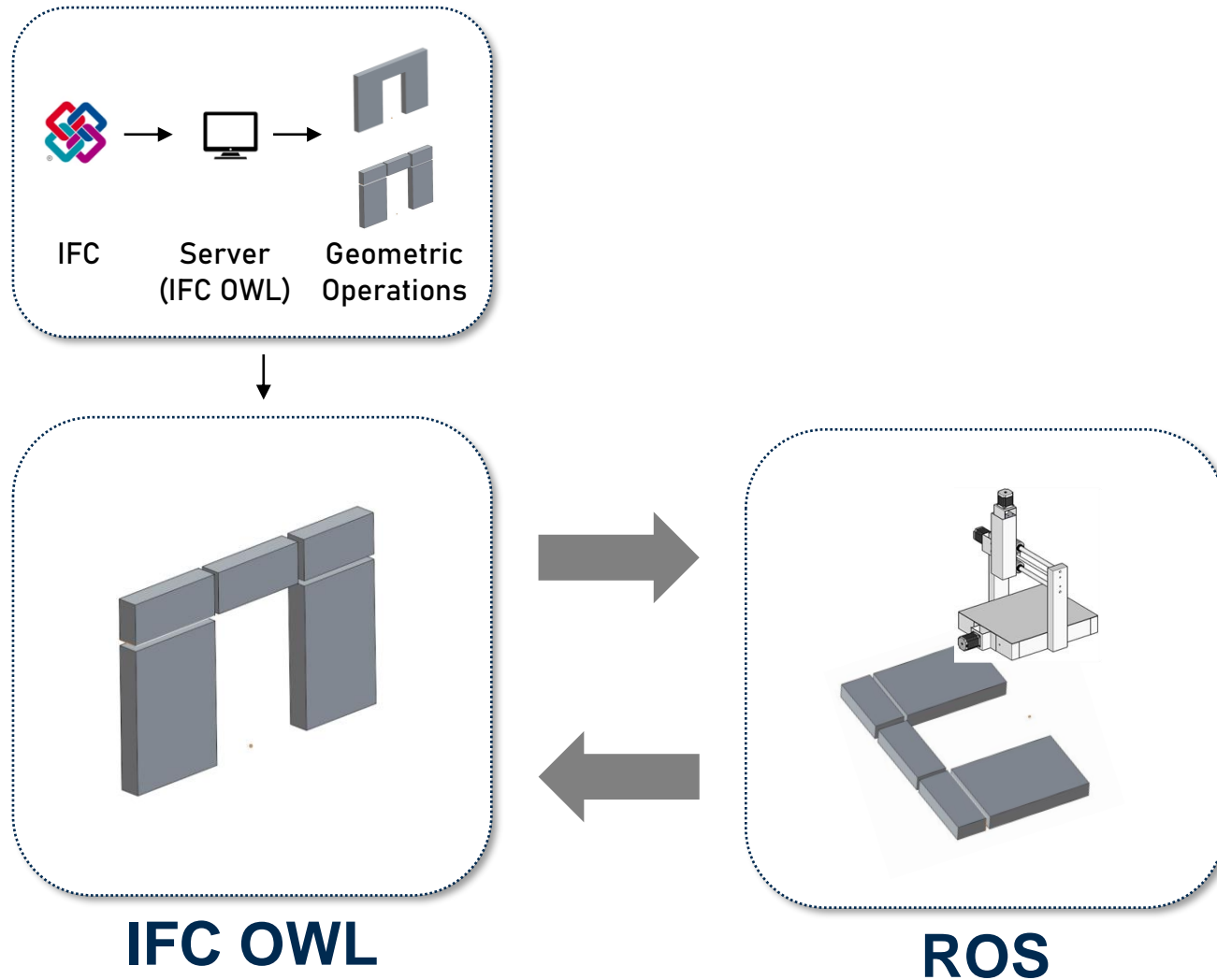





# BIM – ROS INTEGRATION



1. Retrieve data from IFC OWL
2. Visualize in ROS
3. Simulate the actions of the robot (e.g. Cutting of panels or tiles)
4. Feed the production status back into IFC DYNAMICALLY
  -  - To do
  -  - Done
  -  - In Progress
5. Repeat until all selected elements are done