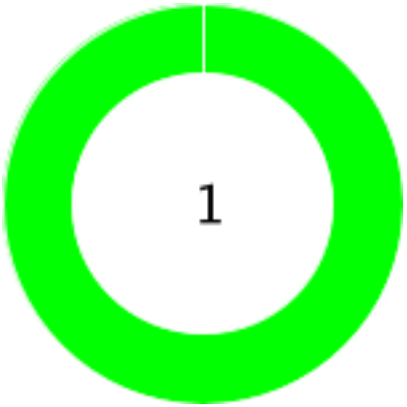
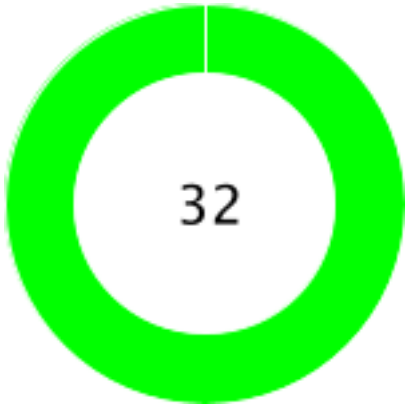
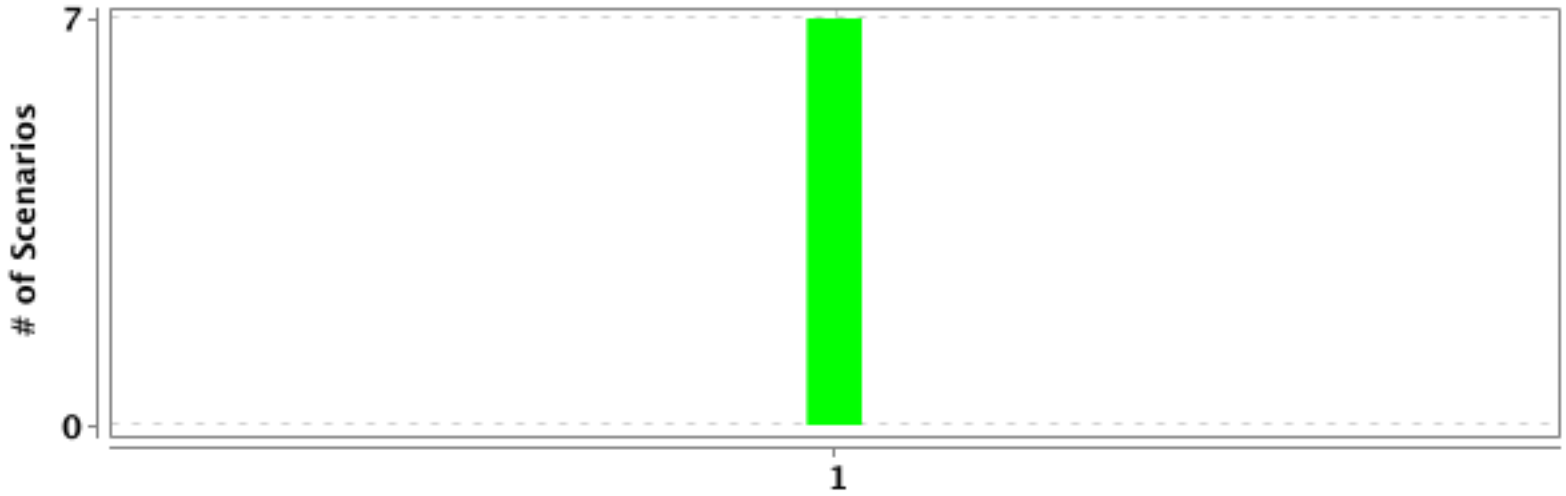
Cucumber Report

