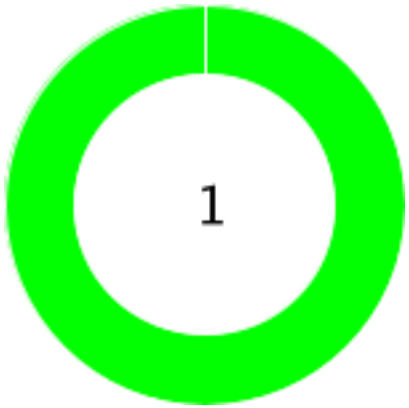
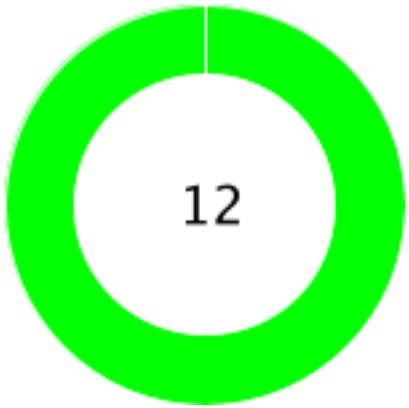
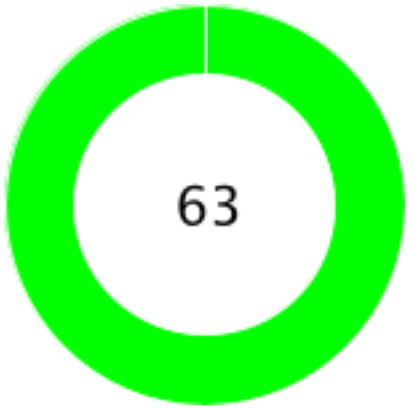
Cucumber Report

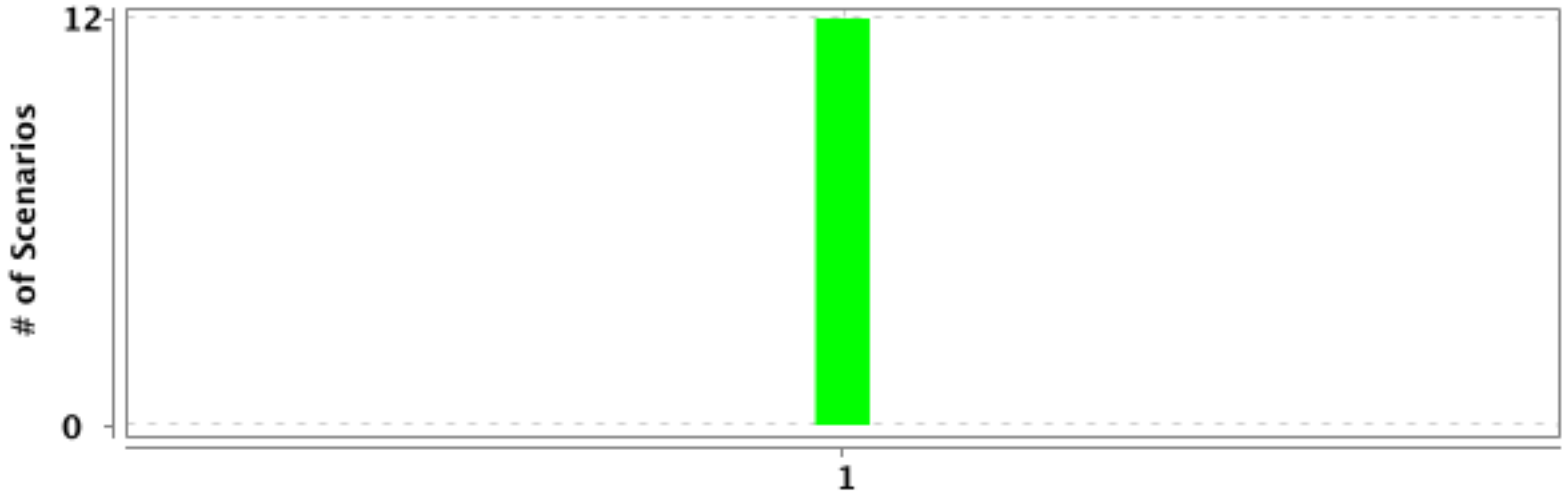
18 Jan 2022, 11:03:25

Start : Jan 18, 11:03:24.866 am	End : Jan 18, 11:03:24.989 am	Duration : 0.123 s
Features	Scenarios	Steps
PASSED - 1 FAILED - 0 SKIPPED - 0	PASSED - 12 FAILED - 0 SKIPPED - 0	PASSED - 63 FAILED - 0 SKIPPED - 0

