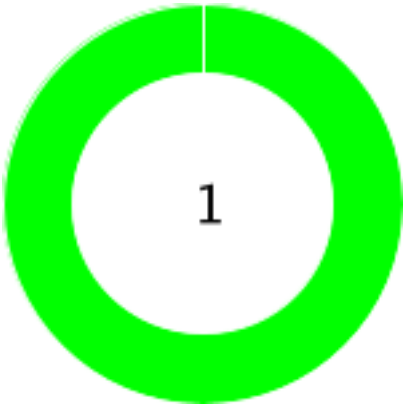
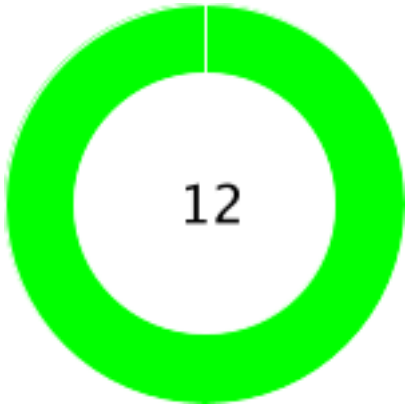
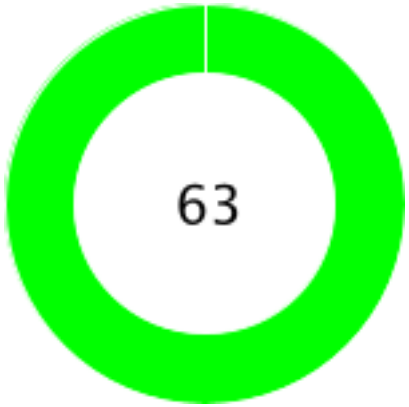
Cucumber Report

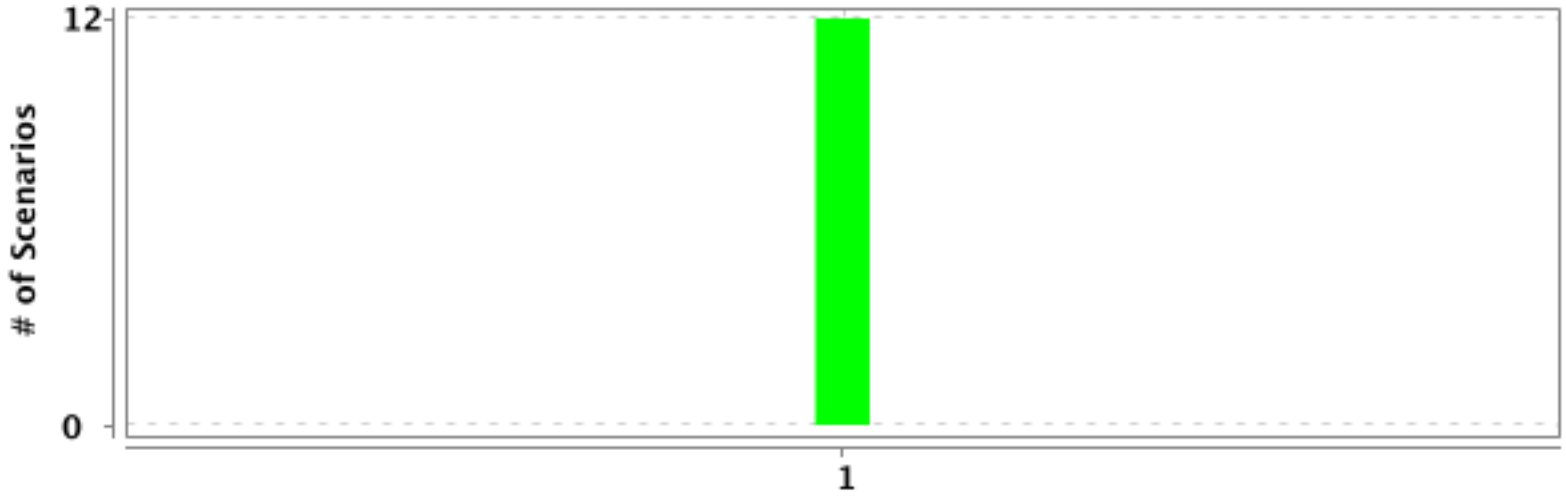
18 Jan 2022, 00:15:30

Start : Jan 18, 12:15:29.964 am	End : Jan 18, 12:15:30.083 am	Duration : 0.119 s
Features	Scenarios	Steps
PASSED - 1 FAILED - 0 SKIPPED - 0	PASSED - 12 FAILED - 0 SKIPPED - 0	PASSED - 63 FAILED - 0 SKIPPED - 0

