# Discrete Mathematics Graphs

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# **Topics**

### Graphs

Introduction

Connectivity

Planar Graphs

Searching Graphs

#### Trees

Introduction

Rooted Trees

Binary Trees

Decision Trees

#### Weighted Graphs

Introduction

Shortest Path

Minimum Spanning Tree

Graphs

#### Definition

graph: G = (V, E)

▶ V: node (or *vertex*) set

▶  $E \subseteq V \times V$ : edge set

▶ if  $e = (v_1, v_2) \in E$ :

 $ightharpoonup v_1$  and  $v_2$  are endnodes of e

• e is incident to  $v_1$  and  $v_2$ 

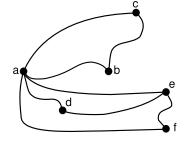
v<sub>1</sub> and v<sub>2</sub> are adjacent

▶ node with no incident edge: isolated node

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# Graph Example

#### Example



 $= \{a, b, c, d, e, f\}$  $\{(a,b),(a,c),$ (a, d), (a, e),(a, f), (b, c), (d, e), (e, f)

**Directed Graphs** 

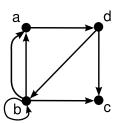
### Definition

directed graph (or digraph): D = (V, A)

- ▶  $A \subseteq V \times V$ : arc set
- origin and terminating nodes

# Directed Graph Example

Example



# Multigraphs

#### Definition

parallel edges: edges between the same pair of nodes

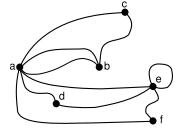
loop: an edge starting and ending in the same node

plain graph: a graph without any loops or parallel edges

multigraph: a graph which is not plain

# Multigraph Example

Example



- ► parallel edges:
  - (a, b)
- ► loop:
- (e, e)

# Subgraph

G' = (V', E') is a subgraph of G = (V, E):

- $V' \subseteq V$
- E' ⊆ E
- $\blacktriangleright \ \forall (v_1,v_2) \in E' \ v_1,v_2 \in V'$

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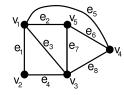
### Representation

- ► incidence matrix:
  - ▶ rows represent nodes, columns represent edges
  - ▶ cell: 1 if the edge is incident to the node, 0 otherwise
- ► adjacency matrix:

  - rows and columns represent nodes
    cells represent the number of edges between the nodes

# Incidence Matrix Example

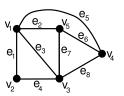
#### Example



	$e_1$	$e_2$	$e_3$	$e_4$	$e_5$	$e_6$	$e_7$	$e_8$
$v_1$	1	1	1	0	1	0	0	0
<i>V</i> 2	1	0	0	1	0	0	0 0 1 0	0
<i>V</i> 3	0	0	1	1	0	0	1	1
<i>V</i> <sub>4</sub>	0	0	0	0	1	1	0	1
V <sub>5</sub>	0	1	0	0	0	1	1	0

# Adjacency Matrix Example

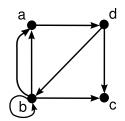
#### Example



	$v_1$	<i>V</i> <sub>2</sub>	<i>V</i> 3	<i>V</i> 4	<i>V</i> 5
$v_1$	0	1	1 1	1	1
<i>V</i> 2	1	0	1	0	0
<i>V</i> <sub>3</sub>	1	1	0	1	1
V <sub>4</sub>	1	0	1	0	1
$V_5$	1	0	1	1	0

# Adjacency Matrix Example

### Example



	а	Ь	С	d
а	0	0	0	1
a b c d	2	0 1 0	1	0
С	0	0	0	0
А	n	1	1	Λ

# Degree

#### Definition

degree: number of edges incident to the node

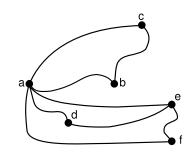
### Theorem

let  $d_i$  be the degree of node  $v_i$ 

$$|E| = \frac{\sum_i d_i}{2}$$

# Degree Example

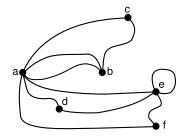
### Example (plain graph)



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# Degree Example

# Example (multigraph)



|E|

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# Degree in Directed Graphs

- ▶ two types of degree

  - in-degree: d<sub>v</sub><sup>i</sup>
     out-degree: d<sub>v</sub><sup>o</sup>
- ▶ node with in-degree 0: source
- ▶ node with out-degree 0: sink

### Degree

#### Theorem

In an undirected graph, there is an even number of nodes which have an odd degree.

#### Proof.

 $ightharpoonup t_i$ : number of nodes of degree i

$$2|E| = \sum_{i} d_{i} = 1t_{1} + 2t_{2} + 3t_{3} + 4t_{4} + 5t_{5} + \dots$$

$$2|E| - 2t_{2} - 4t_{4} - \dots = t_{1} + t_{3} + \dots + 2t_{3} + 4t_{5} + \dots$$

$$2|E| - 2t_{2} - 4t_{4} - \dots - 2t_{3} - 4t_{5} - \dots = t_{1} + t_{3} + t_{5} + \dots$$

▶ since the left-hand side is even, the right-hand side is also even

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# Regular Graphs

#### Definition

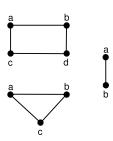
regular graph: all nodes have the same degree

n-regular: all nodes have degree n

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# Regular Graph Examples

#### Example



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# Completely Connected Graphs

#### Definition

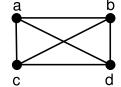
G = (V, E) is completely connected:

- ▶  $\forall v_1, v_2 \in V (v_1, v_2) \in E$
- ▶ there is an edge between every pair of nodes
- $ightharpoonup K_n$ : the completely connected graph with n nodes

