```
2 -
                              -2
                                                                       2
         -4
                                                                                           4
                                              -2 -
> A_ := Matrix(4, 4, [-4, 3, 1, 7, 1, -1, 1, -6, 8, -2, 3, 0, 4, 0,
   5, 1]):
> b := Vector([2, -7, 17, 11]):
> x_:= LinearSolve(A_,b)
                                         x_{-} \coloneqq \begin{bmatrix} 1 \\ -3 \\ 1 \\ 2 \end{bmatrix}
                                                                                                   (2)
<sup>-</sup>3)
```

```
_a)
10
           5
           0
    -10
        -5
               5
                   10
          -5
          -10
b)
```

> animate(plot, [[16*sin(t)**3, 13*cos(t)-5*cos(2*t)-2*cos(3*t)-cos (4*t), t=0..A]], A=0..2*Pi)

```
A = 0.
                                   10
                                    5
                                                 5
                                                            10
                                                                        15
                         -5
                                    0.
 -15
             -10
                                  -5
                                 -10
                                 -15
_c)
> l := Int(
       sqrt(
           (diff(16*sin(t)^3, t))^2 +
           (diff(13*cos(t) - 5*cos(2*t) - 2*cos(3*t) - cos(4*t), t))^2
       ),
             .. 2*Pi
   ):
> delka := evalf(l)
                             delka := 102.1675516
                                                                          (3)
> odes := diff(x(t), t) = x(t) - 8*y(t), diff(y(t), t) = 2*x(t) + y
```

```
(t):
> ics := x(0) = 0, y(0)=1:
> reseni := dsolve([odes, ics], [x(t), y(t)])
                  reseni := \{x(t) = -2 e^{t} \sin(4 t), y(t) = e^{t} \cos(4 t)\}
                                                                             (4)
> trajektorie:=plot([rhs(reseni[1]), rhs(reseni[2]), t=-5..5], title=
   "Trajektorie")
                                   Trajektorie
                                              100
                                               50
            -200
                              -100
                                                                   100
5)
> r1 := implicitplot(x**2-y**2-1=0, x=-5..5, y=-5..5):
> r2 := plot(exp(x)):
```

```
> display(r1, r2, view=[-5..5, -5..5])
                                     4
                                  у
                                     2 -
                                                       2
                                      0
                       -2
        -4
                                                                      4
                                    -2
 => 1 reseni (realne)
> restart
> reseni := evalf(allvalues(solve([x^2 - y^2 - 1 = 0, y - exp(x) = 0)
   0], [x, y]))):
> realne_reseni := op(op(reseni[1]))
                 realne reseni := x = -1.058487282, y = 0.3469802969
                                                                             (5)
6)
> ode := diff(y(x),x) = x*exp(-y(x))
```

```
ode := \frac{d}{dx} y(x) = x e^{-y(x)}
                                                                                                                             (6)
\ge ic := y(0) = 0:
> solution := dsolve([ode, ic], [y(x)])
                                    solution := y(x) = -\ln(2) + \ln(x^2 + 2)
                                                                                                                             (7)
> y(2) = evalf(subs(x=2, rhs(solution)))
                                                 y(2) = 1.098612288
                                                                                                                             (8)
         EulerMethod := proc(f, x0, y0, h, xmax)
           lifermethod := proc(r, xu, y, n, xmax)
local x, y, n, yn, i;
#n := convert((xmax - x0) / h, integer); #pocet iteraci
x := x0; y := y0; # poc podminka
for i from x0 to xmax by h do
    yn := y + h * f(x, y);
    x := x + h;
    v := vn;
                 y := yn;
             return y;
         end proc:
   f := (x,y) \rightarrow x*exp(-y)
                                                  f := (x, y) \mapsto x \cdot e^{-y}
                                                                                                                             (9)
> EulerMethod(f, 0, 0, 0.1, 2); # pro krok 0.1
> EulerMethod(f, 0, 0, 0.01, 2); # pro krok 0.1
                                                     1.154104852
                                                     1.104113833
                                                                                                                           (10)
```

Eulerova metoda hazi reseni, ktere je vetsi -> jde tam z prava