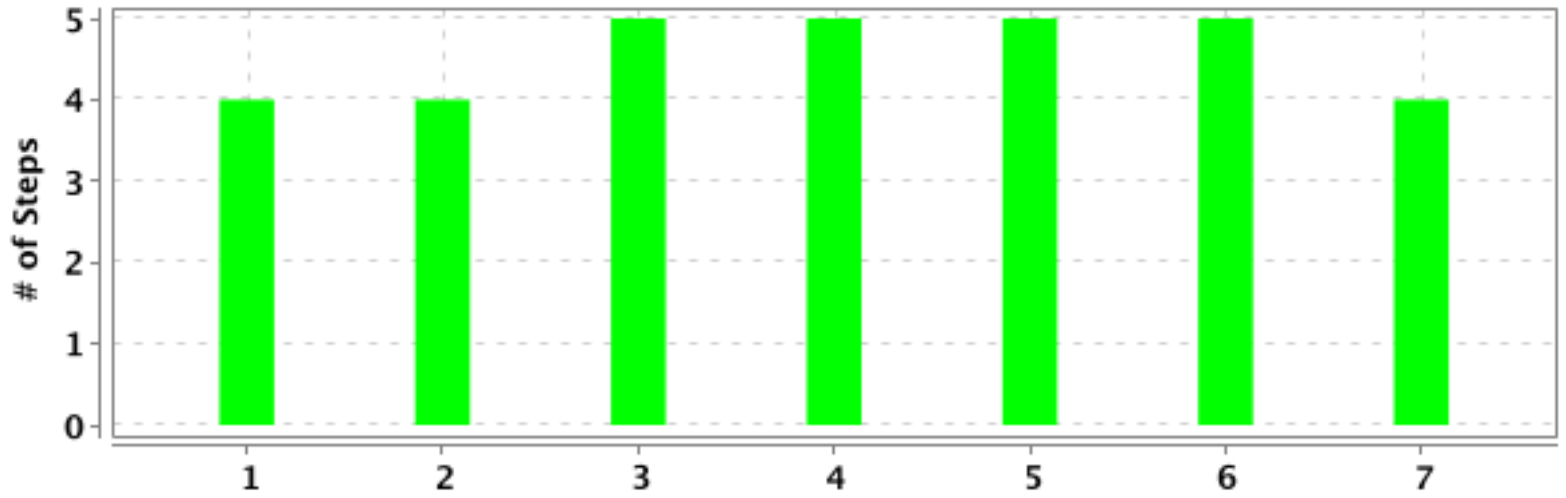




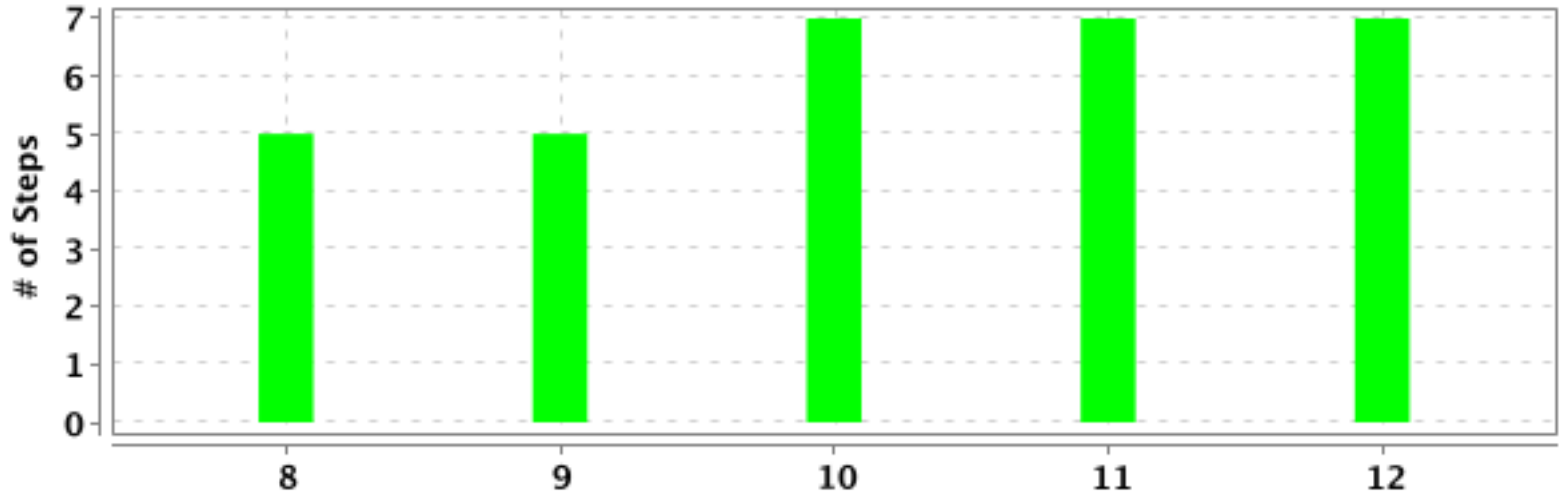




#	Feature Name	T	P	F	S	Duration
1	Navigation of the robotic rover to the left right forward and back directions	12	12	0	0	0.119 s



#	Feature Name	Scenario Name	T	P	F	S	Duration
1	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn left	4	4	0	0	0.026 s
2	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn right	4	4	0	0	0.005 s
3	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to move forward	5	5	0	0	0.009 s
4	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to move back	5	5	0	0	0.003 s
5	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn back over the right hand side	5	5	0	0	0.003 s
6	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn back over the left hand side	5	5	0	0	0.003 s
7	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to navigate to a given location	4	4	0	0	0.003 s

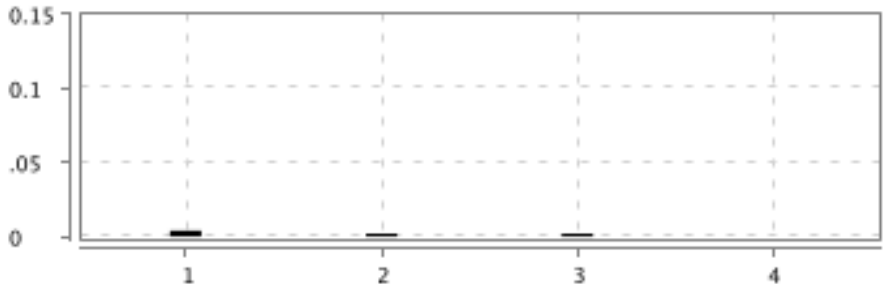