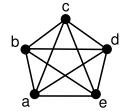
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### Completely Connected Graph Examples

#### Example $(K_4)$



### Example $(K_5)$



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### Bipartite Graphs

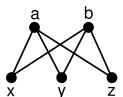
#### Definition

G = (V, E) is bipartite:

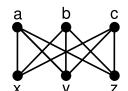
- $\blacktriangleright \forall (v_1, v_2) \in E \ v_1 \in V_1 \land v_2 \in V_2$
- $\blacktriangleright \ V_1 \cup V_2 = V, \ V_1 \cap V_2 = \emptyset$
- ▶ complete bipartite:  $\forall v_1 \in V_1 \ \forall v_2 \in V_2 \ (v_1, v_2) \in E$
- $ightharpoonup |K_{m,n}: |V_1| = m, |V_2| = n$

# Complete Bipartite Graph Examples

Example  $(K_{2,3})$ 



Example  $(K_{3,3})$ 



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# Isomorphism

Definition

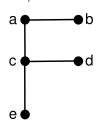
G = (V, E) and  $G^* = (V^*, E^*)$  are isomorphic:

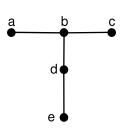
- $ightharpoonup \exists f: V \rightarrow V^* \ (u,v) \in E \Rightarrow (f(u),f(v)) \in E^*$
- ▶ *f* is bijective
- ightharpoonup G and  $G^{\star}$  can be drawn the same way

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# Isomorphism Example

Example



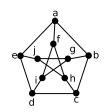


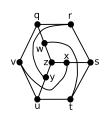
 $f = \{(a,d),(b,e),(c,b),(d,c),(e,a)\}$ 

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# Isomorphism Example

Example (Petersen graph)





 $f = \{(a,q), (b,v), (c,u), (d,y), (e,r), (f,w), (g,x), (h,t), (i,z), (j,s)\}$ 

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### Homeomorphism

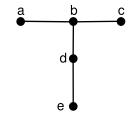
### Definition

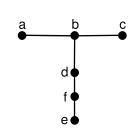
G = (V, E) and  $G^* = (V^*, E^*)$  are homeomorphic:

► G and G\* are isomorphic except that some edges in E\* are divided with additional nodes

# Homeomorphism Example

Example





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#### Walk

#### Definition

walk: a sequence of nodes and edges

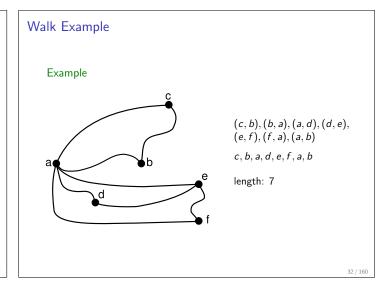
from a starting node  $(v_0)$  to an ending node  $(v_n)$ 

$$v_0, e_1, v_1, e_2, v_2, e_3, v_3, \dots, e_{n-1}, v_{n-1}, e_n, v_n$$

where  $e_i = (v_{i-1}, v_i)$ 

- ▶ no need to write the edges
- ▶ length: number of edges in the walk
- if  $v_0 \neq v_n$  open, if  $v_0 = v_n$  closed

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### Trail

#### Definition

trail: a walk where edges are not repeated

- circuit: closed trail
- ▶ spanning trail: a trail that covers all the edges in the graph

Example (c,b),(b,a),(a,e),(e,d),(d,a),(a,f) c,b,a,e,d,a,f

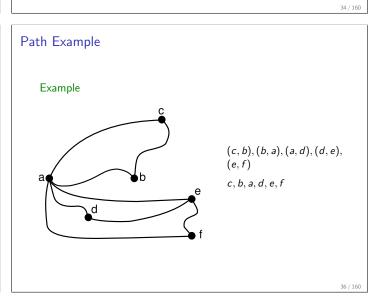
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# Path

# Definition

path: a walk where nodes are not repeated

- ► cycle: closed path
- ▶ spanning path: a path that visits all the nodes in the graph



# Connectivity

#### Definition

connected graph: there is a path between every pair of nodes

► a disconnected graph can be divided into connected components

Example

C

graph is disconnected:
no path between a and c

connected components:
a, d, e
b, c
f

Connected Components Example

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### Distance

#### Definition

the distance between nodes  $v_i$  and  $v_j$ :

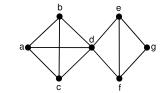
ightharpoonup the length of the shortest path between  $v_i$  and  $v_j$ 

### Definition

diameter: the largest distance in the graph

# Distance Example

#### Example



- ▶ distance between a and e: 2
- ▶ diameter: 3

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#### Cut-Point

#### Definition

#### G - v:

► the graph obtained by deleting the node *v* and all its incident edges from the graph *G* 

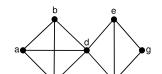
#### Definition

v is a cut-point for G:

• G is connected but G - v is disconnected

# Cut-Point Example

G





G - d



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#### **Directed Walks**

- ▶ same as in undirected graphs
- ▶ ignoring the directions on the arcs: semi-walk, semi-trail, semi-path

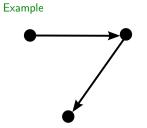
Weakly Connected Graph

Definition
weakly connected:
there is a semi-path
between every pair of nodes

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# Unilaterally Connected Graph

Definition unilaterally connected: for every pair of nodes, there is a path from one to the other

