- 1 #imports
- 2 import pandas as pd
- import numpy as np 3
- import math as mat 4
- from google.colab import drive 5
- 6 import matplotlib.pyplot as plt
- 7 import seaborn as sns
- import statsmodels.api as sm 8
- from matplotlib.colors import ListedColormap 9
- from datetime import datetime 10

11 12

- 1 data1 = pd.read_csv('/content/drive/MyDrive/Colab Notebooks/Assig 4 Logistics Reg wit
- #data2 = pd.read_csv('/content/drive/MyDrive/Colab Notebooks/Assig 4 Logistics Reg wi 2

1 data1.head(10)

₽		trip_id	duration	start_time	end_time	start_lat	start_lon	end_lat	eı
	0	101750280	35	2018-08-07 11:20:00	2018-08- 07 11:55:00	33.748920	-118.275192	33.748920	-118.2
	1	46560345	32	9/17/2017 17:51	9/17/2017 18:23	34.035679	-118.270813	34.047749	-118.2
	2	120016336	6	2019-04-22 09:22:00	2019-04- 22 09:28:00	34.046070	-118.233093	34.047749	-118.2
	3	129547190	138	9/22/2019 11:27	9/22/2019 13:45	34.062580	-118.290092	34.059689	-118.2
Se g	juar	dó correctame	ente	× 2020 17:11	1/31/2020 17:25	34.026291	-118.277687	34.021660	-118.2
	5	63406498	30	2017-12-16 15:18:00	2017-12- 16 15:48:00	34.135250	-118.132370	34.135250	-118. ⁻
	6	25033469	11	2017-04-15 22:02:00	2017-04- 15 22:13:00	34.045181	-118.250237	34.053570	-118.2
	7	107479459	15	2018-10-16 17:27:00	2018-10- 16 17:42:00	34.041130	-118.267982	34.045422	-118.2
	8	132750788	19	2019-11-16 11·24·27	2019-11-	34.046822	-118.248352	34.046822	-118.2 •

1 data1['passholder_type'].nunique

<bound method IndexOpsMixin.nunique of 0</pre>

Walk-up

```
1
                   Walk-up
    2
              Monthly Pass
    3
              One Day Pass
    4
              Monthly Pass
    699995
              Monthly Pass
   699996
              Monthly Pass
                 Flex Pass
   699997
                   Walk-up
    699998
    699999
                   Walk-up
   Name: passholder_type, Length: 693618, dtype: object>
1 data1.shape
    (700000, 14)
1 data1.isna().sum()
   trip_id
                                0
    duration
                                0
    start_time
                                0
    end_time
                                0
    start_lat
                             5563
    start_lon
                             5563
    end_lat
                            18574
    end_lon
                            18574
   bike_id
                                0
   plan_duration
                              208
   trip_route_category
                                0
                             2576
   passholder_type
    start_station
                                0
    end_station
                                0
    dtype: int64
1 data1['end time'].max()
Se guardó correctamente
1 data1['end_time'].min()
    '1/1/2017 0:23'
1
1 data1.dtypes
   trip_id
                              int64
                              int64
    duration
    start_time
                             object
    end_time
                             object
    start lat
                            float64
    start_lon
                            float64
```

float64

float64

end_lat

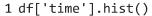
end_lon

```
bike_id object
plan_duration float64
trip_route_category object
passholder_type object
start_station int64
end_station int64
dtype: object
```

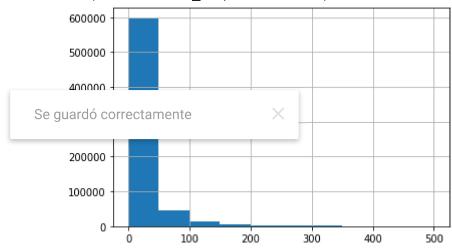
▼ Feature preparation

```
1 data1['end_time'] = pd.to_datetime(data1['end_time'],yearfirst=True)
1 data1['start_time'] = pd.to_datetime(data1['start_time'],yearfirst=True)
1 def timemin(s1,s2):
3
   return pd.Timedelta(s2 - s1).seconds/60
1 data1['time'] = data1.apply(lambda x: timemin(s2=x['end_time'], s1 = x['start_time']),
1 data1['time']
    0
               35.000000
   1
               32.000000
    2
                6.000000
    3
              138.000000
               14.000000
   699995
               17.000000
    699996
                9.683333
Se guardó correctamente
             שששששש. ככ
   Name: time, Length: 700000, dtype: float64
1 data1['time'].max()
    1439.0
1 count = data1[data1['time'] >=500]
2 count.shape
    (6395, 15)
1 data1 = data1[data1['time'] <=500]</pre>
1
```

```
1 import geopy.distance
1 df = data1.copy()
1 df = df.dropna()
1 def hess(a,al,b,bl):
   coords 1 = (a, al)
3
   coords_2 = (b, b1)
4
5
   return geopy.distance.geodesic(coords_1, coords_2).km
1 df['distance_km'] = df.apply(lambda x: hess(a=x['start_lat'], al = x['start_lon'], b=
1 df['distance_km'].head()
         0.000000
    1
         2.882193
    2
         0.949087
    3
         0.529935
   4
         0.521920
   Name: distance_km, dtype: float64
```







