vDSP Vector Scalar Arithmetic Operations Reference

Performance > Carbon



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vDSP Vector Scalar Arithmetic Operations Reference

Framework: Accelerate/vecLib

Declared in vDSP.h

Overview

Describes the C API for the vecLib functions that perform arithmetic operations combining a scalar with each element of a vector.

Functions by Task

Adding a Scalar to Elements of a Vector

Dividing Elements of a Vector by a Scalar

```
vDSP_svdivD (page 7)
```

Divide scalar by vector; double precision.

Multiplying Elements of a Vector by a Scalar

```
vDSP_vsma (page 13)
```

Vector scalar multiply and vector add; single precision.

vDSP_vsmaD (page 14)

Vector scalar multiply and vector add; double precision.

vDSP_zvsma (page 21)

Complex vector scalar multiply and add; single precision.

vDSP_zvsmaD (page 22)

Complex vector scalar multiply and add; double precision.

vDSP_vsmul (page 18)

Multiplies vector signal1 by scalar signal2 and leaves the result in vector result; single precision.

vDSP_vsmulD (page 19)

Multiplies vector signal1 by scalar signal2 and leaves the result in vector result; double precision.

vDSP_zvzsml (page 23)

Complex vector multiply by complex scalar; single precision.

vDSP_zvzsmlD (page 24)

Complex vector multiply by complex scalar; double precision.

Multiplying Elements of a Vector by a Scalar, then Adding or Subtracting Another Scalar

```
vDSP_vsmsa (page 14)
```

Vector scalar multiply and scalar add; single precision.

vDSP_vsmsaD (page 15)

Vector scalar multiply and scalar add; double precision.

vDSP_vsmsb (page 16)

Vector scalar multiply and vector subtract; single precision.

vDSP_vsmsbD (page 17)

Vector scalar multiply and vector subtract; double precision.

Functions

vDSP svdiv

Divide scalar by vector; single precision.

```
void vDSP_svdiv (float * A,
float * B,
vDSP_Stride J,
float * C,
vDSP_Stride K,
vDSP_Length N);
```

```
A Single-precision real input scalar

B Single-precision real input vector

J Stride for B

C Single-precision real output vector

K Stride for C

N Count
```

Discussion

This performs the operation

$$C_{nK} = \frac{A}{B_{nJ}}$$
, $n = \{0, N-1\}$

Divides scalar A by each element of vector B, storing the results in vector C.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_svdivD

Divide scalar by vector; double precision.

```
void vDSP_svdivD (double * A,
double * B,
vDSP_Stride J,
double * C,
vDSP_Stride K,
vDSP_Length N);
```

Parameters

A
Double-precision real input scalar

B
Double-precision real input vector

```
J
Stride for B
C
Double-precision real output vector
K
Stride for C
N
Count
```

Discussion

This performs the operation

$$C_{nK} = \frac{A}{B_{nJ}}$$
, $n = \{0, N-1\}$

Divides scalar A by each element of vector B, storing the results in vector C.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_vsadd

Vector scalar add; single precision.

```
void vDSP_vsadd (float * A,
vDSP_Stride I,
float * B,
float * C,
vDSP_Stride K,
vDSP_Length N);
```

Parameters

```
A Single-precision real input vector

I Stride for A

B Single-precision real input scalar

C Single-precision real output vector

K Stride for C

N Count
```

Discussion

Performs the operation

$$C_{nK} = A_{nI} + B$$
 $n = \{0, N-1\}$

Adds scalar B to each element of vector A and stores the result in the corresponding element of vector C.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP vsaddD

Vector scalar add; double precision.

```
void vDSP_vsaddD (double * A,
vDSP_Stride I,
double * B,
double * C,
vDSP_Stride K,
vDSP_Length N);
```

Parameters

```
A Double-precision real input vector

I Stride for A

B Double-precision real input scalar

C Double-precision real output vector

K Stride for C

N
```

