



MODERN COMPUTER VISION

BY RAJEEV RATAN

Padding

Manipulating the input size

Padding

Notice How Conv Filters Produce an Output Smaller than the Input

1	0	1	0	1
1	0	0	1	1
0	1	1	0	0
1	0	0	1	0
0	0	1	1	0

5 x 5
 $n \times n$

*

0	1	0
1	0	-1
0	1	0

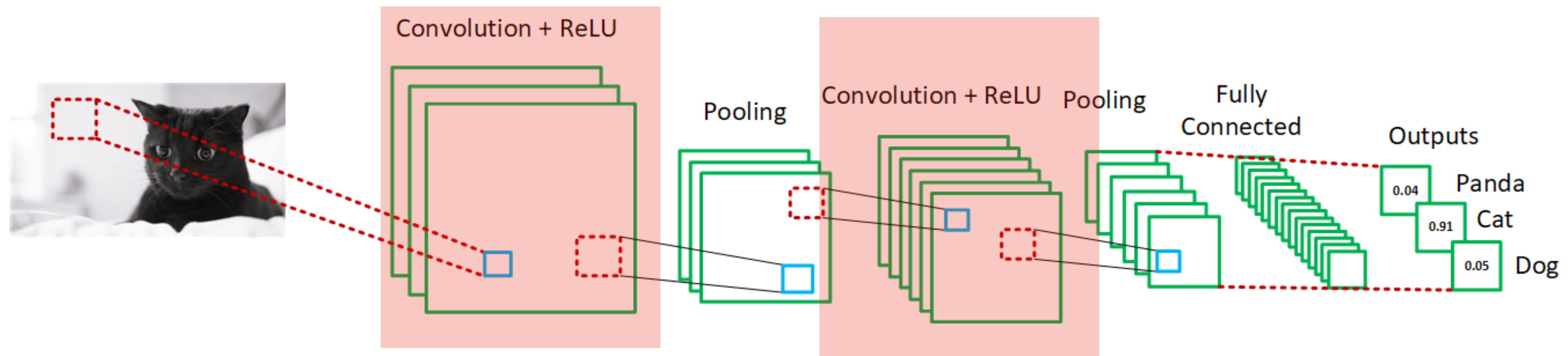
3 x 3
 $f \times f$

=

2	1	-1
-1	1	3
2	1	1

3 x 3
 $m \times m$

CNNs can have several sequences of Convolution layers



Consecutive Conv layers would keep shrinking the output

Can we preserve our image size?

We've added a 1 pixel pad of zeros (zero padding) around our input

0	0	0	0	0	0	0
0	1	0	1	0	1	0
0	1	0	0	1	1	0
0	0	1	1	0	0	0
0	1	0	0	1	0	0
0	0	0	1	1	0	0
0	0	0	0	0	0	0

*

0	1	0
1	0	-1
0	1	0

=

7×7

$n \times n$

3×3

$f \times f$

Padding

Let's Perform our Convolution with the Padding

0	0	0	0	0	0	0
0	1	0	1	0	1	0
0	1	0	0	1	1	0
0	0	1	1	0	0	0
0	1	0	0	1	0	0
0	0	0	1	1	0	0
0	0	0	0	0	0	0

7×7
 $n \times n$

*

0	1	0
1	0	-1
0	1	0

3×3
 $f \times f$

=

Padding

Let's Perform our Convolution with the Padding

0	0	0	0	0	0	0
0	1	0	1	0	1	0
0	1	0	0	1	1	0
0	0	1	1	0	0	0
0	1	0	0	1	0	0
0	0	0	1	1	0	0
0	0	0	0	0	0	0

7×7
 $n \times n$

*

0	1	0
1	0	-1
0	1	0

3×3
 $f \times f$

=

Padding

Let's Perform our Convolution with the Padding

0	0	0	0	0	0	0
0	1	0	1	0	1	0
0	1	0	0	1	1	0
0	0	1	1	0	0	0
0	1	0	0	1	0	0
0	0	0	1	1	0	0
0	0	0	0	0	0	0

7×7
 $n \times n$

*

0	1	0
1	0	-1
0	1	0

3×3
 $f \times f$

=

Padding

Let's Perform our Convolution with the Padding

0	0	0	0	0	0	0
0	1	0	1	0	1	0
0	1	0	0	1	1	0
0	0	1	1	0	0	0
0	1	0	0	1	0	0
0	0	0	1	1	0	0
0	0	0	0	0	0	0

7×7
 $n \times n$

*

0	1	0
1	0	-1
0	1	0

3×3
 $f \times f$

=

Padding

Let's Perform our Convolution with the Padding

0	0	0	0	0	0	0
0	1	0	1	0	1	0
0	1	0	0	1	1	0
0	0	1	1	0	0	0
0	1	0	0	1	0	0
0	0	0	1	1	0	0
0	0	0	0	0	0	0

7×7
 $n \times n$

*

0	1	0
1	0	-1
0	1	0

3×3
 $f \times f$

=

Padding

Let's Perform our Convolution with the Padding

0	0	0	0	0	0	0
0	1	0	1	0	1	0
0	1	0	0	1	1	0
0	0	1	1	0	0	0
0	1	0	0	1	0	0
0	0	0	1	1	0	0
0	0	0	0	0	0	0

7×7
 $n \times n$

*

0	1	0
1	0	-1
0	1	0

3×3
 $f \times f$

=

Padding

Let's Perform our Convolution with the Padding

$$\text{Feature Map Size} = n - f + 1 = m$$

$$\text{Feature Map Size} = 7 - 3 + 1 = 5$$

0	0	0	0	0	0	0
0	1	0	1	0	1	0
0	1	0	0	1	1	0
0	0	1	1	0	0	0
0	1	0	0	1	0	0
0	0	0	1	1	0	0
0	0	0	0	0	0	0

$$7 \times 7$$
$$n \times n$$

*

0	1	0
1	0	-1
0	1	0

$$3 \times 3$$
$$f \times f$$

=

2	1	-1	2	2
-1	1	3	2	1
2	1	1	1	2
1	1	1	0	2
2	0	2	3	1

$$5 \times 5$$
$$m \times m$$

Why Use Padding?

- For very deep networks we don't want to keep reducing the size
- Pixels at the edges contribute less to the output Feature Maps, thus we're throwing away information from them

1	0	1	0	1
1	0	0	1	1
0	1	1	0	0
1	0	0	1	0
0	0	1	1	0

Without padding, our **top left** pixel is only touched by the Conv Filter once

Whereas, our **centre** pixel is passed over numerous times



MODERN COMPUTER VISION

BY RAJEEV RATAN

Next...

Stride