

# Simulation - Lectures 7 - MCMC: Metropolis Hastings

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Part A Simulation and Statistical Programming

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# Metropolis-Hastings Algorithm

- ▶ The Metropolis-Hastings (MH) algorithm allows to simulate a Markov Chain with any given stationary distribution.
- ▶ We will start with simulation of random variable  $X$  on a discrete state space.
- ▶ Let  $p(x) = \tilde{p}(x)/Z_p$  be the pmf on  $\Omega$ . We will call  $p$  the (pmf of the) target distribution.
- ▶ To simplify notations, we assume that  $p(x) > 0$  for all  $x \in \Omega$
- ▶ Choose a 'proposal' transition matrix  $q(y|x)$ . We will use the notation  $Y \sim q(\cdot|x)$  to mean  $\Pr(Y = y|X = x) = q(y|x)$ .

# Metropolis-Hastings Algorithm

## Metropolis-Hastings algorithm

1. Either set  $X_0 = x_0$ , or draw  $X_0$  from some initial distribution
2. For  $t = 1, 2, \dots, n - 1$ :
  - 2.1 Assume  $X_{t-1} = x_{t-1}$ .
  - 2.2 Simulate  $Y_t \sim q(\cdot|x_{t-1})$  and  $U_t \sim \text{Unif}[0, 1]$ .
  - 2.3 If

$$U_t \leq \alpha(Y_t|x_{t-1})$$

where

$$\alpha(y|x) = \min \left\{ 1, \frac{\tilde{p}(y)q(x|y)}{\tilde{p}(x)q(y|x)} \right\}$$

set  $X_t = Y_t$ , otherwise set  $X_t = x_{t-1}$ .

# Metropolis-Hastings Algorithm

- The Metropolis-Hastings algorithm defines a Markov chain with transition matrix  $P$  such that, for  $x, y \in \Omega$

$$\begin{aligned} P_{x,y} &= \mathbb{P}(X_t = y | X_{t-1} = x) \\ &= q(y|x)\alpha(y|x) + \rho(x)\mathbb{I}(y = x) \end{aligned}$$

where  $\rho(x)$  is the probability of rejection

$$\rho(x) = 1 - \sum_{y \in \Omega} q(y|x)\alpha(y|x).$$

# Metropolis-Hastings Algorithm

## Theorem

The transition matrix  $P$  of the Markov chain generated by the Metropolis-Hastings algorithm is **reversible** with respect to  $p$  and therefore admits  $p$  as **stationary** distribution.

► Proof: We check detailed balance. For  $x \neq y$

$$\begin{aligned} p(x)P_{x,y} &= p(x)q(y|x)\alpha(y|x) \\ &= p(x)q(y|x) \min \left\{ 1, \frac{p(y)q(x|y)}{p(x)q(y|x)} \right\} \\ &= \min \{ p(x)q(y|x), p(y)q(x|y) \} \\ &= p(y)q(x|y) \min \left\{ \frac{p(x)q(y|x)}{p(y)q(x|y)}, 1 \right\} \\ &= p(y)q(x|y)\alpha(x|y) \\ &= p(y)P_{y,x}. \end{aligned}$$

# Metropolis-Hastings Algorithm

- ▶ To run the MH algorithm, we need to specify  $X_0 = x_0$  (or  $X_0 \sim \lambda$ ) and a proposal  $q(y|x)$ .
- ▶ We only need to know the target  $p$  up to a normalizing constant as  $\alpha$  depends only on  $p(y)/p(x) = \tilde{p}(y)/\tilde{p}(x)$ .
- ▶ If the Markov chain simulated by the MH algorithm is **irreducible** and **aperiodic** then the ergodic theorem applies.
- ▶ Verifying aperiodicity is usually straightforward, since the MCMC algorithm may reject the candidate state  $y$ , so  $P_{x,x} > 0$  for at least some states  $x \in \Omega$ .
- ▶ In order to check irreducibility we need to check that  $q$  can take us anywhere in  $\Omega$  (so  $q$  itself is an **irreducible** transition matrix), and then that the acceptance step doesn't trap the chain (as might happen if  $\alpha(y|x)$  is zero too often).

