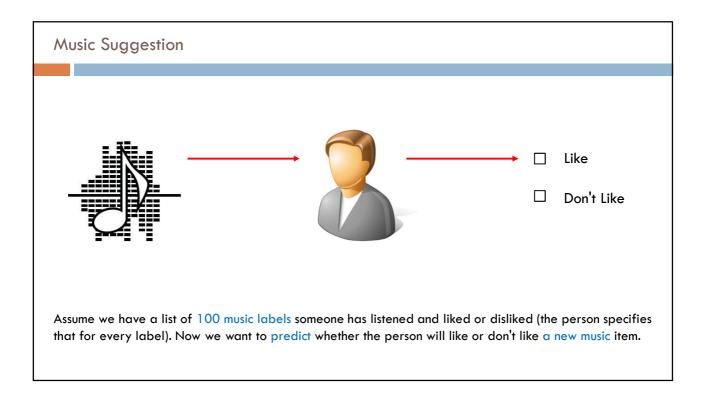
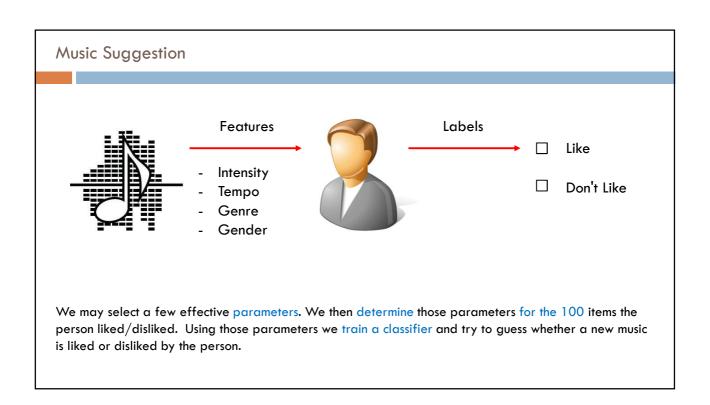
MACHINE LEARNING FOR DATA MINING LECTURE 2-1: SCATTER PLOTS, DECISION SURFACES

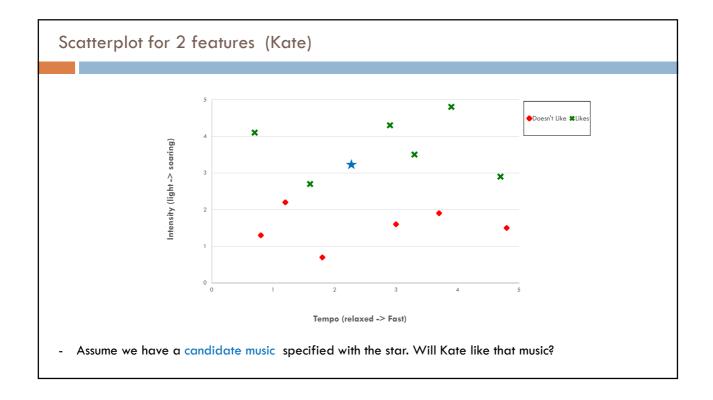
Siamak Sarmady (Urmia University of Technology) Sebastian Thrun, Katie Malone (Google)

