

Development of a Port ENC Standard

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Overview

- 1. Why Port ENC? motivation
- 2. ECDIS / Inland ECDIS status in the Port of Hamburg
- 3. IHO standards (S-44 & S-57)
- 4. Port ENC for Port of Hamburg
- 5. Special port requirements
- 6. EFFORTS Project









Why Port ENC?

- Ports are the hubs for global maritime trade.
- Efficient arrival/departure for ships and their cargo is crucial.
- There are special navigational and manoeuvring requirements.









Increasing global trade

(ISL-forecast 2003 and ISL/Global Insight 2004) related to the Port of Hamburg)



Development of the container handling for the Port of Hamburg (in Mio. TEU = Twenty Feet Equivalent Unit Source: Hafen Hamburg Marketing e.V. C









Very large vessels (VLCCs)











Increasing ship operations in ports











Motivation

Masters and pilots approaching a seaport usually use an Electronic Chart Display and Information System (ECDIS)

But the current ECDIS and Inland ENC standard cannot fulfill requirements in ports for:

- precise maneuvering
- berthing
- turning
- docking











Need for:

- Best available information for safe and efficient operations
- Large-scale data for docking, berthing, & turning manoeuvres
- Up-to-date:
 - hydrographic data (bathymetry)
 - topography (geographic)









ENC requirements for maneuvering big ships in harbour access channels, turning basins, berths, locks and for the port maintenance go far beyond the current ECDIS / Inland ECDIS standards for:

- up-to-date
- quality
- accuracy
- scale
- chart features/objects and attributes
- reliability



Hasenpusch / Hafen Hamburg









Maritime vs. Inland ENC

- The IMO **ECDIS** performance standard using an **ENC** supports maritime navigation in the open sea and coastal areas.
- The Inland ENC Standard is based on IMO and IHO ECDISrelated standards, but is refined for navigation on inland waterways.
 - Defines further extensions for river navigation

At present, there is no standard or extensions to specifically meet the requirements of port operations.









Why Port ENC?

For Port operations, there are special requirements for vertical and horizontal accuracy. This is achieved by using modern sensor technology.

This type of source data (e.g., topography and hydrographic data) should be made available by port authorities.









One example is the official ENC of Hamburg.

- Produced and issued by BSH, it meets all the relevant ENC related standards and fulfills the requirements for maritime navigation.
- But, the ENC too small in scale, does not have any bathymetric detail and poorly defined horizontal accuracy for topographic features such as quay walls, piers, pontoons, etc.

Result: Not suitable for special operations within the port area.









Why Port ENC?

The development of a **Port ENC standard** focuses on high precision operations in ports.

- an independent but complementary standard to "maritime" ECDIS and Inland ECDIS.

A Port ENC intended to align with the ongoing developments for maritime and Inland ENCs.









IHO S-100 Geospatial Standard

- The new IHO geospatial data standard that will be in addition to (not replace) S-57
- Implementation to occur in 2010/2011.
- S-101 will be the product specification for the next-generation ENC. An improved ENC Product Specification (S-101) will not come into force until at least 2012!

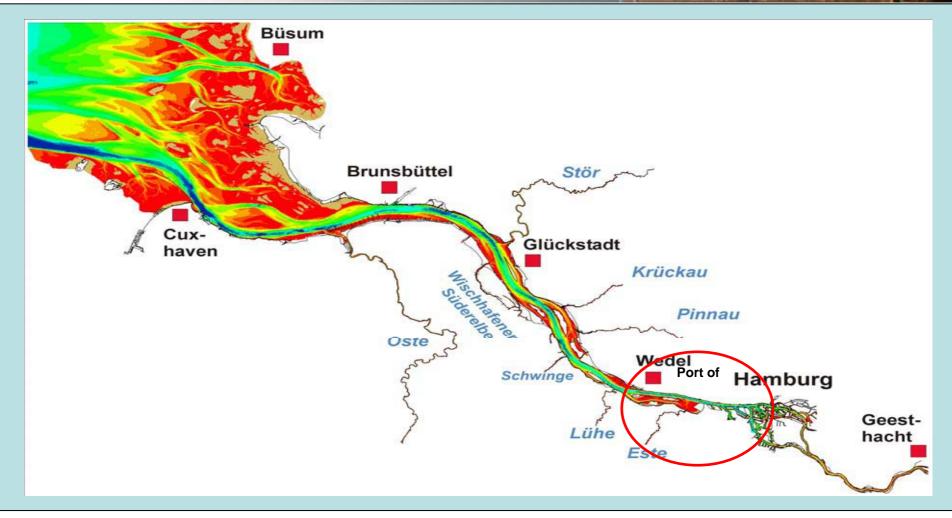
With the special navigational and maneuvering requirements in ports, there is a need to develop a Port ENC without delay.