Discussion

Performs the operation

Count

Adds scalar B to each element of vector A and stores the result in the corresponding element of vector C.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP vsaddi

Integer vector scalar add.

```
void vDSP_vsaddi (int * A,
vDSP_Stride I,
int * B,
int * C,
vDSP_Stride K,
vDSP_Length N);
```

Parameters

```
Integer input vector

I Stride for A

B Integer input scalar

C Integer output vector

K Stride for C

N Count
```

Discussion

Performs the operation

Adds scalar B to each element of vector A and stores the result in the corresponding element of vector C.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_vsdiv

Vector scalar divide; single precision.

```
void vDSP_vsdiv (float * A,
vDSP_Stride I,
float * B,
float * C,
vDSP_Stride K,
vDSP_Length N);
```

Parameters

Α

Single-precision real input vector

```
Ι
       Stride for A
В
       Single-precision real input scalar
C
       Single-precision real output vector
Κ
       Stride for C
Ν
       Count
```

Discussion

Performs the operation

$$C_{nK} = \frac{A_{nI}}{B}$$
 $n = \{0, N-1\}$

Divides each element of vector A by scalar B and stores the result in the corresponding element of vector C.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_vsdivD

Vector scalar divide; double precision.

```
void vDSP_vsdivD (double * A,
vDSP_Stride I,
double * B,
double * C,
vDSP_Stride K,
vDSP_Length N);
```

Parameters

```
Α
       Double-precision real input vector
Ι
       Stride for A
В
       Double-precision real input scalar
С
       Double-precision real output vector
Κ
       Stride for C
Ν
       Count
```

Discussion

Performs the operation

$$C_{nK} = \frac{A_{nI}}{B}$$
 $n = \{0, N-1\}$

Divides each element of vector A by scalar B and stores the result in the corresponding element of vector C.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP vsdivi

Integer vector scalar divide.

```
void vDSP_vsdivi (int * A,
vDSP_Stride I,
int * B,
int * C,
vDSP_Stride K,
vDSP_Length N);
```

Parameters

```
A Integer input vector

I Stride for A

B Integer input scalar

C Integer output vector

K Stride for C

N Count
```

Discussion

Performs the operation

$$C_{nK} = \frac{A_{nI}}{B}$$
 $n = \{0, N-1\}$

Divides each element of vector A by scalar B and stores the result in the corresponding element of vector C.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_vsma

Vector scalar multiply and vector add; single precision.

```
void vDSP_vsma (const float * A,
vDSP_Stride I,
const float * B,
const float * C,
vDSP_Stride K,
float * D,
vDSP_Stride L,
vDSP_Length N);
```

Parameters

```
Α
       Single-precision real input vector
Ι
       Stride for A
В
       Single-precision real input scalar
С
       Single-precision real input vector
Κ
       Stride for C
D
       Single-precision real output vector
L
       Stride for D
Ν
       Count
```

Discussion

Performs the operation

$$D_{nM} = A_{nI} \cdot B + C_{nK}$$
 $n = \{0, N-1\}$

Multiplies vector A by scalar B and then adds the products to vector C. Results are stored in vector D.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP vsmaD

Vector scalar multiply and vector add; double precision.

```
void vDSP_vsmaD (const double * A,
vDSP_Stride I,
const double * B,
const double * C,
vDSP_Stride K,
double * D,
vDSP_Stride L,
vDSP_Length N);
```

Parameters

```
Α
       Double-precision real input vector
Ι
       Stride for A
В
       Double-precision real input scalar
\mathcal{C}
       Double-precision real input vector
Κ
       Stride for C
D
       Double-precision real output vector
L
       Stride for D
Ν
       Count
```

Discussion

Performs the operation

$$D_{nM} = A_{nI} \cdot B + C_{nK} \qquad \mathbf{n} = \{0, \text{N--1}\}$$

Multiplies vector A by scalar B and then adds the products to vector C. Results are stored in vector D.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_vsmsa

