'celltracktech' Data Analysis package

Jessica Gorzo

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AOS2024 - 'celltracktech' Workshop

This RBook goes over the files, functions, and analyses from the 2024 American Ornithological Society (AOS) Workshop in Estes Park, CO on the 'celltracktech' R package. This package was developed by Dr. Jessica Gorzo and Dr. Sean Burcher.

This document will serve as a tutorial on how Cellular Tracking Technologies (CTT) registered users can download their data from our server, analyze the data using multilateration, and visualize the data using the built-in package functions.

This tutorial provides step-by-step instructions on how to obtain your data. This style is used for absolute beginners in R, SQL, and data science.

1.1 Additional Libraries Needed (Linux users)

Note If you are using Linux (specifically Ubuntu), you may need to install the following libraries in the teriminal.

1.1.1 Install PostgreSQL libraries

```
sudo apt install libpq-dev libssl-dev
```

1.1.2 Installing R Spatial on Ubuntu

```
sudo add-apt-repository ppa:ubuntugis/ubuntugis-unstable
sudo apt update
```

sudo apt install libgdal-dev libgeos-dev libproj-dev libtbb-dev

Project Setup

Here we will go over how to create a local project directory (or folder as it is commonly known) on your own personal computer.

2.1 Create a R Studio Project

- 1. Download the latest versions of R and RStudio. As of writing this tutorial, the latest version of R is 4.4.2, and RStudio is '2024-12.0.467'.
- 2. In RStudio, create a new project (.proj) in a new directory. By using an R project, you can create a new directory to store all of your code scripts and data files, as well as keep track of your workflow. You can find more information here.
 - a. Click the 'Create git repository' and 'use renv' check boxes.

2.1.1 Git

Git is a version control system, which allows you keep track of changes to your project, and collaborate with colleagues if you use Github.

2.1.2 renv

Renv stands for 'R Virtual Environment', which creates reproducible environments for your R projects. Many new data scientists would download all their individual packages into one location, usually the R library. While this global (i.e. accessible anywhere on your computer) library is convenient, certain packages or package versions can conflict with each other, causing errors and preventing you from analyzing your data. With renv, you can download all the packages for your project in your project directory, which will lead to fewer problems due to conflicting packages/versions.

```
install.packages('renv')
library(renv)
renv::activate()
```

2.2 Create a '.env' file

For NodeJs and Python projects, many data scientists use environment variables to store sensitive data such as passwords, API credentials, and other info that should not be publicly shared. These environment variables can then be accessed by the R project without displaying the sensitive information on your R script.

To store the environment variables, use a '.env' file and the R package 'dotenv'.

In a terminal window, run the following command to create a .env file in your project directory and store your CTT API key:

```
touch .env
echo "API_KEY=your_api_key" >> .env
install.packages('dotenv')
library(dotenv)

# load the env file
load_dot_env(file='.env')

# get your api key from the env file
my_token <- Sys.getenv('API_KEY')</pre>
```

2.2.1 Add .env file to .gitignore

Finally, you will need to add the .env file to the .gitignore file, so that when you commit changes to your R project the .env file is not included. That way your environmental variables will stay on your computer until you share them with collaborators.

Open the .gitignore file in RStudio and add '.env' (without the quotes) to the file and save it.

```
36 *_cache/
37 /cache/
38
39 # Temporary files created by R markdown
40 *.utf8.md
41 *.knit.md
42
43 # R Environment Variables
44 .Renviron
45
46 # pkgdown site
47 docs/
48
49 # translation temp files
50 po/*~
51
52 # RStudio Connect folder
53 rsconnect/
54
55 ### R.Bookdown Stack ###
56 # R package: bookdown caching files
57 /*_files/
58
59 # Custom files and directories
60 .env
61
62
63 # End of https://www.toptal.com/developers/gitignore/api/r
```

You are now ready to start downloading data!

2.3 Organize your Project Directory

In your project directory create the following folders to organize your files:

- src where you store your .R scripts
- data store downloaded data from CTT and modified dataframes
- results store plots and tables

Download Data

To download your CTT data, you first will need to create an SQL relational database. Why create a relational database instead of loading the csv files directly? Using a database uses much less memory when combining or cleaning data frames compared to loading data directly into RStudio.

If you are new to relational databases, you should use DuckDB, a simple database management systems (DMBS) that is easy to install and use in RStudio.

```
# activate renv environment
renv::activate()
```

!NOTE The DuckDB install will take ~ 30 min. Please allocate time accordingly.

```
# install duckdb using renv
library(renv)

renv::install(c('httr', 'DBI', 'RPostgres', 'tidyverse', 'rjson', 'dplyr', 'tidyr', 'tibble', 're
# renv::install('duckdb', repos = c('https://duckdb.r-universe.dev', 'https://cloud.r-project.org
renv::install('duckdb/duckdb-r')
renv::install('cellular-tracking-technologies/celltracktech')
```

3.1 Create a DuckDB database

Below is a sample script to create a DuckDB database

```
library(celltracktech)
# load env file into environment
load_dot_env(file='.env')
```

3.2 Download data from the CTT API

You are now connected to your DuckDB database, but so far nothing is in the database. The script below will download your data from the CTT servers and insert the files into your local database.

NOTE! Your Sensor Station must be set to upload data to our servers. If your station does not upload data, skip this block and go to section 2.2.1.

You may get this error message:

```
Error in post(endpoint = endpoint, payload = payload) :
   Gateway Timeout (HTTP 504).
```

It is fine, just run the get_my_data() function again and it should work properly.

3.2.1 Create Database from Files on your Computer

If you already have your Sensor Station files on your computer (i.e. your sensor station is not connected to the internet), you can use the code block below to create a database and add those files to it.

3.3 Updating the database

Upload the compressed data (i.e. the '.csv.gz' files) into your DuckDB database: update_db(con, outpath, myproject)

3.4 Disconnecting from the database

The benefit of using a relational database is that it does not need to be loaded into your computer memory the entire time you are analyzing your data. You can connect to it, filter/clean the data you want, and then disconnect once you are done, freeing up computer memory for more intensive data analysis tasks.

To disconnect from the database, run the following command:

```
DBI::dbDisconnect(con)
```

3.5 Uploading Node Data from the SD Card

Note! This step is optional! If you are not uploading data from the Node SD cards, you can skip to chapter 3!