Continue to



WE GROWINGEN

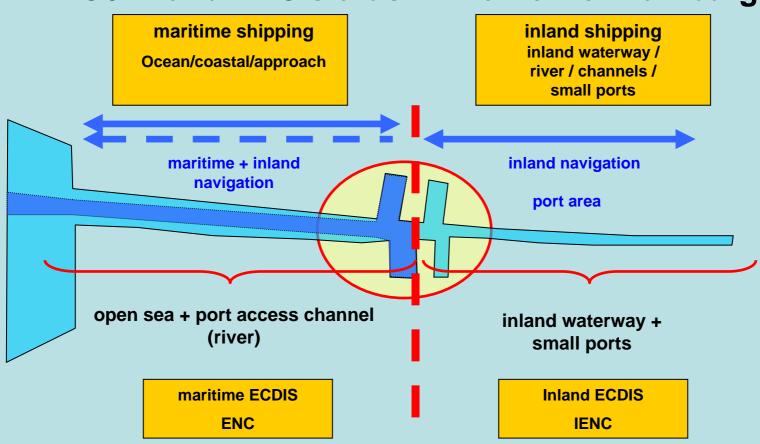








ENC / Inland ENC status in the Port of Hamburg





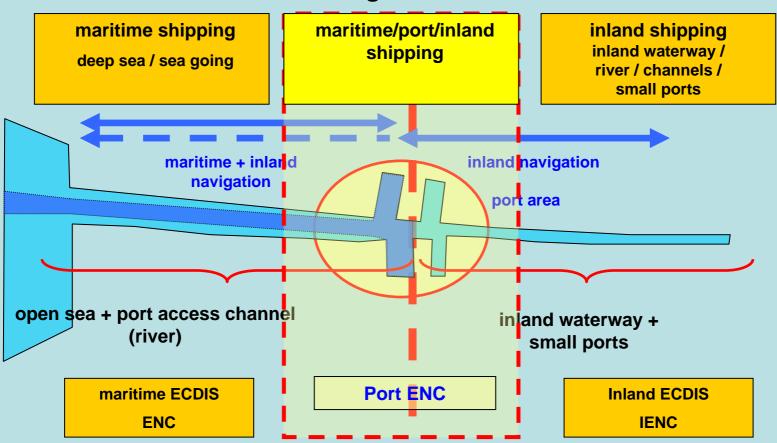




Committees

Adding a Port ENC

WAS CROMINGEN











IHO Standards (S-44 & S-57)

- Do not provide significant topographic source data for integration in ENCs.
- No dedicated accuracy requirements that apply for different navigational purposes / categories (e.g., port operations)

With ENCs and Inland ENCs, the IHO S-57 **Zone of Confidence** (**ZOC**) assessment used to assess the quality of **bathymetric** data.