## Example: Discrete Distribution on a finite state-space

- ▶ Consider a discrete random variable  $X \sim p$  on  $\Omega = \{1, 2, \dots, m\}$  with  $\tilde{p}(i) = i$  so  $Z_p = \sum_{i=1}^m i = \frac{m(m+1)}{2}$ .
- ▶ One simple **proposal distribution** is  $Y \sim q$  on  $\Omega$  such that  $q(i) = 1/m$ .
- ▶ Acceptance probability

$$\alpha(y|x) = \min \left\{ 1, \frac{\tilde{p}(y)q(x|y)}{\tilde{p}(x)q(y|x)} \right\} = \min \left\{ 1, \frac{y}{x} \right\}$$

- ▶ This proposal scheme is clearly irreducible

$$\begin{aligned} \mathbb{P}(X_{t+1} = y | X_t = x) &\geq q(y|x)\alpha(y|x) \\ &= \frac{1}{m} \min(1, y/x) > 0 \end{aligned}$$

## Example: Discrete Distribution on a finite state-space

- ▶ Start from  $X_0 = 1$ .
- ▶ For  $t = 1, \dots, n - 1$ 
  1. Let  $Y_t \sim \text{Unif}\{1, 2, \dots, m\}$  and  $U_t \sim \text{Unif}[0, 1]$
  2. If

$$U_t \leq \frac{Y_t}{X_{t-1}}$$

set  $X_t = Y_t$ , otherwise set  $X_t = X_{t-1}$ .

- ▶ For  $t$  large,  $X_t \stackrel{d}{\simeq} X$
- ▶ Note:  $\alpha(y|x) = \min(1, y/x)$  so  $U_t \leq \alpha(y|x) \iff U_t \leq y/x$



## Code

```
set.seed(7)
n <- 10000
m <- 20
x <- numeric(n)
x[1] <- 1
for(t in 1:(n - 1)) {
  Yt <- sample(1:m, 1)
  Ut <- runif(1)
  if (Ut <= (Yt / x[t])) {
    x[t + 1] <- Yt
  } else {
    x[t + 1] <- x[t]
  }
}
```

## Example: Discrete Distribution on a finite state-space

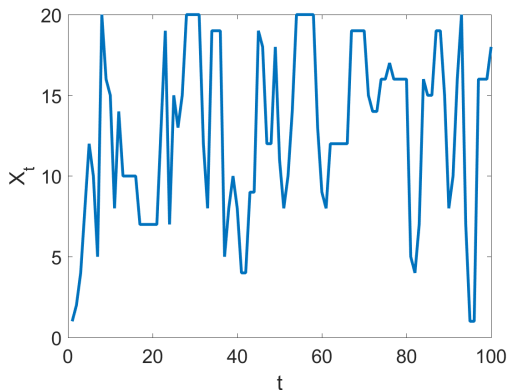


Figure: Realization of the MH Markov chain for  $n = 100$  with  $m = 20$ .

## Example: Discrete Distribution on a finite state-space

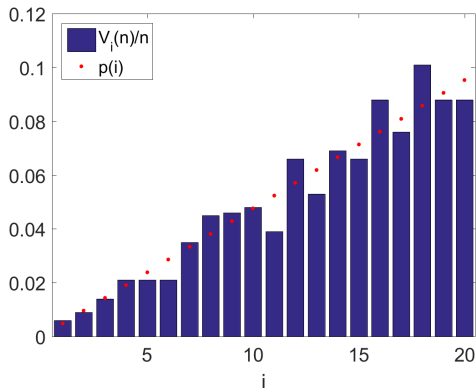


Figure: Average number of visits  $V_i(n)/n$  ( $n = 1000$ ) and target pmf  $p(i)$

$$\text{Where } V_i(n) = \sum_{t=0}^{n-1} \mathbb{I}(X_t = i)$$

## Example: Discrete Distribution on a finite state-space

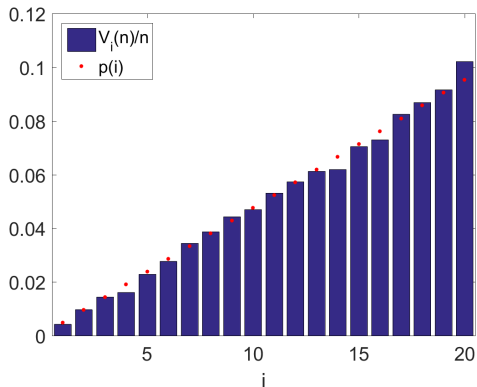


Figure: Average number of visits  $V_i(n)/n$  ( $n = 10,000$ ) and target pmf  $p(i)$