#	Feature Name	Scenario Name	T	P	F	S	Duration
8	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to process a multiple navigation command sequentially	5	5	0	0	0.004 s
9	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to process a multiple navigation command sequentially	5	5	0	0	0.003 s
10	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to process a series of single navigation commands sequentially	7	7	0	0	0.004 s
11	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to process a series of single navigation commands sequentially	7	7	0	0	0.003 s
12	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to process a series of single navigation commands sequentially	7	7	0	0	0.002 s

(F)- Navigation of the robotic rover to the left right forward and back directions

PASSED	DURATION - 0.119 s	Scenarios		Steps	
/ 12:15:29.964 am // 12:15:30.083 am /		Total - 12 Pass - 12 Fail - 0 Skip - 0		Total - 63 Pass - 63 Fail - 0 Skip - 0	

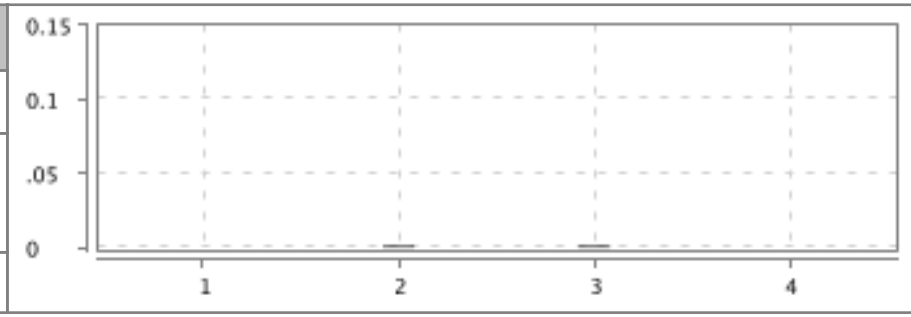
(S)- The rover should be able to turn left

