

# Rudin Chapter 4: Continuity and Compactness

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**Definition:** (Boundedness)

A mapping  $f : E \rightarrow \mathbb{R}^k$  is **bounded** if there is some  $k$  where  $|f(x)| \leq k$  for all  $x$  in  $E$ .

**Theorem:**

Suppose that  $f$  is a continuous mapping of a compact metric space  $X$  to another metric space  $Y$ . Then  $f(X)$  is compact.

**Proof:**

Let's first get our definitions in order.  $f(x)$  is continuous meaning that for every  $\epsilon > 0$ , there is a  $\delta$  such that all the points within  $\delta$  of  $p$  are also within  $\epsilon$  of  $f(p)$ .

Compactness means that all coverings of  $X$  also have a finite subcovering which also covers  $X$ .

Let  $V$  be an open cover of  $f(X)$ . Then the preimage of each open set in  $V$  is also open (as per a previous theorem in this chapter). We take the preimage of all these, and they do cover  $X$ , and we find a finite subcovering since  $X$  is compact. We then take the images of these and they do form a finite covering of  $f(X)$ .

**Theorem:**

Suppose  $f : X \rightarrow \mathbb{R}$  is a continuous function and  $X$  is compact. Then,  $\sup_{p \in X} f(p)$  and  $\inf_{p \in X} f(p)$  are in  $f(X)$ .

**Proof:**

Since  $X$  is compact, so is  $f(X)$ , and compact subsets of  $\mathbb{R}^k$  are closed and bounded by the Heine-Borel theorem. Since it is both closed and bounded, the range must contain its bounds.

**Theorem:**

Suppose that  $f : X \rightarrow Y$  is a continuous 1-1 mapping between a compact metric space  $X$  and a metric space  $Y$ . Then, the inverse mapping,  $f^{-1}$  is a continuous mapping from  $Y$  to  $X$ .

**Proof:**

One way we can ascertain the continuity of a function  $f$  is that it is only continuous if  $f^{-1}(V)$  is open in  $X$  for every open set  $V$  in  $Y$ .

So in this case, to show that  $f^{-1}$  is continuous, we want to show that  $f(V)$  is open in  $Y$  for every open  $V$  in  $X$ .

First, note that  $V^c$  is closed in  $X$ , since  $V$  is open. Closed subsets of compact spaces are compact, so  $V^c$  is compact. Since  $f$  is continuous,  $f(V^c)$  is also compact, and closed in  $Y$ , since compact sets are closed.

**Definition:** (Uniformly Continuous)

Let  $f$  be a mapping of a metric space  $X$  into a metric space  $Y$ .  $f$  is **uniformly continuous** on  $X$  if for every  $\epsilon > 0$  there exists a  $\delta > 0$  such that  $d_Y(f(p), f(q)) < \epsilon$  for all  $p$  and  $q$  where  $d_X(p, q) < \delta$ .

**Theorem:**

Every uniformly continuous function is continuous.

**Proof:**

Think about what uniformly continuous means. If I choose some  $\epsilon > 0$ , there will be a  $\delta > 0$  such that any two points less than  $\delta$  apart have images less than  $\epsilon$  apart. Then, choose some  $f(p)$  in the image. All points that are less than  $\epsilon$  from  $f(p)$  are less than  $\delta$  from  $p$ , otherwise the function wouldn't be uniformly continuous, so the continuity criterion is fulfilled.

**Theorem:**

Let  $f$  be a continuous mapping of a compact metric space  $X$  to a metric space  $Y$ . Then,  $f$  is uniformly continuous on  $X$ .

**Proof:**

Choose some  $\epsilon > 0$ . Since  $f$  is continuous, we can associate every  $p$  in  $X$  to some positive number  $\Phi(p)$  where  $q \in X$  and  $d_X(p, q) < \Phi(p)$  implies that  $d_Y(f(p), f(q)) < \frac{\epsilon}{2}$ . Basically, let  $\Phi(p)$  be the distance that another point has to be from  $p$  such that the distance of their images is  $\frac{\epsilon}{2}$ .

Then, let  $J(p)$  be the set of all points  $q$  such that  $d(p, q) < \frac{1}{2}\Phi(p)$ . Since  $p$  is in  $J(p)$ , the collection of all such  $J(p)$  is a neighborhood and forms an open cover of  $X$ , and since  $X$  is compact, there is a subset of this collection that covers  $X$ . Let  $\delta$  be the smallest radius in this collection of  $J(p)$ .  $\delta > 0$  since there is a finite number of  $J(p)$ .

Now let  $p, q$  be in  $X$  such that  $d(p, q) < \delta$ .  $p$  must be in at least some  $J(p_m)$ , and  $d_X(p, p_m) \leq d_X(p, q) + d_X(p, p_m)$ , and  $d_X(p, q) + d_X(p, p_m) < \delta + \frac{1}{2}\Phi(p_m) \leq \Phi(p_m)$

And since  $d_X(p, q) < \Phi(p)$  implies  $d_Y(f(p), f(q)) \leq \frac{\epsilon}{2}$ , then  $d_Y(f(p), f(q)) \leq d_Y(f(p), f(q)) + d_Y(f(p), f(p_m)) < \epsilon$ , so  $f$  is uniformly continuous.

**Theorem:**

Let  $E$  be a noncompact set in  $\mathbb{R}^1$ . Then:

1. there exists a continuous function on  $E$  which is not bounded
2. there exists a continuous and bounded function on  $E$  which has no maximum.
3. If  $E$  is bounded, then there exists a continuous function on  $E$  which is not uniformly continuous

**Proof:**

Suppose  $E$  is bounded, so there is a limit point  $x_0$  of  $E$  which is not a point of  $E$ . (A compact set is closed and bounded so if  $E$  is noncompact and bounded it must not be closed).  $f(x) = \frac{1}{x-x_0}$  is not bounded, and not uniformly continuous, but is continuous. The function  $g(x) = \frac{1}{1+(x-x_0)^2}$  is bounded but has no maximum. If  $E$  is unbounded,  $f(x) = x$  is continuous and unbounded, and  $h(x) = \frac{x^2}{1+x^2}$  is continuous and bounded but has no maximum.