not used for topographical data









S44 Ed. 5 new - Minimum Standards for Hydrographic Surveys - February 2008

Reference	Order	Special	la	1b	
Chapter 1	Description of areas.	Areas where under-keel clearance is critical	Areas shallower than 100 metres where under-keel clearance is less critical but features of concern to surface shipping may exist.	Areas shallower than 10 metres where under-kee clearance is not consider be an issue for the type of surface shipping expects transit the area.	
Chapter 2	Maximum allowable THU 95% Confidence level	2 metres	used for the	Port of Hamburg	ı
Para 3.2 and note 1	Maximum allowable TVU 95% <u>Confidence level</u>	a = 0.25 metre b = 0.0075	a = 0.5 metre b = 0.013	a = 0.5 metre b = 0.013	
Glossary and <u>note 2</u>	Full Sea floor Search	Required	Required	Not required	
Para 2.1 Para 3.4 Para 3.5 and note 3	Feature Detection	Cubic <i>features</i> > 1 metre	Cubic <u>features</u> > 2 metres, in depths up to 40 metres; 10% of depth beyond 40 metres	Not Applicable	
Para 3.6 and note 4	Recommended maximum Line Spacing	Not defined as <i>full sea floor</i> search is required	Not defined as <i>fluil sea floor</i> search is required	3 x average depth or 25 metres, whichever is gre For bathymetric lidar a s spacing of 5 x 5 metres	
Chapter 2 and note 5	Positioning of fixed aids to navigation and topography significant to navigation. (95% Confidence level)	2 metres	2 metres	2 metres	
Chapter 2	Positioning of the Coastline	qu	ay walls, bridges, lock	s etc. ?!	
and note 5	and topography less significant to navigation (95% <i>Confidence level</i>)	10 metres	20 metres	20 metres	
Chapter 2 and note 5	Mean position of floating aids to navigation (95%	10 metres	10 metres	10 metres	Y of NEW HAMPSHIE





S57 ECDIS definitions (Zone of Confidence)					5
ZOC	Position Accuracy	Depth Accuracy		Seafloor Coverage	Typical Survey Characteristics
			= 0.5 = 1		
A1	± 5 m	Depth (m) 10 30 100 1000	1 0.0	Full seafloor ensonification or sweep. All <u>significant</u> seafloor features detected and depths measured.	Controlled, systematic high accuracy Survey on WGS 84 datum; using DGPS or a minimum three lines of position (LOP) with multibeam, channel or mechanical sweep system.
		a = 1.0 b = 2			
		Depth (m)	Accuracy (m)	Full seafloor ensonification	Controlled, systematic srvey to
A2	± 20 m	10 30 100 1000		or sweep. All <u>significant</u> <u>seafloor features</u> detectedand depths measured.	standard accuracy; using modern survey echosounder with sonar or mechanical sweep.









S57 ECDIS definitions (Zone of Confidence)						5	
ZOC	Position Accuracy	Depth Accuracy		Seafloor Coverage		Typical Survey Characteristics	
A1	± 5 m	(m) 10 30 100	t 0.6 ± 0.8	Full seafloor ensonification or sweep. All <u>significant</u> seafloor features detected and depths measured.	Co ac us:	IHO S-44 Special Order +/- 2m versus ENC ZOC +/- 5m ing DGPS or a minimum three lines Mismatch between IHO S-44 Special Order and S-57 ENC	
A2	± 20 m	(m) 10 30 100	2 Accuracy (m) ± 1.2 ± 1.6	Full seafloor ensonification or sweep. All <u>significant</u> seafloor features detectedand depths measured.	Co st	ZOC (Zone of Confidence) for the Port of Hamburg B (3) = +/- 50m!!	









Port of Hamburg

Comparison between the maritime ENC and Port ENC











Port of Hamburg Port ENC

HPA - Masterchart

name: hafenbestandsplan-1.dwg

date: 13.07.2007

accuracy:

ca. 60% remote sensing (aerial photo) ±20cm

ca. 40% landsurvey ±2-3cm

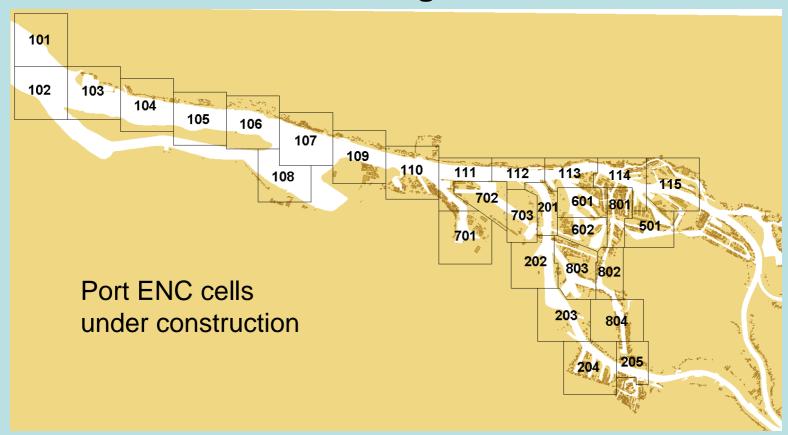








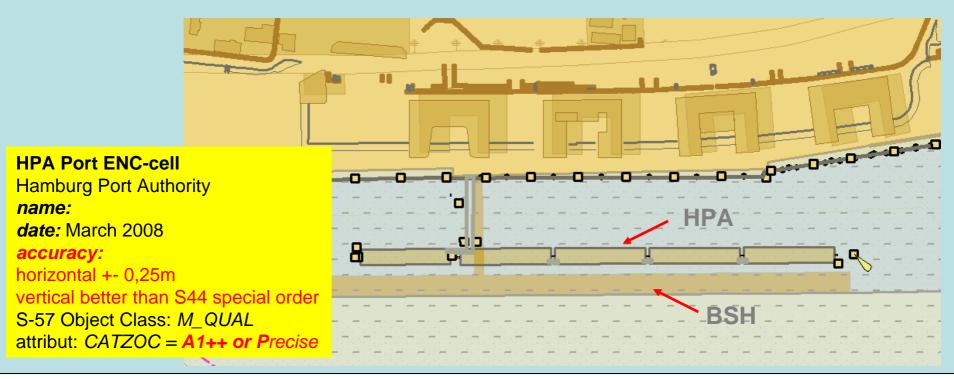
Port of Hamburg Port ENC









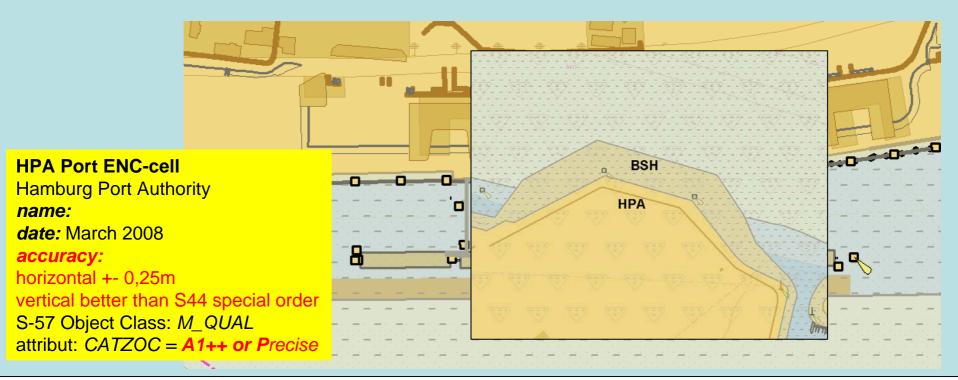








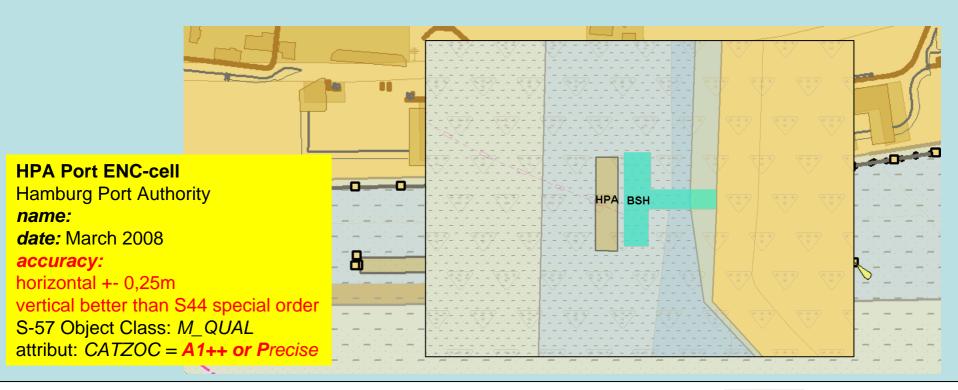
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fixed aids to navigation

topography significant to navigation

quay wall corner

pontoon corner

differencies HPA-BSH

North

differencies HPA-BSH			
rth Dist.	•		
	rth Dist.		