▼ Logistic Regression

1 df1 = df

1 df.head()

	trip_id	duration	start_time	end_time	start_lat	start_lon	end_lat	er
0	101750280	35	2018-08-07 11:20:00	2018-08- 07 11:55:00	33.748920	-118.275192	33.748920	-118.2
1	46560345	32	2017-09-17 17:51:00	2017-09- 17 18:23:00	34.035679	-118.270813	34.047749	-118.2
2	120016336	6	2019-04-22 09:22:00	2019-04- 22 09:28:00	34.046070	-118.233093	34.047749	-118.2
3	129547190	138	2019-09-22 11:27:00	2019-09- 22 13:45:00	34.062580	-118.290092	34.059689	-118.2
4	136619463	14	2020-01-31 17:11:00	2020-01- 31 17:25:00	34.026291	-118.277687	34.021660	-118.2



1

```
1 df1 =df1[df1['distance_km'] <=100]</pre>
```

1 df1[df1['distance_km'] >=100].shape

```
(0. 16)
Se guardó correctamente
```

```
2  if x == "Monthly Pass":
3   return 1
4  else:
```

5 return 0

6

1 df1["passholder_type"] = df1['passholder_type'].map(transform)

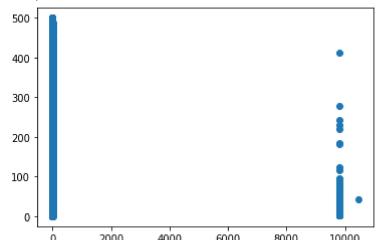
/usr/local/lib/python3.7/dist-packages/ipykernel_launcher.py:1: SettingWithCopyWarnir A value is trying to be set on a copy of a slice from a DataFrame.

Try using .loc[row_indexer,col_indexer] = value instead

See the caveats in the documentation: https://pandas.pydata.org/pandas-docs/stable/us
"""Entry point for launching an IPython kernel.

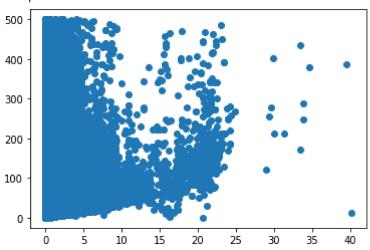
```
1 df1['nassholder tyne'l.nunique()
    2
1 # Shuffle your dataset
2 shuffle_df = df1.sample(frac=1)
4 # Define a size for your train set
5 train_size = int(0.9 * len(df1))
7 # Split your dataset
8 train_df = shuffle_df[:train_size]
9 test_df = shuffle_df[train_size:]
1 def norma(data):
   return (data-data.min())/(data.max()-data.min())
1 X = train_df.loc[:,['time','distance_km']]
2 y = train_df.loc[:,'passholder_type']
1 X.shape
    (604384, 2)
1 \times norm = norma(X)
1 X_test = test_df.loc[:,['time','distance_km']]
2 y_test = test_df.loc[:,'passholder_type']
1 Xtestnorm = norma(X_test)
Se guardó correctamente
    (67154, 2)
1 X = X.to_numpy()
2 y = y.to_numpy()
1 X_test = X_test.to_numpy()
2 y_test = y_test.to_numpy()
1 y_test
    array([0, 1, 1, ..., 1, 0, 1])
1 plt.scatter(df['distance_km'],df['time'])
```

<matplotlib.collections.PathCollection at 0x7f8f269cc310>



1 plt.scatter(df1['distance_km'],df1['time'])

<matplotlib.collections.PathCollection at 0x7f8ef74c2c90>



1 df1.max()

