

Stochastic Modelling Cheatsheet

Probability

Countability

A is called **countable** if A is finite or it's possible to enumerate A by \mathbb{N} .

Countable: $\mathbb{N}, \mathbb{Z}, \mathbb{Q}$

Uncountable: \mathbb{R}, \mathbb{Q}^c

Expectation

Linear: $E[\alpha X + \beta Y] = \alpha E[X] + \beta E[Y]$

Monotone: if $X \leq Y$ then $E[X] \leq E[Y]$

Tail Sum Formula

If X is nonnegative, Continuous r.v.:

$$E[X] = \int_0^\infty [1 - F(x)]dx = \int_0^\infty P(X > x)dx$$

Discrete r.v.:

$$E[X] = \sum_{k=1}^{\infty} P(X \geq k)$$

Moment Generating Function

$$m_x(t) = E[e^{tX}] \quad t \in \mathbb{R}$$

Distribution of X is determined by mgf provided expectation is finite in a neighborhood of the origin.

$$\frac{d^n}{dt^n} m_x(0) = E[X^n]$$

X, Y independent, $Z = X + Y$ is determined by:

$$m_Z(t) = E[e^{tZ}] = E[e^{tX}] \times E[e^{tY}] = m_X(t) \times m_Y(t)$$

Probability Generating Function

$$P_X(t) = E[t^X] \quad |t| \leq 1$$

$$P'_X(1) = E[X], \quad P''_X(1) = E[X(X-1)]$$

Conditional Probability

$$P(B|A) = \frac{P(A \cap B)}{P(A)} = \frac{P(A|B)P(B)}{P(A|B)P(B) + P(A|B^c)P(B^c)}$$

$$P_{X|Y} = P(X = x|Y = y) = \frac{P(X = x \cap Y = y)}{P(Y = y)} = \frac{p_{XY}(x, y)}{p_Y(y)}$$

$$E\{g(X)\} = E[E\{g(X)|Y\}]$$

Mixed Case (X continuous, N discrete):

$$F_{X|N}(x|n) = \frac{P(X \leq x \cap N = n)}{P(N = n)}$$

$$f_{X|N} = \frac{d}{dx} F_{X|N}(x|n)$$

Random Sums

$X = \sum_{n=1}^N \xi_n$, ξ_n 's are i.i.d and $\xi_n \perp N$

If $E[\xi_n] = \mu$, $Var[\xi_n] = \sigma^2$, $E[N] = \nu$, $Var[n] = \tau^2$,

$$E[X] = \mu\nu, \quad Var[X] = \mu^2\tau^2 + \nu\sigma^2$$

$$m_x(t) = E[m_\xi^N(t)] = P_N(m_\xi(t))$$

if $a < 0 < b$:

$$P(a < X \leq b) = \int_a^b \{f^{(n)}(x)p_N(n)\}dx + p_N(0)$$

if $a < b < 0$ or $0 < a < b$:

$$P(a < X \leq b) = \int_a^b \{f^{(n)}(x)p_N(n)\}dx$$

Markov Chain

Definition

A **Markov Chain** $X\{t\}$ is a stochastic process such that simultaneously

1. Countable state space S
2. Discrete time $T = N_0 = 0, 1, 2, \dots$
3. Satisfies Markov property
4. Satisfies stationary transition property

Markov Property

$$P(X_{t+1}|X_0 = x_0, \dots, X_t = x_t) = P(X_{t+1}|X_t = x_t)$$

Stationary Transition Property

$$P(X_{t+1}|X_t = x) = P(X_1|X_0 = x)$$

Absorbing State

State a is absorbing whenever

$$P(a, a) = 1 \text{ and } P(a, y) = 0 \text{ for } y \neq a$$

Recurrence and Transience

Hitting Time

$$T_A = \inf\{t > 0 : X_t \in A\}$$

First Step Analysis

$$U_{ik} := P(\text{Absorbed in state } k)$$

$$= P_{ik} + \sum_{j=0}^{r-1} U_{jk}P_{ij}$$

$$w_i := \sum_{n=0}^{T_A-1} g(X_n)$$

$$= g(i) + \sum_{j=0}^{r-1} P_{ij}w_j$$

$$v_i := E_i[T_A]$$

$$= 1 + \sum_{j=0}^{r-1} P_{ij}v_j$$

Hitting Probability

$$\rho_{xy} := P_x(T_y < \infty) = P(T_y < \infty | X_0 = x)$$

$$\rho_{xC} = \sum_{z \in C} P(x, z) + \sum_{z \in S_T} P(x, z)\rho_{zC}$$

A state y is called

- Recurrent whenever $\rho_{yy} = 1$
- Transient whenever $\rho_{yy} < 1$

Recurrent states need not be absorbing. Absorbing states are recurrent.

