

# Content-based Image Retrieval Using Kernel Methods

Proposal Defense

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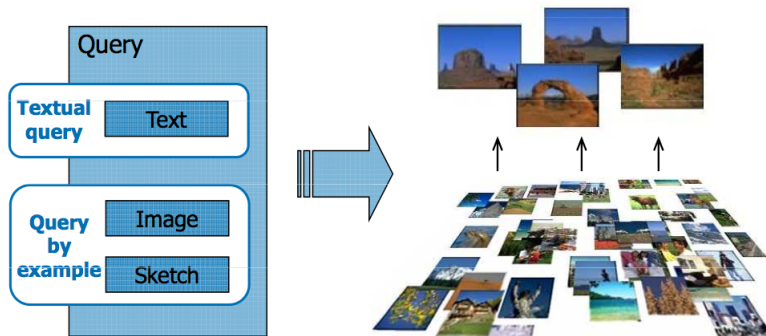
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- What is Content-based Image Retrieval?
- What is Kernel Methods?
- Why is it a good idea to use Kernel Methods?

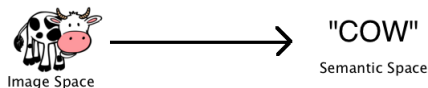
# What is Image Retrieval



*Courtesy of Natalia Vassilieva, Russian Summer School in Information Retrieval 2009*

# What is Image Retrieval

The critical problem is to determine the "meanings" of the images.



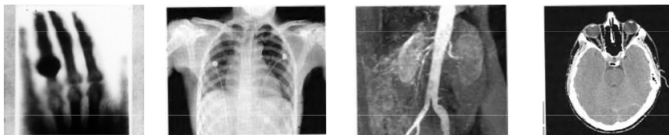
The "meanings" that we allowed to assigned to the images are to be determined by applications. In general human subject can distinguish almost 30,000 "meanings" or categories...

# Application: Image Archives



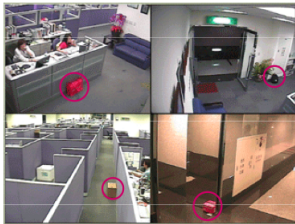
- personal photo collection
- art gallery
- search for uncle John's photos
- search for Monet's painting

# Application: Medical Images



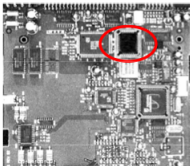
- x-ray
- MRI
- pathological vs healthy

# Application: Security



- suspicious items
- face recognition

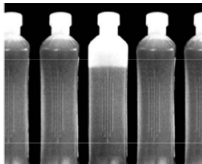
# Application: Industry



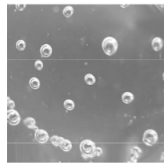
(a) CD-ROM controller



(b) Pack of pills



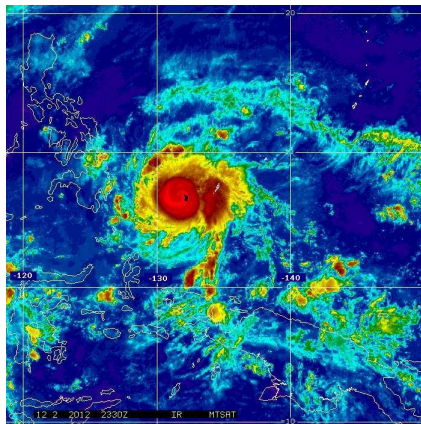
(c) Level of liquid



(d) Air-bladders  
in plastic



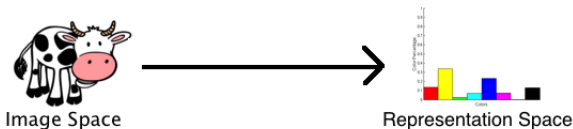
# Application: Satellite Images



- weather monitoring
- military

# Representation Space

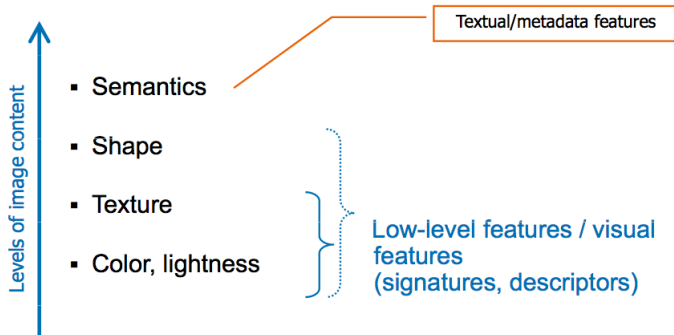
The images must be represented in a way to be processed efficiently.



