

# Usage of SimpleITK



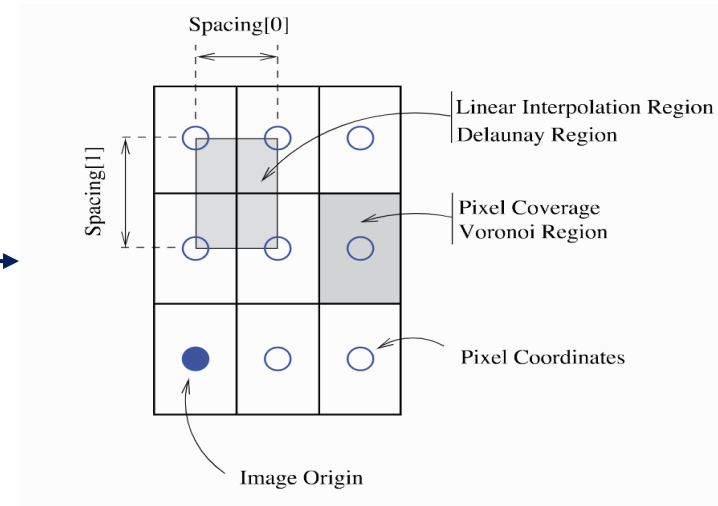
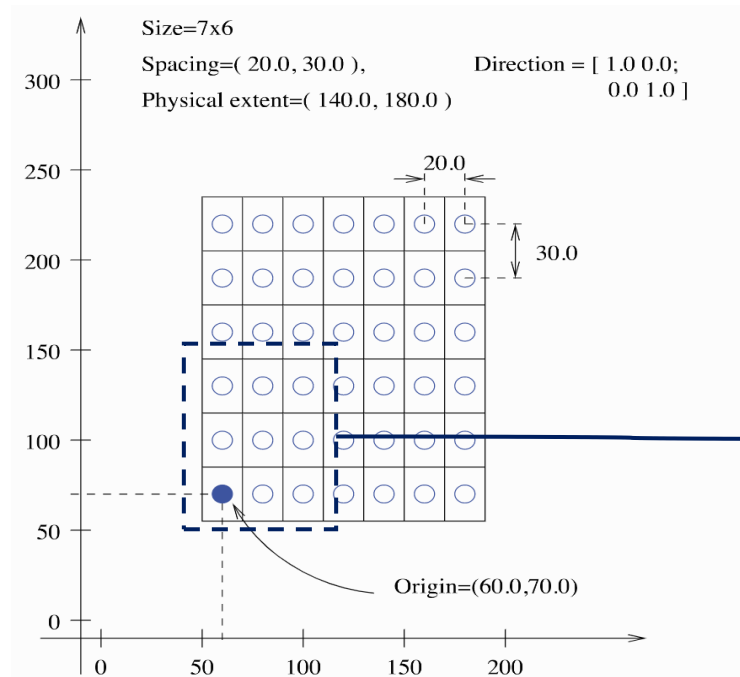
**S I M P L E I T K**

- A simplified version of ITK (Insight Tool Kit) for scientific image processing, segmentation, and registration
- Ideal for medical imaging: X-rays, CT, PET, MRI, and US
- Available in Python:  
`pip install SimpleITK | conda install simpleitk`