3.5.1 Create Nodes directory

To upload Node data from the SD cards, you will need to create a 'nodes' folder in the CTT Project Name folder. For example, we will create a folder in the 'Meadows V2' folder in the './data/meadows/' directory:

```
create_outpath('./data/Meadows V2/nodes/')
```

3.5.2 Create individual directories for each Node

Then, create a folder for each Node. In the example below, we are creating a folder for Node 3B8845:

```
create_outpath('./data/Meadows V2/nodes/3B8845/')
```

3.5.3 Upload Node data to your DuckDB database

Remember, we need to re-connect to the DuckDB database to upload the Node data:

The import_node_data will import the node csv files into the "node_" data tables and insert the csv files into the regular "raw", "blu", and "node_health" tables.

You have finished uploading data to your database!

3.6 Create Postgres Database

If you or your lab are familiar with PostgreSQL, you can connect to your database with this:

```
# create Postgres database
con <- DBI::dbConnect(
   RPostgres::Postgres(),
   dbname="meadows"
)</pre>
```

Creating and editing a Postgres database is vastly different from a DuckDB database. You can find more information on Postgres and R here.

Accessing Database

4.1 Duckplyr

If you are new to database queries but familiar with dplyr and tidyverse, I recommend using duckplyr. You can find more information about duckplyr here but the main takeaway is that you can query your database using dplyr phrases and pipes, while also saving memory on loading data.

4.2 SQL Queries

If you are more comfortable with the SQL syntax, you can use SQL queries to get data from different tables.

This chapter is a quick summary on how to use SQL in R. If you would like more info on how to run different queries, use this tutorial: https://solutions.posit.co/connections/db/getting-started/database-queries/

4.3 List Tables

List the tables in your database. If everything was run correctly, each data file type (raw, blu, node-health, etc.) should be in its own data table.

Remember to reconnect to the database!

4.4 Load each data table into RStudio

Note: you do not need to load each table into RStudio. You should only load the tables you need to for your analysis.

Node Check

With your data you can do the following analyses:

- Presence/absence using detection times
- Activity budget using the change in signal strength over time
- Habitat Use using localization
- Home range/territory size
- Movement patterns

Before you can do any of that, it is a good idea to check if your nodes are working properly, and filter out any that are malfunctioning.

5.1 Node Health

Things to look at:

- Recent health records and detections
- Battery Level
- Are they charging?
- GPS fixes
- Synchronized clocks?

For example, debris on solar panels can lead to the node not to charge, which means the battery voltage will drop, which stops the GPS, leading to an out of sync clock.

Another example is that foliage cover leads to no charging, low battery voltage, stops the GPS, and leads to an out of sync clock.

5.1.1 Node Health - Check Health Records

5.1.1.1 Load Data from Database

```
library(celltracktech)
library(dotenv)
# load env file into environment
load_dot_env(file='.env')
                                      _____
# Settings - ---
# These were created in Chapter 2. If you do not have these in your project directory,
my_token <- Sys.getenv('API_KEY') # load env variable into my_token</pre>
myproject <- "Meadows V2" # this is your project name on your CTT account, here we are
outpath <- "./data/" # where your downloaded files are to go
# Specify the time range of node data you want to import for this analysis
start_time <- as.POSIXct("2023-10-01 00:00:00",tz="GMT")
stop_time <- as.POSIXct("2023-11-01 00:00:00",tz="GMT")
# Connect to Database using DuckDB -----
con <- DBI::dbConnect(duckdb::duckdb(),</pre>
                      dbdir = "./data/Meadows V2/meadows.duckdb",
                      read_only = FALSE)
# load node_health table into RStudio and only load the data between the set start and
node_health_df <- tbl(con, "node_health") |>
  filter(time >= start_time & time <= stop_time) |>
  collect()
# disconnect from database
DBI::dbDisconnect(con)
# filter the node_health_df for unique node ids
node_health_df <- node_health_df %>%
  distinct(node_id,
            time,
            recorded_at,
            .keep_all = TRUE)
```

5.1.1.2 Checking Nodes are operating

```
# Look at the number of health records received from each node
node_record_counts <- node_health_df %>% count(node_id)
```

We can see after running the above script that Nodes 3B3B8F, 339CAE, and 32909D have relatively low number of records, so we may want to exclude them from further analyses.

5.1.2 Battery and Solar Levels

Check if the battery and solar voltages are adequate. If they are too low, they can affect the GPS synchronization.

```
# Plot the Battery voltage vs. time for all nodes
ggplot(node_health_df) +
  geom_point(aes(x = time,
                 y = battery,
                 colour = node_id)) +
  classic_plot_theme
# Plot the Battery & Solar voltage vs. time for a specific node
# Node 326710 is a normal working Node
selected_node_id <- "326710"
batt_solar_plot <- plot_battery_solar(node_health_df = node_health_df,</pre>
                                       selected node id = selected node id)
batt_solar_plot
# based on the Battery voltage vs. time plot, Node 32909D has a low battery voltage
selected_node_id <- '32909D'</pre>
batt_solar_plot <- plot_battery_solar(node_health_df = node_health_df,</pre>
                                       selected_node_id = selected_node_id)
batt_solar_plot
```

Node 326710 is working properly and has consistent solar voltages during the day (~ 5 V) and a consistent battery voltage over time (i.e. 3.5-3.6 V), while node 32909D has inconsistent solar voltages, hinting at either dirty solar panels

or covered solar panels, and a much lower battery voltage ($\sim 2.8 \text{ V}$).