/usr/local/lib/nvthon3 7/dist-nackages/ipykernel_launcher.py:1: FutureWarning: Droppi

e guardó correctamente	an IPython kernel.	
e guardo correctamente	179457605	
auration	1440	
start_time	2021-12-31 22:57:00	
end_time	2022-01-01 21:35:00	
start_lat	55.705528	
start_lon	37.606541	
end_lat	55.705528	
end_lon	37.606541	
plan_duration	999.0	
<pre>trip_route_category</pre>	Round Trip	
passholder_type	1	
start_station	4594	
end_station	4594	
time	500.0	
distance <u></u> km	40.131137	
dtype: object		

Neuronal network

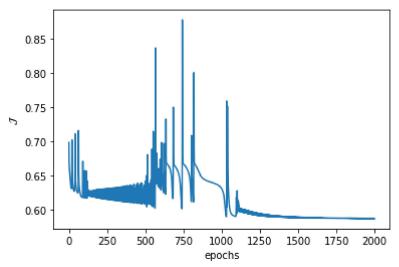
```
1 def linear(H):
 2
    return H
 3
 4 def ReLU(H):
    return H*(H>0)
 5
 6
 7 def sigmoid(H):
    return 1/(1+np.exp(-H))
 8
 9
10 def softmax(H):
    eH=np.exp(H)
11
    return eH/eH.sum(axis=1,keepdims=True)
12
13
14 def cross_entropy(Y, P_hat):
     return -(1/len(Y))*np.sum(Y*np.log(P hat))
16
17 def OLS(Y, Y_hat):
    return (1/(2*len(Y)))*np.sum((Y-Y_hat)**2)
18
19
20 def one_hot_encode(y):
    N=len(y)
21
22
    K=len(set(y))
23
    Y=np.zeros((N,K))
24
25
    for i in range(N):
26
     Y[i, y[i]]=1
27
28
    return Y
29
30 def accuracy(y, y_hat):
    return np.mean(y==y_hat)
31
32
33 def R2(y, y hat):
                                     p.sum((y -y.mean())**2)
 Se guardó correctamente
36 # Derivatives of Activation functions
37
38 def derivative(Z,a):
39
    if a==linear:
      return 1
40
41
   elif a==sigmoid:
42
      return Z*(1-Z)
43
    elif a==np.tanh:
       return 1-Z*Z
44
45
    elif a==ReLU:
46
       return (Z>0).astype(int)
47
48
       ValueError("Unknown Activation Function")
49
 1 cmap_bold = ListedColormap(["#FF0000","#00FF00","#0000FF"])
 2 cmap_light = ListedColormap(["#FFBBBB","#BBFFBB","#BBBBFF"])
```

```
1 class ANN():
 2
 3
     def __init__(self,architecture, activations=None, mode=0):
 4
       self.mode=mode
 5
       self.architecture=architecture
       self.activations=activations
 6
 7
       self.L = len(architecture)+1
 8
 9
     def fit(self, X, y, eta=1e-3, epochs=1e3, show_curve=False):
       epochs=int(epochs)
10
11
       if self.mode:
12
         Y=y
13
       else:
14
         Y=one_hot_encode(y)
15
16
       N,D = X.shape
17
       K=Y.shape[1]
18
19
       #Weights Init
20
       self.W={1: np.random.randn(M[0],M[1]) for 1, M in enumerate
               (zip(([D]+self.architecture),(self.architecture+[K])),1)}
21
22
       self.b={l:np.random.randn(M) for l, M in enumerate(self.architecture +[K],1)}
23
       #Activations Loading
24
       if self.activations is None:
         self.a={1: ReLU for 1 in range(1,self.L)}
25
26
       else:
27
         self.a={1: act for 1, act in enumerate(self.activations,1)}
28
       #Outputs
29
       if self.mode:
30
31
         self.a[self.L]=linear
32
33
         self.a[self.L]=softmax
 Se guardó correctamente
37
       #GradDesc and Back Propagation
38
       for epoch in range(epochs):
         self.forward(X)
39
         if self.mode:
40
           J[epoch] = OLS(Y, self.Z[self.L])
41
42
         else:
43
           J[epoch]=cross_entropy(Y, self.Z[self.L])
44
         dH = (1/N)*(self.Z[self.L]-Y)
45
46
47
         for 1 in sorted(self.W.keys(), reverse=True):
48
           dW = self.Z[1-1].T@dH
49
           db = dH.sum(axis=0)
           #update rules
50
           self.W[1] -= eta*dW
51
           self.b[1] -= eta*db
52
53
54
           if 1>1:
```