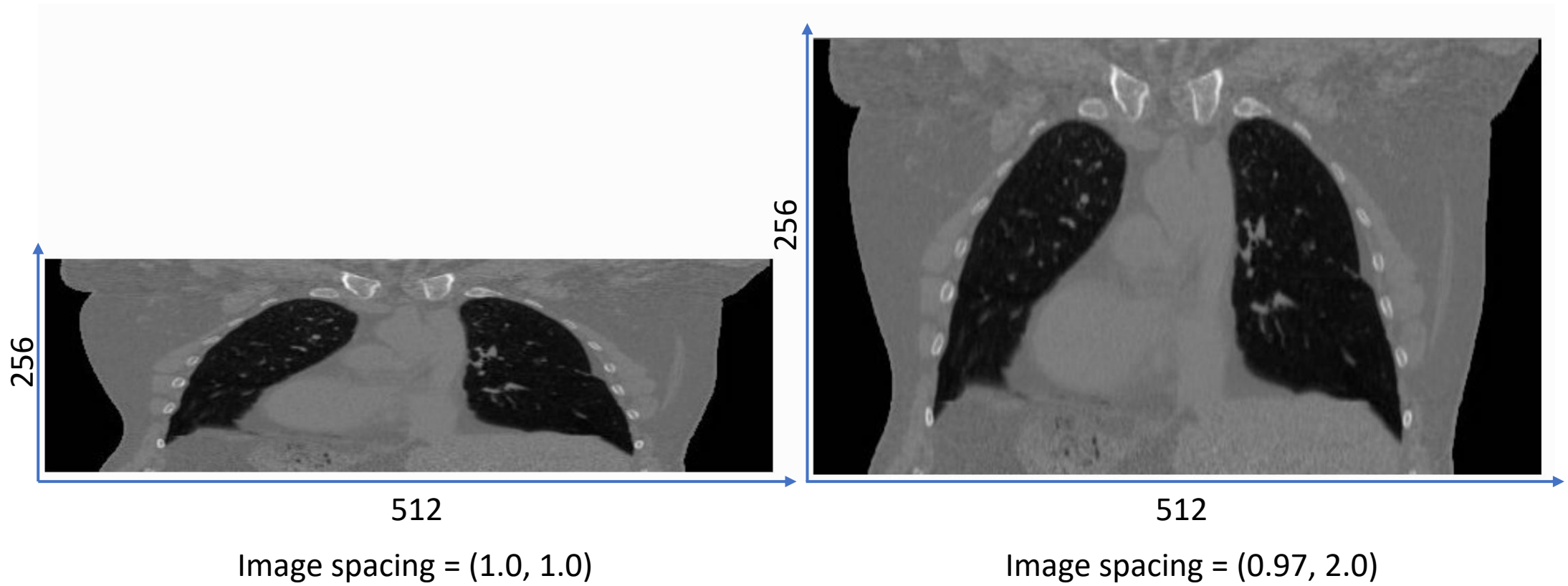
# Image fundamentals

- An image in SITK  $\neq$  than in cv2 or scikit-image
  - SITK = set of points on a grid occupying a physical region in the space
  - Others = array

