

INVOICE

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Ref: 20221013

13/10/2022

Total: \$4821.00

Payment would be appreciated within 7 days.

Bank Details

Name: T.E. Harris
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Description	Hours	Rate	Total
Work onsite TSA per hour on project SBC2022	133:55	\$36.00	\$4821.00
Total			\$4821.00

Date	Description	Start	Finish	Break	Hours
			\$4,821.00	\$36.00	133:55:00
24/08/2022	Plan project, start designing hardware.	9:00	18:10	0:30	8:40:00
25/08/2022	More schematic design, look at Arduino libraries, place order with Digikey for parts.	8:00	17:30	0:30	9:00:00
26/08/2022	Schematic Design completed. Build prototype Relay unit & Sensor unit. Made a start on software.	7:30	18:30	0:45	10:15:00
29/08/2022	Hardware & software debugging on Relay & Sensor boards. Started Display board prototype. Able to send commands to MODBUS relay board.	7:20	18:00	0:35	10:05:00
30/08/2022	Getting Relay Driver working, working on getting boards talking to each other.	7:40	18:30	0:30	10:20:00
31/08/2022	Got accelerometer working, trying to get reliable tilt data from it.	7:50	18:20	0:40	9:50:00
01/09/2022	Tilt sort of going, working on controlling bed motor to drive to tilt, found problem where tilt reading sensitive to roll (tilt around perp axis). Got going at last. Trying out Micropython on ESP32. Decided at last that it would be easier to continue with Arduino.	8:00	18:00	0:30	0

05/09/2022	Built Display prototype, got simple proof of concept software running, no display yet.	8:10	18:30	0:30	9:50:00
06/09/2022	Decided to write own MODBUS driver as could not get Arduino lib driver to work. Got simple MODBUS driver to send commands to relay board. LCD on Display unit working but showing nonsense.	7:45	17:50	0:30	9:35:00
07/09/2022	Fixed display, wrong aspect ratio. Reorganised software to share common code. More work on MODBUS driver. Built test jig for bed with gate linear motor.	8:15	18:20	0:30	9:35:00
08/09/2022	LCD demo working on Display board. Lots of work on modbus driver to receive response from slave. Also had to have timeout to recover from no response. Working on better control of motor, at present very jerky.	7:45	18:00	0:30	9:45:00
09/09/2022	Achieved local control of motor with deadband. Modbus reliable. Relay code does crash intermittently, not sure why. Moving control over to Relay getting tilt from Sensor.	8:20	18:10	0:40	9:10:00
11/09/2022	Get MODBUS driver to read tilt from Sensor. Make Atmel Studio project for Relay. Finally got tilt angle working. Fixed crash in Relay code, due to too much printing onto soft serial. Big cleanup of code.	7:45	19:30	2:20	9:25:00
12/09/2022	PCB for Sensor & Relay boards.	8:00	19:30	1:00	10:30:00
13/09/2022	PCB for Sensor & Relay boards. Schematic for Display unit. Boat out	7:30	16:20	0:55	7:55:00