Vector scalar multiply and scalar add; single precision.

```
void vDSP_vsmsa (float * A,
vDSP_Stride I,
float * B,
float * C,
float * D,
vDSP_Stride L,
vDSP_Length N);
```

```
A Single-precision real input vector

I Stride for A

B Single-precision real input scalar

C Single-precision real input scalar

D Single-precision real output vector

L Stride for D

N Count
```

Discussion

Performs the operation

$$D_{nM} = A_{nI} \cdot B + C$$
 $n = \{0, N-1\}$

Multiplies vector A by scalar B and then adds scalar C to each product. Results are stored in vector D.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_vsmsaD

Vector scalar multiply and scalar add; double precision.

```
void vDSP_vsmsaD (double * A,
vDSP_Stride I,
double * B,
double * C,
double * D,
vDSP_Stride L,
vDSP_Length N);
```

```
Double-precision real input vector

Stride for A

Double-precision real input scalar

Double-precision real input scalar

Double-precision real output vector

Stride for D
```

Discussion

Performs the operation

Count

$$D_{nM} = A_{nI} \cdot B + C$$
 $n = \{0, N-1\}$

Multiplies vector A by scalar B and then adds scalar C to each product. Results are stored in vector D.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_vsmsb

Vector scalar multiply and vector subtract; single precision.

```
void vDSP_vsmsb (float * A,
vDSP_Stride I,
float * B,
float * C,
vDSP_Stride K,
float * D,
vDSP_Stride L,
vDSP_Length N);
```

```
Α
       Single-precision real input vector
Ι
       Stride for A
В
       Single-precision real input scalar
С
       Single-precision real input vector
Κ
       Stride for C
D
       Single-precision real output vector
L
       Stride for D
Ν
       Count
```

Discussion

Performs the operation

$$D_{nM} = A_{nI} \cdot B - C_{nK} \qquad n = \{0, N-1\}$$

Multiplies vector A by scalar B and then subtracts vector C from the products. Results are stored in vector D.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_vsmsbD

Vector scalar multiply and vector subtract; double precision.

Functions
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```
void vDSP_vsmsbD (double * A,
vDSP_Stride I,
double * B,
double * C,
vDSP_Stride K,
double * D,
vDSP_Stride L,
vDSP_Length N);
```

```
Double-precision real input vector

Stride for A

Double-precision real input scalar

Double-precision real input vector

Stride for C

Double-precision real output vector

Stride for D
```

Discussion

Performs the operation

Count

$$D_{nM} = A_{nI} \cdot B - C_{nK} \qquad n = \{0, N-1\}$$

Multiplies vector A by scalar B and then subtracts vector C from the products. Results are stored in vector D.

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_vsmul

Multiplies vector result; single precision.

```
void vDSP_vsmul (const float input1[],
vDSP_Stride stride1,
const float * input2,
float result[],
vDSP_Stride strideResult,
vDSP_Length size);
```

Discussion

This performs the operation

$$C_{nK} = A_{nI} \cdot B$$
 $n = \{0, N-1\}$

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_vsmulD

Multiplies vector signal1 by scalar signal2 and leaves the result in vector result; double precision.

```
void vDSP_vsmulD (const double input1[],
vDSP_Stride stride1,
const double * input2,
double result[],
vDSP_Stride strideResult,
vDSP_Length size);
```

Discussion

This performs the operation

$$C_{nK} = A_{nI} \cdot B$$
 $n = \{0, N-1\}$

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP zvdiv

Complex vector divide; single precision.

```
void vDSP_zvdiv (DSPSplitComplex * A,
vDSP_Stride I,
DSPSplitComplex * B,
vDSP_Stride J,
DSPSplitComplex * C,
vDSP_Stride K,
vDSP_Length N);
```

Single-precision complex input vector

Stride for A

Single-precision complex input vector

Stride for B

C
Single-precision complex output vector

K
Stride for C

Discussion

Divides vector B by vector A.

Count

$$C_{nK} = \frac{B_{nJ}}{A_{nI}}$$
 $n = \{0, N-1\}$

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_zvdivD

Complex vector divide; double precision.