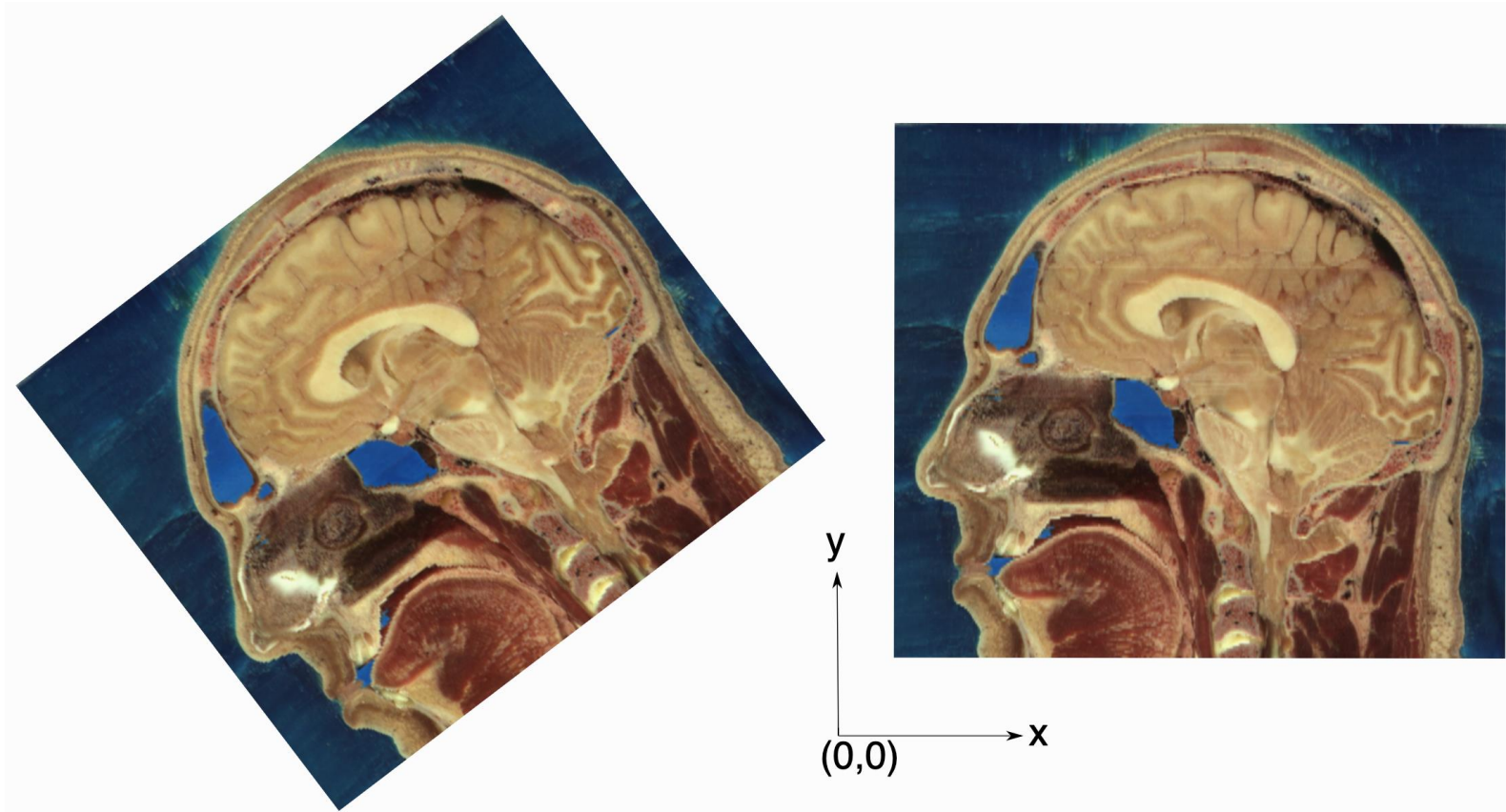
- SITK takes into account:
  1. Pixel/voxel spacing information
  2. Location in the physical space



- Image spacing:



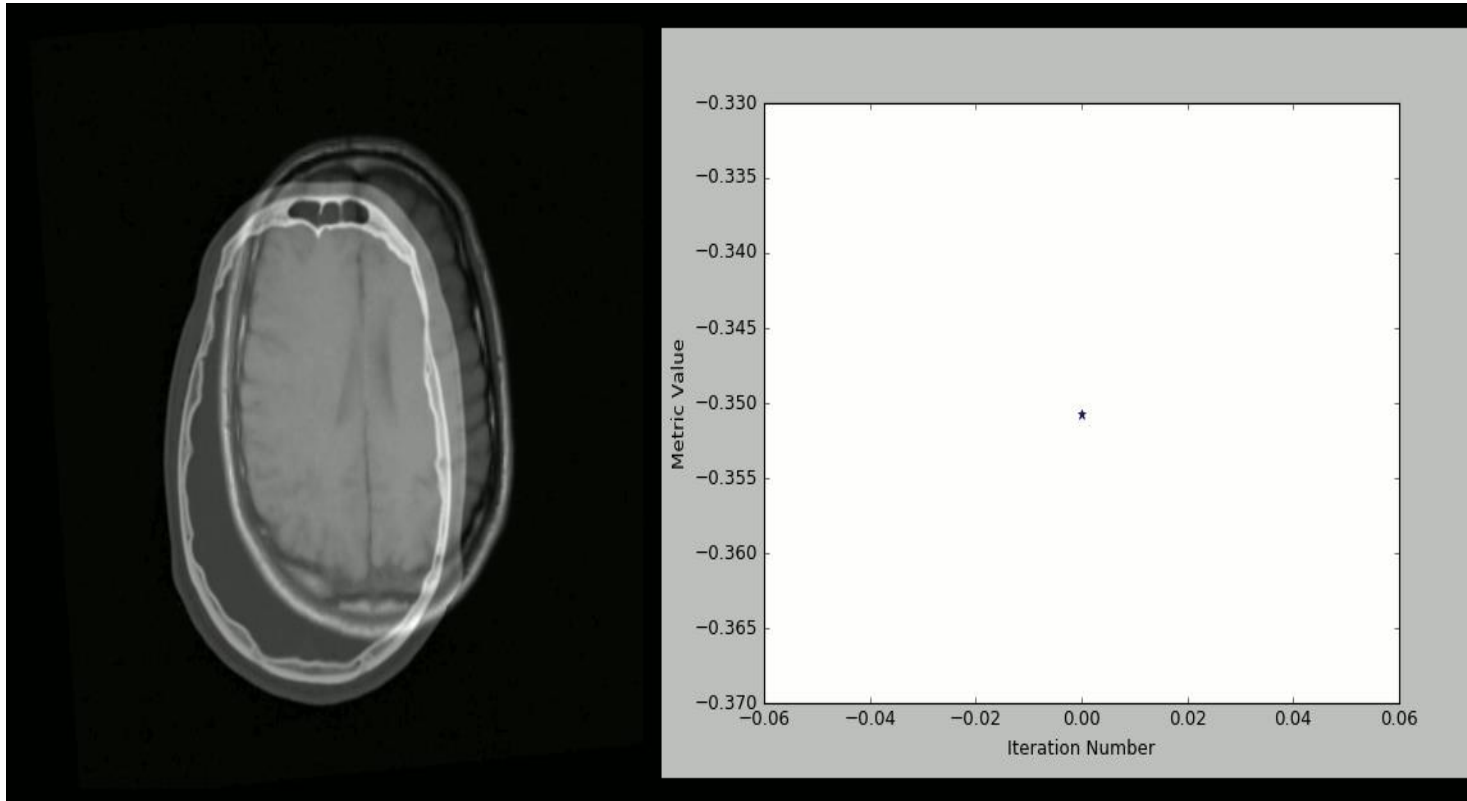
- Image origin and direction:



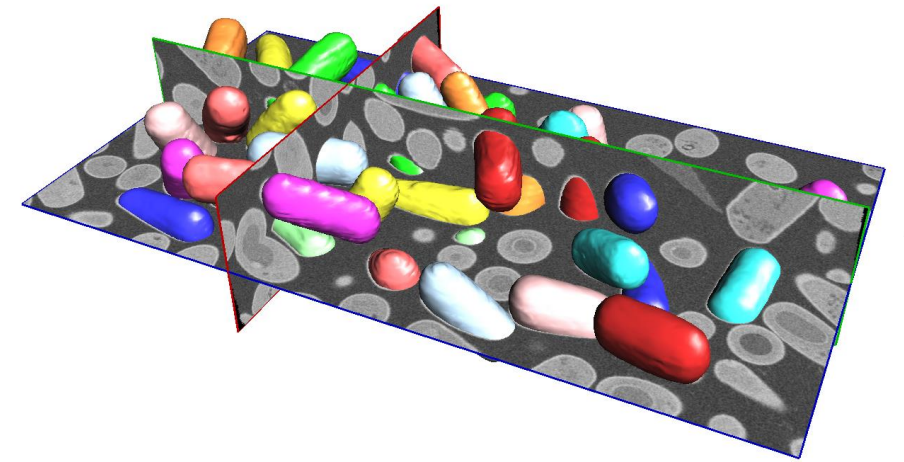
- Image origin =  $(-136.3, -20.5)$
- Orientation matrix =  $(0.7, -0.7, 0.7, -0.7)$

- Image origin =  $(16.9, 21.4)$
- Orientation matrix =  $(1, 0, 0, 1)$

- Image registration:



- Image segmentation:



# How to read an image?

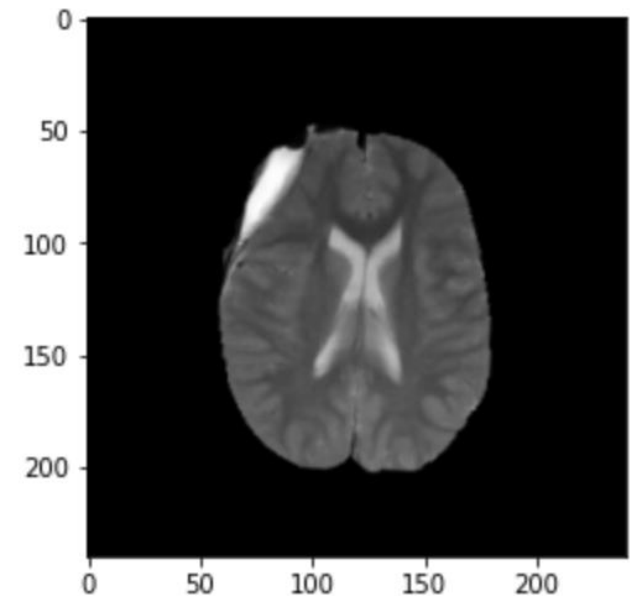
1. `import SimpleITK as sitk`
2. `image = sitk.ReadImage(path_to_image)`