18 Jan 2022, 00:42:46

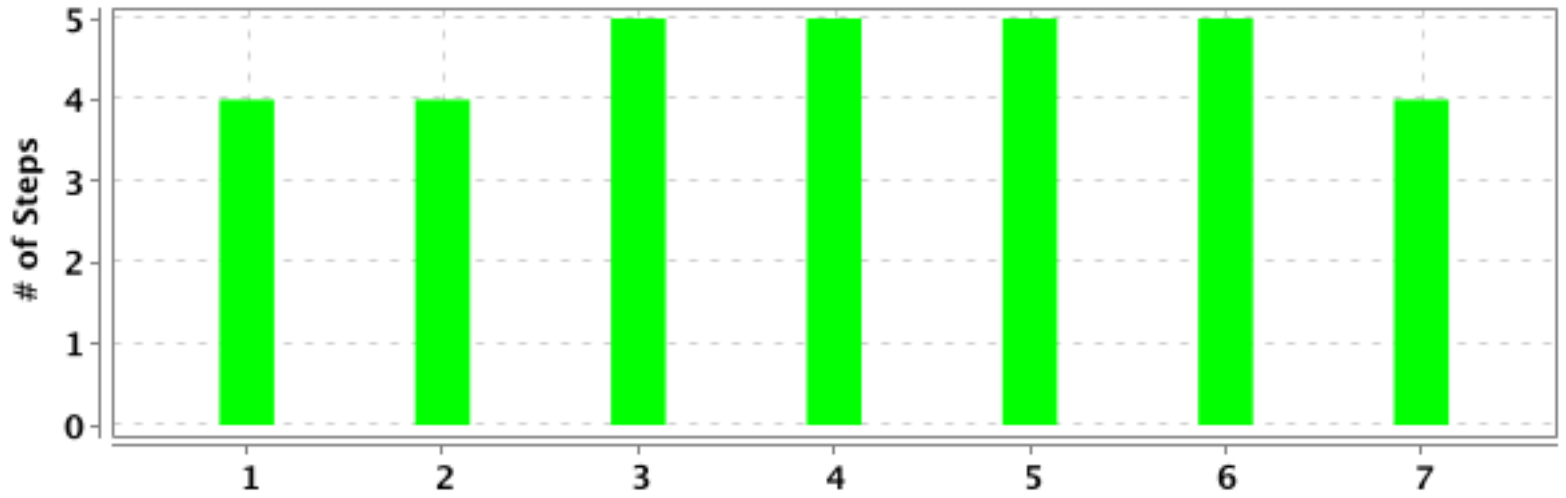
Start : Jan 18, 12:42:46.090 am	End : Jan 18, 12:42:46.186 am	Duration : 0.096 s
Features	Scenarios	Steps
PASSED - 1 FAILED - 0 SKIPPED - 0	PASSED - 7 FAILED - 0 SKIPPED - 0	PASSED - 32 FAILED - 0 SKIPPED - 0







#	Feature Name	T	P	F	S	Duration
1	Navigation of the robotic rover to the left right forward and back directions	7	7	0	0	0.096 s

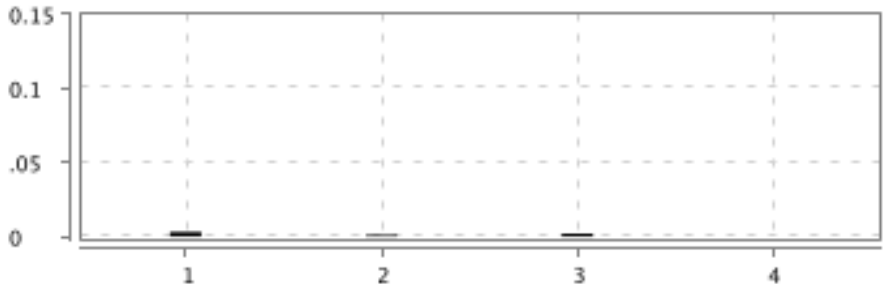


#	Feature Name	Scenario Name	T	P	F	S	Duration
1	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn left	4	4	0	0	0.026 s
2	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn right	4	4	0	0	0.006 s
3	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to move forward	5	5	0	0	0.009 s
4	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to move back	5	5	0	0	0.006 s
5	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn back over the right hand side	5	5	0	0	0.005 s
6	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to turn back over the left hand side	5	5	0	0	0.004 s
7	Navigation of the robotic rover to the left right forward and back directions	The rover should be able to navigate to a given location	4	4	0	0	0.004 s

(F)- Navigation of the robotic rover to the left right forward and back directions

PASSED	DURATION - 0.096 s	Scenarios		Steps	
/ 12:42:46.090 am // 12:42:46.186 am /		Total - 7 Pass - 7 Fail - 0 Skip - 0		Total - 32 Pass - 32 Fail - 0 Skip - 0	

