performed  
(automatically computed if omitted)



# Ardusploit: Automate the process



With few things like:

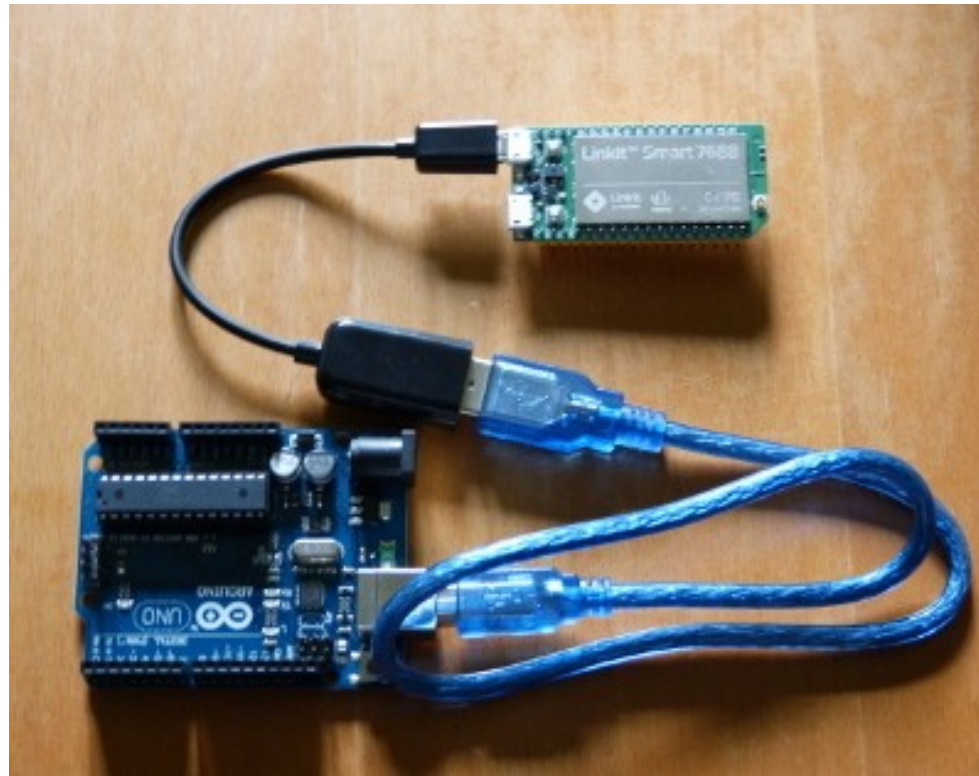
- a 13\$ device (Linkit Smart, Raspberry or something with python support)
- “hotplug2” daemon script
- avrdude + ardusploit
- 30 seconds

You can inject the code without pressing any key



# Ardusploit: Automate the process

Hardware:



# Ardusplot: Automate the process

## Software:

```
#!/bin/sh

BINARY="/IoT/as.sh"
PROID="2341/43/1"

if [ "${PRODUCT}" = "${PROID}" ]; then
    if [ "${ACTION}" = "add" ]; then
        if [ "${DEVPATH}" = "/devices/101c1000.ohci/usb2/2-1/2-1:1.1" ]; then
            ${BINARY}
        fi
    fi
fi
```

```
logger -t ARDUSPLOIT "Starting"

logger -t ARDUSPLOIT "Dumping Flash"
/usr/bin/avrdude -C/etc/avrdude.conf -q -patmega328p -carduino -P/dev/ttyACM0 -b
115200 -D -Uflash:r:/IoT/flash.hex:i

logger -t ARDUSPLOIT "Running injection script"
cd /IoT
/IoT/ardusplot.py -f flash.hex

logger -t ARDUSPLOIT "Writing Flash"
/usr/bin/avrdude -C/etc/avrdude.conf -q -patmega328p -carduino -P/dev/ttyACM0 -b
115200 -D -Uflash:w:/IoT/flash.hex.injected:i

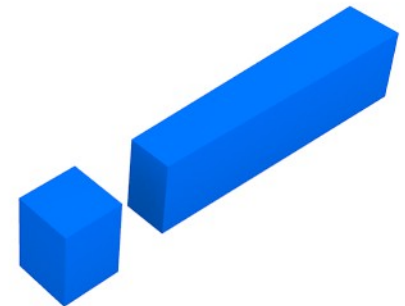
logger -t ARDUSPLOIT "End"
```



# Ardusploit: Live Demo



## LIVE DEMO CODE REVIEW





# Ardusploit: Resources



- ATMEL AVR datasheets

- AVR Assembly:

[https://www.microchip.com/webdoc/avrassembler/avrassembler.wb\\_instruction\\_list.html](https://www.microchip.com/webdoc/avrassembler/avrassembler.wb_instruction_list.html)

[https://en.wikipedia.org/wiki/Atmel\\_AVR\\_instruction\\_set](https://en.wikipedia.org/wiki/Atmel_AVR_instruction_set)

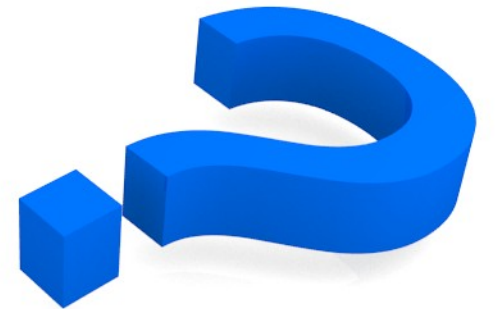
<http://www.avr-tutorials.com>

- Fuses:

<http://www.engbedded.com/fusecalc/>

- Script:

<https://github.com/cecio/>



# Ardusplotit