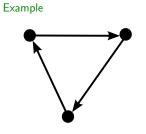


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# Strongly Connected Graph

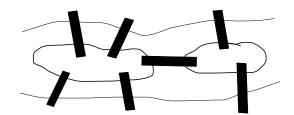
#### Definition

strongly connected: there is a path in both directions between every pair of nodes



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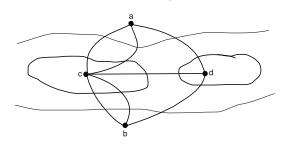
# Bridges of Königsberg



cross each bridge exactly once and return to the starting point Traversable Graphs

Definition

G is traversable: G contains a spanning trail

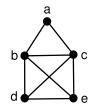


### Traversable Graphs

- ▶ a node with an odd degree must be either the starting node or the ending node of the trail
- ▶ all nodes except the starting node and the ending node must have even degrees

# Traversable Graph Example

#### Example



- ▶ degrees of *a*, *b* and *c* are even
- ightharpoonup degrees of d and e are odd
- ▶ a spanning trail can be formed starting from node d and ending at node e (or vice versa): d, b, a, c, e, d, c, b, e

#### Definition

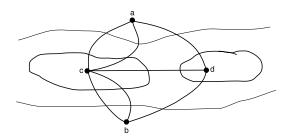
**Euler Graphs** 

Euler graph: a graph that contains a closed spanning trail

ightharpoonup G is an Euler graph  $\Leftrightarrow$  the degrees of all nodes in G are even

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# Bridges of Königsberg

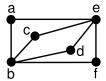


▶ all node have odd degrees: not traversable

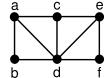
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# Euler Graph Examples

### Example (Euler graph)



#### Example (not an Euler graph)



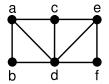
# Hamilton Graphs

### Definition

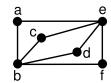
Hamilton graph: a graph that contains a closed spanning path

# Hamilton Graph Examples

### Example (Hamilton graph)



Example (not a Hamilton graph)



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# Connectivity Matrix

- ▶ if the adjacency matrix of the graph is A, the (i,j) element of A<sup>k</sup> shows the number of walks of length k between the nodes i and j
- ightharpoonup in an undirected graph with n nodes, the distance between two nodes is at most n-1
- connectivity matrix:  $C = A^1 + A^2 + A^3 + \dots + A^{n-1}$ 
  - $\,\blacktriangleright\,$  if all elements are non-zero, then the graph is connected

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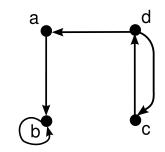
# Warshall's Algorithm

- ▶ it is easier to find whether there is a walk between two nodes instead of finding the number of walks
- ▶ for each node:
  - ► from all nodes which can reach the chosen node (the rows that contain 1 in the chosen column)
  - ▶ to the nodes which can be reached from the chosen node (the columns that contain 1 in the chosen row)

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# Warshall's Algorithm Example

#### Example

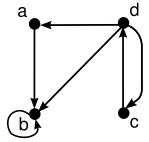


	а	Ь	с	d
а	0	1	0	0
b	0	1	0	0
С	0	0	0	1
d	1	0	0 0 0 1	0

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# Warshall's Algorithm Example

#### Example

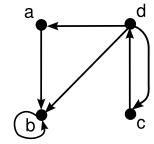


	а	Ь	с	d
а	0	1	0	0
Ь	0	1	0	0
С	0	0	0	1
d	1	1	1	0

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# Warshall's Algorithm Example

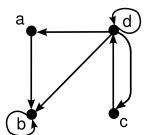
### ${\sf Example}$



	а	Ь	с	d
а		1 1 0	0	0
a b c d	0	1	0	0
С	0	0	0	1
d	1	1	1	0

# Warshall's Algorithm Example

#### Example

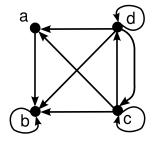


	a	Ь	с	d
а	0	1	0	0
Ь	0	1 0	0	0
С	0	0	0	1
d	1	1	1	1

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# Warshall's Algorithm Example

#### Example



	a	b		d
а	0	1	0	0
a b c	0 0 1	1 1 1	0	0
c	1	1	1	1
А	1	1	1	1

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# Planar Graphs

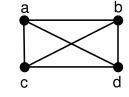
#### Definition

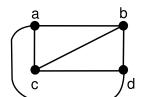
A graph is planar if it can be drawn on a plane without intersecting its edges.

ightharpoonup a map of G: a planar drawing of G

# Planar Graph Example

### Example $(K_4)$





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# Regions

- ▶ a map divides the plane into regions
- the degree of a region: the length of the closed trail that surrounds the region

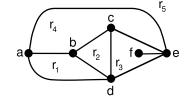
#### Theorem

let  $d_{r_i}$  be the degree of region  $r_i$ 

$$|E| = \frac{\sum_i d_{r_i}}{2}$$

# Region Example

### Example



 $d_{r_1} = 3 ext{ (abda)}$   $d_{r_2} = 3 ext{ (bcdb)}$   $d_{r_3} = 5 ext{ (cdefec)}$   $d_{r_4} = 4 ext{ (abcea)}$  $d_{r_5} = 3 ext{ (adea)}$ 

 $\sum_{r} d_r = 18$ |E| = 9

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#### Euler's Formula

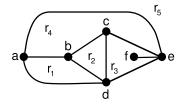
#### Theorem (Euler's Formula)

Let G = (V, E) be a planar, connected graph and let R be the set of regions in a map of G:

$$|V| - |E| + |R| = 2$$

#### Euler's Formula Example

#### Example



$$|V| = 6$$
,  $|E| = 9$ ,  $|R| = 5$ 

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### Planar Graph Theorems

#### Theorem

Let G = (V, E) be a connected, planar graph where  $|V| \geq 3$ :  $|E| \leq 3|V| - 6$ 