## Example: Poisson Distribution

- ▶ We want to simulate  $p(x) = e^{-\lambda} \lambda^x / x! \propto \lambda^x / x!$
- ▶ For the proposal we use

$$q(y|x) = \begin{cases} \frac{1}{2} & \text{for } y = x \pm 1, x \geq 1 \\ 1 & \text{for } x = 0, y = 1 \\ 0 & \text{otherwise,} \end{cases}$$

i.e. toss a coin and add or subtract 1 to  $x$  to obtain  $y$ .

- ▶ Acceptance probability

$$\alpha(y|x) = \begin{cases} \min\left(1, \frac{\lambda}{x+1}\right) & \text{if } y = x + 1, x \geq 1 \\ \min\left(1, \frac{x}{\lambda}\right) & \text{if } y = x - 1, x \geq 2 \end{cases}$$

and  $\alpha(1|0) = \min(1, \lambda/2)$ ,  $\alpha(0|1) = \min(1, 2/\lambda)$ .

- ▶ Markov chain is irreducible (check!)

# Example: Poisson Distribution

- ▶ Set  $X_0 = 1$ .
- ▶ For  $t = 1, \dots, n - 1$ 
  1. If  $X_{t-1} = 0$ , set  $Y_t = 1$
  2. Otherwise, simulate  $V_t \sim \text{Unif}[0, 1]$ 
    - 2.1 If  $V_t \leq \frac{1}{2}$ , set  $Y_t = X_{t-1} + 1$ .
    - 2.2 Otherwise set  $Y_t = X_{t-1} - 1$ .
  3. Simulate  $U_t \sim \text{Unif}[0, 1]$ .
  4. If  $U_t \leq \alpha(Y_t | X_{t-1})$ , set  $X_t = Y_t$ , otherwise set  $X_t = X_{t-1}$ .

## Example: Poisson distribution

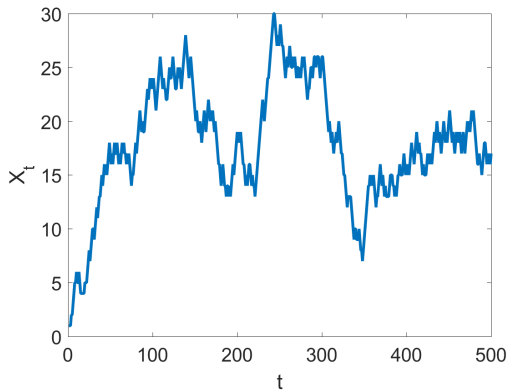


Figure: Realization of the MH Markov chain for  $n = 500$  with  $\lambda = 20$ .

## Example: Poisson distribution

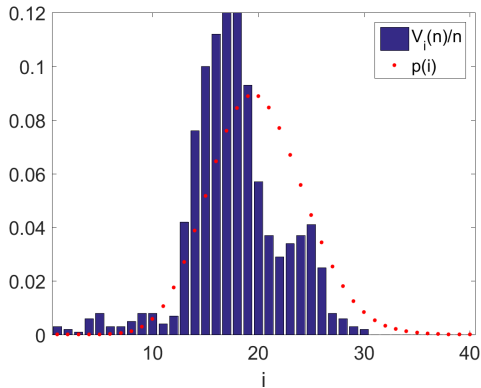


Figure: Average number of visits  $V_i(n)/n$  ( $n = 1000$ ) and target pmf  $p(i)$