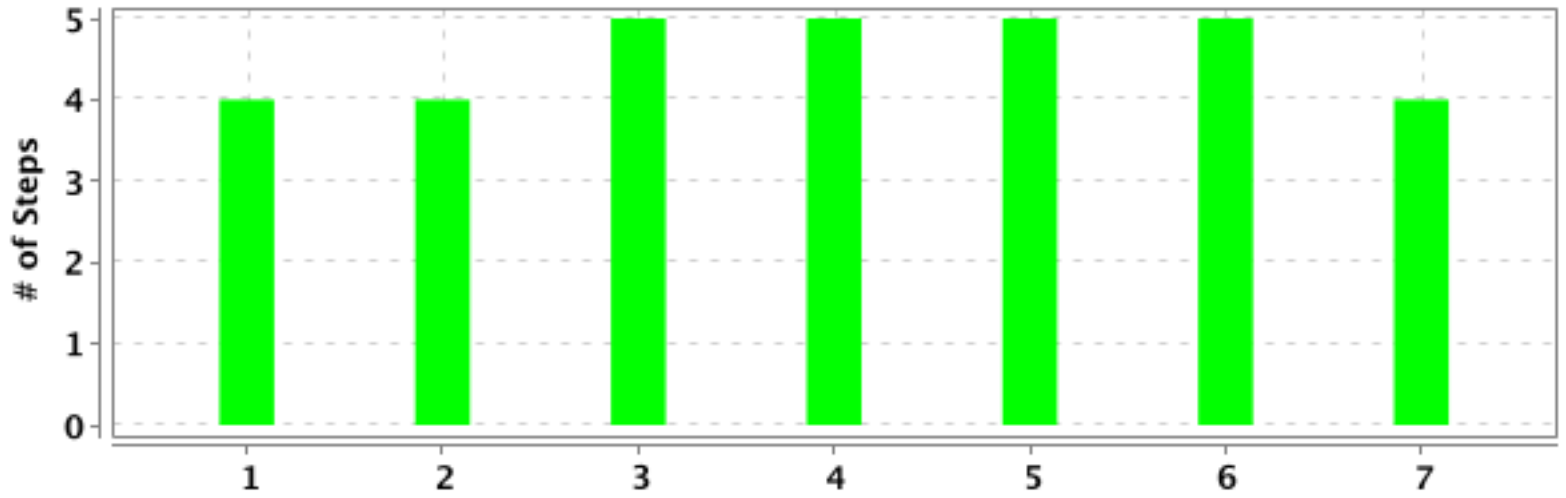




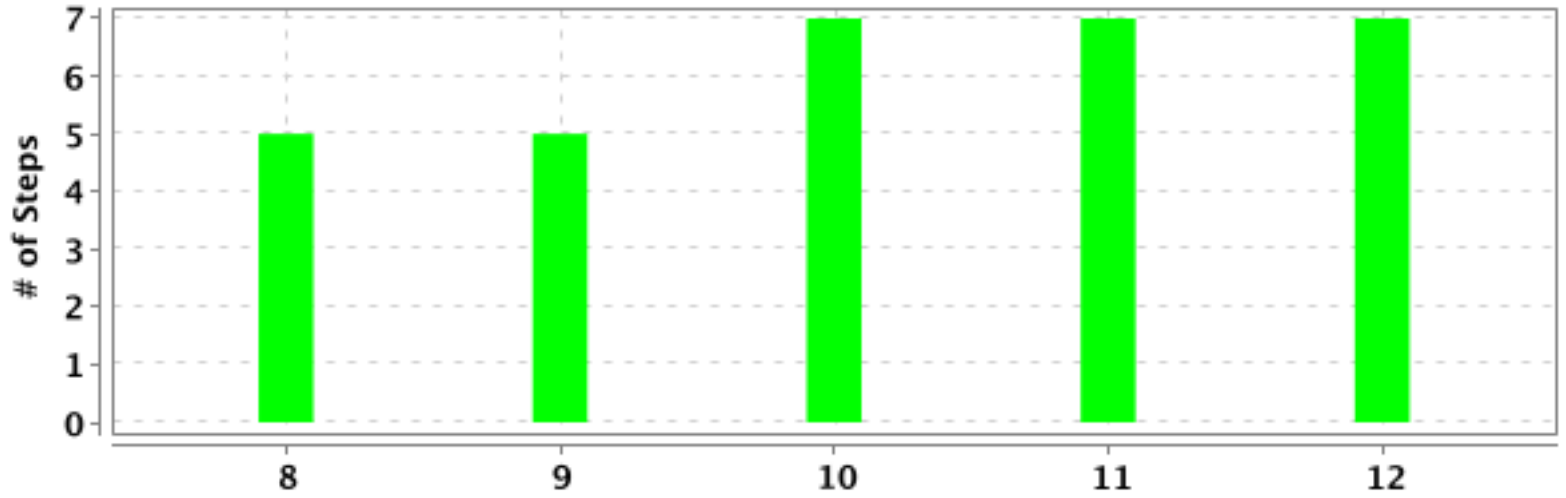




#	Feature Name	T	P	F	S	Duration
1	Navigation of the robotic rover to the left right forward and back directions	12	12	0	0	0.123 s



#	Feature Name	Scenario Name	T	P	F	S	Duration
1	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn left	4	4	0	0	0.030 s
2	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn right	4	4	0	0	0.005 s
3	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to move forward	5	5	0	0	0.007 s
4	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to move back	5	5	0	0	0.004 s
5	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn back over the right hand side	5	5	0	0	0.004 s
6	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn back over the left hand side	5	5	0	0	0.003 s
7	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to navigate to a given location	4	4	0	0	0.002 s

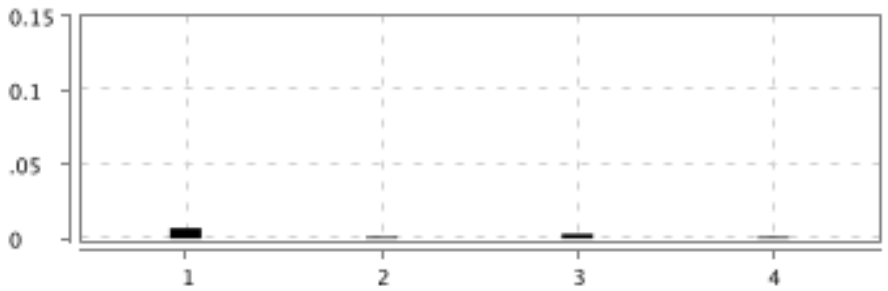