Markovian Martingale Property

$$\sum_{y \in S} yP(x, y) = x \text{ for all } x \in S$$

For a Markovian Martingale with state Space $S = 0, 1, \dots, d$, and only state 0 and d are absorbing. We have $\rho_{xd} = x/d$

Branching Process

Offspring $\xi, \xi_k, \xi_{k,t+1}$ are i.i.d r.v.'s

$$X_{t+1} = \sum_{k=1}^{X_t} \xi_{k,t+1}$$

$$P(x, y) = P\{\sum_{k=1}^x \xi_k = y\}$$

Probability generating function: $P_\xi(u) = E[u^\xi]$

Possibility of extinction:

if $P(\xi = 1) = 1$ then $\rho_{01} = 0$

if $P(\xi = 1) < 1$ and $E[\xi] = P'_\xi(1) \leq 1$ then $\rho_{01} = 1$

if $E[\xi] > 1$ then $\rho_{01} < 1$,

ρ_{10} is the smallest nonnegative solution to $u = P_\xi(u)$

Stationary Distribution

1. π is a valid pmf
2. $\pi P = \pi$

Existence of an unique π i.f.f. an **irreducible positive recurrent** chain

Steady State Distribution

If exists a steady state distribution π :

1. $\pi = \lim_{t \rightarrow \infty} \pi_0 P^t$ for all initial state π_0
2. Existence: π is a stationary distribution
3. Uniqueness: π is the only stationary distribution

Not the other way around: Unique stationary distribution does not guarantee a steady state distribution.

Birth & Death Chain

$$P(x, y) = \begin{cases} q_x, & \text{if } y = x - 1 \\ r_x, & \text{if } y = x \\ p_x, & \text{if } y = x + 1 \\ 0, & \text{otherwise} \end{cases}$$

irreducible $\Leftrightarrow q_x, p_x > 0$ for all $x > 0$ and $p_0 > 0$

$$\gamma_0 = 1, \gamma_y = \frac{\prod_{i=1}^y q_i}{\prod_{i=1}^y p_i} = \prod_{i=1}^y \frac{q_i}{p_i}$$

$$P_x(T_a < T_b) = \frac{\sum_{y=x}^{b-1} \gamma_y}{\sum_{z=a}^{b-1} \gamma_z}$$

$$\rho_{10} = \lim_{b \rightarrow \infty} P_1(T_0 < T_b) = 1 - 1/\sum_{z=0}^{\infty} \gamma_z$$

Recurrent $\Leftrightarrow \sum_{z=0}^{\infty} \gamma_z = \infty$

$$\delta_0 := 1 \text{ and } \delta_y := \frac{\rho_0 \times \dots \times \rho_{y-1}}{q_1 \times \dots \times q_y}$$

Stationary distribution exists: $\sum_{y=0}^{\infty} \delta_y < \infty$ ($p < 1/2$)

$$\pi(x) = \frac{\delta_x}{\sum_{y=0}^{\infty} \delta_y}$$

Stationary distribution = S.S.D. only when $r \neq 0$ (aperiodic)

Positive/Null Recurrent

$$\left\{ \begin{array}{c} \text{Positive} \\ \text{Null} \end{array} \right\} \text{ recurrent if } m_y = E_y[T_y] = \left\{ \begin{array}{c} < \infty \\ = \infty \end{array} \right\}$$

If S is finite:

- S has at least one positive recurrent state
- S has no null recurrent state

The existence and uniqueness of stationary distribution

An **irreducible and positive recurrent** chain has a unique stationary distribution π with $\pi(x) = 1/m_y$

Null positive recurrent chain doesn't have a stationary distribution.

The proportion of time spent in state y is $\frac{\rho_{xy}}{m_y}$

Period of a State

$$x \in S \quad I_x = \{n \geq 1 : P^n(x, x) > 0\}$$

$$d_x := \text{g.c.d of } I_x$$

d_x is the period of state x

if $x \leftrightarrow y$ then $d_x = d_y$

Aperiodic: An irreducible Markov chain with $d_x = 1$ for all $x \in S$

Regular Chain

For some $n \in \mathbb{N}$, P^n has strongly positive entries:

$$P^n(x, y) > 0 \text{ for all } x, y \in S$$

$$d = d_x = 1$$

Existence of Steady State Distribution

When a Markov chain is:

1. irreducible
2. positive recurrent
3. aperiodic

Pure Jump Process

1. State space S is countable
2. Sample paths are **right-continuous**

Time of explosion: $\tau_{\infty} := \lim_{n \rightarrow \infty} \tau_n$

Pure Jump Markov Process

$$P_{x_0}\{X(s_1) = x_1, \dots, X(s_n) = x_n\} = \prod_{i=0}^{n-1} P_{x_i, x_{i+1}}(s_{i+1} - s_i)$$

Embedded Markov Chain

Let $\tau_0 = 0 < \tau_1 \leq \tau_2 \leq \tau_n < \infty$ be the holding times

Let $X_0 \neq X_1, X_1 \neq X_2, \dots, X_{n-1}$ be the associated states

$$q_x = 1/E_x(\tau_1), \quad q_{xx} = -q_x$$

$$Q_{xy} = P_x\{X(\tau_1) = y\} \quad (X \text{ non-absorbing})$$

$$q_{xy} = q_x Q_{xy}$$

$\{X_n\}$ is a Markov chain with initial distribution π_0 and transition matrix Q

As long as $\tau_n < \infty$,

$$X(t) = \sum_{k=0}^n X_k 1_{[\tau_k, \tau_{k+1})}(t)$$

Chapman-Kolmogorov Equation

$$P_{xy} = \sum_{z \in S} P_{xz}(t) P_{zy}(s)$$

Forward and Backward Equations

$$P'_{xy}(t) = \sum_{z \in S} q_{xz} P_{zy}(t)$$

$$P'_{xt}(t) = \sum_{z \in S} P_{xz}(t) q_{zy}$$

Birth & Death Process

The Condition of Explosion

$$\tau_{\infty} = \lim_{n \rightarrow \infty} \tau_n < \infty \Leftrightarrow \sum_{x=0}^{\infty} \frac{1}{\lambda_x} + \sum_{y=1}^{\infty} \sum_{x=y}^{\infty} \frac{\mu_x \dots \mu_{x-y+1}}{\lambda_x \dots \lambda_{x-y}}$$

\Rightarrow no explosion for sublinear birth rates

Stationary distribution:

$$\delta_0 = 0, \delta_y = \frac{\lambda_0 \dots \lambda_y - 1}{\mu_1 \dots \mu_y}$$

$$\pi(x) = \frac{\delta_x}{\sum_{y=0}^{\infty} \delta_y}$$

$$X(t) \text{ transient} \Leftrightarrow X_n \text{ transient} \Leftrightarrow \sum_{y=1}^{\infty} \frac{\mu_1 \dots \mu_y}{\lambda_1 \dots \lambda_y} < \infty$$

Linear ODE

The solution to $f'(t) = -cf(t) + g(t), t \geq 0$ is

$$f(t) = f(0)e^{-ct} + \int_0^t e^{-c(t-s)} g(s) ds$$

Poisson Process

Homogeneous

$$X(0) = 0$$

$$P_{xy}(t) = e^{-\lambda t} (\lambda t)^{y-x} / (y-x)!, \text{ if } x \leq y$$

$$X(t) - X(s) \sim \text{Poisson}\{\lambda(t-s)\}$$

$$\tau_k - \tau_{k-1} \sim \text{Exponential}(\lambda)$$

$$\text{mgf } m_X(s) = E[e^{sX}] = \exp(\lambda_X(e^t - 1))$$

Superposition

If $X \sim \text{Poisson}(\lambda_X)$ and $Y \sim \text{Poisson}(\lambda_Y)$, X, Y independent, then $X + Y \sim \text{Poisson}(\lambda_X + \lambda_Y)$

Thinning

If $\xi_1, \xi_2, \dots \stackrel{i.i.d}{\sim} \text{Bernoulli}(p)$ then $\sum_{l=1}^X \xi_k \sim \text{Poisson}(p\lambda_X)$

Inhomogeneous

Homogeneous: $\lambda_X = \lambda > 0$

Inhomogeneous: $\lambda_X(t) \geq 0$,

$$\Lambda(t) = E[X(t)] = \int_0^t \lambda_X(u) du$$

$$X(t) - X(s) \sim \text{Poisson}\{\Lambda_X(t) - \Lambda_X(s)\}$$

Satisfies Markov property, but not stationary transition property

Compound Poisson Process

Let $X(t) \sim \text{Poisson}(\lambda)$,

Y_n are i.i.d r.v.'s with $G(y) = P(Y_n \leq y)$

$$Z(t) = \sum_{k=1}^{X(t)} Y_k$$

Let $E[Y_n] = \mu$ and $\text{Var}(Y_n) = \sigma^2$ Then

$$E[Z(t)] = \lambda \mu t \text{ and } \text{Var}[Z(t)] = \lambda(\mu^2 + \sigma^2)t$$

$$F_{Z(t)}(t) = e^{(-\lambda t)} 1_{[0, \infty)}(x) + \sum_{n=1}^{\infty} \frac{e^{(-\lambda t)} (\lambda t)^n}{n!} G^{(n)}(x)$$