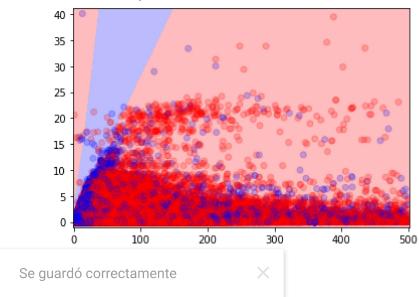
```
dZ = dH@self.W[1].T
55
                                dH = dZ*derivative(self.Z[l-1], self.a[l-1])
56
57
                 if show_curve:
58
                           plt.figure()
59
                           plt.plot(J)
60
                           plt.xlabel("epochs")
61
62
                           plt.ylabel("$\mathcal{J}$")
63
                           plt.show()
64
            def forward(self, X):
65
                 self.Z={0:X}
66
                 for 1 in sorted(self.W.keys()):
67
68
                      self.Z[1]=self.a[1](self.Z[1-1]@self.W[1]+self.b[1])
69
70
            def predict(self, X):
71
                 self.forward(X)
72
                 if self.mode:
73
                      return self.Z[self.L]
74
                 else:
75
                      return self.Z[self.L].argmax(axis=1)
  1 def main_class():
  2
                 D = 2
  3
                 K = 3
                 N = int(K*1e3)
  4
  5
  6
  7
                 ann=ANN([8, 8, 8],[ReLU, np.tanh, np.tanh])
                 ann.fit(X,y, eta =3e-2, epochs=2e3, show_curve=True)
  8
  9
                 y_hat = ann.predict(X)
10
                 y_hatt = ann.predict(X_test)
11
12
                 print(f"Training Accuracy: {accuracy(y, y_hat):0.4f}")
                                                                                         acy(y_test, y_hatt):0.4f}")
   Se guardó correctamente
15
                 xx = np.xx =
                 x2 = np.linspace(X[:,1].min() - 1, X[:,1].max() + 1, 1000)
16
17
18
                 xx1, xx2 = np.meshgrid(x1, x2)
19
                 Z = ann.predict(np.c_[xx1.ravel(),xx2.ravel()]).reshape(*xx1.shape)
20
21
                 plt.figure()
                 plt.pcolormesh(xx1, xx2, Z, cmap = cmap_light)
22
23
                 plt.scatter(X[:,0], X[:,1], c = y, cmap = cmap_bold,alpha=0.2)
24
                 plt.xlim(xx1.min(), xx1.max())
                 plt.ylim(xx2.min(), xx2.max())
25
26
                 plt.show()
  1 gpu_info = !nvidia-smi
  2 gpu_info = '\n'.join(gpu_info)
  3 if gpu_info.find('failed') >= 0:
            print('Not connected to a GPU')
```

```
5 else:
6    print(gpu info)

1 if __name__ =="__main__":
2    main_class()
```



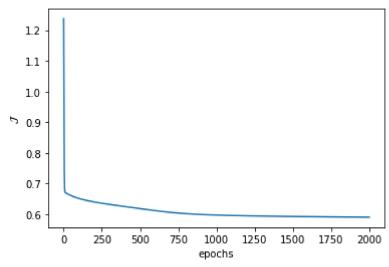
Training Accuracy: 0.6966 Test Accuracy: 0.6994



Data norm

```
1 def main_class2():
       D = 2
 2
 3
       K = 3
 4
       N = int(K*1e3)
 5
 6
 7
       ann=ANN([8, 8, 8],[ReLU, np.tanh, np.tanh])
 8
       ann.fit(Xnorm,y, eta =1e-2, epochs=2e3, show_curve=True)
 9
       y_hat = ann.predict(Xnorm)
10
       y_hatt = ann.predict(Xtestnorm)
11
12
       print(f"Training Accuracy: {accuracy(y, y_hat):0.4f}")
       print(f"Test Accuracy: {accuracy(y_test, y_hatt):0.4f}")
13
14
```

```
1 if __name__ =="__main__":
2  main class2()
```



Training Accuracy: 0.6994 Test Accuracy: 0.7011



▶ 80-20

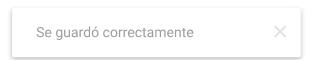


▶ Balance the 0 and 1



→ Other model

1



1

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✓ 0 s se ejecutó 22:59

Se guardó correctamente

×