0,01

-0,62

0,56

0,01

0,02

0,62

average

min

max

-0,01

-0,19

0,15

	differencies HPA-BSH				
	East	North	Dist.		

-3,66

-17,15

4,35

7,79

2,42

17,67

-4,75

-13,93

6,84

average	-1,60	-2,89	8,05
min	-11,00	-11,69	3,84
max	10,42	19,74	22,30

East

surveyed by HPA



average

min

max





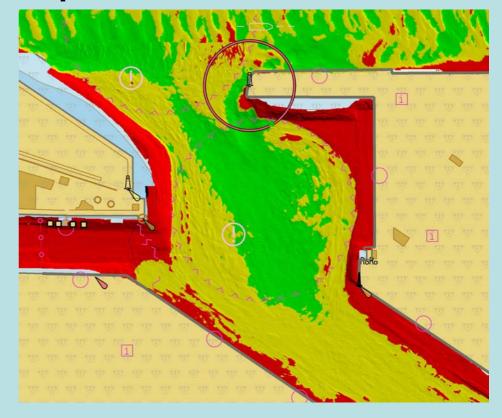
Dist.



A Port ENC includes extensions additional objects / features or information.

For instance:

- gridded bathymetry
- special structures











3-D bridge / lock passages information (air draft)













Sub-surface or underwater structures



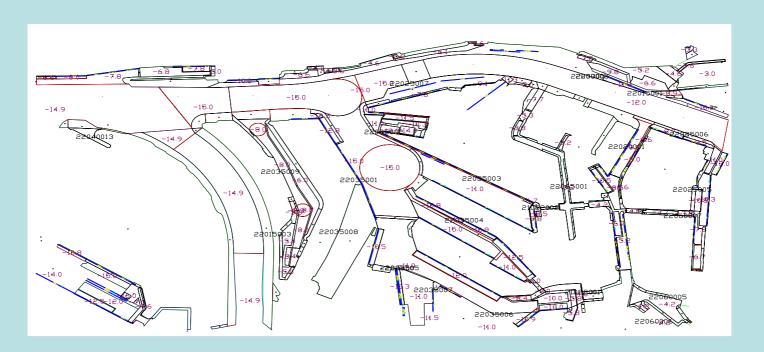








Sub-surface or underwater structures



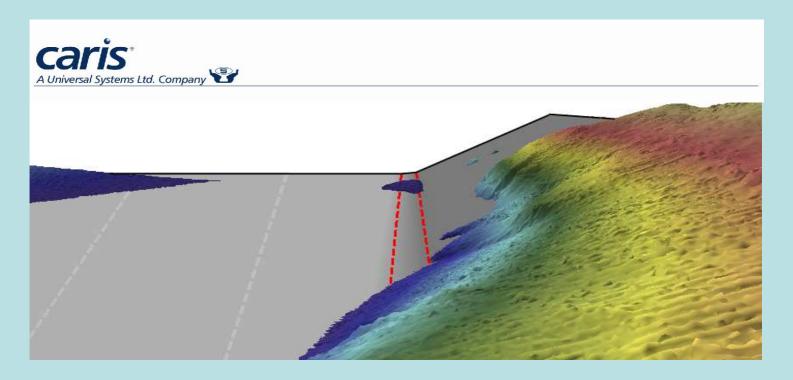








3-D channel model / reference model











Docking maneuver of the "Brilliance of the Seas", Dock Elbe 17, Port of Hamburg, 13 May 2008