PASSED	DURATION - 0.026 s		Steps	
/ 12:15:29.966 am // 12:15:29.992 am /			Total - 4 Pass - 4 Fail - 0 Skip - 0	
Navigation of the robotic rover to the left right forward and back directions				

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.004 s
2	When the operator sends a single command of turn left	PASSED	0.002 s
3	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.002 s
4	And the rover is facing towards west	PASSED	0.000 s

(S)- The rover should be able to turn right

PASSED	DURATION - 0.005 s
/ 12:15:30.001 am // 12:15:30.006 am /	
Navigation of the robotic rover to the left right forward and back directions	

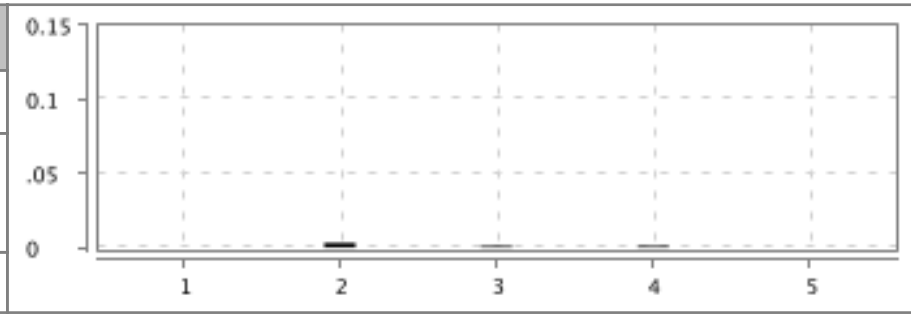


Steps
Total - 4
Pass - 4
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX | axisY | facing 0 | 0 | 1	PASSED	0.000 s
2	When the operator sends a single command of turn right	PASSED	0.001 s
3	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.001 s
4	And the rover is facing towards east	PASSED	0.000 s

(S)- The rover should be able to move forward

PASSED	DURATION - 0.009 s
/ 12:15:30.010 am // 12:15:30.019 am /	
Navigation of the robotic rover to the left right forward and back directions	



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX | axisY | facing 0 | 0 | 1	PASSED	0.000 s
2	When the operator sends a single command of move 3 units forward	PASSED	0.003 s
3	Then the rover is not positioning at its initial coordinates	PASSED	0.001 s
4	And the rover is settled at coordinates x = 0 and y = 3	PASSED	0.001 s

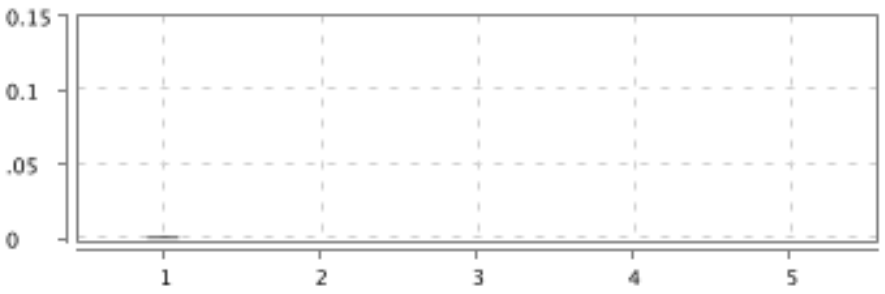
#	Step / Hook Details	Status	Duration
5	And the rover is facing towards north	PASSED	0.000 s