## Example: Poisson distribution

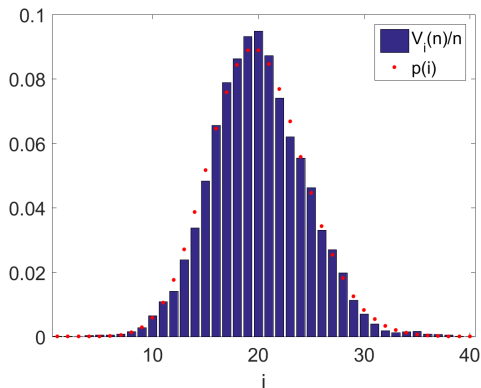


Figure: Average number of visits  $V_i(n)/n$  ( $n = 10,000$ ) and target pmf  $p(i)$

## Example: Image

- ▶ Consider a  $m_1 \times m_2$  image, where  $I(i, j) \in \{0, 1, \dots, 256\}$  is the gray level of pixel  $(i, j) \in \Omega = \{0, \dots, m_1 - 1\} \times \{0, \dots, m_2 - 1\}$
- ▶ Consider a discrete random variable taking values in  $\Omega$
- ▶ Unnormalized pdf

$$\tilde{p}((i, j)) = I(i, j)$$

- ▶ Proposal transition probabilities

$$q((y_1, y_2)|(x_1, x_2)) = q(y_1|x_1)q(y_2|x_2)$$

with

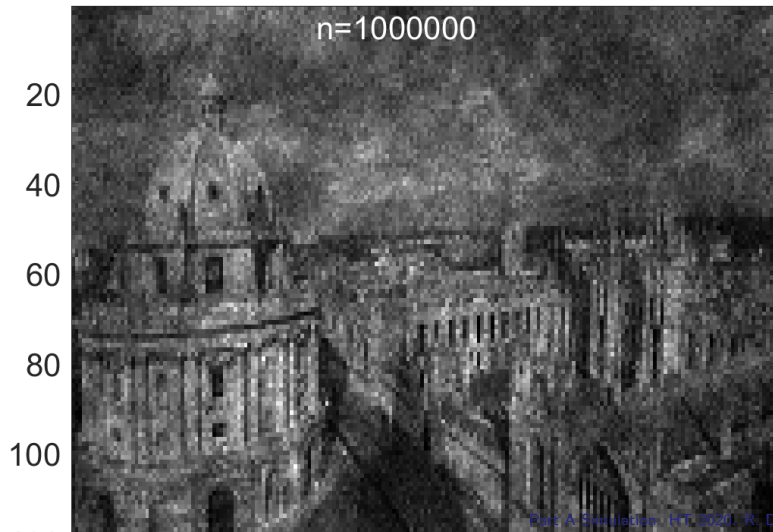
$$q(y_1|x_1) = \begin{cases} 1/3 & \text{if } y_1 = x_1 \pm 1 \text{ or } y_1 = x_1, \quad \text{mod } m_1 \\ 0 & \text{otherwise} \end{cases}$$

and similarly for  $q(y_2|x_2)$ .

## Example: Simulation of an image

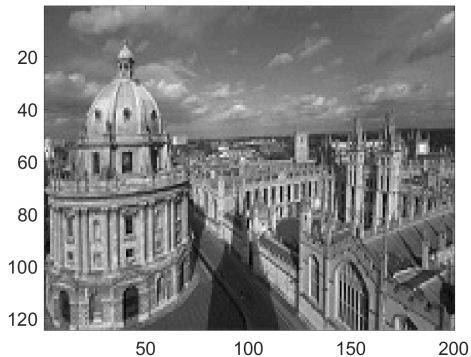
- Average number of visits to each pixel  $(i, j)$ :

$$V_{(i,j)}(n) = \frac{1}{n} \sum_{t=0}^{n-1} \mathbb{I}(X_t = (i, j))$$



# Example: Simulation of an image

## ► Target pmf



# Metropolis-Hastings algorithm on $\mathbb{R}^d$

- ▶ The Metropolis-Hastings algorithm generalizes to continuous state-space where  $\Omega \subseteq \mathbb{R}^d$  with
  1.  $p$  is a pdf on  $\Omega$
  2.  $q(\cdot|x)$  is a pdf on  $\Omega$  for any  $x \in \Omega$
- ▶ The Metropolis-Hastings algorithm thus defines a Markov chain on  $\Omega \subseteq \mathbb{R}^d$
- ▶ Precise definition of Markov chains on  $\mathbb{R}^d$  is beyond the scope of this course. We will just state the most important results without proof. Assume for simplicity that  $p(x) > 0$  for all  $x \in \Omega$

