

$$\frac{1}{3} \left(\underbrace{(0,2) + (-1)}_{-0,8} + \underbrace{(0,2) + 0,26 - 2}_{-1,54} \right) \cdot \frac{1}{3} + \frac{1}{3} \underbrace{(0,2 + 0,26 \cdot 2 - 3)}_{-2,28}$$

$$-0,8 - 1,54 - 2,28 = -4,62$$

$$\frac{-4,62}{3} = -1,54$$

$$\theta_0 = \theta_0 - \alpha \cdot \frac{\partial J(\theta_0)}{\partial \theta_5} \longrightarrow \theta_0 = 0,2 - (0,1)(-1,54)$$

$$\theta_0 = \underline{\underline{0,046}}$$

$$\frac{1}{3} \left(\cancel{(0,2 + 0,26 \cdot 0 - 1)} + \underbrace{(0,2 + 0,26 \cdot 1 - 2)}_{-1,54} + \underbrace{(0,2 + 0,26 \cdot 2 - 3)}_{-4,56} \right)$$

$$-1,54 - 4,56 = -6,1$$

$$\frac{-6,1}{3} = -2,03$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial J(\theta)}{\partial \theta_5} \longrightarrow \theta_1 = 0,26 - (0,1)(-2,03)$$

$$\theta_1 = 0,463$$

$$\underline{\text{Adim 3}} = \frac{1}{n} (Q_0 + Q_1 \cdot x_i - y_i) \cdot x_j$$

$$\frac{1}{3} \left[\underbrace{(0,046 + 0,463 \cdot 0 - 1)}_0 + \underbrace{(0,046 + 0,463 \cdot 1 - 2)}_{-1,491} + \underbrace{(0,046 + 0,463 \cdot 2 - 3)}_{-2,028} \right]$$

$$\begin{aligned} -1,491 - 2,028 &= \underline{\underline{-3,519}} \\ &= -1,291 \end{aligned}$$

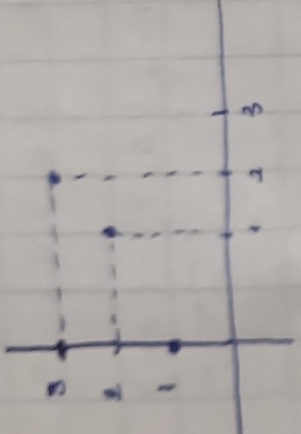
$$Q_0 = Q_0 - \alpha \frac{\partial J(Q_0)}{\partial Q_0} \longrightarrow 0,046 - (0,1) \cdot (-1,291) = 0,1951$$

$$\frac{1}{3} \left(\underbrace{(0,046 + 0,463 \cdot 0 - 1)}_0 + \underbrace{(0,046 + 0,463 \cdot 1 - 2)}_{-1,491} + \underbrace{(0,046 + 0,463 \cdot 2 - 3)}_{-2,056} \right)$$

$$\begin{aligned} -5,547 &= \underline{\underline{-1,849}} \\ &= -1,849 \end{aligned}$$

$$Q_1 = Q_1 - \alpha \frac{\partial J(Q_1)}{\partial Q_1} \longrightarrow 0,463 - (0,1) \cdot (-1,849) = \underline{\underline{0,6479}}$$

ÖRNEK



Döğrusal regresyon yöntemiyle
verilen modeli çıkarınız.

x	y
0	1
1	2
2	3

Gözüm :

Model polinomu $h_0(x) = \theta_0 + \theta_1 x$
Başlangıç aşamasında $\theta_0 = 0, \theta_1 = 0$

x	$h_0(x)$	y	Hata
0	$0 + 0 \cdot 0 = 0$	1	-1
1	$0 + 0 \cdot 1 = 0$	2	-2
2	$0 + 0 \cdot 2 = 0$	3	-3

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^m (h_0(x_i) - y_i)^2$$

$$J(\theta) = \frac{1}{2 \cdot 3} \sum_{i=1}^3 (h_0(x_i) - y_i)^2 = \frac{1}{6} ((-1)^2 + (-2)^2 + (-3)^2) = 14/6$$

$$\theta_J = \theta_J - \alpha \frac{\partial J(\theta)}{\partial \theta_J}$$

$$\frac{\partial J(\theta)}{\partial \theta_0} = \frac{1}{m} \sum_{i=1}^m (\theta_0 + \theta_1 x_i - y_i) \cdot 1 = \frac{1}{3} [(-1) + (-2) + (-3)] = -2$$

$$\frac{\partial J(\theta)}{\partial \theta_1} = \frac{1}{m} \sum_{i=1}^m (\theta_0 + \theta_1 x_i - y_i) \cdot x_i = \frac{1}{3} [(-1) \cdot 0 + (-2) \cdot 1 + (-3) \cdot 2] = -\frac{8}{3}$$

$$\theta_0 = 0 - (0.1) (-2) = 0.2$$

$$\theta_1 = 0 - (0.1) (-2.6) = 0.26$$