1. Current Method for Tracking:
2. Accurate 3D Pose Estimation from a Single Depth Estimation
   1. What does algorithm do they use?
      1. view-independent matching algorithm between a 3D full-body surface mesh and a depth map
   2. How did they evaluated their results?
   3. <http://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=6126310>
3. KinectFusion: Real-Time Dense Surface Mapping and Tracking
   1. simultaneous localisation and mapping