

# Model comparison

Choose the best model!

Test if the model is correct!

(model checking)

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Existing methods can say:

“If the model is true it produces such data extremely rarely.”

Or

“If the model is true it produces such data extremely rarely.”

# Model comparison

Choose the best model!

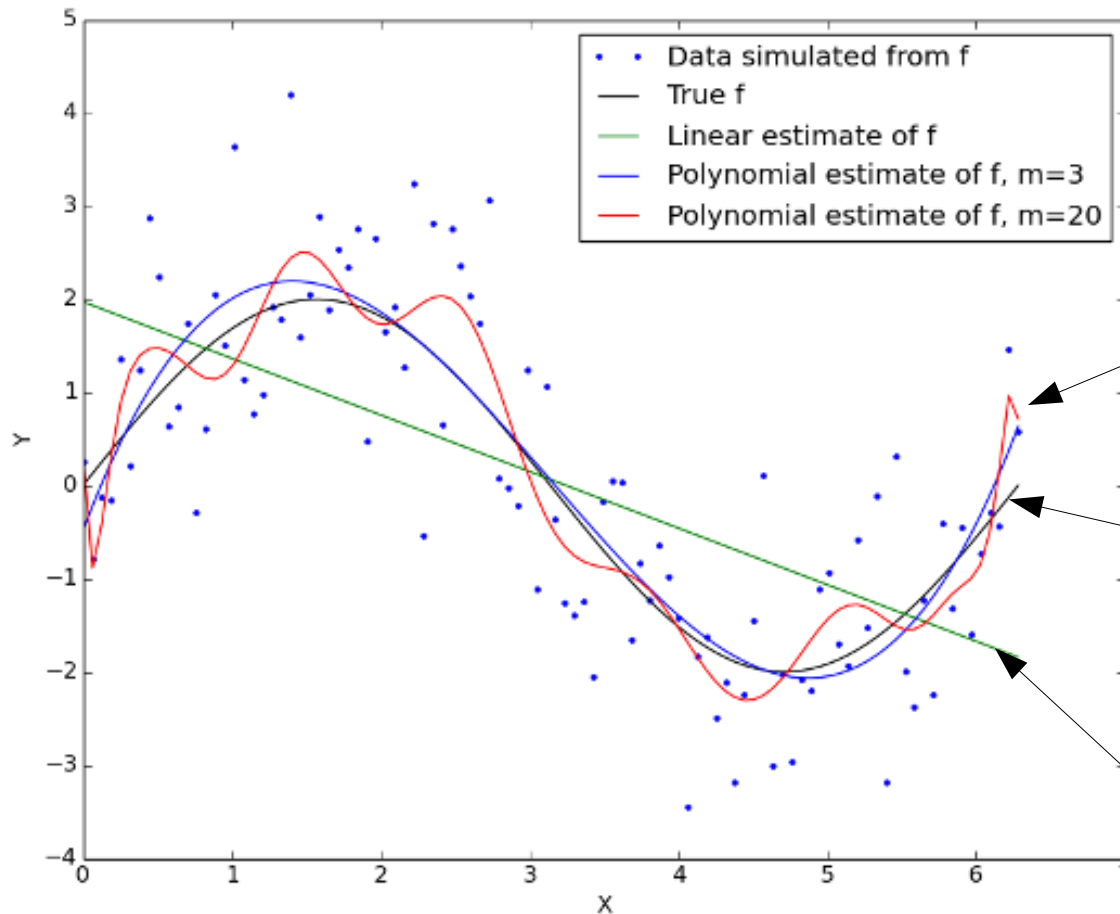
What is best?

- If it fits the data!