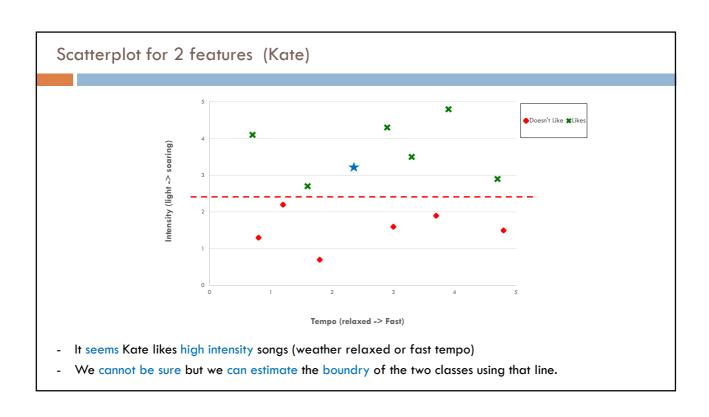
Inductive (Supervised) Learning

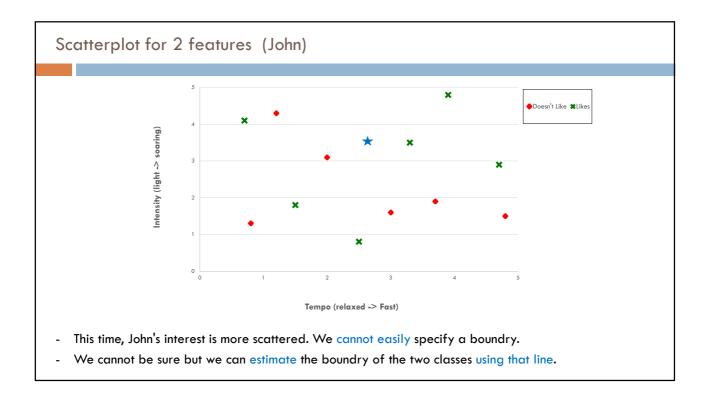
- \Box Given examples of a function (X, F(X))
- $\ \square$ Build a function (or model) that can predict F(X) for new examples X
 - □ **Discrete F(X)**: Classification
 - □ Continuous F(X): Regression
 - **F**(X) = Probability(X) : Probability estimation
 - in fact a regression with output value in the range of [0,1]