(S)- The rover should be able to move back

PASSED DURATION - 0.003 s

/ 12:15:30.024 am // 12:15:30.027 am /

Navigation of the robotic rover to the left right forward and back directions



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

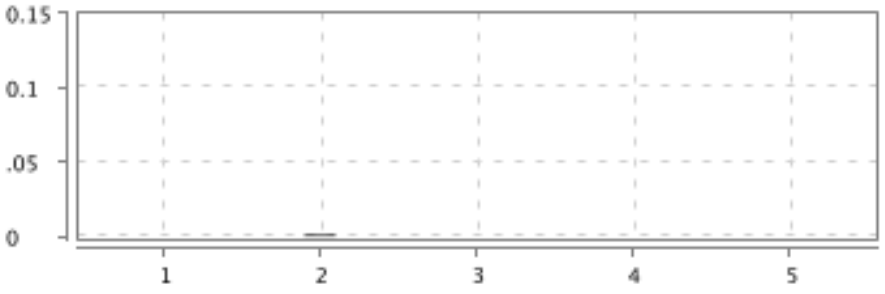
#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s
2	When the operator sends a single command of move 5 units back	PASSED	0.000 s
3	Then the rover is not positioning at its initial coordinates	PASSED	0.000 s
4	And the rover is settled at coordinates x = 0 and y = -5	PASSED	0.000 s
5	And the rover is facing towards south	PASSED	0.000 s

(S)- The rover should be able to turn back over the right hand side

PASSED DURATION - 0.003 s

/ 12:15:30.031 am // 12:15:30.034 am /

Navigation of the robotic rover to the left right forward and back directions



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.000 s

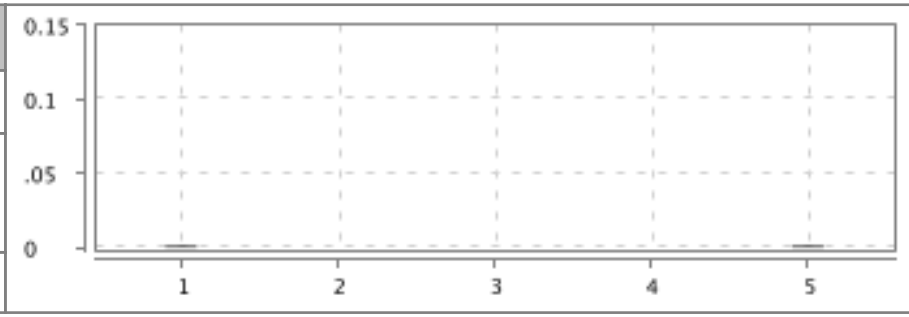
#	Step / Hook Details	Status	Duration
2	When the operator sends a single command of turn right	PASSED	0.001 s
3	And the operator sends a single command of turn right	PASSED	0.000 s
4	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.000 s
5	And the rover is facing towards south	PASSED	0.000 s

(S)- The rover should be able to turn back over the left hand side

PASSED DURATION - 0.003 s

/ 12:15:30.038 am // 12:15:30.041 am /

Navigation of the robotic rover to the left right forward and back directions



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

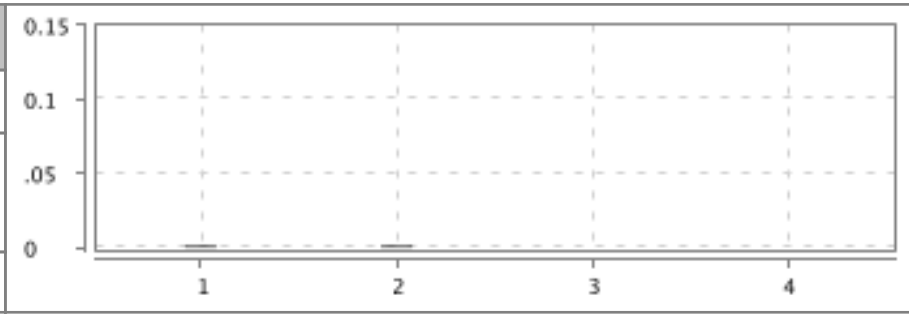
#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s
2	When the operator sends a single command of turn left	PASSED	0.000 s
3	And the operator sends a single command of turn left	PASSED	0.000 s
4	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.000 s
5	And the rover is facing towards south	PASSED	0.001 s

