BLG 351E – Microcomputer Laboratory
Experiment 6

Introduction

This experiments aims to enhance the practical experience about driving 7-segment displays and initializing interrupts.

Students are recommended both to read the supplementary material **MSP430 User Guide - Chapter 8** on Ninova and to bring their own computers to the laboratory on which Texas Instruments Code Composer Studio IDE is installed (For installation instructions, review **CCS_Installation.pdf**).

Background Information

A 7-segment display contains 7+1 (including the dot at the lower corner) distinct LEDs which are controlled by the distinct inputs. In this experiment, you are requested to use these displays to show decimal integers. Thus, the first objective you need to do is to decide which inputs have to be set high or low to represent the integers between 0-9.

For example, in order to show "0" on the 7-segment display, LEDs A, B, C, D, E and F have to be lit. This means that the related bits of the GPIO ports have to be set high. Before, the experiment, please fill the table below for the other decimal integers.

Integer	H	G	F	E	D	C	B	A
0	0	0	1	1	1	1	1	1
1	0							
2	0							
3	0							
4	0							
5	0							
6	0							
7	0							
8	0							
9	0							

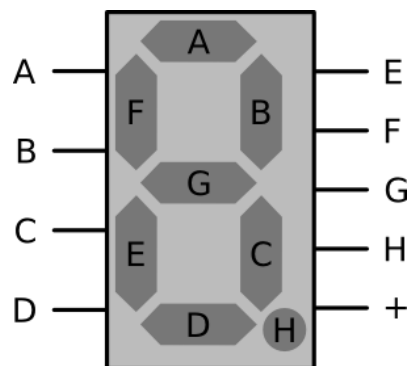**Table 1**: Inputs for decimal integers

Figure 1: 7-segment display

GPIO Port 1 and Port 2 are physically connected to the 4-digit 7-segment display as follows.
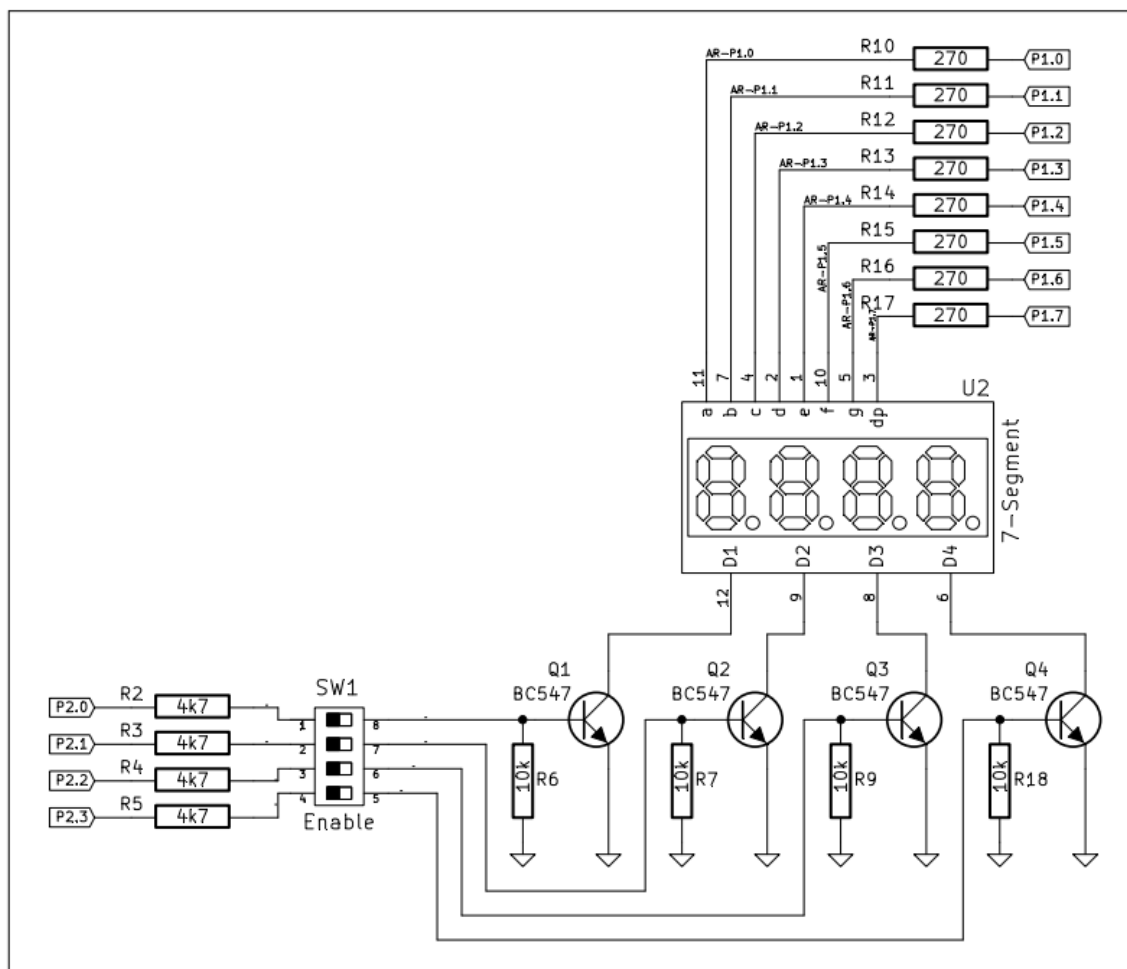