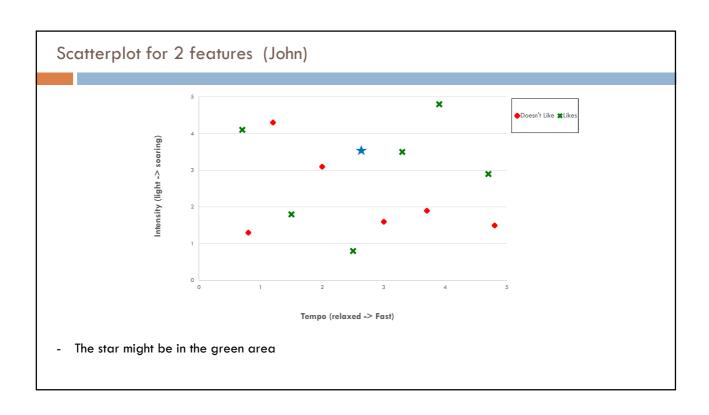


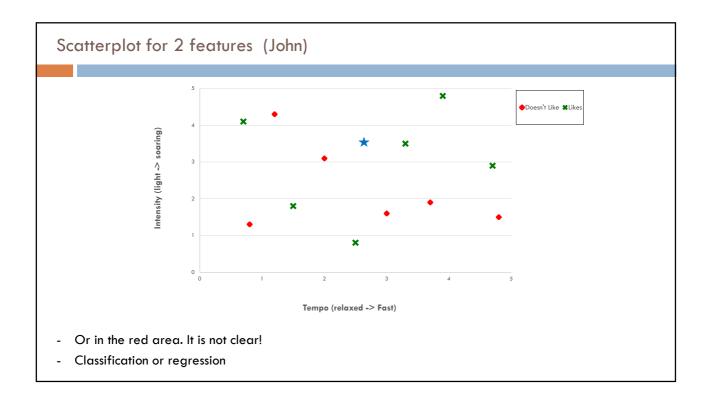


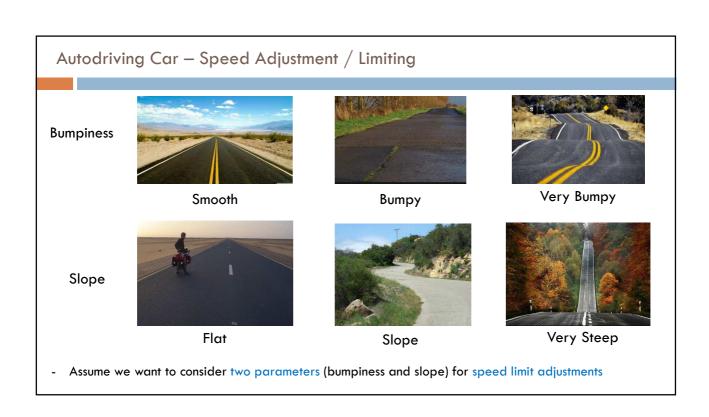




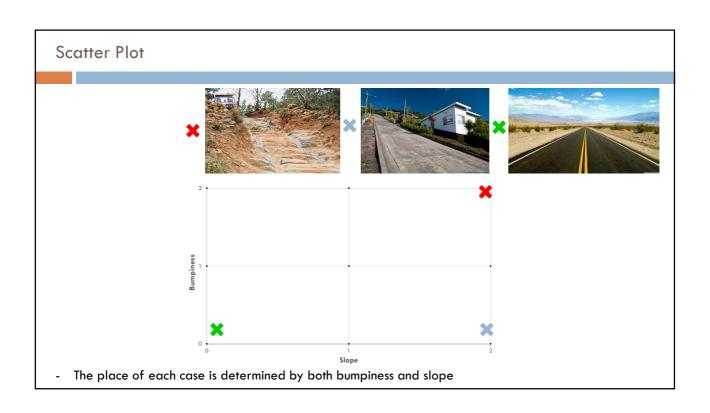




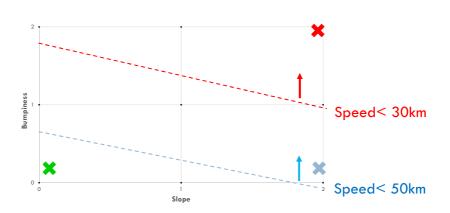






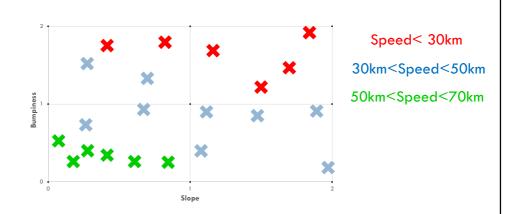


Speed Limiting – without learning



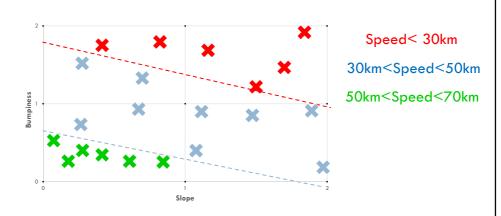
- Based on the area of the scatter plot we may determine the proper speeds. We call these lines 'Class Boundries' or 'Decision surface'. We can also design a discrete speed limit function like v = f(S,B) ...
- In this example, we manually design the behaviour of the car...

Speed Limiting – with learning



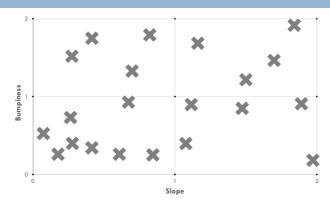
- If we want to use learning, we drive the car in different places and situations, with proper speeds. The sensors gather slope, bumpiness and speed levels (i.e. One of 3). We then use the data for learning.
- Note: we have decided to have 3 different speed limits even before performing the experiments

Speed Limiting – with learning



- What machine learning is doing, is to find decision surfaces that separates classes
- Based on those surfaces (and the sensor values for slope and bumpiness), the car decides on a proper speed limit

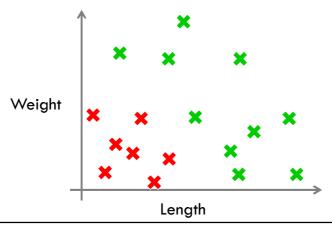
Cruise Speed Adjustment



- What if we wanted the mechanism to determine the proper cruise speed (Instead of speed limit ranges)?
- We would need the speed of each of those data points (i.e. continuous) instead of just speed level (discrete class).
- We then would need the supervised learning algorithm to solve a regression problem and estimate a function for us i.e. v = f(s,b). The function would then calculate the proper speed for every continuous value of slope and bumpiness
- We would need a 3rd dimension to show the speed function.

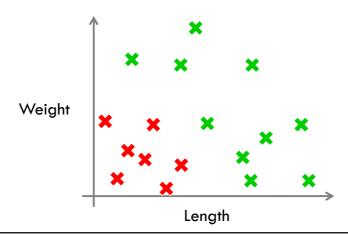
Decision Surface

- □ What machine learning does, is to define a decision surface which separates the data into two or more classes.
- □ Assume we have 1000 kg of Tuna fish. We want to select quality ones and send them to market. A worker selects fishes manually and we record the parameters and his decisions.



Decision Surface

□ Based on learning data, the machine will select those fishes that fall in green section. Those in red section are too small to be sold.



Decision Surface Now the decision boundry can be used for the decision making about the future fishes. We actually generalize what we learned to unseen cases. Don't send to market Weight

Length

Linear Decision Surface If the decision surface is a line, we call it a linear decision surface. You may calculate different lines for the purpose. Which one is the best? What is a good decision surface? - Red line misclassifies 1 point, it is to near to red data points - Blue line misclassifies multiple data points - The black line seems more ok

Good Decision Surface

□ A good decision surface is the line which gives low error for the learning data

as well as

it generalizes the learned knowledge in a way that the average error is lowest for the unseen data.

Classification:

□ Data -> Decision Surface -> Predictions (Generalization)

Regression:

□ Data -> Function (model) -> Predictions (Generalization)