# Conversion between SimpleITK and NumPy

From SimpleITK to NumPy:

1. `image = sitk.ReadImage(path_to_image)`
2. `array = sitk.GetArrayFromImage(image)`
  - `array.shape -> (155, 240, 240)`

```
plt.imshow(array[87, :, :], cmap='gray')  
plt.show()
```





# Reading an image

- Multiple image formats:
  - Standard ones: .jpeg, .png, .tiff, etc
  - Medical ones: .mha, .nii, .dcm
- `image = sitk.ReadImage(path_to_image)`
  - Default = '16-bit signed integer'
- `image = sitk.ReadImage(path_to_image, sitk.sitkUInt8)`

<code>sitkUInt8</code>	Unsigned 8 bit integer
<code>sitkInt8</code>	Signed 8 bit integer
<code>sitkUInt16</code>	Unsigned 16 bit integer
<code>sitkInt16</code>	Signed 16 bit integer
<code>sitkUInt32</code>	Unsigned 32 bit integer
<code>sitkInt32</code>	Signed 32 bit integer
<code>sitkUInt64</code>	Unsigned 64 bit integer
<code>sitkInt64</code>	Signed 64 bit integer
<code>sitkFloat32</code>	32 bit float
<code>sitkFloat64</code>	64 bit float

# Practical Session 3

Image enhancement and denoising

# Exercise 1: Image histogram

1. Linear stretching \*
2. Histogram equalization \*
3. CLAHE (skimage implementation)

# Exercise 1: Image histogram

## 1. Linear stretching \*

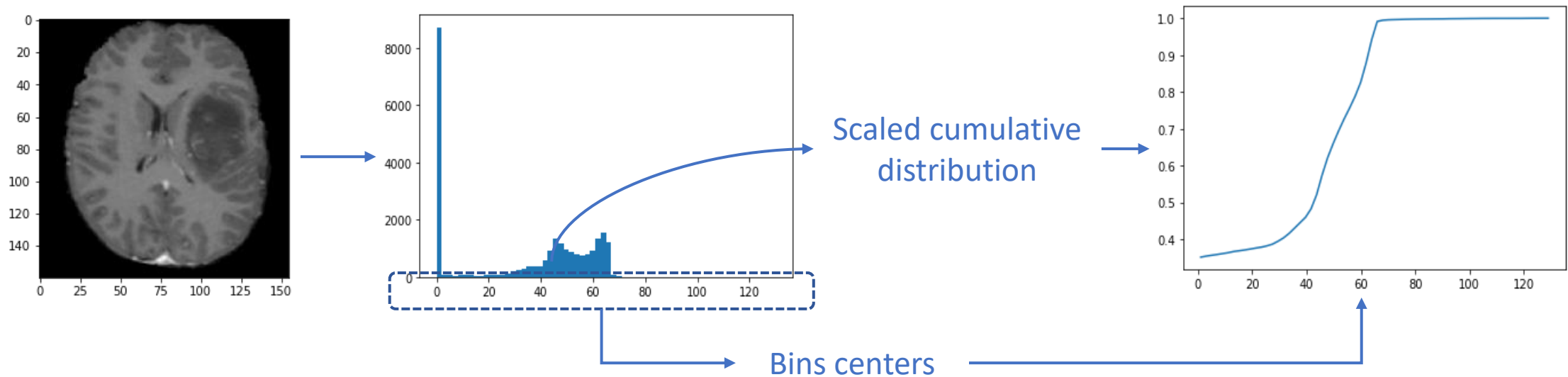
$$j = \frac{i - i_{\min}}{i_{\max} - i_{\min}} (j_{\max} - j_{\min}) + j_{\min}$$