- Create a model that equals the data  
→ fits perfectly

different styles of model comparison

# Bias-variance trade-off



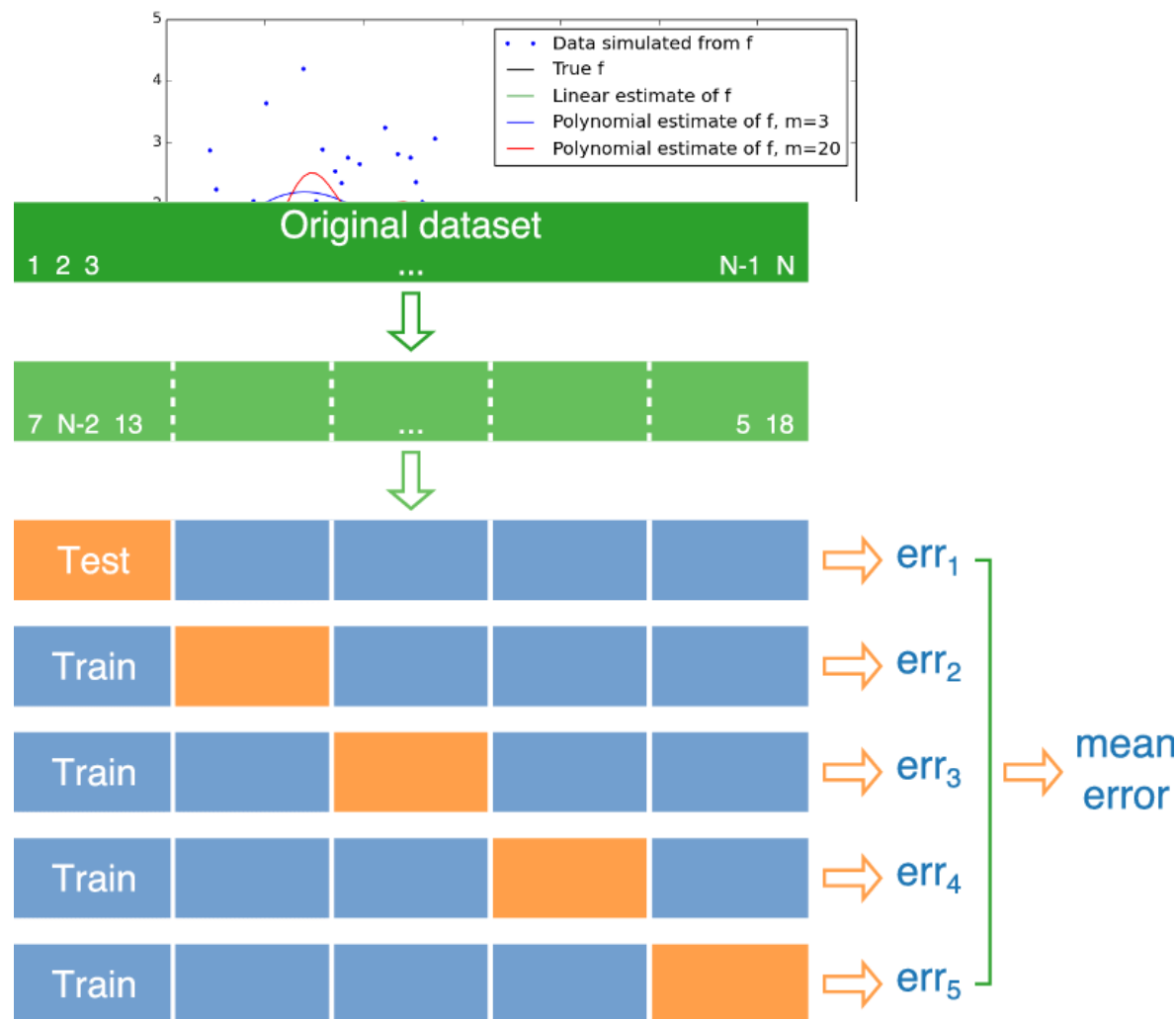
# Empirical models

- Polynomials, splines, ...
- Capture effective behaviour
- Prediction quality of left-out data

K-folding  
Boot-strapping

leave-one-out, LOO  
Jackknife

Problem-dependent  
how to split



Common in machine learning!

Best = predicts unseen data from the same pool of data

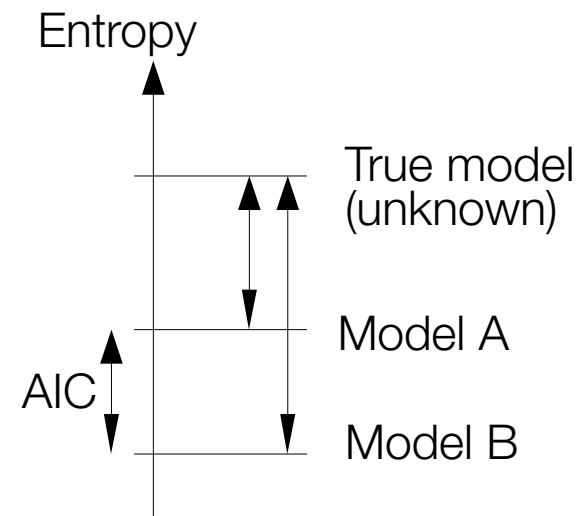
# Information theory

- Store data into the fitted model
- Measure entropy, loss of information
- KL divergence between model result and true model
- Akaike information criterion:

$$\text{AIC} = -2 * \underset{\substack{\text{maximum} \\ \text{likelihood}}}{\log(L)} + 2 * \underset{\substack{\text{number of} \\ \text{parameters}}}{p}$$

