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IVP Assignment 4

```
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```

Creating a new environment.

```
clc;
clear all;
close all;
```

Image Imports

```
orig_fingerprint = imread('C:\Chanakya\Projects\ivp-assignments
\Assignment-3\images\fingerprint.jpg');
fingerprint = rgb2gray(orig_fingerprint);
```

Adding Noise to the image

Noise is added to the image via the following distribution:

```
P(a) if a

P(b) if b

else 1 - P(a) - P(b)

[row, col] = size(fingerprint);
noise = randi(255, row, col);
noisy_image = fingerprint;
noisy_image(noise<=15)=0;
noisy_image(noise>=240) = 255;
```





Using the Median Filter

The median filtered image is obtained by the following expression:

```
f(x,y) = median_{(s,t) \in S_{x,y}}(g(s,t))
median\_filtered\_image = median\_filter(noisy\_image, 3, 3);
figure('Name', 'Median Filtering', 'units', ... 'normalized', 'outerposition', [0 0 1 1]);
subplot(1, 2, 1)
imshow(mat2gray(noisy\_image));
title('Salt and Pepper added Noisy Image');
subplot(1, 2, 2)
imshow(mat2gray(median\_filtered\_image));
title('Median Filtered Image');
```





Using the Contraharmonic Filter

The contraharmonic filtered image is obtained via the following expression:

$$f(x,y) = \frac{\sum_{(s,t) \in S_{x,y}} g(s,t)^{(Q+1)}}{\sum_{(s,t) \in S_{x,y}} g(s,t)^{(Q)}}$$







Conclusion

Through this assignment, we observed how salt and pepper noise can be generated. We also observerved that the median filter is useful for elimating salt and pepper noise and the contraharmonic filter with a positive Q value eliminates only pepper noise and with a negative Q value, elimanates only salt noise.

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