5.1.3 Check GPS

If the clock is out of sync, the GPS coordinates may not be calculated correctly. Use the below script to check the coordinate deviations.

```
# calculate the node locations based on the latitude and longitude from node health re
node_locations <- calculate_node_locations(node_health_df)

# plot reported node locations and calculated node locations
plot_node_locations(node_health_df, node_locations)

# looks like we have an outlier in our nodes list, let's filter that out
# filter meadows nodes due to outlier
nodes_meadows = node_health_df %>%
    filter(!node_id %in% '3B3B8F') # get data from all nodes EXCEPT node 3B3B8F

# calculate the node locations based on the latitude and longitude from node health re
node_locations <- calculate_node_locations(nodes_meadows)

# plot reported node locations and calculated node locations
plot_node_locations(nodes_meadows, node_locations)</pre>
```

5.1.4 Check Time Offset

Plot time offset for each node.

```
# subtract time from recorded_at, then calculate the average time offset for each node
node_summary = node_health_df %>%
  mutate(time_offset = time-recorded_at) %>%
  group_by(node_id) %>%
  summarize(mean_time_offset = mean(time_offset), n = n())
# save node time offsets to csv
readr::write_csv(node_summary,
                 file = './data/Meadows V2/node_time_offset_20230802.csv')
# plot the time offset
ggplot(node_summary,
       aes(x = node_id,
           # y = scale(mean\_time\_offset),
           y = as.numeric(mean time offset),
           color=factor(node_id))) +
  geom_point() +
  ggtitle("Time Offset") +
  # xlab("Time (UTC)") +
```

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Node Calibration

In the previous chapter we saw that various ways that the node gps can differ, which can lead to inaccurate received signal strength indicators (RSSI) from the tag.

To account for any small changes in the gps values, we need to calibrate the node grid. ## Load libraries

library(celltracktech)

6.1 Load sidekick data file

```
# Specify the path to the sidekick data file you recorded for calibration
# it is best if you create a 'sidekick' folder to store your calibration file(s).

create_outpath('./data/Meadows V2/sidekick/')
# place all of your sidekick calibration files in the newly created folder after running the above
sidekick_file_path <- "./data/Meadows V2/sidekick/calibration_2023_8_3_all.csv"</pre>
```

6.1.1 IF YOU DO NOT HAVE A SIDEKICK DATA FILE:

Create your own sidekick file by walking with a tag through node grid, stopping at specific spots you choose, and note the gps coordinates and time. Then create a csv similar to the sidekick calibration file.

Example:

tag_type	tag_id	time_utc	rssi	lat	lon	heading	antenna_angle
radio434ml	nz4C34074	B2023-08-		38.93	35561	24.273	
		03			74.94	48195	
		19:42:44.72	21001Z				
radio434ml	nz072A663	332023-08-		38.93	35561	23.548	
		03			74.94	48195	
		19:42:45.30)7456Z				
radio434mł	nz 19332A0	72023-08-		38.93	35569	15.840	
		03			74.94	48195	
		19:42:48.36	6123Z				

6.2 Setup

6.2.1 Load environmental variables into RStudio

```
# load env file into environment
load_dot_env(file='.env')
```

6.2.2 Load settings

```
# Settings - ----
options(digits = 10)
# These were created in Chapter 2. If you do not have these in your project directory,
my_token <- Sys.getenv('API_KEY') # load env variable into my_token
myproject <- "Meadows V2" # this is your project name on your CTT account, here we are
outpath <- "./data/" # where your downloaded files are to go
# Specify the path to your database file
database_file <- "./data/Meadows V2/meadows.duckdb"</pre>
# Specify the tag ID that you used in your calibration
my_tag_id <- "072A6633"</pre>
# my_tag_id <- "614B661E"
# Specify the time range of node data you want to import for this analysis
   This range should cover a large time window where you nodes were in
# a constant location. All node health records in this time window
# will be used to accurately determine the position of your nodes
start_time <- as.POSIXct("2023-08-01 00:00:00", tz = "GMT")
stop_time <- as.POSIXct("2023-08-07 00:00:00", tz = "GMT")
# Specify a list of node Ids if you only want to include a subset in calibration
```

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```
# IF you want to use all nodes, ignore this line and SKIP the step below
# where the data frame is trimmed to only nodes in this list
my_nodes <- c("B25AC19E", "44F8E426", "FAB6E12", "1EE02113", "565AA5B9", "EE799439", "1E762CF3",

# You can specify an alternative map tile URL to use here
my_tile_url <- "https://mt2.google.com/vt/lyrs=y&x={x}&y={y}&z={z}"</pre>
```

6.2.3 Load Node Health Data from Files

```
# connect to the database
con <- DBI::dbConnect(duckdb::duckdb(),</pre>
                      dbdir = database_file,
                      read_only = TRUE)
# load node_health table in to RStudio and subset it based on your start and stop times
node_health_df <- tbl(con, "node_health") |>
  filter(time >= start_time & time <= stop_time) |>
  collect()
# disconnect from the database
DBI::dbDisconnect(con)
# remove any duplicate records
node_health_df <- node_health_df %>%
  distinct(node_id,
           time,
           recorded_at,
           .keep_all = TRUE)
```

6.2.4 Get Node Locations

6.2.5 Load Station Detection from Files

```
# connect to database
con <- DBI::dbConnect(duckdb::duckdb(),</pre>
                      dbdir = database_file,
                      read_only = TRUE)
# load raw data table and filter from start_time to stop_time
detection_df <- tbl(con, "raw") |>
  filter(time >= start_time && time <= stop_time) |>
  collect()
# if you are working with blu data, uncomment the lines below and load data from the b
# detection_blu <- tbl(con, "blu") />
   filter(time >= start_time &@ time <= stop_time) />
   collect
# disconnect from database
DBI::dbDisconnect(con)
# Get beeps from test tag only
detection_df <- subset.data.frame(detection_df,</pre>
                                   tag_id == my_tag_id)
```

6.2.6 Load Sidekick Calibration Data from File

```
calibration_map
```

6.3 Calculate the RSSI vs. Distance Relationship

This function will match sidekick detections to detections recorded by nodes and sent to the station. Then using the sidekick location, the node locations calculated above, and the rssi measured in the node, a list of rssi and distance pairs is generated and returned.

For Blu Series tags use sync=TRUE, for 434 MHz tags use sync=FALSE.