Beware: derived in the limit of high-data

Best = retains information in the data



## Variations

DIC: Deviance information criterion  
“effective” number of parameters

AICc: correction for few data

WAIC: uses the likelihood contribution from each data point

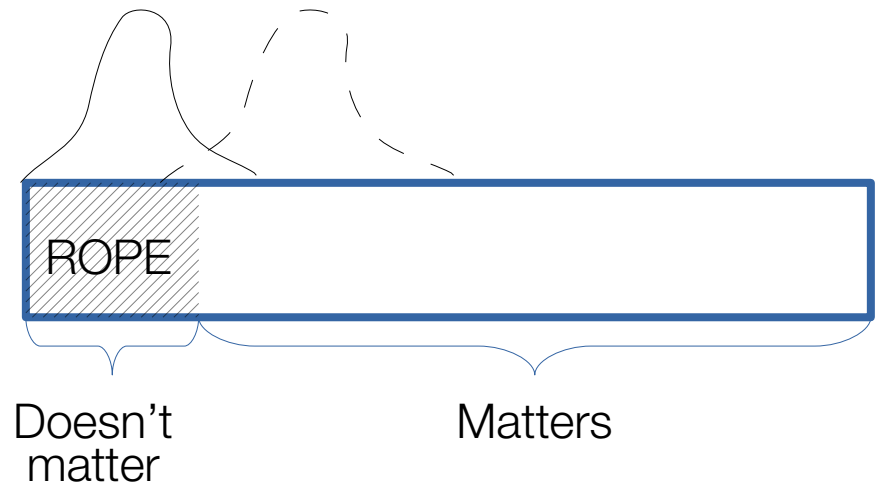
# Effect size

- Model B = Model A + some effect  
(e.g., a line, process)
- Does the effect matter?

Define

Region of practical equivalence (ROPE)

between the models



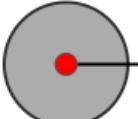
- Is parameter posterior contained in ROPE? (parameter estimation)

# Model comparison

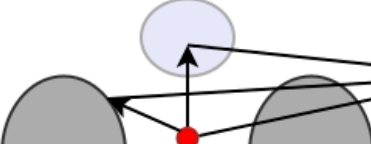
- Empirical models
  - Information content
  - Prediction quality
- Physical effects
  - Priors often well-justified
  - Bayesian model comparison