# Content-based vs. Description-based

	DBIR	CBIR
+	<ul style="list-style-type: none"><li>▪ Fulltext search algorithms are applicable</li><li>▪ Search results corresponds to image semantics</li></ul>	<ul style="list-style-type: none"><li>▪ Automatic index construction</li><li>▪ Index is objective</li></ul>
-	<ul style="list-style-type: none"><li>▪ Manual annotating is hardly feasible</li><li>▪ Manual annotations are subjective</li></ul>	<ul style="list-style-type: none"><li>▪ Semantic gap</li><li>▪ Querying by example is not convenient for a user</li></ul>

# Features



# Similarity

Image A



$x_1^A$   $x_2^A$  ...  $x_N^A$

$y_1^A$   $y_2^A$  ...  $y_M^A$

$z_1^A$   $z_2^A$  ...  $z_K^A$

$\vdots$

Image B



$x_1^B$   $x_2^B$  ...  $x_N^B$

$y_1^B$   $y_2^B$  ...  $y_M^B$

$z_1^B$   $z_2^B$  ...  $z_K^B$

$\vdots$

← Similarity measure →

← Similarity measure →

← Similarity measure →



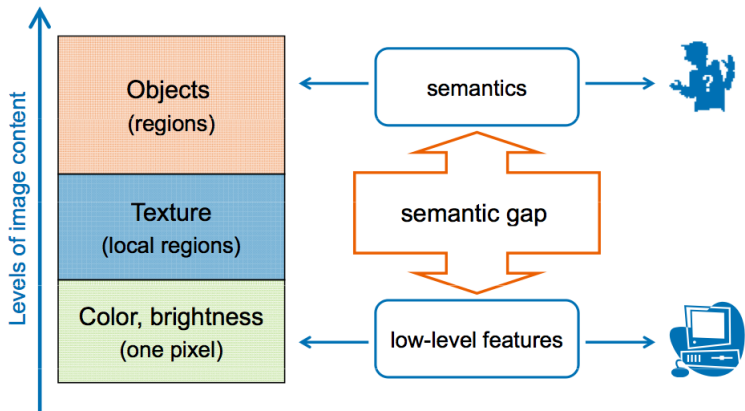
$d_1$

$d_2$

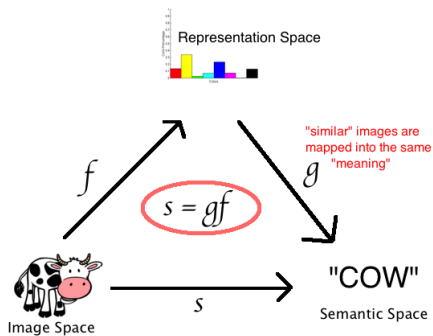
$d_3$

$\vdots$

# Semantic Gap

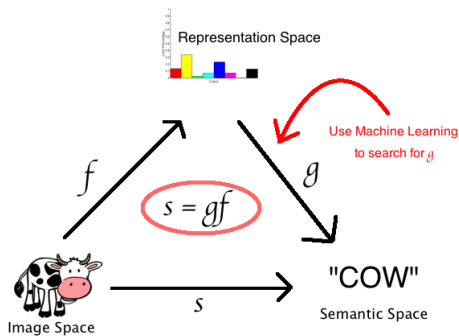


# How They Fit Together?



But sometime the mapping is not that simple....