```
rssi_v_dist <- calc_rssi_v_dist(node_locs, sidekick_tag_df, detection_df, use_sync = FALSE)
# Plot the resulting RSSI and distance data
ggplot() +
  geom_point(data = rssi_v_dist,
             aes(x = distance,
                 y = rssi,
                 colour = node id)) +
 labs(title="RSSI vs. Distance",
       x="Distance (m)",
       y="RSSI (dBm)",
       colour="Node ID") +
  classic_plot_theme
# Fit the RSSI vs distance data with exponential relationship
nlsfit <- nls(</pre>
  rssi ~ a - b * exp(-c * distance),
  rssi_v_dist,
  start = list(a = -105, b = -60, c = 0.17)
)
summary(nlsfit)
# Get the coefficients from the fit result
co <- coef(summary(nlsfit))</pre>
rssi_coefs \leftarrow c(co[1, 1], co[2, 1], co[3, 1])
# Add a predicted column to the RSSI vs distance data
rssi_v_dist$pred <- predict(nlsfit)</pre>
# Plot the RSSI vs distance data with the fit curve
calibration_plot <- plot_calibration_result(rssi_v_dist, classic_plot_theme)</pre>
calibration plot
```

Print the coefficients from the fit. You'll need these coefficients later

```
# for localization.
print(rssi_coefs)
```

Your node grid is now calibrated!

Presence/Absence Analysis

This type of analysis can be used to answer questions on stopover duration or for threat monitoring at airports, windmills, etc.

You will need to manually create a tag deployment csv file. This file will contain: * the tag id (all uppercase) * the tag deployment date * the standardized 4-letter Alpha code (if your study involves birds) * the tag type (Power, Life, Blu) * the antenna type (1/8 wave) * any other characteristics of the individual wearing the tag (sex, weight, etc.).

Ex.

TagId	${\bf DeployDate}$	Species	${\bf TagType}$	AntennaType
332D074B	09/03/23	NOWA	Power	1/8 wave
664C5219	08/23/23	NOWA	Power	1/8 wave
4C2A0707	08/20/23	NOWA	Power	1/8 wave

Then move that tag deployment file into the 'outpath' folder. For example, we will move the meadows_deployments_2023.csv, which contains the above info on numerous tags across multiple species into the data/meadows/ folder.

We are now ready to start calculating presence/absence.

7.1 Set parameters

```
options(digits = 10)
# Specify the path to your database file
database_file <- "./data/Meadows V2/meadows.duckdb"</pre>
```

```
# Specify the path to the deployment info file
deployment_info_file <- "data/Meadows V2/meadows_deployments_2023.csv"

# Specify the time range of node data you want to import for this analysis
start_time <- as.POSIXct("2023-08-01 00:00:00", tz = "GMT")
stop_time <- as.POSIXct("2023-12-31 00:00:00", tz = "GMT")</pre>
```

7.2 Load data from database

7.3 Load Tag Deployment Info

7.3.1 Load Tag Deployment File

Again, you will need to create this file yourself. You might want to include other info about the individuals in this file for later analysis (species, weight, sex, etc.).

```
deployment_df <- read.csv(deployment_info_file)</pre>
```

7.3.2 Get List of Detected Tags

```
# count the number of detections for each tag. the minimum number of detections to be
tag_det_count <- get_tag_detection_count(detection_df, min_det_count = 250000)
# plot the number of detections for each individual tag</pre>
```

7.4 Generate Detection Summary

While it is good to know how many detections an individual tag has, it is better to know how many detections there were across time. The code chunk below will subset your detection_df based on the tags in your tag deployment file, and create a plot of detections across time.

```
# Discard detections that aren't from deployed tags
detection_df <- subset.data.frame(detection_df,</pre>
                                   tag_id %in% deployment_df$TagId)
# OPTIONAL: You can select individual species here
# subsetting the deployment dataframe to only include NOWA or northern waterthrush
deployment_df <- subset.data.frame(deployment_df,</pre>
                                    Species == "NOWA")
# detection_df <- subset.data.frame(detection_df, TagId %in% deployment_df$TagId)
det_summary_df <- detection_summary(</pre>
  detection_df = detection_df,
  tag_list = deployment_df$TagId
# create detection summary data frame and sort it based on last detection date
det_summary_df <- det_summary_df[order(det_summary_df$last_det, decreasing = TRUE), ]</pre>
# create a heat-bin plot, with the bins reperesenting time periods, and the color representing the
ggplot(data = detection_df,
       aes(x = time,
           y = factor(tag_id,
                      det_summary_df$tag_id))) +
  geom_bin2d(binwidth = c(3600, 1)) + # Hour time bins
  scale_fill_continuous(type = "viridis") +
  labs(x = "Time (UTC)",
       y = \text{"Tag Id"}) +
  tag_hist_plot_theme
```

7.5 Show Detection History for a Specific Tag

```
# selected tag is a power tag on a swamp sparrow
selected_tag_id <- "2D4B782D"</pre>
# set your start and stop times
plot_start_time <- as.POSIXct("2023-10-05 10:00:00", tz = "GMT")</pre>
plot_stop_time <- as.POSIXct("2023-10-05 14:00:00", tz = "GMT")</pre>
# subset the detection_df to only include the selected tag id
tag_dets <- subset.data.frame(detection_df, tag_id == selected_tag_id)</pre>
# plot the number of detections for this specific tag at each node across time
ggplot(tag dets) +
  geom_point(aes(x = time,
                 y = tag_rssi,
                 colour = node_id),
             shape = 1) +
  xlim(as.POSIXct(plot_start_time),
       as.POSIXct(plot_stop_time)) +
  ggtitle(paste("Detections",
                selected_tag_id)) +
  xlab("Time (UTC)") +
  ylab("RSSI (dBm)") +
  classic_plot_theme
```

7 Activity Budget

When is the animal active and/or inactive? Use the following script to answer research questions like:

- Nesting/Incubation behavior
- Roosting times
- Foraging times
- Mortality detection

8.1 7.1 Load settings

```
# activate renv
renv::activate()

# load celltracktech library
library(celltracktech)
# library(dplyr)
# library(ggplot2)

options(digits = 10)

# Specify the path to your database file
database_file <- "./data/Meadows V2/meadows.duckdb"

start_time <- as.POSIXct("2023-09-01 00:00:00",tz = "GMT")
stop_time <- as.POSIXct("2023-09-02 00:00:00",tz = "GMT")</pre>
```

8.2 7.2 Load Tag Node Detection Data

8.3 7.3 Tag Activity

```
# selected_tag_id <- "2D4B782D", # SWSP (swamp sparrow) - Power Tag

# select a specific tag, below is a Power Tag on a Northern Waterthrush (NOWA)
selected_tag_id <- '614B661E'

# subset detection_df dataframe to only included the selected_tag_id
tag_dets <- subset.data.frame(detection_df, tag_id == selected_tag_id)