a)  powerlaw

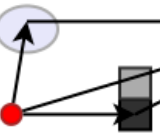
b)  wabs

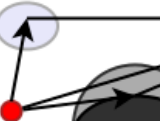
c)  sphere

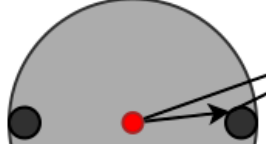
d)  torus

e)  torus  
+scattering

f)  wabs  
+pexmon

g)  wabs  
+pexmon  
+scattering

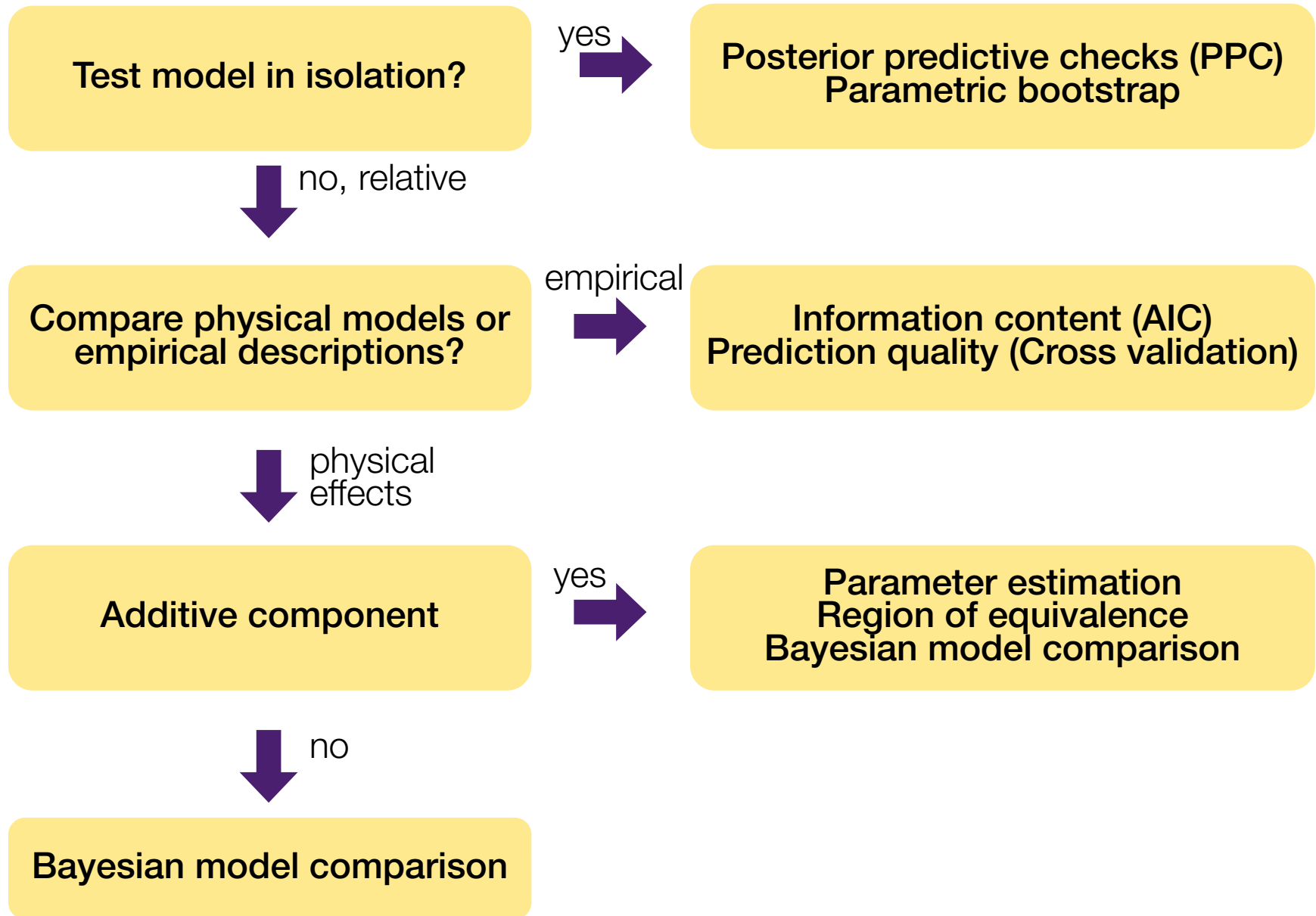
h)  torus  
+pexmon  
+scattering

i)  sphere  
+pexmon

Obscurer geometry of  
AGN in the CDF-S  
Buchner+14

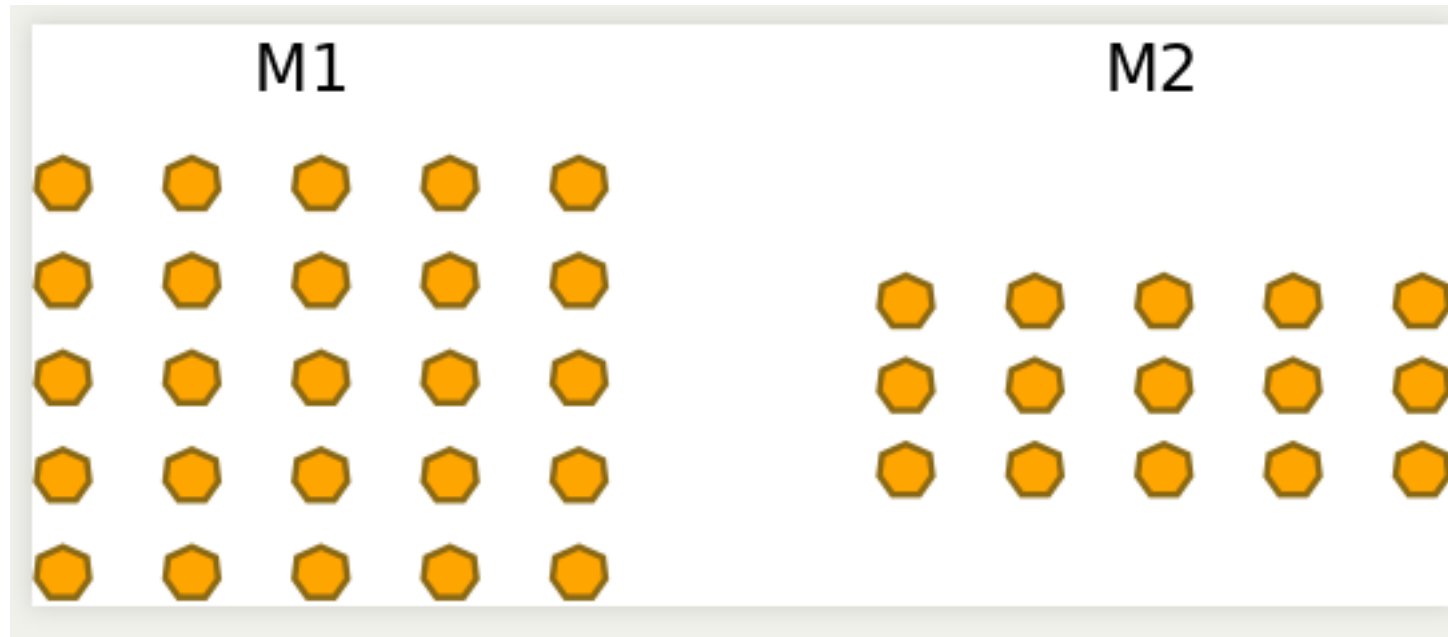