Figure 2: Connection of the 7-segment display

Part 1 – Counter Program

In the first part of the experiment, you are requested to write a main program which counts from 0 to 9 in ten seconds and shows the value of the counter at one of the digits of the 7-segment display. Details of this program are explained below.

Firstly, you should to initialize GPIO Port 1 and Port 2 to activate and use 7-segment display. Then, you should write a loop which increments a counter you defined and waits one-second at each iteration. Notice that, the counter has to be reset when it reaches the decimal number 10 (0Ah).

You could use the following **Delay** function to implement one-second delay.

```
Delay        mov.w   #0Ah,R14                    ;Delay to R14
L2           mov.w   #07A00h,R15
             dec.w                               ;Decrement R15
             jnz     L1
             dec.w   R14
             jnz     L2
             ret
```

Moreover, you could call this function in your code as follows.

```
             ...
             call    #Delay
             ...
```

Lastly, at each iteration, you should convert the value of the counter (integer) to values that you determine in the **Table 1** in order to show meaningful integers on 7-segment display. One of the simple ways of this conversion is defining an array to hold the values of integers for 7-segment display. So, the number you would like to convert could be used as the index of the array. In CCS editor, an array could be defined as follows.

```
;Integer to 7-segment array
array  .byte 00111111b, ... , 00111111b  ;contains 10 values
lastElement
```

Part 2 – Interrupt Subroutine

In this part, you are requested to write an interrupt subroutine and enhance your main program so that your program able to count upwards OR downwards by an external interrupt.

You could define a Boolean variable in your program which represents the direction of the counting. So, in your main loop, you could check the value of this variable and decide to increment or decrement the value of the counter. And, you could simply toggle the value of the direction to change the direction of the counting.

After, changing your main program, you should implement necessary part to utilize interrupts. In the following steps, use of interrupts is explained in detail.

First, you should activate a mask-able interrupt in one of the GPIO Port Pins. The following code is given as an example to initialize the interrupt at the 6th bit of Port 2.

```
init_INT           bis.b #040h,&P2IE          ; enable interrupt at P2.6
                   and.b #0BFh,&P2SEL         ; set 0 P2SEL.6
                   and.b #0BFh,&P2SEL2        ; set 0 P2SEL2.6
```

```
        bis.b  #040h,&P2IES            ; high-to-low interrupt mode
        clr    &P2IFG                  ; clear the flag
        eint                           ; enable interrupts
```

Then, you need to store the address of your interrupt subroutine to the interrupt vector of the GPIO Port 2. So that, whenever an interrupt comes from the Port 2, your interrupt subroutine begins running. To do this, you should implement the following code at the end of your main program.

```
;-------------------------------------------------------------------------------
; Interrupt Vectors
;-------------------------------------------------------------------------------
        .sect   ".reset"               ; MSP430 RESET Vector
        .short  RESET
        .sect   ".int03"               ; Port Interrupt Vector
        .short  ISR
```

Lastly, you should write your interrupt subroutine which is pointed in the interrupt vector of the GPIO Port 2. The following code part is given as a template for your interrupt subroutine. You need the fill the body of the subroutine in order to accomplish the requested behavior.

```
ISR             dint                   ; disable interrupts

        ;YOUR CODE goes here

                eint                   ; enable interrupts
                reti                   ; return from ISR
```

Report
Your report should contain your program code (with explanations) for Part 1 and Part 2.