Failure Time (critical value a):

$$\{F > t\} = \{Z(t) < a\}, \quad P(F > t) = F_{Z(t)}(a)$$

$$E[F] = \int_0^{\infty} P(F > t) dt = \lambda^{-1} \sum_{n=0}^{\infty} G^{(n)}(a)$$

If $Y_n \sim \text{Exponential}(\mu)$, then

$$E[F] = \frac{1 + \mu a}{\lambda}$$

Long Run Behaviour

Solve $\pi q = 0$.

$$\pi(x) = \begin{cases} \frac{1}{q_x m_x} & x \in C \\ 0 & x \notin C \end{cases}$$

C is the union of positive recurrent communication classes.

Irreducible positive recurrent process \Rightarrow steady state distribution exists.

Infinite Server Queue

$$\lambda_x = \lambda, \mu_x = \mu x$$
$$\pi(x) = \frac{(\lambda/\mu)^x}{x!} e^{-\lambda/\mu}$$

Finite(N-server) Server Queue

$$\lambda_x = \lambda, \mu_x = \begin{cases} \mu & a \leq x < N \\ N\mu & x \geq N \end{cases}$$

Gaussian Process

Univariate Gaussian Distribution

$$X \sim \text{Normal}(\mu, \sigma^2)$$
$$\text{mgf } m_X(T) = \exp(\mu t + \sigma^2 t^2 / 2)$$

Bivariate Gaussian Distribution

$$X = (X_1, X_2)' \sim N(\mu, \Sigma)$$

$$\mu = \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}, \Sigma = \begin{pmatrix} \Sigma_{1,1} & \Sigma_{1,2} \\ \Sigma_{2,1} & \Sigma_{2,2} \end{pmatrix}$$

$$\text{mgf } m_X(T) = \exp(\mu' t + t' \Sigma' t / 2)$$

Multivariate Gaussian Distribution

$$\text{pdf exist} \Leftrightarrow \det \Sigma_x \neq 0 \text{ Then}$$

$$f(x) = \frac{1}{(2\pi)^{d/2} \sqrt{\det(\Sigma)}} \exp\left(-\frac{1}{2}(x - \mu)' \Sigma^{-1}(x - \mu)\right)$$

Conditional Distribution: Bivariate

$$E[X_1|X_2] = E[x_1] + \frac{\text{Cov}(X_1, X_2)}{\text{Var}(X_2)}(X_2 - E[X_2])$$

$$\text{Var}(X_1|X_2) = \text{Var}(X_1) - \frac{\text{Cov}(X_1, X_2)^2}{\text{Var}(X_2)}$$

$$X_1|X_2 = x_2 \sim N(E[X_1|X_2 = x_2], \text{Var}(X_1|X_2 = x_2))$$

Conditional Distribution: Multivariate

$$\mu_X = (\mu'_X, \mu'_Y)', \Sigma_Z = \begin{pmatrix} \Sigma_X & C'_{XY} \\ C_{XY} & \Sigma_Y \end{pmatrix}$$

$$\text{Find } b \text{ s.t. } \Sigma_Y b' = C_{XY}$$

$$\mu_{X|Y=y} = E[X] + b(y - E[Y])$$

$$\Sigma_{X|Y=y} = \Sigma_X - b C_{XY}$$

$$X|Y = y \sim N(\mu_{X|Y=y}, \Sigma_{X|Y=y})$$

Gaussian Process

$$\{X(t)\}_{t \in [0, \infty)}, \text{ for all } d, t_1, \dots, t_d \in [0, \infty),$$
$$(X(t_1), \dots, X(t_d)) \text{ is a } d\text{-dimensional Gaussian vector.}$$

Brownian Motion

$$\{W(t) : t \in [0, \infty)\}, W(0) = 0$$
$$\text{For } t \geq s \geq 0, W(t) - W(s) \sim N(0, \sigma^2(t - s))$$

Increments of non-overlapping time intervals are independent

$$r_W(s, t) = \text{Cov}(W(s), W(t)) = \sigma^2 \min\{s, t\}$$

Brownian Bridge

$$B = \{B(t) : 0 \leq t \leq 1\}$$
$$\mu_B(t) = 0, r_B(s, t) = \sigma^2 \{\min\{s, t\} - st\}$$