# Model comparison



# Punishing prediction diversity

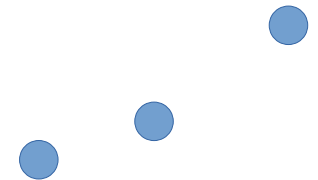
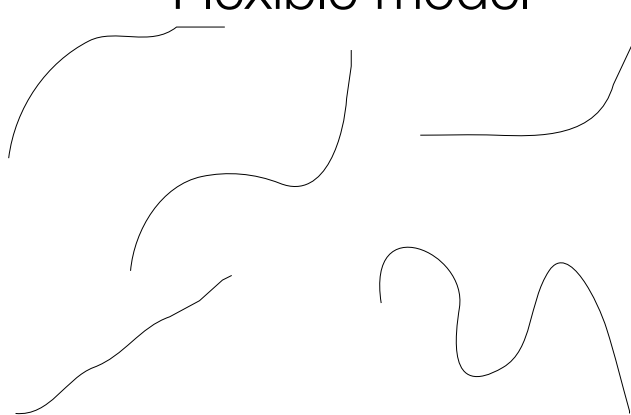
(not number of parameters)



Flexible model

Inflexible model

Data



L high, V tiny

L medium, V medium

# What to do with Z

- $Z_1, Z_2$

$$\underbrace{\frac{p(M1|D)}{p(M2|D)}}_{\text{Posterior odds ratio}} = \underbrace{Z_1}_{\text{Bayes factor}} \cdot \underbrace{\frac{p(M1)}{p(M2)}}_{\text{Prior odds ratio}}$$