#### Proof

- ▶ the sum of region degrees: 2|E|
- ▶ degree of a region is at least 3 ⇒  $2|E| \ge 3|R| \Rightarrow |R| \le \frac{2}{3}|E|$
- ► |V| |E| + |R| = 2⇒  $|V| - |E| + \frac{2}{3}|E| \ge 2$  ⇒  $|V| - \frac{1}{3}|E| \ge 2$ ⇒  $3|V| - |E| \ge 6$  ⇒  $|E| \le 3|V| - 6$

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### Planar Graph Theorems

#### Theorem

Let G = (V, E) be a connected, planar graph where  $|V| \ge 3$ :  $\exists v \in V \ d_v \le 5$ 

#### Proof.

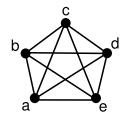
► let  $\forall v \in V \ d_v \ge 6$ ⇒  $2|E| \ge 6|V|$ ⇒  $|E| \ge 3|V|$ ⇒ |E| > 3|V| - 6

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### Nonplanar Graphs

# Theorem

 $K_5$  is not planar.



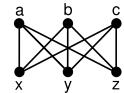
#### Proof.

- ▶ |*V*| = 5
- ▶  $3|V| 6 = 3 \cdot 5 6 = 9$
- ▶  $|E| \le 9$  should hold
- $\blacktriangleright \ \mathsf{but} \ |E| = 10$

### Nonplanar Graphs

#### Theorem

 $K_{3,3}$  is not planar.



#### Proof.

- |V| = 6, |E| = 9
- if planar then |R|=5
- ▶ degree of a region is at least 4  $\Rightarrow \sum_{r \in R} d_r \ge 20$
- ▶  $|E| \ge 10$  should hold
- ▶ but |*E*| = 9

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#### Kuratowski's Theorem

#### Theorem

 $\begin{tabular}{ll} $G$ contains a subgraph homeomorphic to $K_5$ or $K_{3,3}$. \\ &\Leftrightarrow & $G$ is not planar. \\ \end{tabular}$ 

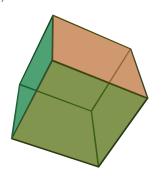
Platonic Solids

- ► regular polyhedron: a 3-dimensional solid where the faces are identical regular polygons
- the projection of a regular polyhedron onto the plane is a planar graph
  - every corner is a node
  - every side is an edge
  - every face is a region

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#### Platonic Solids

### Example (cube)



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### Platonic Solids

- ▶ v: number of corners (nodes)
- e: number of sides (edges)
- ▶ r: number of faces (regions)
- ▶ n: number of faces meeting at a corner (node degree)
- ▶ m: number of sides of a face (region degree)
- **▶** *m*, *n* ≥ 3
- $ightharpoonup 2e = n \cdot v$
- $ightharpoonup 2e = m \cdot r$

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# Platonic Solids

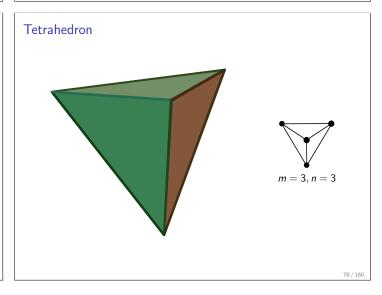
▶ from Euler's formula:

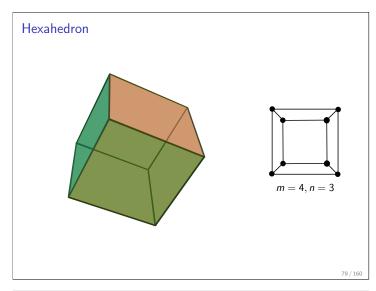
$$2 = v - e + r = \frac{2e}{n} - e + \frac{2e}{m} = e\left(\frac{2m - mn + 2n}{mn}\right) > 0$$

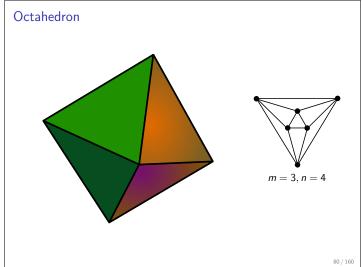
► *e*, *m*, *n* > 0:

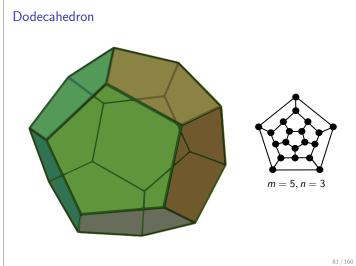
$$2m - mn + 2n > 0 \Rightarrow mn - 2m - 2n < 0$$
  
  $\Rightarrow mn - 2m - 2n + 4 < 4 \Rightarrow (m-2)(n-2) < 4$ 

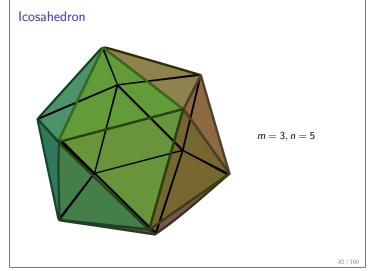
- ▶ the values that satisfy this inequation:
  - 1. m = 3, n = 3
  - 2. m = 4, n = 3
  - 3. m = 3, n = 4
  - 4. m = 5, n = 35. m = 3, n = 5