# sort the rows by time, ascending
tag_dets <- tag_dets[order(tag_dets$time, decreasing = FALSE), ]

tag_beep_interval <- 13 # seconds, will need to know of tag type beep intervals

# calculate tag activity - this turns the number of detections into a single value for
tag_activity <- calculate_tag_activity(tag_dets, tag_beep_interval)

# calculate average tag activity
avg_tag_act <- calc_avg_activity(tag_activity, start_time, stop_time)

# set start and stop times for the plots (next section)
plot_start_time <- as.POSIXct("2023-09-01 06:00:00", tz = "GMT")
plot_stop_time <- as.POSIXct("2023-09-02 06:00:00", tz = "GMT")</pre>
```

8.3.1 7.3.1 Scatter Plot of RSSI vs time by Node

Here we see that this bird was spending most of the time in the vicinity of nodes 3282EC, 339CAE, and 37824B, but then spends a considerable amount of time near node 32941A.

8.3.2 7.3.2 Scatter Plot of activity vs time by Node

Next we will quantify the activity level. Activity is an arbitrary variable; it can be movement, roosting, a specific behavior, etc. You will need to define what activity is based on your study.

Here we see the activity level (y-axis) for every 5 min from September 1 to September 2. Each color represents a unique Node ID. From a brief glance, this tag had low to mid activity levels near nodes 3282EC and 37824B, but it is still difficult to discern what is going on in this plot.

8.3.3 7.3.3 2D Histogram of Activity over Time

We can summarize the above plot even further by creating a heatmap. The code chunk below creates a heatmap bin plot, which displays the activity for an individual over a period of time, with the color of each bin representing the count of activity (on a log scale), while the bins tell us the activity level.

```
my_breaks <- c(1, 10, 100, 1000, 10000)
ggplot(tag_activity,
```

From this plot, we can see that there are multiple instances of low activity (demonstrated by the yellow bins at activity/hour 1), and fewer instances of high activity (demonstrated by the blue bins at activity/hour 4 and above).

8.3.4 7.3.4 2D histogram of activity vs time WITH avg activity

This code chunk makes the same plot as above, but also displays the average activity level as a red line.

```
ggplot(tag_activity,
       aes(x = time,
           y = abs_act) +
 geom_bin2d(binwidth = c(3600, 1)) +
  geom_line(data = avg_tag_act,
            aes(x = time,
                y = avg_activity),
            colour = "Red") +
  geom_point(data = avg_tag_act,
             aes(x = time,
                 y = avg_activity),
             colour = "Red") +
 xlim(plot_start_time,
       plot_stop_time) +
 xlab("Time (UTC)") +
 ylab("Activity / Hour (Arb. Units)") +
  scale_fill_viridis_c(name = "Counts",
                       trans = "log",
                       breaks = my_breaks,
                       labels = my_breaks) +
  classic_plot_theme
```

Here we see the average activity level for this tag is roughly 1 per hour from

September 1 to September 2.

8.3.5 7.3.5 Avg activity / hour Vs time.

Let's zoom in and isolate the average activity per hour:

```
ggplot(tag_activity) +
  geom_line(data = avg_tag_act,
            aes(x = time,
                y = avg_activity),
            colour = "Red") +
  geom_point(data = avg_tag_act,
             aes(x = time,
                 y = avg_activity),
             colour = "Red") +
  xlim(plot_start_time, plot_stop_time) +
  xlab("Time (UTC)") +
  ylab("Activity / Hour (Arb. Units)") +
  scale_fill_viridis_c(name = "Counts",
                       trans = "log",
                       breaks = my_breaks,
                       labels = my_breaks) +
  classic_plot_theme
```

We see that average activity is highest between 6am-12pm but decreases suddenly after that, which is what we would expect for bird activity level in September.

Chapter 9

8 Habitat Use

If you are interested in where animals spend time, use this chapter to provide you with the code scripts to calculate tag detections into habitat use.

9.1 8.1 Load libraries and settings

9.1.1 8.1.1 Activate renv

```
renv::activate()
```

9.1.2 8.1.2 Load libraries and settings

```
library(dplyr)
library(duckdb)
library(ggplot2)
library(celltracktech)
```

9.1.3 8.1.3 Load Functions

```
# DEFS
source("R/defs/plot_themes.R")
# TAG
source("R/functions/tag/load_node_detection_data.R")
# NDOE
source("R/functions/node/node_functions.R")
# GRID SEARCH
source("R/functions/grid_search_functions.R")
```

```
# Specify the path to your database file
database_file <- "data/meadows/meadows.duckdb"

# Specify the path to the deployment info file
deployment_info_file <- "data/meadows/meadows_deployments_2023.csv"</pre>
```

9.1.4 8.1.4 Load RSSI Coefficients

Remember Chapter 5 in which we calibrated the node grid? We will want to use those RSSI coefficients to accurately calculate the tag tracks from the detection data.

We will set the coefficients in the code block below, as well as our start and stop time for the Nodes, and for the tag detections.

```
# Specify the RSSI vs Distance fit coefficients from calibration
a <- -103.46373779280
b <- -59.03199894670
c <- 0.01188255653
rssi_coefs <- c(a, b, c)
```

9.1.5 8.1.5 Load Settings

```
options(digits = 10)

# Specify the time range of node data you want to import for this analysis
# This range should cover a large time window where your nodes were in
# a constant location. All node health records in this time window
# will be used to accurately determine the position of your nodes
node_start_time <- as.POSIXct("2023-08-01 00:00:00", tz = "GMT")
node_stop_time <- as.POSIXct("2023-08-07 00:00:00", tz = "GMT")

# Selected Tag Id - Hybrid tag on a Gray Catbird (GRCA)
selected_tag_id <- '2A33611E' # tag with most detections, 1/4 wave

# Analysis Time Range
det_start_time <- as.POSIXct("2023-10-01 12:00:00", tz = "GMT")
det_stop_time <- as.POSIXct("2023-10-06 12:00:00", tz = "GMT")

# You can specify an alternative map tile URL to use here
my_tile_url <- "https://mt2.google.com/vt/lyrs=y&x={x}&y={y}&z={z}"</pre>
```

0.2 Q.2 Load Mode Health Data from Files