(S)- The rover should be able to navigate to a given location

PASSED DURATION - 0.003 s

/ 12:15:30.045 am // 12:15:30.048 am /

Navigation of the robotic rover to the left right forward and back directions



Steps
Total - 4
Pass - 4
Fail - 0
Skip - 0

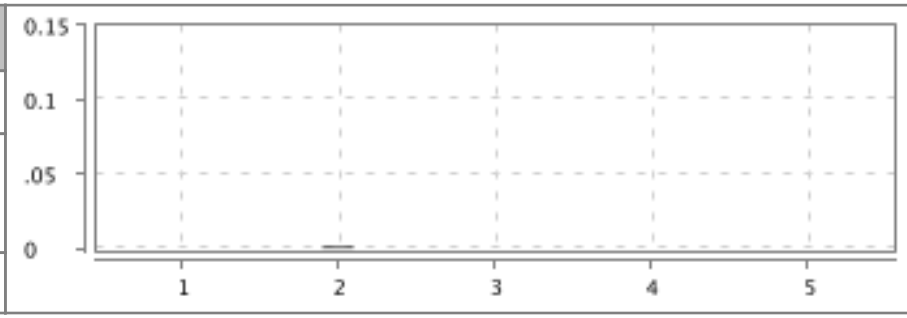
#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s
2	When the operator sends the navigation coordinates as x = -5 and y = -3 facing 1	PASSED	0.001 s
3	Then the rover is settled at coordinates x = -5 and y = -3	PASSED	0.000 s
4	And the rover is facing towards north	PASSED	0.000 s

(S)- The rover should be able to process a multiple navigation command sequentially

PASSED *DURATION - 0.004 s*

/ 12:15:30.054 am // 12:15:30.058 am /

Navigation of the robotic rover to the left right forward and back directions

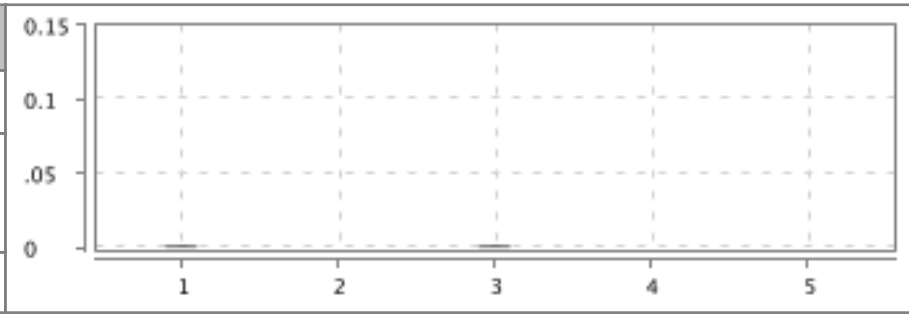


Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.000 s
2	When the operator sends the navigation coordinates as x = 1 and y = 2 facing 1	PASSED	0.001 s
3	And the operator sends a series of navigation command as LMLMLMLMM	PASSED	0.000 s
4	Then the rover is settled at coordinates x = 1 and y = 3	PASSED	0.000 s
5	And the rover is facing towards north	PASSED	0.000 s

(S)- The rover should be able to process a multiple navigation command sequentially

PASSED	DURATION - 0.003 s
/ 12:15:30.061 am // 12:15:30.064 am /	
Navigation of the robotic rover to the left right forward and back directions	

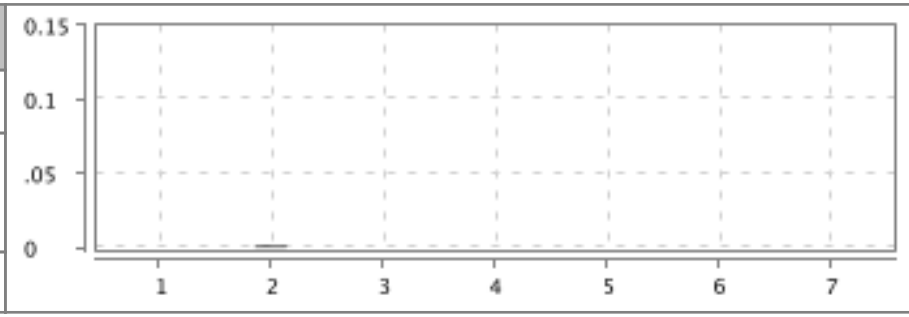


Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s
2	When the operator sends the navigation coordinates as x = 3 and y = 3 facing 2	PASSED	0.000 s
3	And the operator sends a series of navigation command as MMRMMRMRRM	PASSED	0.001 s
4	Then the rover is settled at coordinates x = 5 and y = 1	PASSED	0.000 s
5	And the rover is facing towards east	PASSED	0.000 s