# **Graph Coloring**

#### Definition

proper coloring of G = (V, E):  $f : V \to C$  where C is a set of colors

- $\blacktriangleright \ \forall (v_i,v_j) \in E \ f(v_i) \neq f(v_j)$
- ► minimizing |*C*|

# Graph Coloring Example

### Example

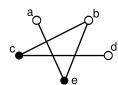
- ▶ a company produces chemical compounds
- $\,\blacktriangleright\,$  some compounds cannot be stored together
- ▶ such compounds must be placed in separate storage areas
- ▶ store the compounds using the least number of storage areas

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# **Graph Coloring**

### Example

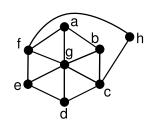
- ▶ every compound is a node
- $\,\blacktriangleright\,$  two compounds that cannot be stored together are adjacent



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# Graph Coloring Example

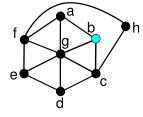
Example

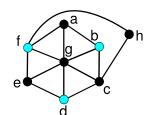


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# Graph Coloring Example

Example

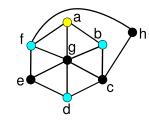


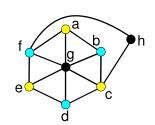


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# Graph Coloring Example

Example

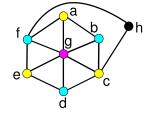


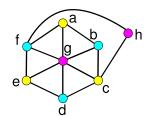


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# **Graph Coloring Example**

# Example





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### **Chromatic Number**

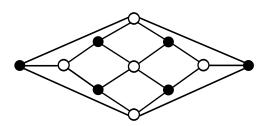
# Definition

chromatic number of G:  $\chi(G)$ 

- lacktriangle the minimum number of colors needed to color the graph  ${\sf G}$
- lacktriangle calculating  $\chi(\mathcal{G})$  is a very difficult problem
- $\chi(K_n) = n$

# Chromatic Number Example

Example (Herschel graph)



chromatic number: 2

# Graph Coloring Example

Example (Sudoku)

_	_							
15	3			1				
5 6			1	တ	5			
	თ	8					6	
8				6				3
4			8		Ω			1
7				2				6
	6					2	8	
			4	1	9			5
				8			7	9

- ▶ every cell is a node
- ► cells of the same row are adjacent
- ► cells of the same column are adjacent
- ightharpoonup cells of the same  $3 \times 3$  block are adjacent
- ▶ every number is a color
- ▶ problem: properly color a graph that is partially colored

# Region Coloring

▶ coloring a map by assigning different colors to adjacent regions

#### Theorem (Four Color Theorem)

The regions in a map can be colored using four colors.

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# Searching Graphs

- ightharpoonup searching nodes of graph G = (V, E) starting from node  $v_1$
- depth-first
- ▶ breadth-first

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### Depth-First Search

- 1.  $v \leftarrow v_1, T = \emptyset, D = \{v_1\}$
- 2. find smallest i in  $2 \le i \le |V|$  such that  $(v, v_i) \in E$  and  $v_i \notin D$ 

  - ▶ if no such i exists: go to step 3 ▶ if found:  $T = T \cup \{(v, v_i)\}, D = D \cup \{v_i\}, v \leftarrow v_i$ , go to step 2
- 3. if  $v = v_1$  then the result is T
- 4. if  $v \neq v_1$  then  $v \leftarrow parent(v)$ , go to step 2

Breadth-First Search

- 1.  $T = \emptyset$ ,  $D = \{v_1\}$ ,  $Q = (v_1)$
- 2. if Q is empty: the result is T
- 3. if Q not empty:  $v \leftarrow front(Q)$ ,  $Q \leftarrow Q v$ for  $2 \le i \le |V|$  check the edges  $(v, v_i) \in E$ :
  - if  $v_i \notin D : Q = Q + v_i$ ,  $T = T \cup \{(v, v_i)\}, D = D \cup \{v_i\}$
  - ▶ go to step 3

#### References

#### Required Reading: Grimaldi

- ► Chapter 11: An Introduction to Graph Theory
- ▶ Chapter 7: Relations: The Second Time Around
  - ► 7.2. Computer Recognition: Zero-One Matrices and Directed Graphs

Definition

Tree

tree: a connected graph that contains no cycle

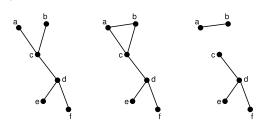
▶ forest: a graph where the connected components are trees

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### Tree Examples

#### Example



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# Tree Theorems

#### Theorem

In a tree, there is one and only one path between any two distinct nodes.

- ▶ there is at least one path because the tree is connected
- ▶ if there were more than one path, they would form a cycle



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#### Tree Theorems

#### Theorem

Let T = (V, E) be a tree:

$$|E| = |V| - 1$$

 $\,\blacktriangleright\,$  proof method: induction on the number of edges

#### Tree Theorems

#### Proof: base step

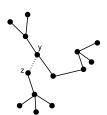
- $\blacktriangleright |E| = 0 \Rightarrow |V| = 1$
- $|E|=1 \Rightarrow |V|=2$
- $ightharpoonup |E| = 2 \Rightarrow |V| = 3$
- lacksquare assume that |E|=|V|-1 for  $|E|\leq k$

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#### Tree Theorems

#### Proof: induction step.

▶ |E| = k + 1



let's remove the edge (y, z):  $T_1 = (V_1, E_1), T_2 = (V_2, E_2)$ 

$$|V| = |V_1| + |V_2|$$

$$= |E_1| + 1 + |E_2| + 1$$

$$= (|E_1| + |E_2| + 1) + 1$$

$$= |E| + 1$$

#### Tree Theorems

#### Theorem

In a tree, there are at least two nodes with degree 1.