```
# Load from DB
con <- DBI::dbConnect(duckdb::duckdb(),</pre>
                      dbdir = database_file,
                      read_only = TRUE)
# load node_health data table into RStudio and filter it based on the start and stop time
node_health_df <- tbl(con, "node_health") |>
  filter(time >= node_start_time && time <= node_stop_time) |>
  collect()
# disconnect from the database
DBI::dbDisconnect(con)
# Remove duplicates
node_health_df <- node_health_df %>%
  distinct(node_id,
           time,
           recorded_at,
           .keep_all = TRUE)
```

9.3 8.3 Get Node Locations

Due to variations in GPS coordinates, it is a good idea to plot the Node locations and overlay the plot over a satellite image of your study site.

9.4 8.4 Load Station Detection Data

These are your tag detections in the 'raw' or 'blu' data tables in your database.

```
# Load from DB
con <- DBI::dbConnect(duckdb::duckdb(), dbdir = database_file, read_only = TRUE)
# load raw data table into RStudio and filter it based on start and stop time
detection_df <- tbl(con, "raw") |>
    filter(time >= det_start_time && time <= det_stop_time) |>
    filter(tag_id == selected_tag_id) |>
    collect()

# disconnect from the databse
DBI::dbDisconnect(con)
# create time_value variable
detection_df <- detection_df %>%
    mutate(time_value = as.integer(time))
```

9.5 8.5 Build a Grid

To actually quantify the amount of habitat an animal uses, we will create a 500x800 m grid and overlay it over the map. Each grid bin will be 5x5m.

```
# set the grid coordinates
grid_center_lat <- 38.93664800
grid_center_lon <- -74.9462
grid_size_x <- 500 # meters</pre>
grid_size_y <- 800 # meters</pre>
grid_bin_size <- 5 # meters</pre>
# Create a data frame with the details about the grid
grid_df <- build_grid(</pre>
  node_locs = node_locs,
  center_lat = grid_center_lat,
  center_lon = grid_center_lon,
  x_size_meters = grid_size_x,
  y_size_meters = grid_size_y,
  bin_size = grid_bin_size
# Draw all of the grid bins on a map
grid_map <- draw_grid(node_locs, grid_df)</pre>
grid_map
```

9.6 8.6 Calculate Locations

This will display the tag tracks and the tag location on the node grid map.

```
# create a locations dataframe with the calculate_track() function
locations_df <- calculate_track(</pre>
  start time = "2023-10-04 \ 23:00:00",
  # start_time = "2023-08-01 00:00:00",
 length_seconds = 6 * 3600,
  step_size_seconds = 15,
  det_time_window = 30, # Must have detection within this window to be included in position calcu
  filter_alpha = 0.7,
  filter_time_range = 60, # Time range to include detections in filtered value
  grid_df = grid_df,
  detection_df = detection_df,
 node_locs = node_locs,
 rssi_coefs = rssi_coefs,
 track_frame_output_path = NULL # If NULL no individual frames will be saved
)
print(locations_df)
# overlay the tag tracks on the node grid and satelitte picture
track_map <- map_track(node_locs,</pre>
                       locations df,
                        my_tile_url)
track_map
# calculate and display the location density on the node grid map
source("R/functions/grid_search/grid_search_functions.R")
loc_density <- calc_location_density(grid_df = grid_df,</pre>
                                      locations_df = locations_df)
loc_density_map <- map_location_density(loc_density_df = loc_density, my_tile_url)</pre>
loc_density_map
```

For tags with 1/8 wavelengths, you may need to use a lower RSSI coefficient to accurately map tracks and habitat use. Try using -115 for RSSI coefficient 'a'.

Below is an example of a Power Tag with a 1/8 wave antenna, and will need a lower RSSI coefficient:

```
# Specify the RSSI vs Distance fit coefficients from calibration
a <- -115.0 # for 1/8 wave tags
b <- -59.03199894670
c <- 0.01188255653

rssi_coefs <- c(a, b, c)
```

Selected Tag Id - Power Tag on a Swamp Sparrow (SWSP), 1/8 wave, may need to set rss selected_tag_id <- "2D4B782D"

Chapter 10

9 Grid Search Analysis

If you are interested in the extent of an animal's movement, use the following grid search analysis.

Like in Chapter 8 - Habitat Use, the grid search analysis divides an area into a grid, and calculates the received signal strength at each node. Then this process is repeated for each time step in a series of detections recorded by the node network.

10.1 9.1 Loading Settings

10.1.1 9.1.1 Activate renv

```
renv::activate()
```

10.1.2 9.1.2 Load libraries

```
library(dplyr)
library(duckdb)
library(ggplot2)
```

10.1.3 9.1.3 Load functions

```
# DEFS
source("R/defs/plot_themes.R")
# UTILS
source("R/functions/utils/get_time_value.R")
# NDOE
source("R/functions/node/node_functions.R")
```

```
# TAG
source("R/functions/tag/load_node_detection_data.R")
# SIDEKICK
source("R/functions/sidekick/load_sidekick_data.R")
# GRID SEARCH
source("R/functions/grid_search/grid_search_functions.R")
```

10.1.4 9.1.4 Load settings

```
# Specify the path to your database file
database_file <- "./data/meadows/meadows.duckdb"</pre>
# (OPTIONAL) Specify Node time offsets if necessary
node_time_offset_file <- "./data/node_time_offset_8_2_2023.csv"</pre>
node_toff_df <- read.csv(node_time_offset_file)</pre>
# Specify the tag ID that you want to locate
my tag id <- "072A6633"
# Specify the RSSI vs Distance fit coefficients from calibration
a <- -103.0610446987
b <- -60.6023833206
c <- 0.0120558164
rssi coefs <- c(a, b, c)
# Specify the time range of node data you want to import for this analysis
# This range should cover a large time window where your nodes were in
# a constant location. All node health records in this time window
   will be used to accurately determine the position of your nodes
node_start_time <- as.POSIXct("2023-08-01 00:00:00", tz = "GMT")</pre>
node_stop_time <- as.POSIXct("2023-08-07 00:00:00", tz = "GMT")
# Specify time range of detection data you want to pull from the DB
det_start_time <- as.POSIXct("2023-08-03 00:00:00", tz = "GMT")</pre>
det_stop_time <- as.POSIXct("2023-08-04 00:00:00", tz = "GMT")</pre>
# Specify a list of node Ids if you only want to include a subset in calibration
# IF you want to use all nodes, ignore this line and SKIP the step below
# where the data frame is trimmed to only nodes in this list
# my_nodes <- c("B25AC19E", "44F8E426", "FAB6E12", "1EE02113", "565AA5B9", "EE799439",
# You can specify an alternative map tile URL to use here
my_tile_url <- "https://mt2.google.com/vt/lyrs=y&x={x}&y={y}&z={z}"</pre>
```

10.2 9.2 Load Node Health data from Database

