Cem Koç

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https://github.com/cemkoc

EDUCATION

University of California, Berkeley

Theory Artificial Intelligence

B.S. in Electrical Engineering and Computer Sciences
M.Eng. in Electrical Engineering and Computer Sciences
(concentration: Data Science & Systems)

May 12, 2017 May 14, 2021

(concentration: Data Science & Systems)

Relevant Coursework: Data Science, Deep Learning, Natural Language Processing, Parallel Computing & Distributed Systems, Advanced Linear Algebra, Convex Optimization, Computer Vision, Operating Systems, Data Structures, Algorithms, Computer Architecture, Machine Learning, Statistics & Probability

INDUSTRY EXPERIENCE

Apple

Software Engineer

July 2017 – Present Sunnyvale, CA

- Working in the Maps Data Science & Analytics Platform team. Working on creating parallel batch and stream processing algorithms, distributed computation frameworks on top of Spark to do processing of geospatial (GIS) and textual data at scale including GPS probe, relatime traffic, routing and search data.
- Worked on building the POI (place of interest) popularity pipeline with MapReduce, using a distributed deterministic pushdown automaton (DPDA) to extract popularity features from user event logs.
- Worked on building a reverse geocoder library that provides a scalable and fast solution when doing point-in-polygon lookups and more.
- Working on creating a modular graph based stream or batch data processing framework for doing complex stateful transformations, joins, projections and approximations. Supports languages such as Python and Scala and allows users to create complex data processing graphs using higher level operators built on top of Spark.
- Patent: I am the co-inventor on a 2019 US Patent Application filed by Apple in distributed combinatorial optimization.

Apple

Software Engineering Intern

June 2016 – September 2016 Sunnyvale, CA

- Worked in Apple Special Projects Group. Worked on creating distributed combinatorial optimization algorithm in Java to tackle a specific NP-hard problem similar to Capacitated Arc Routing. Approximated near-optimal solutions using a perturbation based randomized algorithms on large sparse graphs. Worked with technologies such as Kafka, Apache Spark, Hive for computation/analysis and build systems like Gradle.
- Built a distributed system for submitting fast spatial queries against a KD-tree backed representation of a large graph using internal Maps data. Implemented, spatial indexing to cut regions and distribute them to worker nodes for route generation.
- Created a custom Spark ETL pipeline to ingest internal data and to estimate edge weights from multimodal datasets such as: realtime GPS probe, POI and imagery data. Created custom Spark UDFs in Java and Scala to do complex transformations. Created a statistical model based on time-series analysis for detecting anomalies in data for alerting. Created dimension tables and schemas to store datasets and did analysis on them using SparkSQL.

TubeMogul (Adobe Inc.) Software Engineering Intern June 2015 – September 2015 Emeryville, CA

• Worked in the Ads Machine Learning team. Developed and integrated a Java framework working with Gradle/Maven build systems to collect and process real-time bidding results of digital ads in batch (Kafka/Hadoop/Spark) and in streams using Apache Flink. Created a Bayesian forecasting tool using Python and Java to be used in real-time forecasting.

• Created an ETL pipeline to process peta-bytes of time-series data using MapReduce/Spark to forecast how likely an add will win in a given online auction. Created an auction simulator in back-end using Java and a front-end dashboard to monitor the results and add them to a database to query using SQL in an OLAP system.

PUBLICATIONS Body Lift and Drag for a Legged Millirobot in Compliant Beam Environment

CONFERENCES

Cem Koc*, Can Koc*, Brian Su*, Carlos Casarez, Ron S. Fearing.

Published in ICRA, 2019. arXiv 1904.09101.

Terrain Classification with Force-Torque Sensor Equipped Millirobot

Cem Koc*, Can Koc*, Brian Su*, Carlos Casarez, Ron S. Fearing.

Presented at 2016 Bay Area Robotics Symposium (BARS).

RESEARCH **EXPERIENCE**

Berkeley Artificial Intelligence Research (BAIR) Lab Research Assistant

May 2015 - June 2017

Berkeley, CA

Worked under guidance of Professor Ronald S. Fearing in Biomimetic Millisystems Lab

Research Projects

• Terrain Classification with Force-Torque Sensor Equipped Millirobot

Worked with a 10cm long, hexapedal milli-robot with force-torque sensing shell attached on top. Worked on binary classification of densely cluttered terrain using time series force-torque sensor data. Implemented and trained ensemble learning, gradient boosted decision trees, SVMs and neural nets to create a robust model. Our model can identify dense terrains in noisy environments with 97% accuracy.

• Body Lift and Drag for a Legged Millirobot in Compliant Beam **Environment through Intrinsic Force Sensing**

In this work we utilized a (previously developed) low-cost 6-axis force/torque sensing shell to measure the interaction forces between a hexapedal millirobot and a set of compliant beams which models a densely cluttered environment. Built a batch and online data processing framework to analyze large timeseries dataset of sensor readings. Discovered the drag and lift forces, specific resistance required to pass through dense terrains could be measured. We further discovered that, interestingly, some contact between the robot and the compliant beams can lower specific resistance of locomotion.

PERSONAL **PROJECTS**

Parallelized Point Cloud Similarity: Implemented a parallelized Chamfer distance algorithm for Point Cloud similarity using a CPU based algorithm using OpenMP/MPI and a GPU based algorithm (for comparison) which utilizes distributed memory paralelism.

Deep Portfolio: Implemented a financial model-free reinforcement learning framework from Jiang et al. for the portfolio management problem. Trained agent utilized policy gradient methods to trade on cryptocurrencies in real life.

Deep Doom: Implemented Prioritized Experience Replay from Schaul et al. to do fast deep reinforcement learning on Doom game. Uses ViZDoom, Keras, OpenAI Gym. AnimeFaces: Learn to recognize faces in Anime frames! Fine tuned computer vision models such as GoogleNet, AlexNet and VGGFace. Uses Caffe and Keras.

TECHNICAL SKILLS

Interest Areas: Machine Learning Systems, Numerical Linear Algebra, Optimization, Parallel Computing, Streaming & Big Data Frameworks

ML/DS Frameworks (order of recency): PyTorch, Numpy/Scipy, Sklearn,

Pandas, SparkML, Keras/Tensorflow, Caffe

Computing Frameworks: Spark/MapReduce, OpenMP, MPI, UPC++, CUDA, Docker/Kubernetes/AWS, Kibana/ElasticSearch

Analytics Frameworks (order of recency): Hive, SparkSQL, Zeppelin, MySQL/PostgreSQL, Spark Streaming, Flink

Programming Languages (order of recency): Python, Java, C++, Scala, Go, C