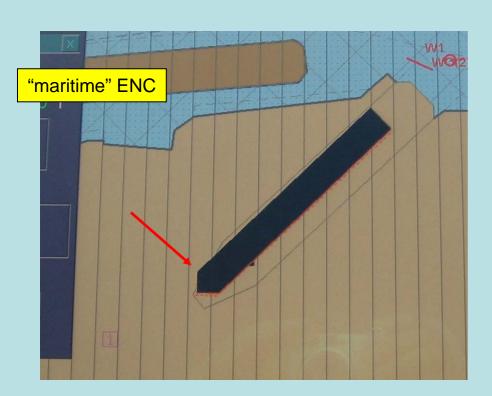


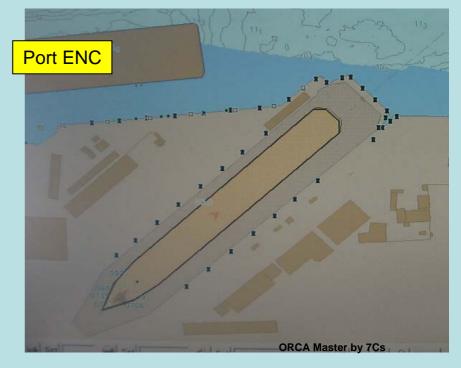






Docking maneuver of the "Brilliance of the Seas", Dock Elbe 17, Port of Hamburg, 13 May 2008





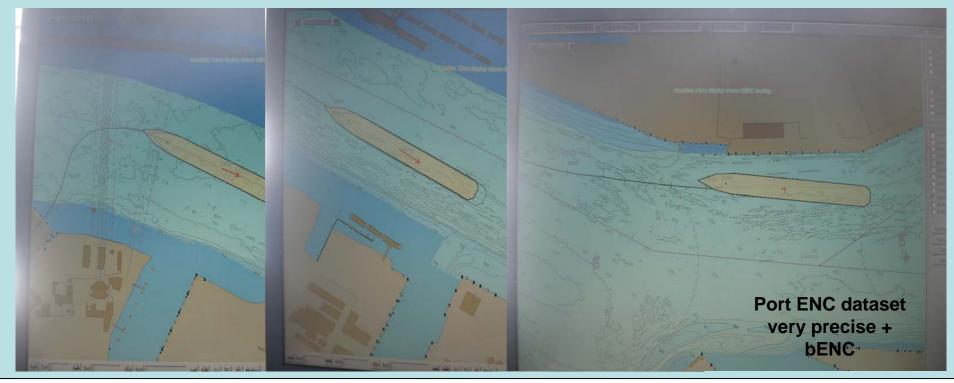








Docking maneuver of the "Brilliance of the Seas", Dock Elbe 17, Port of Hamburg, 13 May 2008











Docking maneuver of the "Brilliance of the Seas", Dock Elbe 17, Port of Hamburg, 13 May 2008











The European FP-6 DG Research Integrated Project "Effective Operations in Ports (EFFORTS)

- Aims to improve the competitiveness of European port operations and the quality of the ports labour conditions and market
- Started on 1 May 2006 and lasting for 42

http://www.efforts-project.org/cms/









Three main parts:

SP 1 Navigation in Ports

3 work packages dealing with safe and efficient approach and berthing of vessels

WP1.1: Tug Assistance

WP1.2: Precise Navigation and Manoeuvring in Ports

WP1.3: Port ECDIS

SP 2 Ports and Environment

4 work packages covering the most relevant environmental areas related to port operation

SP 3 Port Organisation

2 work packages providing an overall architecture, and software tools for operational support and risk assessment/management.









WP1.3: Port ECDIS

Using ECDIS as the base, overlay other types information to improve the interoperability of harbour-related tasks.