- $ightharpoonup 2|E| = \sum_{v \in V} d_v$
- ▶ assume that there is only 1 node with degree 1:

$$\Rightarrow 2|E| \geq 2(|V|-1)+1$$

$$\Rightarrow 2|E| \geq 2|V| - 1$$

$$\Rightarrow |E| \ge |V| - \frac{1}{2} > |V| - 1$$

#### Tree Theorems

#### Theorem

T is a tree (T is connected and contains no cycle).

There is one and only one path between any two distinct nodes in T.

 ${\cal T}$  is connected, but if any edge is removed it will no longer be connected.

T contains no cycle, but if an edge is added between any pair of nodes one and only one cycle will be formed.

# Tree Theorems

#### Theorem

T is a tree (T is connected and contains no cycle).

T is connected and |E| = |V| - 1.

T contains no cycle and |E| = |V| - 1.

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#### Rooted Tree

- ▶ a hierarchy is defined between nodes
- ▶ hierarchy creates a natural direction on edges  $\Rightarrow$  in and out degrees
- ▶ node with in-degree 0 (top of the hierarchy): root
- ▶ nodes with out-degree 0: leaf
- ▶ nodes that are not leaves: internal node

### Node Level

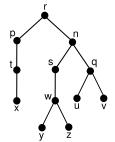
#### Definition

level of a node: the distance of the node from the root

- parent: adjacent node in the next upper level
- children: adjacent nodes in the next lower level
- ▶ sibling: nodes which have the same parent

# Rooted Tree Example

#### Example



- ▶ root: *r*
- ▶ leaves: x y z u v
- ▶ internal nodes: r p n t s q w
- ▶ parent of *y*: *w*
- children of w: y and z ▶ y and z are siblings

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#### Rooted Tree Example Example Book ► C1 Book ► S1.1 ► S1.2 Ċ2 ► S3.1 S1.1 S1.2 S3.1 S3.2 S3.3 ► S3.2 ► \$3.2.1 ► \$3.2.2 S3.2.2 S3.2.1 ► S3.3

#### Ordered Rooted Tree

- ▶ sibling nodes are ordered from left to right
- universal address system
  - ▶ assign the address 0 to the root
  - $\blacktriangleright$  assign the positive integers  $1,2,3,\ldots$  to the nodes at level 1, from left to right
  - ▶ let *v* be an internal node with address *a*, assign the addresses *a*.1, *a*.2, *a*.3, . . . to the children of *v* from left to right

# Lexicographic Order

#### Definition

Let b and c be two addresses. b comes before c if one of the following holds:

1. 
$$b = a_1 a_2 \dots a_m x_1 \dots$$
  
 $c = a_1 a_2 \dots a_m x_2 \dots$ 

 $x_1$  comes before  $x_2$ 

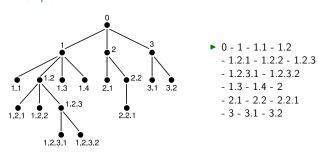
2. 
$$b = a_1 a_2 \dots a_m$$

 $c=a_1a_2\dots a_ma_{m+1}\dots$ 

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### Lexicographic Order Example

### Example



### Binary Trees

#### Definition

T = (V, E) is a binary tree:  $\forall v \in V \ d_v^{\ o} \in \{0, 1, 2\}$ 

T = (V, E) is a *complete* binary tree:  $\forall v \in V \ d_v^{\ o} \in \{0, 2\}$ 

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# Expression Tree

- lacktriangle a binary operation can be represented as a binary tree
  - operator as the root, operands as the children
- every mathematical expression can be represented as a tree
  - operators at internal nodes, variables and values at the leaves

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# Expression Tree Examples

Example (7 - a)



Example (a + b)



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# Expression Tree Examples

Example ((7 - a)/5)



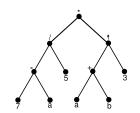
Example  $((a+b)\uparrow 3)$ 



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### Expression Tree Examples

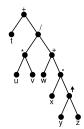
Example  $(((7 - a)/5) * ((a + b) \uparrow 3))$ 



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### Expression Tree Examples

Example  $(t + (u * v)/(w + x - y \uparrow z))$ 



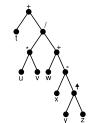
**Expression Tree Traversals** 

- 1. inorder traversal: traverse the left subtree, visit the root, traverse the right subtree
- 2. preorder traversal: visit the root, traverse the left subtree, traverse the right subtree
- 3. postorder traversal: traverse the left subtree, traverse the right subtree, visit the root
  - ► reverse Polish notation

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# Inorder Traversal Example

### Example

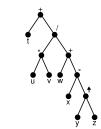


$$t + u * v / w + x - v \uparrow z$$

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# Preorder Traversal Example

#### Example

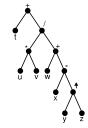


$$+t/*uv+w-x\uparrow yz$$

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# Postorder Traversal Example

#### Example



$$tuv * wxyz \uparrow - + / +$$

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# Expression Tree Evaluation

- ▶ inorder traversal requires parantheses for precedence
- preorder and postorder traversals do not require parantheses

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# Postorder Evaluation Example

Example (
$$t \ u \ v \ * \ w \ x \ y \ z \ \uparrow \ - \ + \ / \ +$$
)  
4 2 3 \* 1 9 2 3  $\uparrow \ - \ + \ / \ +$ 

$$4 \ 6 \ 1 \ 1 \ +$$

4 3

Regular Tree

Definition

$$T = (V, E)$$
 is an m-ary tree:  $\forall v \in V \ d_v^{\ o} \leq m$ 

T = (V, E) is a complete m-ary tree:  $\forall v \in V \ d_v^{\ o} \in \{0, m\}$ 

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# Regular Tree Theorem

#### Theorem

Let T = (V, E) be a complete m-ary tree.