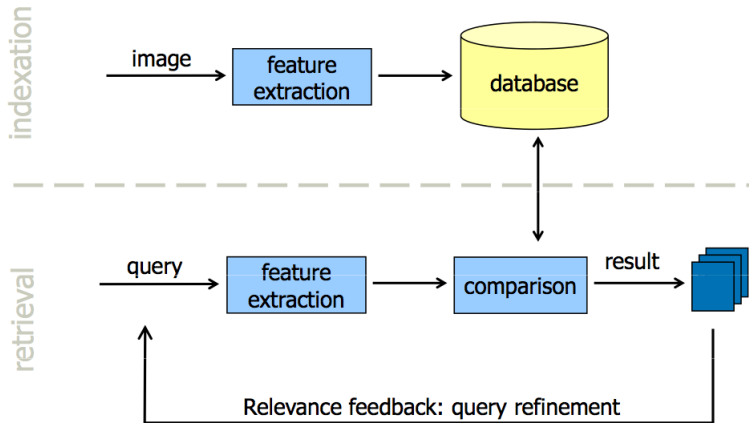
# Where Machine Learning Comes in?



Using similarity measure is equivalent to kNN method...

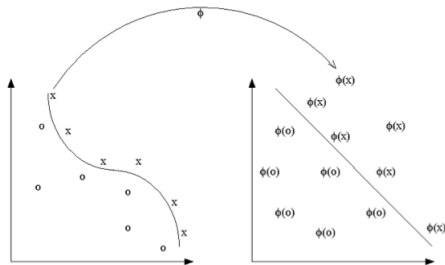


# Main Components



*Courtesy of Natalia Vassilieva, Russian Summer School in Information Retrieval 2009*

# Kernel Methods



$$\phi : X \mapsto H$$

We illustrate the kernel trick by a simple example. Consider the case of linear regression, we have data  $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ , and wish to model it via  $y = w^T \phi(x)$ , where  $\phi$  is some basis functions. The main task here is to learn  $w$  that best fit the data.

The main observation here is that we can write  $w = \sum a_i \phi(x_i)$ , so that  $y = \sum a_i \phi^T(x_i) \phi(x)$ . Now the question involves only the dot product  $\phi^T(x_i) \phi(x)$ , which can be readily replaced by a kernel function  $K(x', x)$

# General Representer Theorem

## Theorem

*Suppose  $X$  is a non-empty set,  $k$  a kernel on  $X \times X$ ,  $\{(x_i, y_i)\}_1^n$  a training sample,  $g$  a monotonically increasing real-valued function,  $c$  an arbitrary cost function, and a class of function*

$$F = \{f \in R^X | f(\cdot) = \sum_1^{\infty} \beta_i k(\cdot, z_i), \beta_i \in R, z_i \in X, |f| < \infty\}$$

*Then any  $f \in F$  minimizing the regularized risk functional*

$$c((x_1, y_1, f(x_1), \dots, (x_m, y_m, f(x_m))) + g(|f|)$$

*admits a representation of the form*

$$f(\cdot) = \sum_1^m \alpha_i k(\cdot, x_i)$$

## Definition

A positive definite kernel  $k(x, x')$  is a function from  $X^2$  to real number such that:

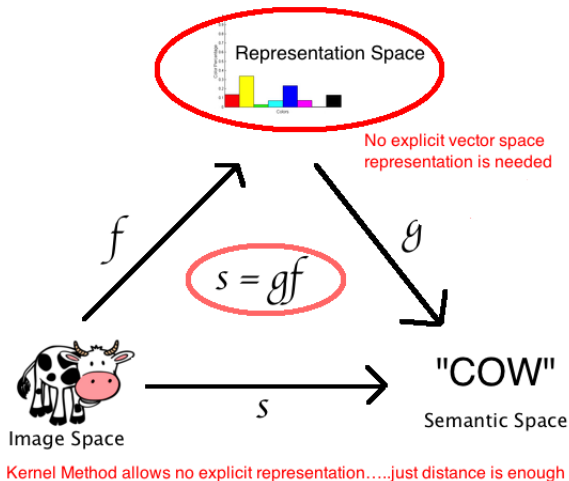
$$\sum_{i,j} a_i a_j k(x_i, x_j) > 0$$

## Theorem (Aronszajn theorem)

*$k$  is a positive definite kernel if and only if there exist a Hilbert Space  $H$  and a mapping  $\phi : X \mapsto H$  such that  $k(x, x') = \phi(x)^T \phi(x')$  for all  $(x, x') \in X^2$*