Ships – maneuvering and docking by Pilots using Portable Piloting Units (PPUs) with Port ENCs

Port Authority – dredging and maintenance activities at piers and terminal facilities









WP1.3: Port ECDIS

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WP 1.3 Port I																		П									
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	Month	5		7 1	,	18 11	12	1 2	,	4 5 1	6 7	1 1	18 11	12	1 2	3 4	5 6	,	1 1	18 1	11 12	1 2	3	4 5	6 7	1 1	11
	Year			200)6					21	007						2	800							2009		
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V₩P 1.3.0	Verification phase			ver	ificat	tion ph	iase																				
₩P 1.3.1	Potential users and requirements (questionnaire, interview, study)										П		qu	estio	User naire /		ement										
₩P 1.3.2	Port ECDIS specification (document)									S	pecifi	cation	Phase	1		Sp	ecific	ation I	Phase	2							
₩P 1.3.2.1	Specification of bathymetric data									1.7) bath	ymetr	ie														
₩P 1.3.2.2	Specification of reference model				П					2.	.) char	nel / i	eferer	ice m	odel												
₩P 1.3.2.3	Specification of additional requirements		\Box		П		\top	\top	\top		.) add													\top		\top	
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¥P 1.3.4	Tests with Port ECDIS prototype and evaluation of tests (report)																pre	ototy	ping	and fi	rst ti	ials		PPU?	,		
₩P 1.3.5	Port ECDIS follow-up requirements (document)																					fol	llow u	IP.	2. fol	low up	
₩P 1.3.6	Defining cost and business related figures																								costs		









WP1.3: Port ECDIS

Interviewed different users / stakeholders

(e.g., harbourmasters, masters, pilots, water police, ECDIS and Inland ECDIS experts, marine consultancies)

Questionnaire	8.April 2008 Hafenklub - Hamburg
Name:	
Organisation:	
Job / function:	
1 Questions about group membersl	hip
What Group do you belong to? (Choose from t	he list of groups)
1.1 Group A - main user	
1.1.1 Group A1	
☐ Harbour master ☐ Harbour pilots	
□ ∨TMIS	









WP1.3: Port ECDIS

Researched data quality aspects of IHO standards.