```
void vDSP_zvdivD (DSPDoubleSplitComplex * A,
vDSP_Stride I,
DSPDoubleSplitComplex * B,
vDSP_Stride J,
DSPDoubleSplitComplex * C,
vDSP_Stride K,
vDSP_Length N);
```

Α

Double-precision complex input vector

Ι

Stride for A

В

Double-precision complex input vector

J

Stride for B

С

Double-precision complex output vector

Κ

Stride for C

Ν

Count

Discussion

Divides vector B by vector A.

$$C_{nK} = \frac{B_{nJ}}{A_{nI}}$$
 $n = \{0, N-1\}$

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_zvsma

Complex vector scalar multiply and add; single precision.

```
void vDSP_zvsma (DSPSplitComplex * A,
vDSP_Stride I,
DSPSplitComplex * B,
DSPSplitComplex * C,
vDSP_Stride K,
DSPSplitComplex * D,
vDSP_Stride L,
vDSP_Length N);
```

```
Α
       Single-precision complex input vector
Ι
       Stride for A
В
       Single-precision complex input scalar
С
       Single-precision real input vector
Κ
       Stride for C
D
       Single-precision real output vector
L
       Stride for C
Ν
       Count
```

Discussion

Multiplies vector A by scalar B and add the products to vector C. The result is stored in vector D.

$$D_{nL} = A_{nI}B + C_{nK}$$

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_zvsmaD

Complex vector scalar multiply and add; double precision.

```
void vDSP_zvsmaD (DSPDoubleSplitComplex * A,
vDSP_Stride I,
DSPDoubleSplitComplex * B,
DSPDoubleSplitComplex * C,
vDSP_Stride K,
DSPDoubleSplitComplex * D,
vDSP_Stride L,
vDSP_Length N);
```

```
A Double-precision complex input vector

I Stride for A

B Double-precision complex input scalar

C Double-precision real input vector

K Stride for C

D Double-precision real output vector

L Stride for C
```

Discussion

Multiplies vector A by scalar B and add the products to vector C. The result is stored in vector D.

$$D_{nL} = A_{nI}B + C_{nK}$$

Count

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP zvzsml

Complex vector multiply by complex scalar; single precision.

```
void vDSP_zvzsml (DSPSplitComplex * A,
vDSP_Stride I,
DSPSplitComplex * B,
DSPSplitComplex * C,
vDSP_Stride K,
vDSP_Length N);
```

```
Α
       Single-precision complex input vector
Ι
       Stride for A
В
       Single-precision complex input scalar
C
       Single-precision complex output vector
Κ
       Stride for C
Ν
       Count
```

Discussion

This peforms the operation

$$C_{nK} = A_{nI}B$$

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

vDSP_zvzsmlD

Complex vector multiply by complex scalar; double precision.

```
void vDSP_zvzsml (DSPSplitComplex * A,
vDSP_Stride I,
DSPSplitComplex * B,
DSPSplitComplex * C,
vDSP_Stride K,
vDSP_Length N);
```

Parameters

```
Α
      Double-precision complex input vector
Ι
      Stride for A
В
      Double-precision complex input scalar
```

 ${\cal C}$ Double-precision complex output vector ${\cal K}$ Stride for ${\cal C}$ ${\cal N}$ Count

Discussion

This peforms the operation

$$C_{nK} = A_{nI}B$$

Availability

Available in Mac OS X v10.4 and later.

Declared In

vDSP.h

Document Revision History

This table describes the changes to vDSP Vector Scalar Arithmetic Operations Reference.

Date	Notes
2007-06-15	New document that describes the C API for the vDSP functions that perform arithmetic operations combining a scalar with each element of a vector

REVISION HISTORY

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