- no explicit representation, only kernel function
- implicitly calculate in higher dimensional space
- higher dimension  $\Rightarrow$  higher capacity
- separation of data representation and algorithm
- sparse representation - efficient query

# Kernel Methods





## Definition (Kernel Trick)

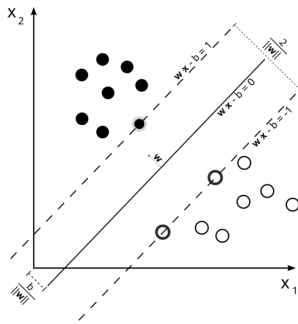
any algorithm for finite-dimensional vectors that only uses pairwise dot-products can be applied in the feature space.

The algorithm and data are separated, hence *Modularity*

# Kernel Examples

- linear kernel,  $k_L(x, x') = x^T x'$  and
- polynomial kernel,  $k_P(x, x') = (x^T x')^d$
- Gaussian RBF kernel,  $k_G(x, x') = \exp(-\frac{|x-x'|^2}{2\sigma^2})$
- Given a distance function  $d$ ,  
 $k(x, y) = \frac{1}{2}(d(x, 0) + d(0, y) - d(x, y))$  is a kernel.

# Support Vector Machine



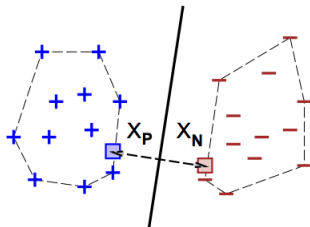
Minimize

$$\frac{1}{2}|w|^2$$

subject to

$$y_i(w \cdot x_i - b) > 1$$

# Support Vector Machine - online version

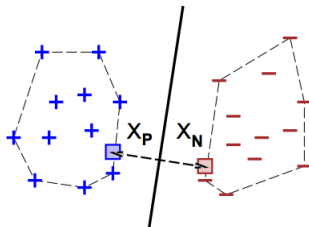


The points  $X_P$  and  $X_N$  can be parametrized as:

$$X_P = \sum_{i \in P} a_i x_i, \sum a_i = 1$$

$$X_N = \sum_{j \in N} a_j x_j, \sum a_j = 1$$

# Support Vector Machine - online version



The solution can be found by optimizing:

$$\max ||X_P - X_N||^2$$

# Support Vector Machine - online version

## UPDATE( $k$ ):

- Compute  $\mathbf{X}_P \mathbf{x}_k$ ,  $\mathbf{X}_N \mathbf{x}_k$ , and  $\mathbf{x}_k \mathbf{x}_k$ .
- Compute  $\lambda_u$  using equations (4) or (5).
- Compute  $\lambda$  using equation (6)
- $\alpha_i \leftarrow (1 - \lambda)\alpha_i$  for all  $i$  such that  $y_i = y_k$ .
- $\alpha_k \leftarrow \alpha_k + \lambda$ .
- Update  $\mathbf{X}_P \mathbf{X}_P$ ,  $\mathbf{X}_N \mathbf{X}_P$  and  $\mathbf{X}_N \mathbf{X}_N$  using equation (7) or (8).

## HULLER:

- Initialize  $\mathbf{X}_P$  and  $\mathbf{X}_N$  by averaging a few points.  
Compute initial  $\mathbf{X}_P \mathbf{X}_P$ ,  $\mathbf{X}_N \mathbf{X}_P$ , and  $\mathbf{X}_N \mathbf{X}_N$ .
- Iterate:
  - Pick a random  $p$  such that  $\alpha_p = 0$
  - **UPDATE**( $p$ )
  - Pick a random  $r$  such that  $\alpha_r \neq 0$
  - **UPDATE**( $r$ )

*The Huller: a simple and efficient online SVM, Antoine Bordes and Leon Bottou*

# Conclusion

- to side-step the need for explicit representation
- to construct a kernel as generalized distance function
- to prune the data for efficiency, for example: to use kNN to narrow down the classes label before training the SVM

# Questions ?