$$j_{\min} = 0 \quad j_{\max} = 1$$

$$i_{\min} = P_5 \quad i_{\max} = P_{95}$$

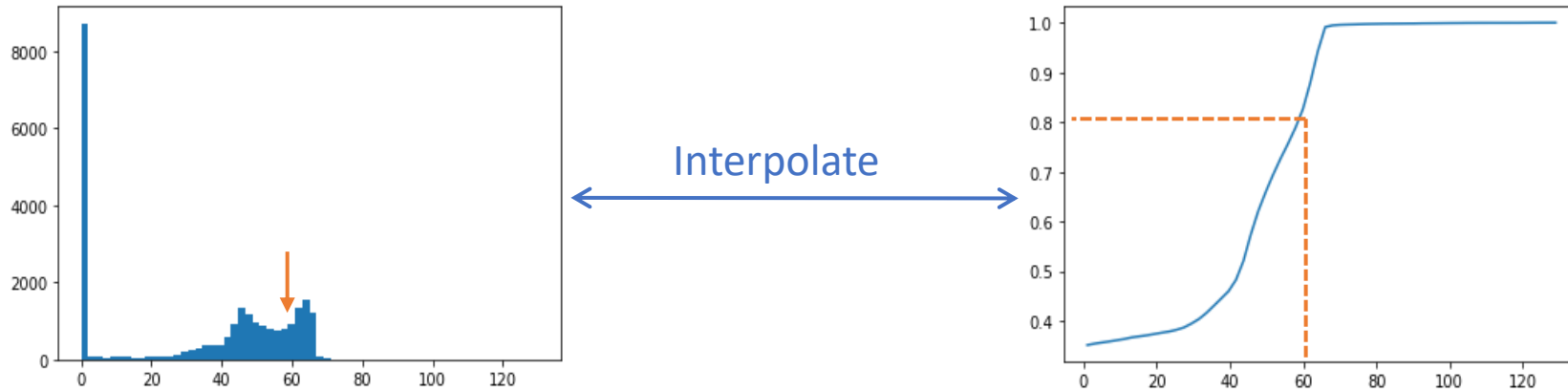
# Exercise 1: Image histogram

## 2. Histogram equalization\*

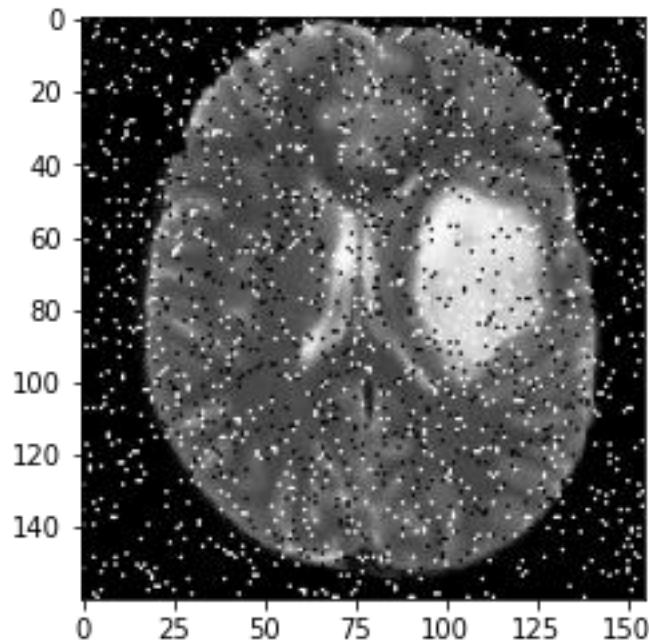


# Exercise 1: Image histogram

## 2. Histogram equalization\*



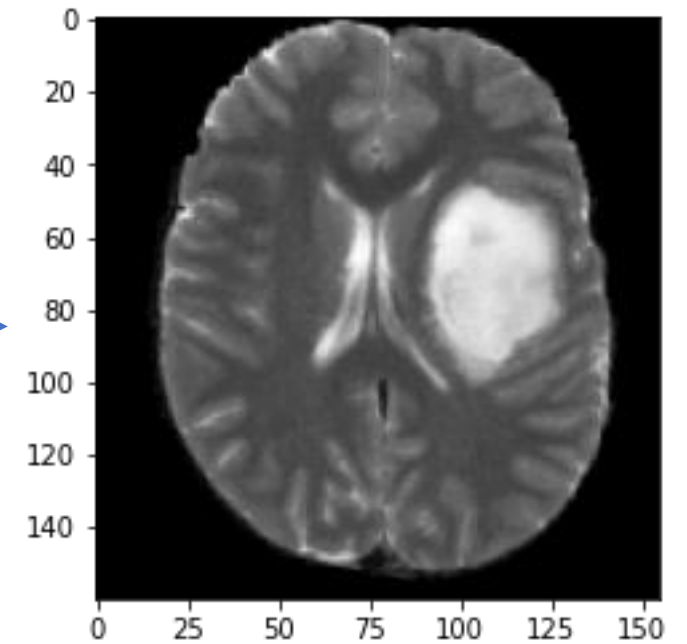
# Exercise 2: Image denoising



1. Gaussian filter

2. Median filter

3. Mean filter \*



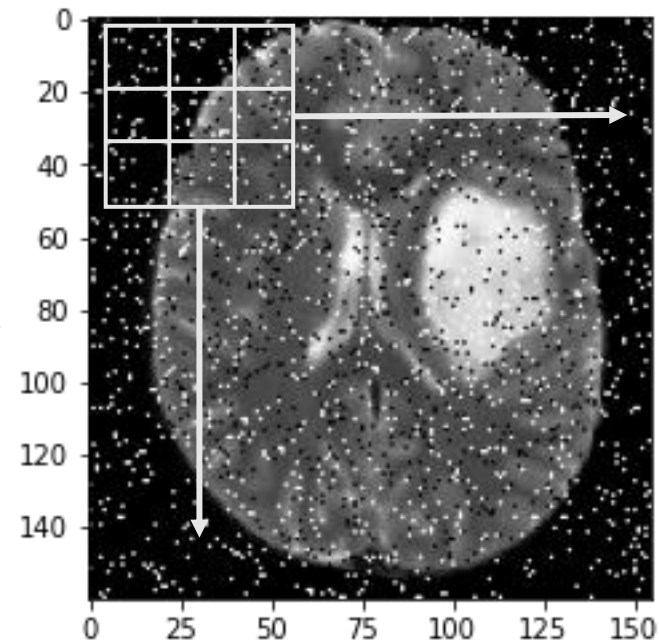
# Exercise 2: Image denoising

## 3. Mean filter \*

$1/9$

1	1	1
1	1	1
1	1	1