```
# Load from DB
con <- DBI::dbConnect(duckdb::duckdb(), dbdir = database_file, read_only = TRUE)
node_health_df <- tbl(con, "node_health") |>
  filter(time >= node_start_time & time <= node_stop_time) |>
  collect()
DBI::dbDisconnect(con)
```

10.3 9.3 Get Node Locations

10.4 9.4 Load Station Detection Data

```
# Load from DB
con <- DBI::dbConnect(duckdb::duckdb(), dbdir = database_file, read_only = TRUE)
detection_df <- tbl(con, "raw") |>
  filter(time >= det_start_time & time <= det_stop_time) |>
  filter(tag_id == my_tag_id) |>
  collect()
DBI::dbDisconnect(con)
detection_df <- detection_df %>% mutate(time_value = as.integer(time))
```

10.5 9.5 Build a Node Grid

```
grid_center_lat <- 38.93664800
grid_center_lon <- -74.9462
grid_size_x <- 500 # meters
grid_size_y <- 800 # meters
grid_bin_size <- 5 # meters</pre>
```

```
# Create a data frame with the details about the grid
grid_df <- build_grid(
  node_locs = node_locs,
  center_lat = grid_center_lat,
  center_lon = grid_center_lon,
  x_size_meters = grid_size_x,
  y_size_meters = grid_size_y,
  bin_size = grid_bin_size
)
# Draw all of the grid bins on a map
grid_map <- draw_grid(node_locs, grid_df)
grid_map</pre>
```

10.6 9.6 (Optional) Calculate Test Solution

```
test_time <- as.POSIXct("2023-08-03 19:57:50", tz = "GMT")
test_rec_df <- calc_receiver_values(</pre>
  current_time = test_time,
  det_window = 60,
  station_tag_df = detection_df,
 node_locs = node_locs,
  node_t_offset = node_toff_df,
  rssi_coefs = rssi_coefs,
  filter_alpha = 0.7,
  filter_time_range = 120
print(test_rec_df)
# Find the GridSearch Solution
test_grid_values <- calc_grid_values(grid_df, test_rec_df, rssi_coefs)</pre>
solution <- subset(test_grid_values, test_grid_values$value == max(test_grid_values$va
print(solution)
# Multilateration calculation
reduced_rec_df <- subset.data.frame(test_rec_df, test_rec_df$filtered_rssi >= a)
node_w_max <- reduced_rec_df[reduced_rec_df$filtered_rssi == max(reduced_rec_df$filtered_rssi</pre>
multilat_fit <- nls(reduced_rec_df$exp_dist ~ haversine(reduced_rec_df$lat,reduced_rec
                       reduced_rec_df,
                       start= list(ml_lat = node_w_max$lat, ml_lon = node_w_max$lon),
                       control=nls.control(warnOnly = T, minFactor=1/65536, maxiter = 1
print(multilat_fit)
co <- coef(summary(multilat_fit))</pre>
```

10.7 9.7 Calculate Track

```
track_df <- calculate_track(</pre>
  start_time = "2023-08-03 19:50:45",
 length_seconds = 1050,
  step_size_seconds = 10,
  det_time_window = 60, # Must have detection within this window to be included in position calcu
  filter_alpha = 0.7,
  filter_time_range = 120, # Time range to include detections in filtered value
  grid_df = grid_df,
  detection_df = detection_df,
 node_locs = node_locs,
 node_t_offset = node_toff_df,
 rssi coefs = rssi coefs,
  track_frame_output_path = NULL # If NULL no individual frames will be saved
print(track_df)
track_map <- map_track(node_locs, track_df, my_tile_url)</pre>
track_map
```

10.8 9.8 (Optional) Compare with Known Track

```
# If you've recorded a test track with the sidekick and want to see how well you
# are able to recreate it you can use the commands below.
sidekick_file_path <- "data/meadows/sidekick/calibration_2023_8_3_t2.csv"
# Get Sidekick data from CSV (note I modified the headers for cleaner names in here)
sidekick_df <- read.csv(sidekick_file_path)
# Correct sidekick time formatting
sidekick_df <- sidekick_df %>% mutate(time_utc = substring(c(sidekick_df$time_utc), 1, 19))
# Add numerical time value column
sidekick_df <- sidekick_df %>% mutate(time_value = get_time_value(sidekick_df$time_utc))
# Trim Sidekick data to the time of the calculated track
```

```
sidekick_df <- subset.data.frame(sidekick_df, time_value <= max(track_df$time))

track_error_df <- calc_track_error(sidekick_df, track_df)
print(track_error_df)
print(min(track_error_df$error))
print(max(track_error_df$error))
print(paste("GS Solution Error = ", mean(track_error_df$error), " +/- ", sd(track_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_error_frack_erro
```

10.9 9.9 Plot Uncertainty Analysis

```
# need legend for different color dots
ggplot() +
    geom_point(data = track_error_df, aes(x = i, y = ml_error), color = "orange") +
    geom_point(data = track_error_df, aes(x = i, y = error)) +
    xlab("Track Point #") +
    ylab("Solution Error (m)") +
    classic_plot_theme

ggplot() +
    #geom_point(data = track_error_df, aes(x = max_rssi, y = ml_error), color = "orange"
    geom_point(data = track_error_df, aes(x = max_rssi, y = error)) +
    xlab("Max RSSI (dBm)") +
    ylab("Position Error (m)") +
    classic_plot_theme
```

Chapter 11

Multilateration

This process is just like habitat use and grid search analysis, but instead of using the RSSI, it uses time difference of arrival instead to calculate the location of an animal

Best to use when your node grid is evenly spaced.

Multilateration paper

11.1 Load settings

11.1.1 Reset R's brain, remove all previous objects