#	Feature Name	Scenario Name	T	P	F	S	Duration
8	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to process a multiple navigation command sequentially	5	5	0	0	0.004 s
9	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to process a multiple navigation command sequentially	5	5	0	0	0.003 s
10	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to process a series of single navigation commands sequentially	7	7	0	0	0.004 s
11	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to process a series of single navigation commands sequentially	7	7	0	0	0.003 s
12	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to process a series of single navigation commands sequentially	7	7	0	0	0.003 s

(F)- Navigation of the robotic rover to the left right forward and back directions

PASSED	DURATION - 0.123 s	Scenarios		Steps	
/ 11:03:24.866 am // 11:03:24.989 am /		Total - 12 Pass - 12 Fail - 0 Skip - 0		Total - 63 Pass - 63 Fail - 0 Skip - 0	

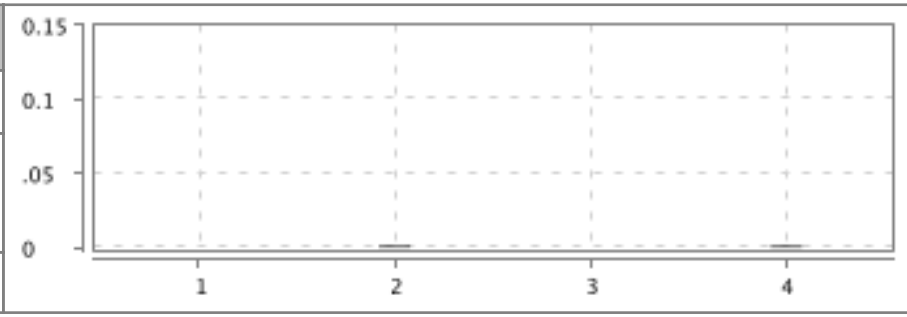
(S)- The rover should be able to turn left