- ▶ n: number of nodes
- ► 1: number of leaves
- ▶ i: number of internal nodes

#### Then:

- $I = n i = m \cdot i + 1 i = (m 1) \cdot i + 1$

$$i = \frac{l-1}{m-1}$$

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### Regular Tree Examples

#### Example

- ► how many matches are played in a tennis tournament with 27 players?
- every player is a leaf: I = 27
- ightharpoonup every match is an internal node: m=2
- ▶ number of matches:  $i = \frac{l-1}{m-1} = \frac{27-1}{2-1} = 26$

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# Regular Tree Examples

#### Example

- ► how many extension cords with 4 outlets are required to connect 25 computers to a wall socket?
- every computer is a leaf: I = 25
- lacktriangledown every extension cord is an internal node: m=4
- ▶ number of cords:  $i = \frac{l-1}{m-1} = \frac{25-1}{4-1} = 8$

# Decision Trees

#### Example

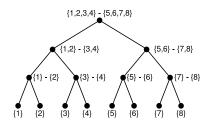
- ▶ one of 8 coins is counterfeit (it's heavier)
- ▶ find the counterfeit coin using a beam balance

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# **Decision Trees**

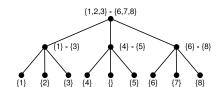
### Example (in 3 weighings)



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#### **Decision Trees**

#### Example (in 2 weighings)



#### References

#### Required Reading: Grimaldi

- ► Chapter 12: Trees
  - ▶ 12.1. Definitions and Examples
  - ▶ 12.2. Rooted Trees

# Weighted Graphs

► assign labels to edges: weight, length, cost, delay, probability, . . .

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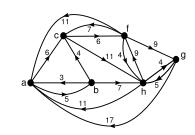
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### Shortest Path

► find the shortest paths from a node to all other nodes: Dijkstra's algorithm

# Dijkstra's Algorithm Example

Example (initialization)



▶ starting node: *c* 

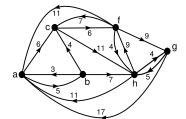
а	$(\infty, -)$
b	$(\infty, -)$
С	(0, -)
f	$(\infty, -)$
g	$(\infty, -)$
h	$(\infty, -)$

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# Dijkstra's Algorithm Example

Example (from node c - base distance=0)

- $ightharpoonup c 
  ightharpoonup f:6,6<\infty$
- $ightharpoonup c 
  ightharpoonup h: 11, 11 < \infty$



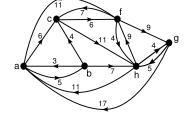
а	$\mid (\infty, -)$	
b	$(\infty, -)$	
С	(0, -)	
f	(6, cf)	
g	$(\infty, -)$	
h	(11, ch)	

▶ closest node: *f* 

Dijkstra's Algorithm Example

Example (from node f - base distance=6)

- ▶  $f \to a : 6 + 11, 17 < \infty$
- $\blacktriangleright \ f \to g: 6+9, 15 < \infty$
- ▶  $f \rightarrow h: 6+4, 10 < 11$



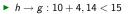
а	(17, cfa)	
b	$(\infty, -)$	
С	(0, -)	
f	(6, cf)	
g	(15, cfg)	
h	(10, cfh)	

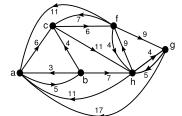
► closest node: h

# Dijkstra's Algorithm Example

Example (from node h - base distance=10)

 $\blacktriangleright \ h \rightarrow a: 10+11, 21 \not< 17$ 





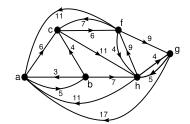
а	(17, cfa)	
b	$(\infty, -)$	
С	(0, -)	$\sqrt{}$
f	(6, cf)	$\sqrt{}$
g	(14, cfhg)	
h	(10, cfh)	

▶ closest node: g

# Dijkstra's Algorithm Example

Example (from node g - base distance=14)

▶ 
$$g \rightarrow a: 14 + 17, 31 \nleq 17$$

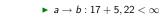


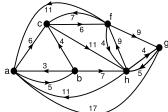
а	(17, cfa)	
b	$(\infty, -)$	
С	(0, -)	
f	(6, cf)	
g	(14, cfhg)	
h	(10, cfh)	

closest node: a

# Dijkstra's Algorithm Example

Example (from node a - base distance=17)





а	(17, cfa)	
b	(22, cfab)	
С	(0, -)	
f	(6, cf)	
g	(14, cfhg)	
h	(10, cfh)	

▶ last node: b

### Spanning Tree

#### Definition

#### spanning tree:

a subgraph which is a tree and contains all the nodes of the graph

### minimum spanning tree:

a spanning tree for which the total weight of edges is minimal

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### Kruskal's Algorithm

### Kruskal's algorithm

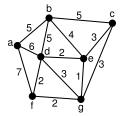
- 1.  $i \leftarrow 1$ ,  $e_1 \in E$ ,  $wt(e_1)$  is minimal
- 2. for  $1 \le i \le n 2$ :

the selected edges are  $e_1, e_2, \ldots, e_i$ select a new edge  $e_{i+1}$  from the remaining edges such that:

- $wt(e_{i+1})$  is minimal
- $lackbox{ } e_1,e_2,\ldots,e_i,e_{i+1}$  contains no cycle
- 3.  $i \leftarrow i + 1$ 
  - $lackbox{ }i=n-1\Rightarrow$  the subgraph  $\emph{G}$  containing the edges  $e_1, e_2, \dots, e_{n-1}$  is a minimum spanning tree  $i < n-1 \Rightarrow$  go to step 2

Kruskal's Algorithm Example

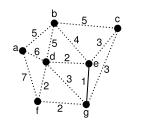
Example (initialization)



- minimum weight: 1 (e,g)
- ▶  $T = \{(e,g)\}$

# Kruskal's Algorithm Example

### Example (1 < 6)

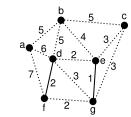


- ▶ minimum weight: 2
- (d, e), (d, f), (f, g) $T = \{(e, g), (d, f)\}$
- i ← '

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# Kruskal's Algorithm Example

### Example (2 < 6)

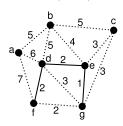


- ▶ minimum weight: 2
  - (d,e),(f,g)
- ►  $T = \{(e,g), (d,f), (d,e)\}$
- $i \leftarrow 3$

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# Kruskal's Algorithm Example

### Example (3 < 6)

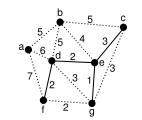


- ▶ minimum weight: 2 (f,g) forms a cycle
- (f,g) forms a cycle▶ minimum weight: 3
- (c,e),(c,g),(d,g)(d,g) forms a cycle
- ►  $T = \{(e,g), (d,f), (d,e), (c,e)\}$
- i ← i

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# Kruskal's Algorithm Example

### Example (4 < 6)

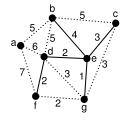


- $I = \{ (e,g), (d,f), (d,e), \}$
- (c,e),(b,e)
- · *i* ← 5

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# Kruskal's Algorithm Example

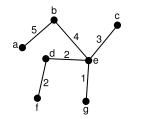
# Example (5 < 6)



- $T = \{ (e,g), (d,f), (d,e), (c,e), (b,e), (a,b) \}$
- i ← 6

Kruskal's Algorithm Example

# Example $(6 \nless 6)$



▶ total weight: 17

# Prim's Algorithm

#### Prim's algorithm

1.  $i \leftarrow 1, v_1 \in V, P = \{v_1\}, N = V - \{v_1\}, T = \emptyset$ 

2. for  $1 \le i \le n-1$ :  $P = \{v_1, v_2, \dots, v_i\}$ ,  $T = \{e_1, e_2, \dots, e_{i-1}\}$ , N = V - P select a node  $v_{i+1} \in N$  such that for a node  $x \in P$   $e = (x, v_{i+1}) \notin T$ , wt(e) is minimal  $P \leftarrow P + \{v_{i+1}\}$ ,  $N \leftarrow N - \{v_{i+1}\}$ ,  $T \leftarrow T + \{e\}$ 

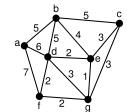
3.  $i \leftarrow i + 1$ 

 $i=n\Rightarrow$ : the subgraph G containing the edges  $e_1,e_2,\ldots,e_{n-1}$  is a minimum spanning tree

•  $i < n \Rightarrow \text{go to step } 2$ 

### Prim's Algorithm Example

#### Example (initialization)



i ← 1

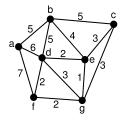
 $P = \{a\}$ 

►  $N = \{b, c, d, e, f, g\}$ 

 $T = \emptyset$ 

Prim's Algorithm Example

# Example (1 < 7)



▶  $T = \{(a, b)\}$ 

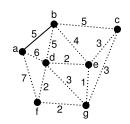
 $\triangleright$   $P = \{a, b\}$ 

 $N = \{c, d, e, f, g\}$ 

i ← 2

# Prim's Algorithm Example

### Example (2 < 7)



▶  $T = \{(a, b), (b, e)\}$ 

 $P = \{a, b, e\}$ 

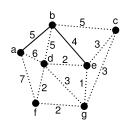
 $N = \{c, d, f, g\}$ 

i ← 3

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# Prim's Algorithm Example

# Example (3 < 7)



►  $T = \{(a, b), (b, e), (e, g)\}$ 

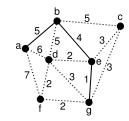
 $P = \{a, b, e, g\}$ 

 $N = \{c, d, f\}$ 

i ← 4

Prim's Algorithm Example

# Example (4 < 7)



 $T = \{(a,b), (b,e), (e,g), (d,e)\}$ 

 $P = \{a, b, e, g, d\}$ 

▶  $N = \{c, f\}$ 

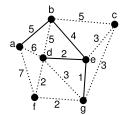
**▶** *i* ← 5

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# Prim's Algorithm Example

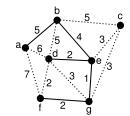
# Example (5 < 7)



- (a, b), (b, e), (e, g),(d,e),(f,g)
- $P = \{a, b, e, g, d, f\}$
- $N = \{c\}$

# Prim's Algorithm Example

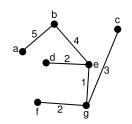
# Example (6 < 7)



- (a, b), (b, e), (e, g),(d,e),(f,g),(c,g)
- ▶  $P = \{a, b, e, g, d, f, c\}$

# Prim's Algorithm Example

# Example $(7 \nless 7)$



▶ total weight: 17

References

### Required Reading: Grimaldi

- ► Chapter 13: Optimization and Matching

  - 13.1. Dijkstra's Shortest Path Algorithm
     13.2. Minimal Spanning Trees:
     The Algorithms of Kruskal and Prim