Geometric Brownian Motion

$$S(t) := s_0 e^{\alpha t + \sigma W(t)}$$

$$\text{If } s_0 = 1, \alpha = 0, \text{ and } \sigma = 1, \text{ then } \mu_S(t) = e^{t/2} \text{ and}$$
$$r_S(s, t) = e^{(s+t)/2} (e^{\min\{s, t\}} - 1)$$

Log-normal distribution of r.v. X:

$$E[X] = \exp(\mu + \sigma^2/2)$$

$$f(x) = \frac{1}{\sqrt{2\pi\sigma x}} \exp\left(-\frac{(\ln x - \mu)^2}{2\sigma^2}\right)$$

Reflection Principle

$$P(W(t) > 0) = P(W(t) < 0) = 1/2$$

$$P(W(t) > a) = P(T_a \leq t)/2$$

$$F_{T_1}(t) = P(|W(t)| > a) = 2(1 - \Phi(a/\sqrt{\sigma^2 t}))$$

$$\text{Let } M(t) := \max_{0 \leq s \leq t} W(s), M_t \stackrel{D}{=} |W(t)|$$

Brownian Martingale

$$\text{One of NASC: } \mu_X(t) \equiv \text{const}$$

Donsker's Theorem

$$\text{Let } \xi, \xi_1, \xi_2, \dots \text{ be i.i.d. r.v.'s with } E[\xi] = 0 \text{ and } \text{Var}(\xi) = \sigma^2$$

$$\text{Let } S_n = \sum_{k=1}^n \xi_k. \text{ For } \Delta_t, \triangle_x > 0 \text{ define:}$$

$$X_{\Delta}(t) := X_{\Delta_t, \Delta_x}(t) := \Delta_x S_{\lfloor t/\Delta_t \rfloor}$$

$$\mu_{X_{\Delta}}(t) = \Delta_x E(S_{\lfloor t/\Delta_t \rfloor}) \equiv 0$$

$$r_{X_{\Delta}}(t) = \Delta_x^2 E(S_{\lfloor t/\Delta_t \rfloor} S_{\lfloor s/\Delta_t \rfloor}) = \Delta_x^2 \sigma^2 \min\{\lfloor t/\Delta_t \rfloor, \lfloor s/\Delta_t \rfloor\}$$

$$\text{take } \Delta_x := \sqrt{\Delta_t}$$

$$\text{Theorem: } X_{\Delta} \xrightarrow{D} W \quad \Delta_t = \Delta_x^2 \downarrow 0$$

$$\text{CLT: } \Delta_t = 1/n$$

$$P\left(\frac{S_n}{\sqrt{n}} \leq x\right) = P(X_{\Delta}(1) \leq x) \approx P(W(1) \leq x) = \Phi\left(\frac{x}{\sigma}\right)$$

Heat Equation

$$\frac{\partial}{\partial t} f(t, x) = \frac{\sigma^2}{2} \frac{\partial^2}{\partial x^2} f(t, x)$$

Boundary Crossing with Drift

$$P(T_b^{\mu} < T_a^{\mu}) = \frac{\exp(-2\mu a/\sigma^2) - 1}{\exp(-2\mu a/\sigma^2) - \exp(-2\mu b/\sigma^2)}$$

Integrated Brownian Motion

$$Y(s) = \int_0^s W(u) du$$

Gaussian (the limit of a linear combination of normal r.v.)

$$\mu_Y = E[Y(s)] = E[\int_0^s W(u) du] = \int_0^s \mu_W(u) du = 0$$

$$r_Y(s, t) = \text{Cov}\{Y(s), Y(t)\} = \frac{s^2(3t-s)}{6}, s \leq t$$

$$\text{Not Markovian} \Rightarrow \text{Cov}\{Y(t) - Y(s), Y(s)\} = s^2(t-s)/2 \neq 0\}$$

$$\text{Cov}\{Y(s), W(t)\} = s \min\{s, t\} - (\min\{s, t\})^2/2$$

White Noise

$$Y = \int_a^b g(t) W'(t) dt = \int_a^b g(t) dW(t)$$

$$= g(b)W(b) - g(a)W(a) - \int_a^b g'(t)W(t)dt$$

White noise: $W'(t)$ or $dW(t)$

Gaussian

$$E[y] = 0$$

$$r_Y(s, t) = \sigma^2 \int_0^{\min\{s, t\}} g^2(u) du$$

$$r_Y(t, t) = \sigma^2 \int_0^t g^2(u) du$$

$$\text{if } g(t) = 1, \text{ then } Y(t) = W(t)$$