Definition of Data Quality in Standards used for ENC Data

EC FP6 project Efforts WP 1.3 Port ECDIS









EU project EFFORTS

WP1.3: Port ECDIS

Developing a
Port ECDIS
specification;
under development,
living document

Task 2 – Port ECDIS specification under development

EFFORTS

Requirements for new objects in a

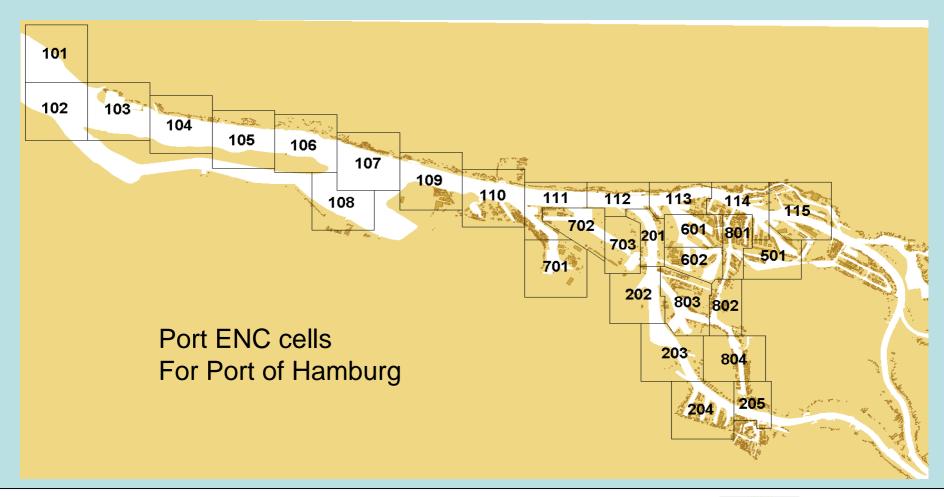
Port-ECDIS







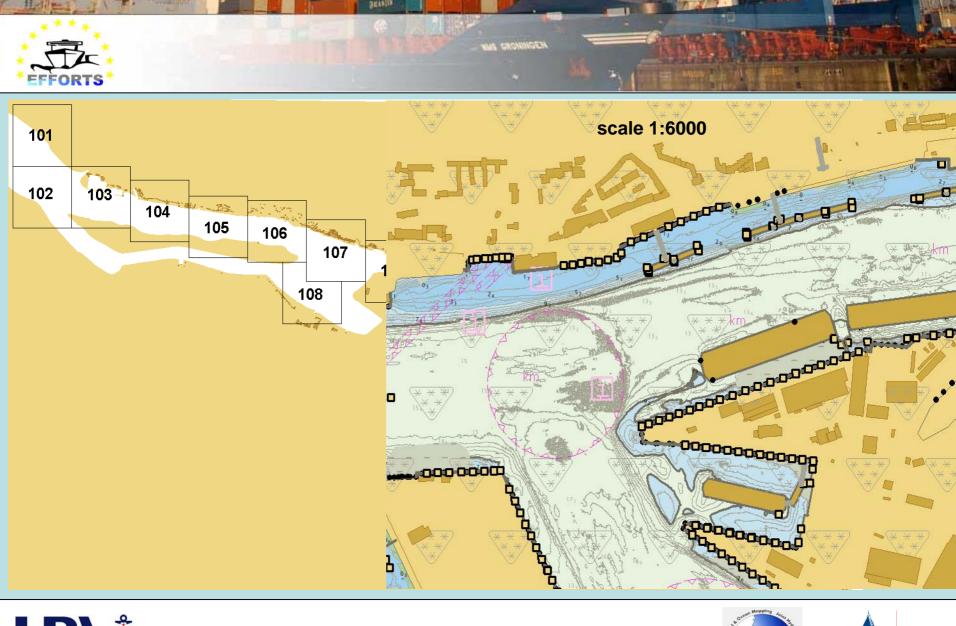
Constitution of







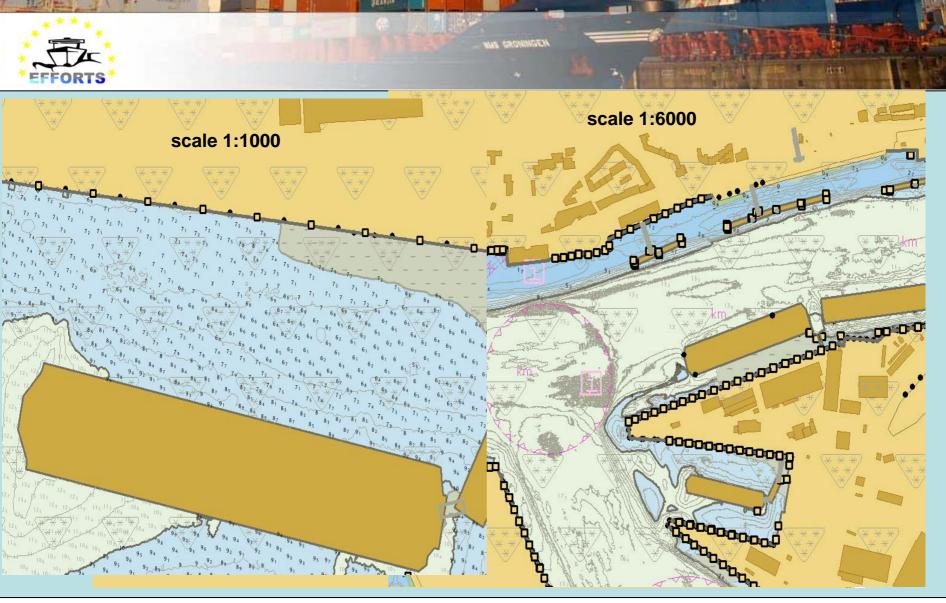




















Summary

- In order to meet navigational, manoeuvring, berthing, turning requirements in ports there is a need for a **Port ENC**.
- A **Port ENC** dataset was produced for the Port of Hamburg including new objects and features like gridded bathymetry and channel model.
- A **Port ENC** tested during EFFORTS Project.
- The Port of Hamburg will continue to produce and use Port ENCs.









First trials on board of our survey vessel with a base Port ECDIS/ECS











Conclusion

Need for three different types of ENC data:

"maritime" ENC for open sea and coastal areas

Inland IENC for rivers/inland waterways

Port PENC for precision manoeuvring/docking in ports









Thank you for your attention