## What to do with Z

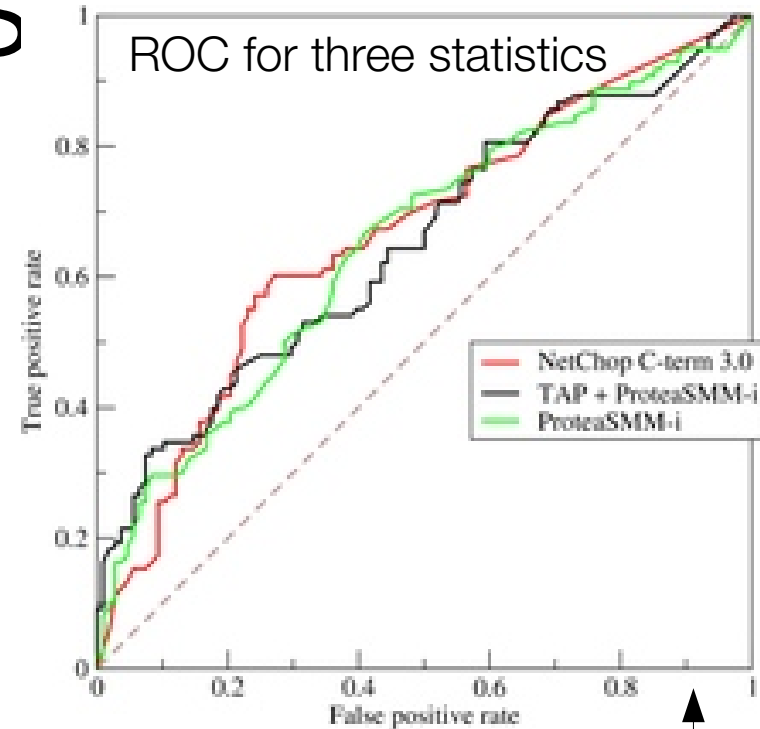
- $Z_1, Z_2$

$$\frac{p(M1|D)}{p(M2|D)} = \frac{Z_1 \cdot p(M1)}{Z_2 \cdot p(M2)}$$

- model priors: leave to reader or motivated by theory
- Does  $\frac{p(M1|D)}{p(M2|D)} = 3/1$  mean M2 is correct in a quarter of the cases?

# Comparing selection methods

- You have a statistic (a indicator) – (signal strength, likelihood ratio, Bayes factor, classifier probability)
- If you apply threshold:
  - if above → select model A
  - if below → select model B
- There will be
  - cases where you will be right
  - cases where you will be wrong
- determine the rates with simulations from model A and model B.
- Plot the rates as a function of threshold: ROC curve

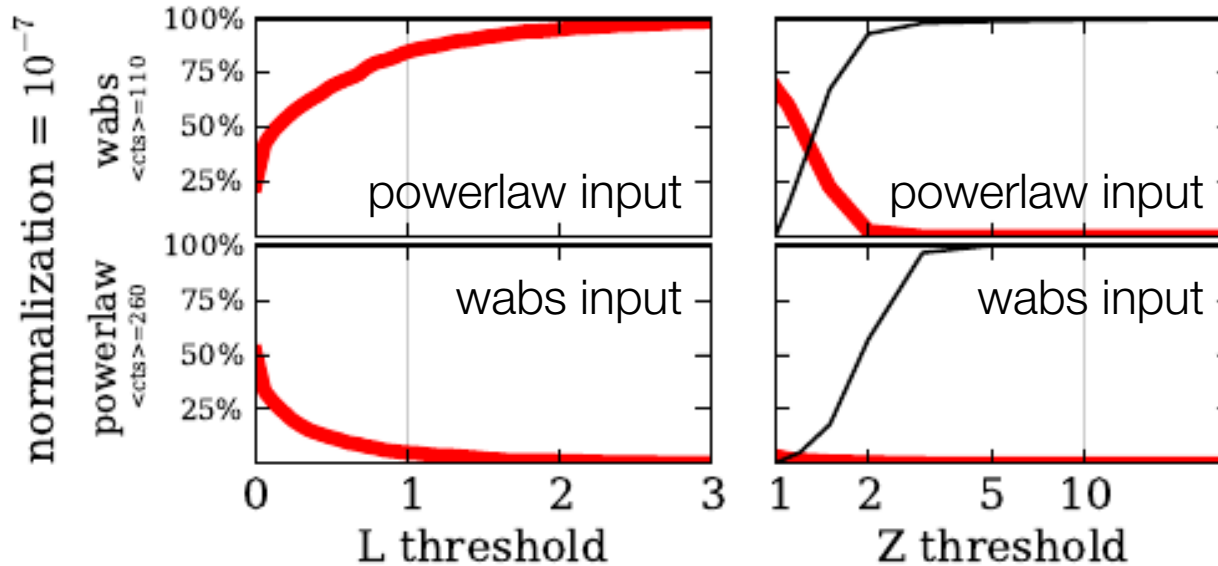


Predicted class \ Actual class	Predicted class	
	Cat	Dog
Cat	6	2
Dog	1	3

# Calibrating model decisions

- Model probabilities  $\rightarrow$  decisions
- False decision rate (false positives/negatives)
  - Monte Carlo simulations (parametric bootstrap)

# Calibrating model decisions



Buchner+14

False negatives  
Non-decisions

## Advantages:

- Get rid of parameter prior dependences
- Have frequentist properties of Bayesian method
- Completely Bayesian treatment + decisions

## Disadvantages:

- Can be computationally expensive

# Exercise

- Create a Bayes factor distribution  
 $P(\text{model A} | D) / P(\text{model B} | D)$
- from simulations from the simpler model

→ `example-sine-modelcomparison.ipynb`