```
rm(list=ls())
tagid = c("072A6633","2D4B782D") #"0C5F5CED"
timezone="UTC"
options(digits=9)
```

11.1.2 Load functions

```
library(data.table)
source("R/Functions_Paxton-CTTUpdate.R")
```

11.1.3 Re-create sample data for calibration

```
#create time window by reducing location precision or can input data with TestId column (user-degree where does calibration file come from?
mytest <- read.csv("./calibration_2023_8_3_all.csv")
mytest$Time <- as.POSIXct(mytest$time_utc, tz="UTC")</pre>
```

```
# connect to database
con <- DBI::dbConnect(duckdb::duckdb(),</pre>
                      dbdir = "./data/meadows/meadows.duckdb",
                      read_only = TRUE)
# filter for specific dates and for the specified tags in tagid
testdata <- tbl(con, "raw") |>
  filter(time >= as.Date("2023-07-31") && time <= as.Date("2023-10-31")) |>
  filter(tag_id %in% tagid) |>
  collect()
# set node start and stop dates
start_buff = as.Date("2023-08-01", tz="UTC")
end_buff = as.Date("2023-08-07", tz="UTC")
nodehealth <- tbl(con, "node_health") |>
  filter(time >= start_buff && time <= end_buff) |>
  collect()
# disconnect from database
DBI::dbDisconnect(con)
# create dataframe of nodes and their locations (lat, lon)
nodes <- node file(nodehealth)</pre>
```

11.2 Isolate raw Received Signal Strength (RSS) data from Node network associated with Test Data

11.3 Exponential Decay Function - Relationship between Distance and Tag RSS Values

```
# Plot of the relationship between RSS and distance
ggplot(data = combined_data,
    aes(x = distance,
        y = avgRSS,
        color = node_id)) +
geom_point(size = 2)
```

As distance increases, we see average RSS decreasing exponentially.

11.3.1 Preliminary Exponential Decay Model - Determine staring values for the final model

- SSasvmp self start for exponential model to find the data starting values
- Asvm horizontal asymptote (when large values) y values decay to this
 value
- R0 numeric value when avgRSS (i.e., response variable) = 0
- lrc natural logarithm of the rate constant (rate of decay)

11.3.2 Final Exponential Decay Model

User provides self-starting values based on visualization of the data and values in the Preiliminary Model Output

exponential model formula: $avgRSS \sim a * exp(-S * distance) + K$

- a = intercept
- S = decay factor
- \bullet K = horizontal asymptote

```
## ***** Variables to define for final model below - replace values below with values from exp.m
a <- coef(exp.mod)[["R0"]]
S <- exp(coef(exp.mod)[["lrc"]])</pre>
```

```
K <- coef(exp.mod)[["Asym"]]</pre>
  # Final Model
nls.mod <- nls(avgRSS ~ a * exp(-S * distance) + K,</pre>
                start = list(a = a,
                             S = S,
                             K=K),
                data = combined_data)
  # Model Summary
summary(nls.mod)
  # Model Coefficients
coef(nls.mod)
## Check the fit of the model and get predicted values
  # Get residuals and fit of model and add variables to main table
combined_data$E <- residuals(nls.mod)</pre>
combined_data$fit <- fitted(nls.mod)</pre>
  # Plot residuals by fit or distance
\#ggplot(combined\_data, aes(x = distance, y = E, color = node\_id)) +
         geom\_point(size = 2)
\#qqplot(combined\_data, aes(x = fit, y = E, color = node\_id)) +
# geom_point(size = 2)
  # Get model predictions
combined_data$pred <- predict(nls.mod)</pre>
## Plot with predicted line
ggplot(combined_data, aes(x = distance, y = avgRSS, color=node_id)) +
  geom_point() +
  geom_line(aes(y = pred), color="black", lwd = 1.25) +
  scale_y_continuous(name = "RSS (dB)") +
  scale_x_continuous(name = "Distance (m)") +
  theme_classic()
K <- unname(coef(nls.mod)[3])</pre>
a <- unname(coef(nls.mod)[1])
S <- unname(coef(nls.mod)[2])
combined_data <- estimate.distance(combined_data, K, a, S)</pre>
tile_url = "https://tile.openstreetmap.org/{z}/{x}/{y}.png"
testout <- combined_data[combined_data$TestId==0,]</pre>
leaflet() %>%
```

```
addTiles(
      urlTemplate = tile_url,
      options = tileOptions(maxZoom = 25)
    ) %>%
    addCircleMarkers(
      data = nodes,
      lat = nodes$node_lat,
     lng = nodes$node_lng,
     radius = 5,
      color = "cyan",
      fillColor = "cyan",
     fillOpacity = 0.5,
     label = nodes$node_id
    ) %>%
    addCircles(
     data=testout,
      lat = testout$node_lat,
      lng = testout$node_lng,
     radius = testout$distance,
      color = "red",
      #fillColor = "red",
      fillOpacity = 0)
no.filters <- trilateration.TestData.NoFilter(combined_data)</pre>
RSS.FILTER \leftarrow c(-80, -85, -90, -95)
RSS.filters <- trilateration.TestData.RSS.Filter(combined_data, RSS.FILTER)
#DIST.FILTER <- c(315,500,750,1000)
# Calculate error of location estimates of each test location when Distance filters are applied
#Dist.filters <- trilateration.TestData.Distance.Filter(combined data, DIST.FILTER)
SLIDE.TIME <- 2
GROUP.TIME <- "1 min"</pre>
test_data <- testdata %>%
  filter(time >= as.Date("2023-10-05") & time <= as.Date("2023-10-15")) %>%
 filter(tag_id == "2D4B782D") %>%
  collect()
# Function to prepare beep data for trilateration
# by estimating distance of a signal based on RSS values
beep.grouped <- prep.data(test_data,nodes,SLIDE.TIME,GROUP.TIME,K, a, S)</pre>
RSS.filter <- -95
location.estimates <- trilateration(beep.grouped, nodes, RSS.FILTER)</pre>
```

mapping(nodes, location.estimates)