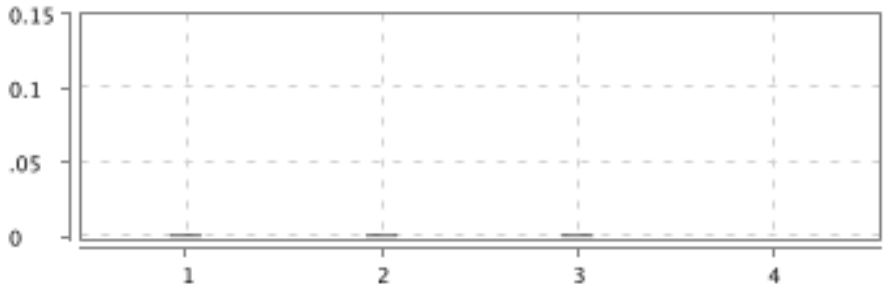
(S)- The rover should be able to turn left

PASSED	DURATION - 0.026 s		Steps	
/ 12:42:46.091 am // 12:42:46.117 am /			Total - 4 Pass - 4 Fail - 0 Skip - 0	
Navigation of the robotic rover to the left right forward and back directions				
@Smoke				

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.003 s
2	When the operator sends a single command of turn left	PASSED	0.001 s
3	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.002 s
4	And the rover is facing towards west	PASSED	0.000 s

(S)- The rover should be able to turn right

PASSED	DURATION - 0.006 s
/ 12:42:46.127 am // 12:42:46.133 am /	
Navigation of the robotic rover to the left right forward and back directions	
@Smoke	

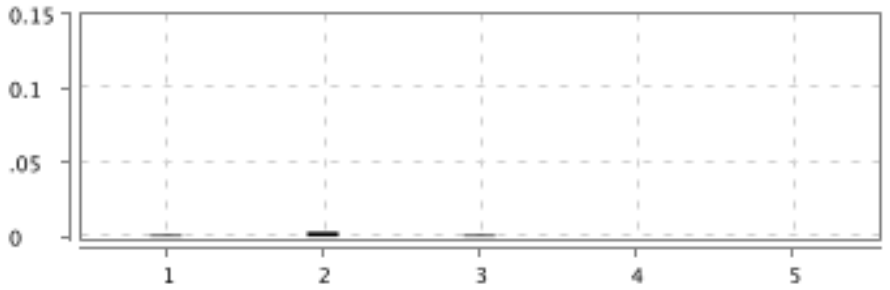


Steps
Total - 4
Pass - 4
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX | axisY | facing 0 | 0 | 1	PASSED	0.001 s
2	When the operator sends a single command of turn right	PASSED	0.001 s
3	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.001 s
4	And the rover is facing towards east	PASSED	0.000 s

(S)- The rover should be able to move forward

PASSED	DURATION - 0.009 s
/ 12:42:46.141 am // 12:42:46.150 am /	
Navigation of the robotic rover to the left right forward and back directions	
@Smoke	



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX | axisY | facing 0 | 0 | 1	PASSED	0.001 s
2	When the operator sends a single command of move 3 units forward	PASSED	0.003 s
3	Then the rover is not positioning at its initial coordinates	PASSED	0.001 s
4	And the rover is settled at coordinates x = 0 and y = 3	PASSED	0.000 s

#	Step / Hook Details	Status	Duration
5	And the rover is facing towards north	PASSED	0.000 s

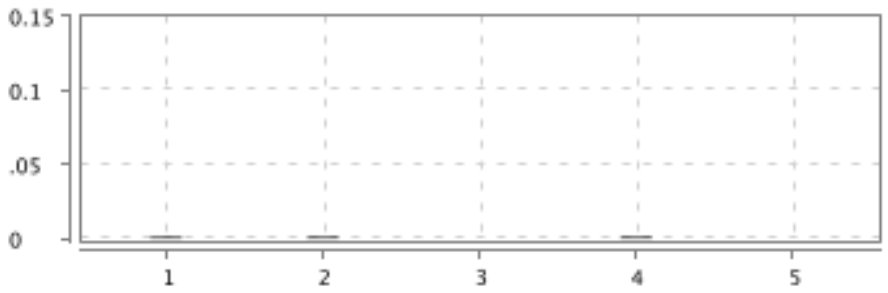
(S)- The rover should be able to move back

PASSED DURATION - 0.006 s

/ 12:42:46.155 am // 12:42:46.161 am /

Navigation of the robotic rover to the left right forward and back directions

@Smoke



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s
2	When the operator sends a single command of move 5 units back	PASSED	0.001 s
3	Then the rover is not positioning at its initial coordinates	PASSED	0.000 s
4	And the rover is settled at coordinates x = 0 and y = -5	PASSED	0.001 s
5	And the rover is facing towards south	PASSED	0.000 s