Convolve





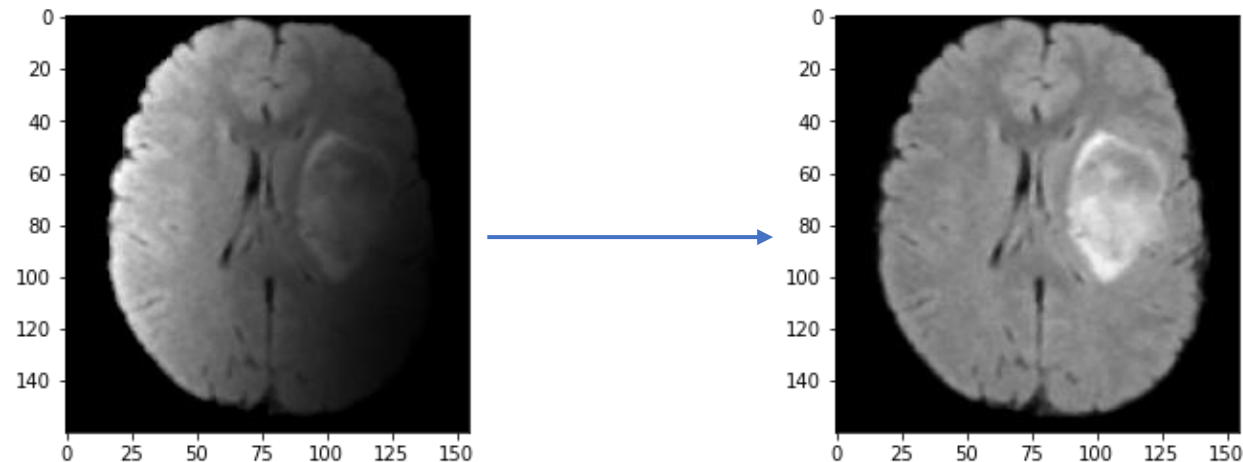
# Exercise 3: HUM algorithm

- Remove bias noise

$$f_{i,j} = g_{i,j} \cdot \frac{\mu}{\mu_{i,j}},$$

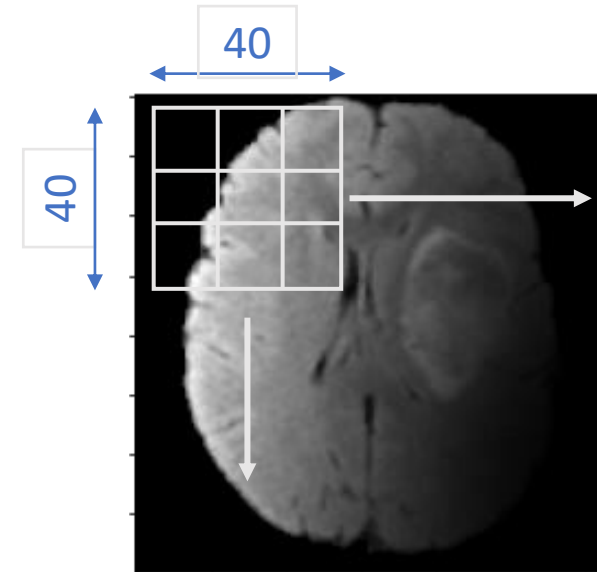
$f_{i,j}$  = output pixel intensity       $\mu$  = global mean intensity

$g_{i,j}$  = input pixel intensity       $\mu_{i,j}$  = local mean intensity



# Exercise 3: HUM algorithm

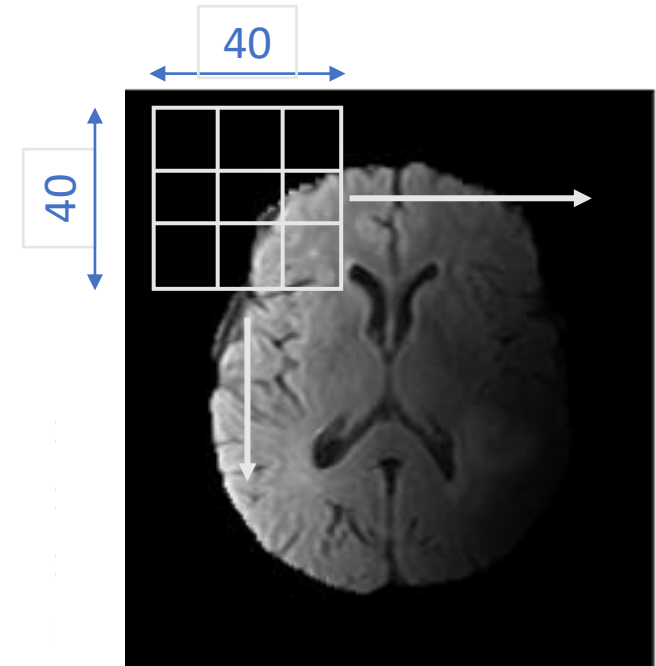
1. Direct implementation:
  - i. Get mean intensity (global)
  - ii. Define a window of 40 x 40
  - iii. Get mean intensity (local)
  - iv. Compute HUM
  - v. Move the window, and repeat



# Exercise 3: HUM algorithm

## 2. Pad image:

- i. Pad the image
- ii. Get mean intensity (global)
- iii. Define a window of 40 x 40
- iv. Get mean intensity (local)
- v. Compute HUM
- vi. Move the window, and repeat



# Exercise 3: HUM algorithm

## 3. Pad + threshold:

- i. Pad the image
- ii. Filter pixels below a threshold (10)
- iii. Get mean intensity (global)
- iv. Define a window of 40 x 40
- v. Get mean intensity (local)
- vi. Compute HUM
- vii. Move the window, and repeat