PASSED	DURATION - 0.030 s		Steps	
/ 11:03:24.868 am // 11:03:24.898 am /			Total - 4 Pass - 4 Fail - 0 Skip - 0	
Navigation of the robotic rover to the left right forward and back directions				
@Smoke				

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.007 s
2	When the operator sends a single command of turn left	PASSED	0.001 s
3	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.003 s
4	And the rover is facing towards west	PASSED	0.001 s

(S)- The rover should be able to turn right

PASSED	DURATION - 0.005 s
/ 11:03:24.906 am // 11:03:24.911 am /	
Navigation of the robotic rover to the left right forward and back directions	
@Smoke	

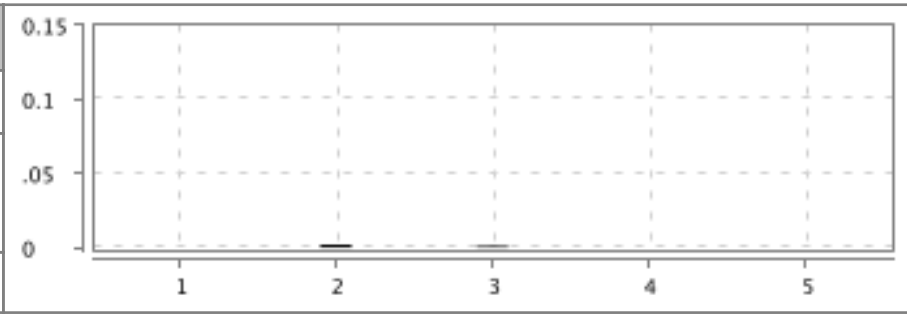


Steps
Total - 4
Pass - 4
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX | axisY | facing 0 | 0 | 1	PASSED	0.000 s
2	When the operator sends a single command of turn right	PASSED	0.001 s
3	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.000 s
4	And the rover is facing towards east	PASSED	0.001 s

(S)- The rover should be able to move forward

PASSED	DURATION - 0.007 s
/ 11:03:24.916 am // 11:03:24.923 am /	
Navigation of the robotic rover to the left right forward and back directions	
@Smoke	



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX | axisY | facing 0 | 0 | 1	PASSED	0.000 s
2	When the operator sends a single command of move 3 units forward	PASSED	0.002 s
3	Then the rover is not positioning at its initial coordinates	PASSED	0.001 s
4	And the rover is settled at coordinates x = 0 and y = 3	PASSED	0.000 s

#	Step / Hook Details	Status	Duration
5	And the rover is facing towards north	PASSED	0.000 s

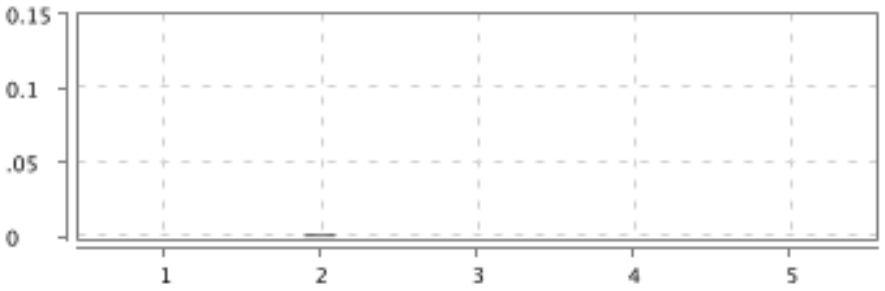
(S)- The rover should be able to move back

PASSED *DURATION - 0.004 s*

/ 11:03:24.928 am // 11:03:24.932 am /

Navigation of the robotic rover to the left right forward and back directions

@Smoke



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.000 s
2	When the operator sends a single command of move 5 units back	PASSED	0.001 s
3	Then the rover is not positioning at its initial coordinates	PASSED	0.000 s
4	And the rover is settled at coordinates x = 0 and y = -5	PASSED	0.000 s
5	And the rover is facing towards south	PASSED	0.000 s