# Metropolis-Hastings algorithm on $\mathbb{R}^d$

- The Markov chain  $X_0, X_1, \dots$  on  $\Omega \subseteq \mathbb{R}^d$  is **irreducible** if for any  $x \in \Omega$  and  $A \subset \Omega$ , there is  $n$  such that

$$\mathbb{P}(X_n \in A | X_0 = x) > 0$$

## Theorem

*If the Metropolis-Hastings chain is irreducible, then for any function  $\phi$  such that  $\mathbb{E}_p[|\phi(X)|] < \infty$ , the MH estimator is strongly consistent*

$$\hat{\theta}_n^{MH} = \frac{1}{n} \sum_{t=0}^{n-1} \phi(X_t) \rightarrow \theta \quad \text{almost surely as } n \rightarrow \infty$$

## Example: Gaussian distribution

- ▶ Let  $X \sim N(\mu, \sigma^2)$  with

$$p(x) = (2\pi\sigma^2)^{-1/2} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

- ▶ MH algorithm with target pdf  $p$  and proposal transition pdf

$$q(y|x) = \begin{cases} 1 & \text{for } y \in [x - 1/2, x + 1/2] \\ 0 & \text{otherwise} \end{cases}$$

- ▶ Acceptance probability

$$\alpha(y|x) = \min \left( 1, \frac{p(y)q(x|y)}{p(x)q(y|x)} \right) = \min \left( 1, e^{-\frac{(y-\mu)^2}{2\sigma^2} + \frac{(x-\mu)^2}{2\sigma^2}} \right)$$

## Example: Gaussian distribution

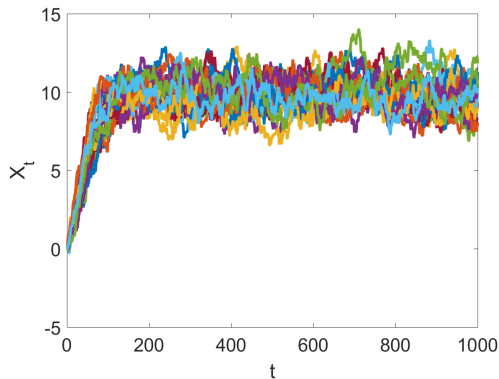


Figure: Realizations from the MH Markov chain  $(X_0, \dots, X_{1000})$  with  $X_0 = 0$ .



## Example: Gaussian distribution

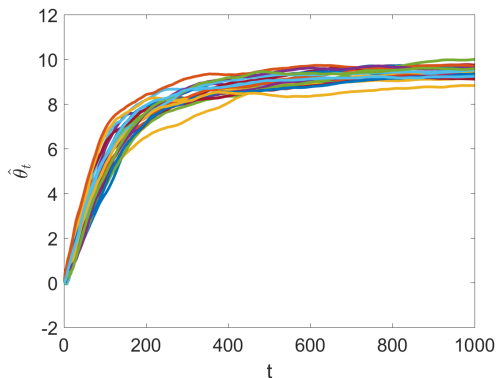


Figure: MH estimates  $\hat{\theta}_t = \frac{1}{t} \sum_{i=0}^{t-1} X_i$  of  $\theta = \mathbb{E}_p[X]$  for different realizations of the Markov chain.

# Recap

- ▶ Given an proposal transition matrix  $q(y|x)$  that is irreducible over  $\Omega$ , MCMC:Metropolis-Hastings defines an algorithm that produces a Markov chain that admits  $p$  as a stationary distribution
- ▶ **Next time:** Properties of MCMC, tuning parameters, and Gibbs sampling