(S)- The rover should be able to process a series of single navigation commands sequentially

PASSED	DURATION - 0.004 s
/ 12:15:30.068 am // 12:15:30.072 am /	
Navigation of the robotic rover to the left right forward and back directions	



Steps
Total - 7
Pass - 7
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.000 s
2	When the operator sends a single command of move 5 units forward	PASSED	0.001 s
3	And the operator sends a single command of move 2 units left	PASSED	0.000 s

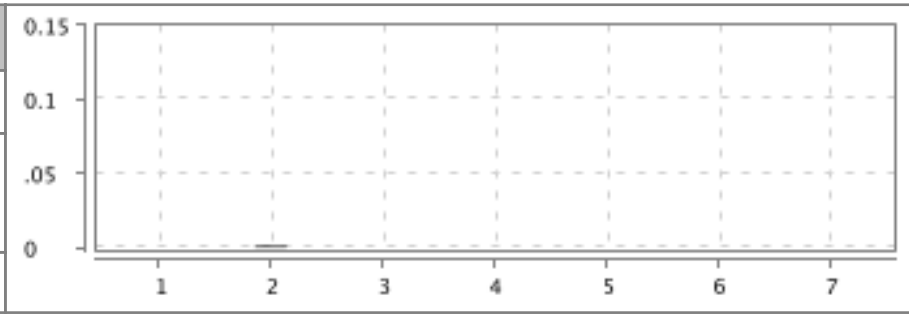
#	Step / Hook Details	Status	Duration
4	And the operator sends a single command of turn right	PASSED	0.000 s
5	And the operator sends a single command of turn left	PASSED	0.000 s
6	Then the rover is settled at coordinates x = -2 and y = 5	PASSED	0.000 s
7	And the rover is facing towards west	PASSED	0.000 s

(S)- The rover should be able to process a series of single navigation commands sequentially

PASSED *DURATION - 0.003 s*

/ 12:15:30.075 am // 12:15:30.078 am /

Navigation of the robotic rover to the left right forward and back directions

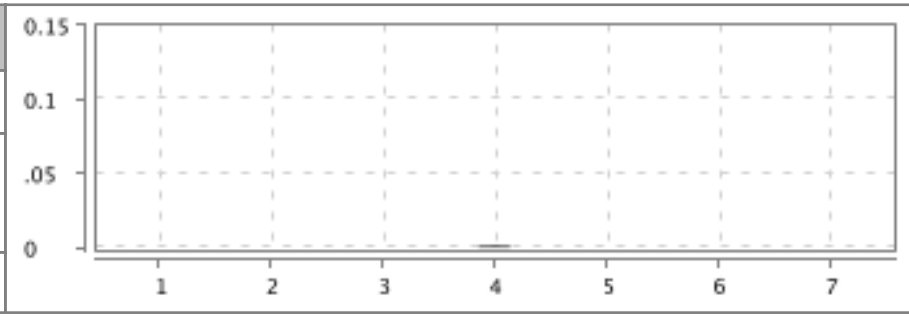


Steps
Total - 7
Pass - 7
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.000 s
2	When the operator sends a single command of move 4 units back	PASSED	0.001 s
3	And the operator sends a single command of move 6 units right	PASSED	0.000 s
4	And the operator sends a single command of turn back	PASSED	0.000 s
5	And the operator sends a single command of turn left	PASSED	0.000 s
6	Then the rover is settled at coordinates x = -6 and y = -4	PASSED	0.000 s
7	And the rover is facing towards north	PASSED	0.000 s

(S)- The rover should be able to process a series of single navigation commands sequentially

PASSED	DURATION - 0.002 s
/ 12:15:30.081 am // 12:15:30.083 am /	
Navigation of the robotic rover to the left right forward and back directions	



Steps
Total - 7
Pass - 7
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX | axisY | facing 0 | 0 | 1	PASSED	0.000 s
2	When the operator sends a single command of move 1 units left	PASSED	0.000 s
3	And the operator sends a single command of move 1 units back	PASSED	0.000 s
4	And the operator sends a single command of turn back	PASSED	0.001 s
5	And the operator sends a single command of turn right	PASSED	0.000 s
6	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.000 s
7	And the rover is facing towards north	PASSED	0.000 s