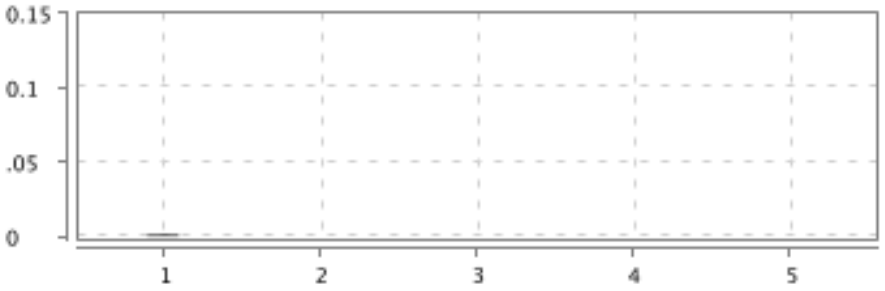
(S)- The rover should be able to turn back over the right hand side

PASSED *DURATION - 0.004 s*

/ 11:03:24.935 am // 11:03:24.939 am /

Navigation of the robotic rover to the left right forward and back directions

@Smoke



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s

#	Step / Hook Details	Status	Duration
2	When the operator sends a single command of turn right	PASSED	0.000 s
3	And the operator sends a single command of turn right	PASSED	0.000 s
4	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.000 s
5	And the rover is facing towards south	PASSED	0.000 s

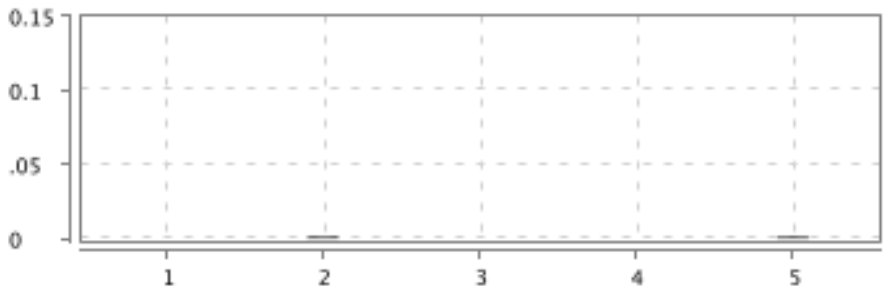
(S)- The rover should be able to turn back over the left hand side

PASSED DURATION - 0.003 s

/ 11:03:24.942 am // 11:03:24.945 am /

Navigation of the robotic rover to the left right forward and back directions

@Smoke



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.000 s
2	When the operator sends a single command of turn left	PASSED	0.001 s
3	And the operator sends a single command of turn left	PASSED	0.000 s
4	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.000 s
5	And the rover is facing towards south	PASSED	0.001 s

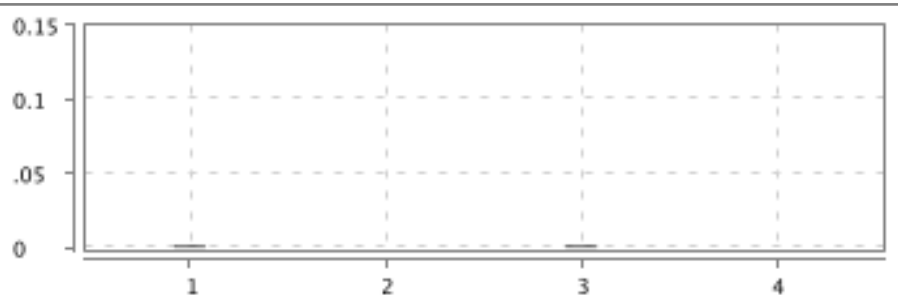
(S)- The rover should be able to navigate to a given location

PASSED DURATION - 0.002 s

/ 11:03:24.949 am // 11:03:24.951 am /

Navigation of the robotic rover to the left right forward and back directions

@Smoke



Steps
Total - 4
Pass - 4
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s
2	When the operator sends the navigation coordinates as x = -5 and y = -3 facing 1	PASSED	0.000 s
3	Then the rover is settled at coordinates x = -5 and y = -3	PASSED	0.001 s
4	And the rover is facing towards north	PASSED	0.000 s

