

Homework 4

ATSC 507

Christopher Rodell

$$T(^{\circ}\text{C}) = A (c m \Delta t + T_{\text{ref}} - T_{\text{ref}_0}) (T_{\text{ref}_0} - c m \Delta t)$$

Given the above function with $T_{\text{ref}_0} = 2$, $A = 1$, $c = 1.5$, $\Delta t = 1$, and $t = m\Delta t$. *This was the basis for the worksheet that I handed out today in class (the coloured curved lines in the fig below), where I used variable T_{ref} in the range of 2 to 6, and m in the range of 0 to 1. Given the info above, the function that you should apply to the finite difference methods (a) - (d) below is:*

$$\partial T / \partial t = f(t, T) = 1.5 \{ 2 - 1.5 t - [T / (2 - 1.5 t)] \}$$

Hint: To get the eq above for $f(t, T)$, I first solved the eq above for $T_{\text{ref}}(T, t)$. Then I analytically found $\partial T / \partial t$ from the first equation above, and substituted in the expression for T_{ref} . This takes advantage of the fact that T_{ref} is constant along any of the curves in the fig below.*

Please start from initial condition of $T = 2 \text{ degC}$ as we did in class, but compute the new $T \text{ (degC)}$ at 1 timestep ($1\Delta t$) ahead using:

- a) Euler forward

$$T_{n+1} = f(T_n, t_n) * \Delta t + T_n$$

- b) Runge–Kutta 2nd order (mid-point)

$$T^* = T_n + \frac{\Delta t}{2} f(T_n, t_n, \dots)$$

$$T_{n+1} = T_n + \Delta t f\left(T^*, t_n + \frac{\Delta t}{2}, \dots\right)$$

- c) Runge–Kutta 3rd order

$$T^* = T_n + \frac{\Delta t}{3} f(T_n, t_n, x_n)$$

$$T^{**} = T_n + \frac{\Delta t}{2} f\left(T^*, t_n + \frac{\Delta t}{3}\right)$$

$$T_{n+1} = T_n + \Delta t + \left(T^{**}, t_n + \frac{\Delta t}{2}, \dots\right)$$

- d) Runge–Kutta 4th order

$$k_1 = f(T_n, x_n, t_n)$$

$$k_2 = f\left(T_n + \frac{1}{2}\Delta t k_1, x_n, t_n + \frac{1}{2}\Delta t\right)$$

$$k_3 = f\left(T_n + \frac{1}{2}\Delta t k_2, x_n, t_n + \frac{1}{2}\Delta t\right)$$

$$k_4 = f(T_n + \Delta t k_3, x_n, t_n + \Delta t)$$

$$T_{n+1} = T_n + \frac{\Delta t}{6} (k_1 + 2k_2 + 2k_3 + k_4)$$

- e) Which one gave an answer closest to the actual analytical answer as given by the function above?
(Note: do NOT use the 1-D model from the previous HW for this.)

Runge–Kutta 3rd order gave the best approximation and was closest to the analytical solution.

In [1]:

```

import context
import numpy as np
from collections import namedtuple

class Approximator:

    def __init__(self, valueDict):
        self.__dict__.update(valueDict)

    def solution(self):
        T = self.A * ((self.c * self.m * self.dt) \
            + self.Tref - self.Tn) * (self.Tn - (self.c * self.m * self.dt))
        return T

    # function slope
    def TempFun(self):
        f = 1.5 * ( 2 - 1.5 * self.t - (self.Tn / (2 - (1.5 * self.t))))
        return f

    ## Euler forward
    def eulerf(self):
        T = self.TempFun() * self.dt + self.Tn
        return T

    ## Runge-Kutta 2nd order (mid-point)
    def rk2(self):
        Tn = self.Tn
        t = self.t

        T_str = Tn + (self.dt/2) * self.TempFun()

        self.Tn = T_str
        self.t = (t + (self.dt/2))
        T = Tn + self.dt * self.TempFun()

        self.Tn = Tn
        self.t = t
        return round(T, 4)

    ## Runge-Kutta 3rd order
    def rk3(self):
        Tn = self.Tn
        t = self.t

        T_str = self.Tn + (self.dt/3) * self.TempFun()

        self.Tn = T_str
        self.t = (t + (self.dt/3))
        T_str_str = Tn + (self.dt/2) * self.TempFun()

        self.Tn = T_str_str
        self.t = (t + (self.dt/2))
        T = Tn + self.dt * self.TempFun()

        self.Tn = Tn
        self.t = t
        return round(T, 4)

```

```

## Runge-Kutta 4th order
def rk4(self):
    Tn = self.Tn
    t = self.t

    k1 = self.TempFun()

    self.Tn = (Tn + (self.dt/2)*k1)
    self.t = (t + (self.dt/2))
    k2 = self.TempFun()

    self.Tn = (Tn + (self.dt/2)*k2)
    self.t = (t + (self.dt/2))
    k3 = self.TempFun()

    self.Tn = (Tn + self.dt*k3)
    self.t = (t + (self.dt))
    k4 = self.TempFun()

    T = Tn + (self.dt/6) * (k1 + (2 * k2) + (2 * k3) + k4)

    self.Tn = Tn
    self.t = t
    return round(T, 4)

```

context imported. Front of path:

/Users/crode11/at5c507

/private/var/folders/9s/0p5yd78j0yd94hjttzwb6gq00000gp/T/f359e1ba-11

a8-4bdb-a61a-782a94744618

through /Users/crode11/at5c507/py/hw4/context.py -- pha

In [2]:

```

initialVals={'Tn': 2. , 't':0. , 'm':1. , 'dt':1. , 'A': 1. , 'Tref': 3. , 'c':
1.5 }
intVals= Approximator(initialVals)

```

```
T_dict = {}
```

```
T_dict.update({"Analytic Solution": intVals.solution()})
```

```
T_dict.update({"Euler Forward": intVals.eulerf()})
```

```
T_dict.update({"Runge-Kutta 2nd order": intVals.rk2()})
```

```
T_dict.update({"Runge-Kutta 3rd order": intVals.rk3()})
```

```
T_dict.update({"Runge-Kutta 4th order": intVals.rk4()})
```

```
print(T_dict)
```

```

{'Analytic Solution': 1.25, 'Euler Forward': 3.5, 'Runge-Kutta 2nd o
rder': 0.575, 'Runge-Kutta 3rd order': 1.625, 'Runge-Kutta 4th orde
r': 0.845}

```