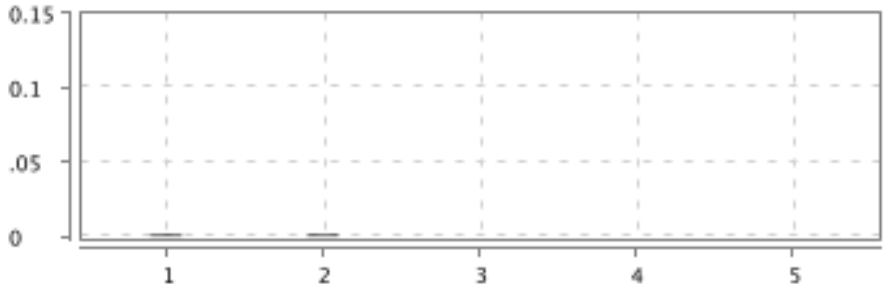
(S)- The rover should be able to turn back over the right hand side

PASSED DURATION - 0.005 s

/ 12:42:46.166 am // 12:42:46.171 am /

Navigation of the robotic rover to the left right forward and back directions

@Smoke



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s

#	Step / Hook Details	Status	Duration
2	When the operator sends a single command of turn right	PASSED	0.001 s
3	And the operator sends a single command of turn right	PASSED	0.000 s
4	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.000 s
5	And the rover is facing towards south	PASSED	0.000 s

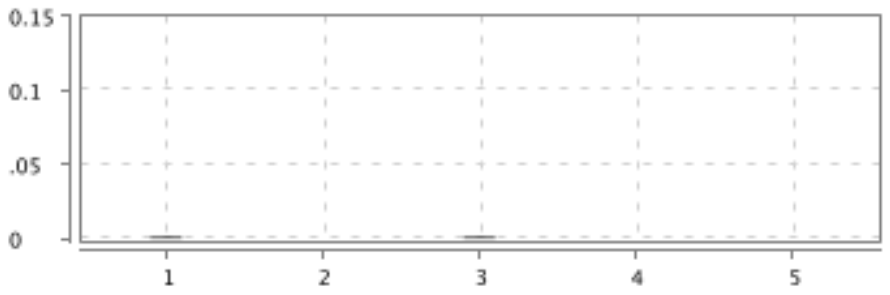
(S)- The rover should be able to turn back over the left hand side

PASSED DURATION - 0.004 s

/ 12:42:46.174 am // 12:42:46.178 am /

Navigation of the robotic rover to the left right forward and back directions

@Smoke



Steps
Total - 5
Pass - 5
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX: 0, axisY: 0, facing: 1	PASSED	0.001 s
2	When the operator sends a single command of turn left	PASSED	0.000 s
3	And the operator sends a single command of turn left	PASSED	0.001 s
4	Then the rover is settled at coordinates x = 0 and y = 0	PASSED	0.000 s
5	And the rover is facing towards south	PASSED	0.000 s

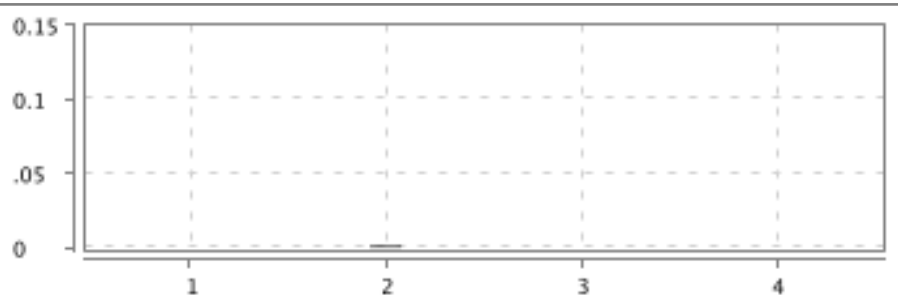
(S)- The rover should be able to navigate to a given location

PASSED DURATION - 0.004 s

/ 12:42:46.182 am // 12:42:46.186 am /

Navigation of the robotic rover to the left right forward and back directions

@Smoke



Steps
Total - 4
Pass - 4
Fail - 0
Skip - 0

#	Step / Hook Details	Status	Duration
1	Given the rover is landed mars at the given coordinates axisX | axisY | facing 0 | 0 | 1	PASSED	0.000 s
2	When the operator sends the navigation coordinates as x = -5 and y = -3 facing 1	PASSED	0.001 s
3	Then the rover is settled at coordinates x = -5 and y = -3	PASSED	0.000 s
4	And the rover is facing towards north	PASSED	0.000 s