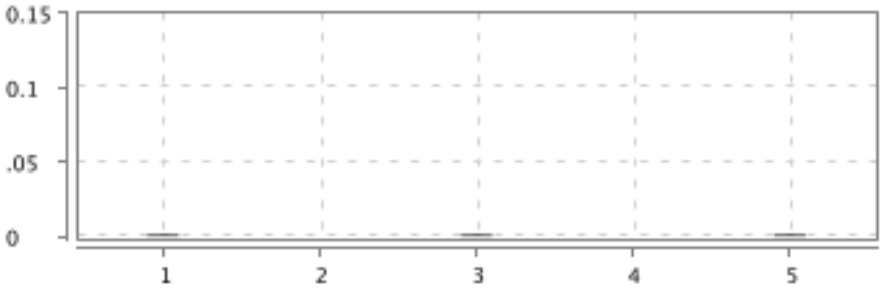
(S)- The rover should be able to process a multiple navigation command sequentially

PASSED *DURATION - 0.004 s*

/ 11:03:24.957 am // 11:03:24.961 am /

Navigation of the robotic rover to the left right forward and back directions

@Regression

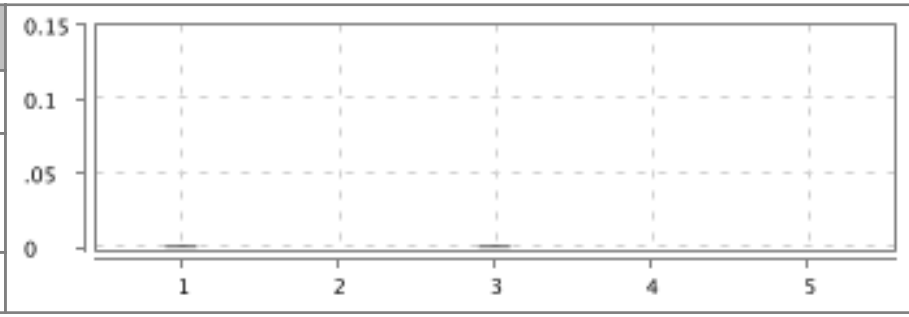


Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s
2	When the operator sends the navigation coordinates as x = 1 and y = 2 facing 1	PASSED	0.000 s
3	And the operator sends a series of navigation command as LMLMLMLMM	PASSED	0.001 s
4	Then the rover is settled at coordinates x = 1 and y = 3	PASSED	0.000 s
5	And the rover is facing towards north	PASSED	0.001 s

(S)- The rover should be able to process a multiple navigation command sequentially

PASSED	DURATION - 0.003 s
/ 11:03:24.965 am // 11:03:24.968 am /	
Navigation of the robotic rover to the left right forward and back directions	
@Regression	

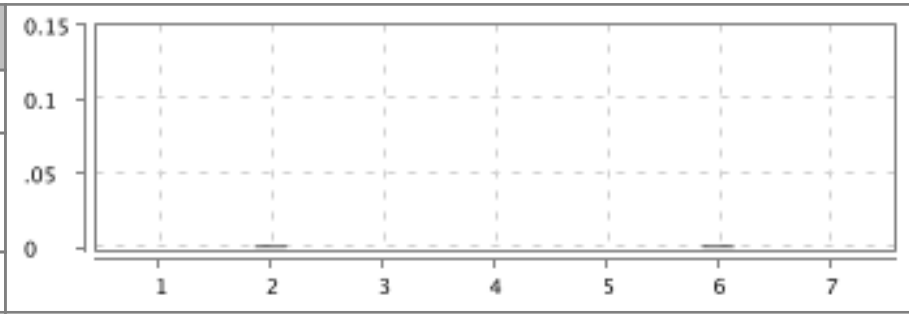


Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s
2	When the operator sends the navigation coordinates as x = 3 and y = 3 facing 2	PASSED	0.000 s
3	And the operator sends a series of navigation command as MMRMMRMRRM	PASSED	0.001 s
4	Then the rover is settled at coordinates x = 5 and y = 1	PASSED	0.000 s
5	And the rover is facing towards east	PASSED	0.000 s

(S)- The rover should be able to process a series of single navigation commands sequentially

PASSED	DURATION - 0.004 s
/ 11:03:24.971 am // 11:03:24.975 am /	
Navigation of the robotic rover to the left right forward and back directions	
@Regression	



Steps
Total - 7
Pass - 7
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.000 s
2	When the operator sends a single command of move 5 units forward	PASSED	0.001 s
3	And the operator sends a single command of move 2 units left	PASSED	0.000 s

#	Step / Hook Details	Status	Duration
4	And the operator sends a single command of turn right	PASSED	0.000 s
5	And the operator sends a single command of turn left	PASSED	0.000 s
6	Then the rover is settled at coordinates x = -2 and y = 5	PASSED	0.001 s
7	And the rover is facing towards west	PASSED	0.000 s

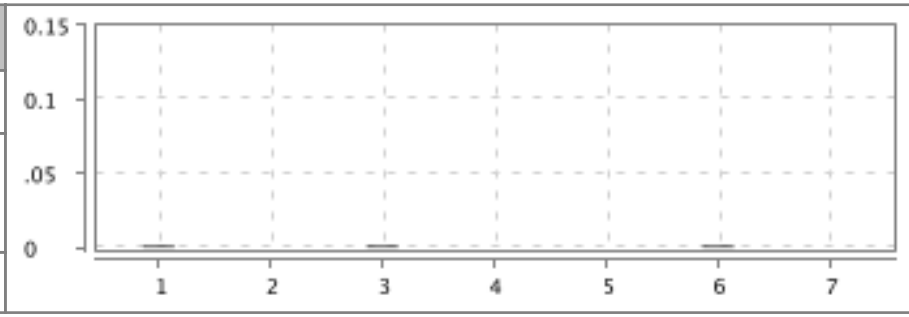
(S)- The rover should be able to process a series of single navigation commands sequentially

PASSED *DURATION - 0.003 s*

/ 11:03:24.979 am // 11:03:24.982 am /

Navigation of the robotic rover to the left right forward and back directions

@Regression



Steps

Total - 7

Pass - 7

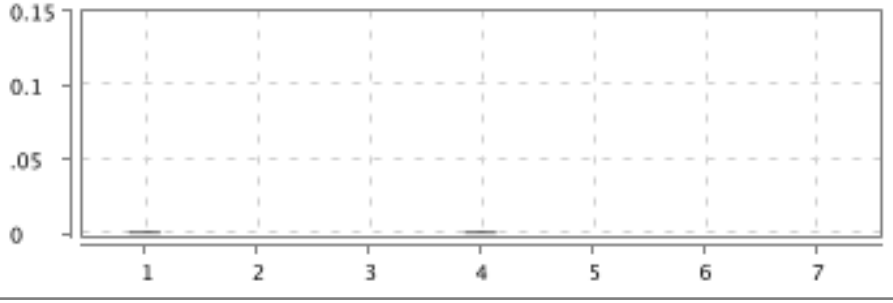
Fail - 0

Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s
2	When the operator sends a single command of move 4 units back	PASSED	0.000 s
3	And the operator sends a single command of move 6 units right	PASSED	0.001 s
4	And the operator sends a single command of turn back	PASSED	0.000 s
5	And the operator sends a single command of turn left	PASSED	0.000 s
6	Then the rover is settled at coordinates x = -6 and y = -4	PASSED	0.001 s
7	And the rover is facing towards north	PASSED	0.000 s

(S)- The rover should be able to process a series of single navigation commands sequentially

PASSED	DURATION - 0.003 s
/ 11:03:24.986 am // 11:03:24.989 am /	
Navigation of the robotic rover to the left right forward and back directions	
@Regression	



Steps
Total - 7
Pass - 7
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX | axisY | facing 0 | 0 | 1	PASSED	0.001 s
2	When the operator sends a single command of move 1 units left	PASSED	0.000 s
3	And the operator sends a single command of move 1 units back	PASSED	0.000 s
4	And the operator sends a single command of turn back	PASSED	0.001 s
5	And the operator sends a single command of turn right	PASSED	0.000 s
6	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.000 s
7	And the rover is facing towards north	PASSED	0.000 s